Anti-Lock Braking System (ABS)

This example describes a simple model for an Anti-Lock Braking System

(ABS). The model simulates the dynamic behavior of a vehicle

under hard braking conditions. The model represents a single wheel, which

may be replicated a number of times to create a model for a multi-wheel

vehicle.

This model uses the signal logging feature in Simulink(R). You log signals to the

MATLAB(R) workspace where you can analyze and view them. You can view

the code in sldemo\_absbrakeplots.m to see how this is done.