

Interview Prep Notes

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1 Image processing 101

1.1 Preparing input

```
import cv2
import numpy as np
img = cv2.imread("./Image_Processing_100_Questions/Question_01_10/imori.jpg")
print(img)
```

```
[[file:[[[132 80 67] [104 55 39] [100 54 36] ... [175 109 110] [134 88 70] [163 126 100]]
[[140 88 71] [117 65 52] [106 54 47] ... [177 139 135] [176 137 123] [152 110 91]]
[[137 85 69] [131 77 66] [119 67 60] ... [207 155 148] [232 179 159] [161 104 82]]
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```

1.2 Preparing output

```

def save_output(fname, image):
    cv2.imwrite(fname, image)
    return fname

```

1.3 Otsu Thresholding

1.4 BGR to HSV

First the RGB values are normalized by dividing by 255. Therefore, $R' = R/255$, $G' = G/255$, $B' = B/255$. Then we calculate C_{max} and C_{min} . Now $\Delta = C_{max} - C_{min}$. To calculate:

$$C_{max} = \max(R', G', B')$$

$$C_{min} = \min(R', G', B')$$

C_{max} and C_{min} are the largest and smallest of R , G and B respectively.

For **hue** calculation If $C_{max} = R'$, then,

$$H = 60 \times \left(\frac{G' - B'}{\Delta} \text{mod} 6 \right)$$

If $C_{max} = G'$, then,

$$H = 60 \times \left(\frac{B' - R'}{\Delta} + 2 \right)$$

If $C_{max} = B'$, then,

$$H = 60 \times \left(\frac{R' - G'}{\Delta} + 4 \right)$$

For **saturation** calculation, if $C_{max} = 0$,

$$S = 0$$

else if $C_{max} \neq 0$,

$$S = \frac{\Delta}{C_{max}}$$

For value calculation,

$$V = C_{max}$$

1.5 Discretization of Color

Refers to the quantization of color

- Find the quantization levels, here we use 4
- Get the ranges for example for 4 levels: $(-1, 63)$, $(64, 127)$, $(127, 191)$, $(191, 255)$

```
out = img.copy()
for i in range(4):
    ind = np.where(((64*i-1) <=out) & (out < (64*(i+1)-1)))
    out[ind] = 32* (2*i+1)

fname = save_output("q6.jpg", out)
fname
```

- Find the midpoint of each quantization levels: 32, 96, 122
- The Value of output is these values where the older values occur in that range

1.6 Average pooling

Image avg pooling keeps its size the same. We can avg/max pool image by doing it in each dim separately in x

- First image chunks Nh and Nw

```
out = img.copy()
H, W, C = img.shape
G = 8
Nh = int(H / G)
Nw = int(W / G)
```

- Then do the pooling

```
for y in range(Nh):
    for x in range(Nw):
        for c in range(C):
            out[G*y:G*(y+1),
                G*x:G*(x+1),
                c] = np.max(out[G*y:G*(y+1),
                                G*x:G*(x+1),
                                c])
fname = save_output("q8.jpg", out)
fname
```

1.7 Gaussian filter

The formula for gaussian filter is

$$G(x, y) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{x^2+y^2}{2\sigma^2}}$$

- First we have to set the filter parameters: size and σ

```
K_size = 3
sigma = 1.3
```

- Do zero padding of the kernel size on each side

```
out = img.copy()
H, W, C = img.shape
pad = K_size // 2
out = np.zeros([H+pad*2, W+pad*2, 3], dtype=np.float32)
out[pad:pad+H, pad:pad+W] = img.copy().astype(np.float32)
```

- Create the filter using the formula ??.

```
K = np.zeros([K_size, K_size], dtype=np.float32)
for x in range(-pad, -pad+K_size):
    for y in range(-pad, -pad+K_size):
        K[y+pad, x+pad] = np.exp(-(x**2+y**2)/(2*(sigma**2)))
K /= (sigma*np.sqrt(2*np.pi))
K /= K.sum()
print(K)
```

```
[[file:[[0.08941182 0.12019445 0.08941182] [0.12019445 0.1615749 0.12019445]
[0.08941182 0.12019445 0.08941182]]]] [[file:[[0.08941182 0.12019445 0.08941182]
[0.12019445 0.1615749 0.12019445] [0.08941182 0.12019445 0.08941182]]]]
```

- Run this filter on the image and save results

```
for y in range(H):
    for x in range(W):
        for c in range(C):
            out[pad+y, pad+x, c] = np.sum(K* out[y:y+K_size, x:x+K_size, c])
out = out[pad:pad+H, pad:pad+W].astype(np.uint8)
fname = save_output("q9.jpg", out)
fname
```

1.8 Median filter

- Do zero padding of the kernel size on each side

```
K_size = 3
out = img.copy()
H, W, C = img.shape
pad = K_size // 2
out = np.zeros([H+pad*2, W+pad*2, C], dtype=np.float32)
out[pad:pad+H, pad:pad+W] = img.copy().astype(np.float32)
```

- Run the filter over image using `np.median`

```
for y in range(H):
    for x in range(W):
        for c in range(C):
            out[pad+y, pad+x, c] = np.median(out[y:y+K_size, x:x+K_size, c])
out = out[pad:pad+H, pad:pad+W].astype(np.uint8)
fname = save_output("q10.jpg", out)
fname
```

1.9 Smoothing filter

- Do zero padding of kernel size on each side

```
K_size = 3
out = img.copy()
H, W, C = img.shape
```



```

pad = K_size // 2
out = np.zeros([H+pad*2, W+pad*2, C], dtype=np.float32)
out[pad:pad+H, pad:pad+W] = img.copy().astype(np.float32)
tmp = out.copy()

for y in range(H):
    for x in range(W):
        for c in range(C):
            out[pad+y, pad+x, c] = np.mean(tmp[y:y+K_size, x:x+K_size, c])
out = out[pad:pad+H, pad:pad+W].astype(np.uint8)
fname = save_output("q11.jpg", out)
fname

```

1.10 Motion Filter

1.11 Max Min filter

1.12 Differential filter

1.13 Sobel Filter

1.14 Prewitt Filter

1.15 Laplacian Filter

1.16 Emboss Filter

1.17 Log Filter

1.18 Histogram display

- Histogram graph depicts the frequency of pixels.

```

import matplotlib.pyplot as plt
img_dark = cv2.imread("./Image_Processing_100_Questions/Question_11_20/imori_dark.jpg")
plt.hist(img_dark.ravel(), bins=255, rwidth=0.8, range=(0, 255))
plt.savefig("q20.jpg")
"q20.jpg"

```

1.19 Histogram normalization

- Get the histogram of the greyscale image
- calcu