

## ADS-LAB Red-Black tree

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class RBTree

```
{
    Private:
        Node * root;
        protected:
            void rotateLeft(Node *X, Node *Y);
            void rotateRight(Node *X, Node *Y);
            void fixViolation(Node *X, Node *Y);
```

Public:

```
    RBTree() { root = NULL; }
    void insert(const int X);
    void inorder();
    void levelorder();
};
```

```
void inorderHelper(Node *root)
{
```

```
    if (root == NULL)
        return;
    inorderHelper(root->left);
    cout << root->data << " ";
    inorderHelper(root->right);
}
```

```
Node *BSTInsert(Node *root, Node *pt)
{
    if (root == NULL)
        return pt;
    if (pt->data < root->data)
```



```

{
    root->left = BSTInsert(root->left, pt);
    root->left->parent = root;
}
else if (pt->data > root->data)
{
    root->right = BSTInsert(root->right, pt);
    root->right->parent = root;
}
return root;
}

void levelOrderHelper(Node *root)
{
    if (root == NULL)
        return;
    std::queue<Node*> q;
    q.push(root);
    while (!q.empty())
    {
        Node *temp = q.front();
        cout << temp->data << " ";
        q.pop();
        if (temp->left != NULL)
            q.push(temp->left);
        if (temp->right != NULL)
            q.push(temp->right);
    }
}

void KBTree::fixViolation(Node * &root;
Node * &pt)
{
    Node * parent_pt = NULL;

```



```

Node * grandParent_Pt = NULL;
while ((Pt != root) && (Pt->color != Black) &&
(Pt->parent->color == RED))
{
    parent_Pt = Pt->parent;
    grandParent_Pt = Pt->parent->parent;
    if (parent_Pt == grandParent_Pt->left)
    {
        Node * uncle_Pt = grandParent_Pt->right;
        if (uncle_Pt != NULL && uncle_Pt->color == Red)
        {
            grandParent_Pt->color = Red;
            parent_Pt->color = Black;
            uncle_Pt->color = Black;
            Pt = grandParent_Pt;
        }
        else
        {
            if (Pt == parent_Pt->right)
            {
                rotateLeft(root, parent_Pt);
                Pt = parent_Pt;
                parent_Pt = Pt->parent;
            }
            rotateRight(root, grandParent_Pt);
            swap(parent_Pt->color, grandParent_Pt->color);
            Pt = parent_Pt;
        }
    }
}

```



```

else
{
Node *uncle_Pt = grand_Parent_Pt -> left;
if ((uncle_Pt != NULL) && (uncle_Pt -> color == red))
{
grand_Parent_Pt -> color = red;
parent_Pt -> color = black;
uncle_Pt -> color = black;
Pt = grand_Parent_Pt;
}
else
{
if (Pt == parent_Pt -> left)
{
rotateRight(root, parent_Pt);
Pt = parent_Pt;
parent_Pt = Pt -> parent;
}
rotateLeft(root, grand_Parent_Pt);
swap(parent_Pt -> color, grand_Parent_Pt -> color);
Pt = parent_Pt;
}
}
}
root -> color = black;
}

void KBTree::insert(int &data)
{
Node *Pt = new Node(data);
root = BSTInsert(root, Pt);
fixViolation(root, Pt);
}

```