

Batch-3 : CN-LAB

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Dijkstra's algorithm to compute shortest path

```
#include <bits/stdc++.h>
using namespace std;
#define V 9

int minDistance(int dist[], bool sptSet[])
{
    int min = 9999, min_index;
    for (int v = 0; v < V; v++)
        if (sptSet[v] == false && dist[v] != min)
            min = dist[v], min_index = v;
    return min_index;
}

void printPath(int parent[], int j)
{
    if (parent[j] == -1)
        return;
    printPath(parent, parent[j]);
    cout << j << " ";
}

int printSolution(int dist[], int n, int parent[])
{
    int src = 0;
    cout << "Vertex \t Distance \t Path" << endl;
    for (int i = 1; i < n; i++)
    {
        cout << " \t" << src << " -> " << i << " \t"
            << dist[i] << " \t" << src << endl;
    }
}
```



```
printPath (Parent, i);
}
```

```
}
void dijkstra (int graph[V][V], int src)
{
```

```
    int dist[V];
    bool sptset[V];
    int Parent[V];
    for (int i=0; i<V; i++)
```

```
    {
        Parent[i] = -1;
        dist[i] = 9999;
        sptset[i] = false;
    }
```

```
    dist[src] = 0;
    for (int count=0; count<V-1; count++)
```

```
    {
        int u = minDistance (dist, sptset);
        sptset[u] = true;
        for (int v=0; v<V; v++)
```

```
        if (!sptset[v] && graph[u][v] && dist[u]
            + graph[u][v] < dist[v])
```

```
        {
            Parent[v] = u;
            dist[v] = dist[u] + graph[u][v];
        }
```

```
    }
    printSolution (dist, u, Parent);
}
```