**HPC\_Based\_ImageManipulation**

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***Abstract –* Image processing incurs a lot of overhead when operating over the entire image. High Performance Computing helps address this increasing demand for processing speed and analyzing/processing huge amount of data. One can try to parallelize different steps in image processing by leveraging HPC based implementation and bring down the runtime. This mini-project focusses on comparison between a normal implementation v/s HPC based implementation for image augmentation.**

***Keywords*: HPC, OpenMP, CI, CUDA, High Resolution, Flip, Rotate**

**Section I – Methodology**

It is quite common to perform image processing/image augmentation using C/C++. For applications like medical imaging, image augmentation is done on very large images, and using just one CPU to process the image will be quite time consuming. Ensuring that image augmentation process does not take too much time and pose as a bottleneck, becomes pertinent.

With technology advancing at such a fast pace over the last few years, it is common to find personal computers/laptops to have multiple physical cores, and also with ability to operate over multiple logical cores. This is where High Performance Computing comes into picture. High performance computing (HPC) is the ability to process data and perform complex calculations at high speeds.

OpenMP is a library for parallel programming in shared-memory processors (i.e.) all threads share memory and data. An OpenMP program has sections that are sequential and sections that are parallel. The sequential section sets up the environment, initializes variables, etc and it runs on the master thread. Parallel sections of the program (under omp pragma) start execution on multiple threads. (slave threads)

CUDA is an extension of C/C++ programming that uses the Graphical Processing Unit (GPU). It is a parallel computing platform that allows computations to be performed in parallel while providing well-formed speed. Using CUDA, one can utilize the power of the Nvidia GPU to perform common computing tasks, such as processing matrices and other linear algebra operations.

**GitHubActions/CI:** For our project Continuous Integration, seamless handling and parallel working we created GitHub project repository[5] and used it’s component as per our project requirement. Single workflow with one job is used, job: “build” involve multiple steps to install, run build for CUDA and OpenMP make. To build and test our code in parallel and merge it via pull/push to the project repository.

In this paper, different methodologies, and techniques tried to implement image augmentation for flip/rotate by leveraging shared memory parallel computing will be discussed. Image augmentation was tried with OpenMP, as well as CUDA, and the performance/speedup was compared with a CPU based implementation.

**Section II –Experimentation**

**A - OpenMP**

OpenMP implementation was done to flip the images vertically and horizontally which had a huge impact in the speedup compared to the sequential implementation for the same. The *" # pragma omp parallel for "* was used to parallelize the flipping of image where the pixels have been manipulated and stored in the new array. The number of threads that needs to be used in the OpenMP implementation was taken as an argument.

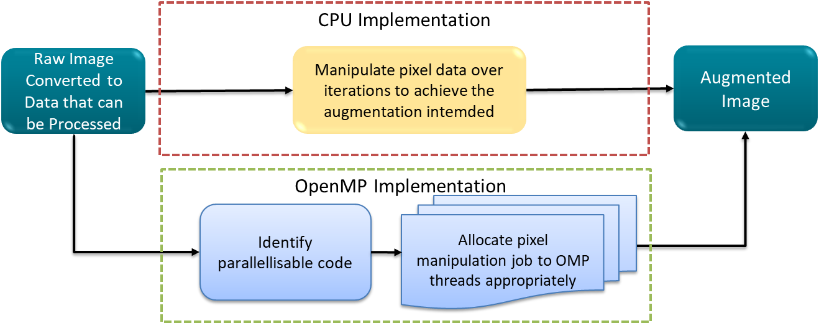


Figure 1 - OpenMP Image Augmentation Flow

**B - CUDA**

General CUDA flow includes Computation on the Host, Computation on the Device, Memory transfer from Host to Device and Device to Host, and CUDA Kernel calls. Code/Logic that can be parallelized is identified and allocated to different threads to generate the final augmented image.

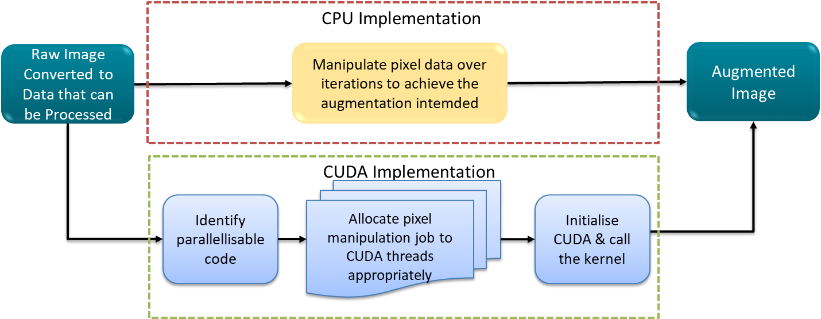


Figure 2 - CUDA Image Augmentation Flow

Different experiments were tried for CUDA based implementation.

**CV::Mat**

OpenCv C++ was another method that was used to load and save the images. This required a lot of effort since the loaded image was stored as a Mat datatype and processing the Mat datatype was quite tedious. Also, copying the image into the GPU was not straight forward, and the use of GPU Mat was required which did not have proper documentation. So, this idea was dropped off to load and save the images.

**LodePNG**

LodePNG is a header that helps one load PNG extension images of any size onto C/C++. It offers different in-built functions that helps one to encode an image into a vector of characters that contain the RBGAlpha information, as well as decode a character array/vector of RBGAlpha information back into a PNG image.

The only drawback with this header is that it is limited to only PNG images, and the method in which it encodes the actual RBG data is abstracted. Hence manipulating this data can meddle with the contrast/RBG settings of the image. The image was first loaded onto a character vector and later to a 1D character array using the *encode* function.

Fist, a CPU based image augmentation (Vertical Flip and Horizontal Flip) was implemented where every iteration of pixel manipulation was run on just from CPU.

Image augmentation (Vertical Flip and Horizontal Flip) was then done using this header using a CUDA based implementation. For vertical flip, the pixel manipulation was done on a 1-D grid of blocks each with 32 threads, and the CUDA kernel took care of flipping the pixels. For horizontal flipping, image manipulation was done on a 2-D grid of blocks with 32 threads each, and the CUDA kernel took care of properly flipping the pixel from the right rows and columns. The major problem that was faced was that while flipping the pixels, the RBG proportions changed and hence the image color changed. This method of loading images was dropped and stbi was used in future experiments.

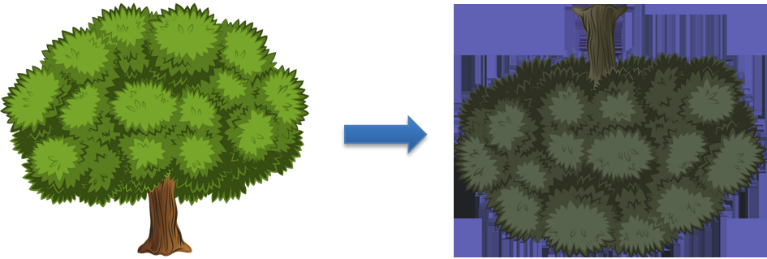


Figure 3 - Vertical Flip using LodePNG

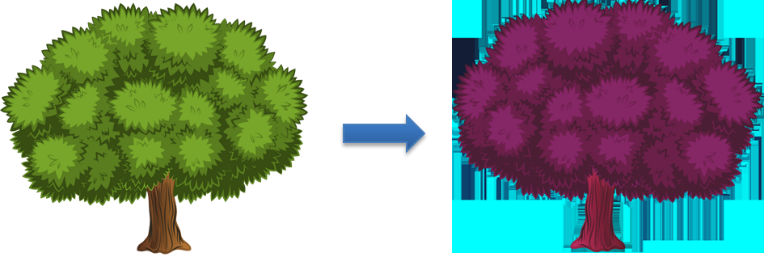


Figure 4 - Horizontal Flip using LodePNG

**STB**

Stb\_image libraries have been used to read and write the images for CUDA based HPC implementation of image augmentation (Vertical Flip, Horizontal Flip, Rotate, Scaling).

STB\_IMAGE\_IMPLEMENTATION has to be defined the before including the stb\_image.h header for reading the image and STB\_IMAGE\_WRITE\_IMPLEMENTATION has to be defined for writing an image. It offers an in-built function stbi\_load for loading an image which receives the image file path, width and number of channels as the arguments. This also gives the flexibility to load upto 3 channels for a 4 channel image. Similarly, stibi\_image\_write functions can be used to save back the image in the disk. This library offers much more flexibilty than the LodePNG as it supports multiple extensions of the image such as jpg,png etc and was also easier to do the image processing the loaded image and write back the processed image. The actual CUDA implementation for all the image augmentation variants utilized 2-D grid of blocks, and the CUDA kernel took care of manipulating the appropriate pixel based on the current executing thread.

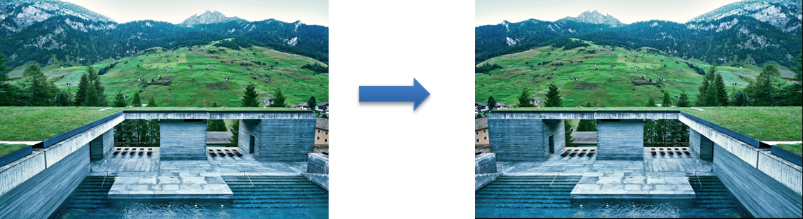


Figure 5 - Horizontal Flip using STBI

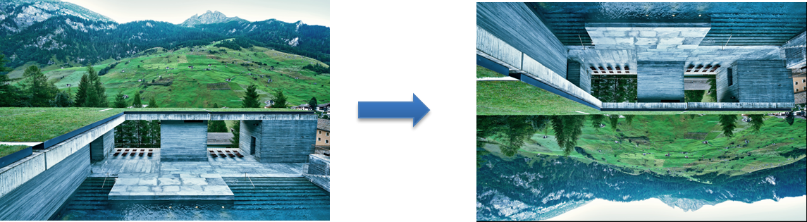


Figure 6 - Vertical Flip using STBI



Figure 7 - Image Rotation using STBI



Figure 8 - Image scaled-up from 7952x5304px to 31808x21216px



Figure 9 - Image scaled-down from 7952x5304px to 3976x2652px

**C – CODE BUILD AND CONTINOUS INTEGRATION (CI)**

For efficiently maintain our codes, its version, build and continuous integration, we created a GitHub repo: **https://github.com/prakash90om/MLOps\_HPC\_Image\_Processing**.

For CI, we have used GitHub Actions. We are using a single workflow to be triggered when we push any changes to our repo. Inside the workflow a single job (build) is being triggered which runs all the mentioned steps, such as cloning the repository to the runner using “actions/checkout@v3”, installing Cuda setup and then build the code.

For code compilation and build, we have used Makefile. In the Makefile we have added a set of rules, so that we can compile different portion of files with those rules. A rule generally looks like this: target: prerequisites, then commands. So, to build/compile/clean we can use commands like: make cuda (for CUDA files to build), make clean (to clean the build folder) etc.

**Section III – Results**

This section captures the results from different experiments tried out.

OpenMP based image augmentation was one on **7952x5304 px** image of size ~17Mb. Below is the execution time on CPU implementation v/s OpenMP implementation and the speedup achieved. The time taken below purely denotes the time to manipulate the image.

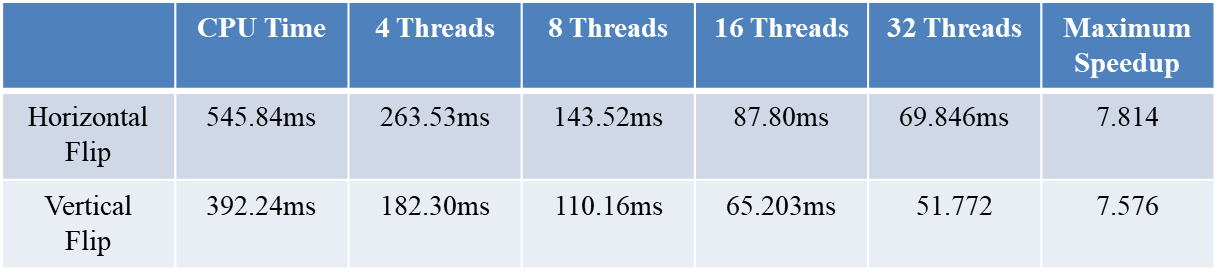


Figure 10 - Computation Time Comparison for sequential v/s OpenMP based implementation

CUDA based Image Augmentation using LodePNG was done on a **8000x6612 px** image of size **5.5 Mb**. Below is the execution time on CPU implementation v/s GPU implementation and the speedup achieved for 32 threads. The time taken below purely denotes the time to manipulate the image.

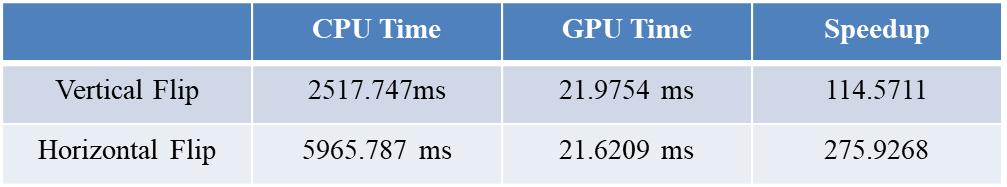


Figure 11 - Computation Time comparison for CPU v/s GPU in LodePNG based CUDA implementation

CUDA based Image Augmentation using STBI was done on a **7952x5304 px** image of size ~**17 Mb**. Below is the execution time on CPU implementation v/s GPU implementation and the speedup achieved for 32 threads. The time taken below purely denotes the time to manipulate the image.

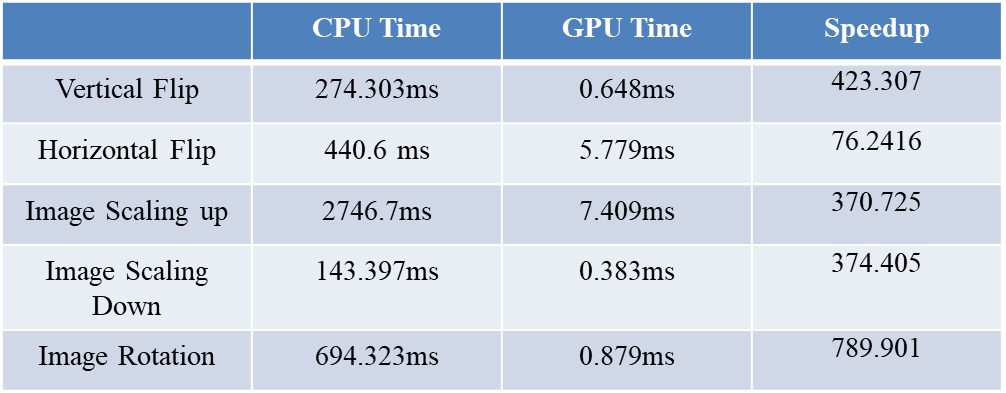


Figure 12 - Computation Time comparison for CPU v/s GPU in STBI based CUDA implementation

**Section IV –Conclusion**

In conclusion, we can see that a HPC based implementation offers a large speedup compared to a CPU based implementation. The sheer processing power that multiprocessor workstations offer can be leveraged to speed-up image processing applications.

**Section V –References**

1. LodePNG Documentation: <https://lodev.org/lodepng>
2. OpenMP Documentation: <https://www.openmp.org/spec-html/5.0/openmp.html>
3. GitHub Actions: <https://docs.github.com/en/actions>
4. CUDA: <https://docs.nvidia.com/cuda/cuda-c-programming-guide/index.html>
5. Project GitHub Repo: <https://github.com/prakash90om/MLOps_HPC_Image_Processing>
6. STB Image: https://github.com/nothings/stb