Data Structures and Algorithms

SORTING ALGORITHMS HANDOUT

Bubble Sort

```
ALGORITHM BubbleSort(A[o..n-1])

// Sorts a given array using bubble sort

// Input: An array A[o..n-1] of orderable

// elements

// Output: Array A[o...n-1] sorted in

// ascending order

for i ← o to n - 2 do

for j ← o to n - 2 - i do

if A[j+1] < A[j]

swap A[j] and A[j+1]
```

ALGORITHM MergeSort(A[o..n-1])

Selection Sort

```
ALGORITHM SelectionSort(A[o..n-1])

// Sorts a given array using selection sort

// Input: An array A[o..n-1] of orderable

// elements

// Output: Array A[o... n-1] sorted in

// ascending order

for i ← o to n - 2 do

min ← i

for j ← i + 1 to n - 1 do

if A[j] < A[min]

min ← j

swap A[i] and A[min]
```

Insertion Sort

```
ALGORITHM InsertionSort(A[o..n-1])

// Sorts a given array using insertion sort

// Input: An array A[o..n-1] of orderable

// elements

// Output: Array A[o... n-1] sorted in

// ascending order

for i←1 to n-1 do

v ← A[i]
j ← i-1

while j >= 0 and A[j] > v do

A[j+1] ← A[j]
j ← j-1

A[j+1] ← v
```

Merge Sort

```
// Sorts a given A[o..n-1] by recursive mergesort
// Input: An array A[o..n-1] of orderable elements
// Output: Array A[o...n-1] sorted in nondecreasing order
if n > 1
  copy A[o... | n/2 | -1] to B[o... | n/2 | -1]
  copy A[| n/2 | ... n-1 ] to C[0...... | n/2 | -1]
  MergeSort(B[o...|n/2|-1])
  MergeSort(C[0.....|^{T} n/2^{T}] - 1)
  Merge(B,C, A)
ALGORITHM Merge(B[o...p-1], C[o...q-1], A[o...p+q-1])
// Merges two sorted arrays into one sorted array
// Input: Arrays B[o...p-1] and C[o...q-1] both sorted
// Output: Sorted array A[o...p+q-1] of the elements of B and C
i ← 0
i ← 0
k← o
while i < p and j < q do
   if B[i] <= C[j]
      A[k] \leftarrow B[i]
      i ← i + 1
  else
      A[k] \leftarrow C[j]
     j \leftarrow j + 1
   k ← k + 1
if i = p
   copy C[j...q-1] to A[k...p+q-1]
else
  copy B[i...p-1] to A[k...p+q-1]
```

Quick Sort

```
ALGORITHM QuickSort(A[l...r])

// Sorts a subarray by quicksort

// Input: A subarray A[l...r] of A[o...n-1], defined by its left and right indices I and r

// Output: Subarray A[l...r] sorted in nondecreasing order

if I < r

s ← Partition(A[l...r])

QuickSort(A[l...s-1])

QuickSort(A[s+1...r])
```

```
ALGORITHM Partition(A[l...r])
// Partitions a subarray by using its first element as a pivot
// Input: A subarray A[1...r] of A[0...n-1], defined by its left and right indices I and r (I < r)
// Output: Subarray A[I...r], with split position returned as this functions value
p \leftarrow A[I]
i \leftarrow 1
j \leftarrow r + 1
repeat
  repeat i \leftarrow i + 1 until A[i] >= p
  repeat j \leftarrow j - 1 until A[j] <= p
  swap(A[i] and A[j])
until i >= j
swap (A[i], A[j])
swap (A[I], A[j])
return j
Heap Sort
Step 01: Heap construction – construct a heap for a given array
Step 02: Maximum Deletions – Apply the root-deletion operation n-1 times to the remaining heap
Algorithm for Heap Construction
ALGORITHM HeapBottomUp(H[1..n])
// Constructs a heap from the elements of a given array by the bottom up algorithm
// Input: An array H[1...n] of orderable items
// Output: A heap H[1... n]
for i \leftarrow | n/2 | downto 1 do
   k ← i
   v \leftarrow H[k]
   heap ← false
   while not heap and 2 * k <= n do
      j \leftarrow 2 * k
      if j < n
          if H[j] < H[j+1]
             j \leftarrow j + 1
      if v >= H[ j ]
          heap ← true
      else
          H[k] \leftarrow H[j]
          K ← j
   H[k] \leftarrow v
Algorithm for maximum key deletion
```

Step o1: Exchange the root's key with the last key K of the Heap

Step 02: Decrease the heap's size by 1 Step o3: "Heapify" the smaller tree

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Reference: Introduction to the Design and Analysis of Algorithms by Anany Levitin