Pranav Kedia

Contact: +91-7899003522

Email-id: pranav.kedia@iiitb.org

https://www.linkedin.com/in/praked/

ACADEMIC DETAILS

University	Year	CGPA/Percentage
International Institute of Information Technology, Bangalore (IIIT-B)	2015-Pursuing	3.21/4.00
Modern Vidya Niketan Sr. Sec. School, Faridabad	2013-2015	91.4 %
Modern School, Faridabad	2000-2013	10.0/10.0

KEY PROJECTS

• Design and Development of swarm robotics platform

(Guide: Prof. Madhav Rao, Aug'18 - Till Date)

• Investigations into the working of swarms in nature (eg: army ants, weaver ants, school of fishes and even cells in a multicellular organism). Designing and developing bio-inspired Swarm robotics platform artificially imitating these natural processes of communication and coordination among group of robots.

• Design and development of an autonomous emergency vigilance system for passenger vehicle

(Guide: Prof. Madhav Rao, Jan'18 - Till Date)

An automotive enabled integrated sensory system is designed to identify physical discomfort of the passenger travelling in the public transportation system. The sensory system is designed to connect with the emergency response team for any immediate action.

• Design and Development of an Automated Solar Tiller

(Guide: Prof. Madhav Rao, Jun'17 - May'18)

 Designed and developed an autonomous solar powered field tiller using image processing and magnetic encoders to solve simultaneous localization and mapping(SLAM) problem.

More Info: https://goo.gl/brkM9U

• Beowulf cluster of 15 Raspberry pi

(Guide: Prof. Madhav Rao, Jun'17 - Jul'17)

Distributed computing applications of Beowulf cluster of Raspberry pi using Message Passing Interface to
estimate timing data with various no. of nodes and networking bottlenecks. More Info: https://goo.gl/
CAxqws

• C.M.O.W.C (Cross Platform, Multi Utility, On board, Wearable, Controller)

(Nov'16-Feb'17)

Developed a hand based controller for various peripherals like mouse and keyboard through hand gesture
and movement with applications in fields of VR and to help disabled people to communicate with others and
is an easy interface to technology. More Info: https://goo.gl/YrJeaL

TECHNICAL SKILLS

C, C++, Python, MATLAB, Assembly(ARM),	
Java(basic)	
Python, Linux Shell	
ROS (Robot Operating System), OpenCV,	
freeRTOS, KEIL, GNU Octave, GNU Make,	
Open MPI, Vim	
Fusion360, Inkscape, Solidworks(basic),	
KICAD, Autdesk Eagle	
Gazebo, V-REP, Netlogo, LTspice, Multisim	
ARM CORTEX M4, STM32F4, MSP430,	
MSP430, Raspberry Pi, BeagleBone, ATmega328	
Arduino	
Linux (Ubuntu, Manjaro), Windows	
CAD, 3D Printing(Creality, Ultimaker	
and Makerbot)	

WORK EXPERIENCE

• Indian Institute of Technology, Bombay

(Research Intern, May'19 - Jul'19)

• I worked at the A.R.M.S. Lab at Inter Disciplinary Program in Systems and Control Engineering under Dr. Arpita Sinha. My work involved simulation of swarm behaviour in a swarm collective of Kilobot robots.

• Haryana Police

(Research Intern, Jun'16 - Jul'16)

• My work at the Commissionerate involved looking over the available infrastructure and developing low-cost crime mapping and analysis software solutions for the Law enforcement agency.

PUBLICATIONS

- Design and development of an autonomous emergency vigilance system for passenger vehicle (Co-Authored with: Pranav Aggarwal and Dr. Madhav Rao, 2019 IEEE International Conference on Vehicular Electronics and Safety (ICVES'2019), Accepted)
- Crime mapping and analysis using GIS: an Indian perspective (Co-Authored with: Dr. Hanif Qureshi and Mr. Aman Yadav , Under Submission, DOI: 10.13140/RG.2.2.11064.14081)

POSITIONS OF RESPONSIBILITY

• Trainer and Deputy Head, Enigma (College Robotics Club)

(Jan'17 - till date)

- Co-Founder of college robotics club.
- Served as Finance Manager and Trainer, have conducted workshops "Arduino, Microcontrollers, Inter Device Communication" which was attended by a total of 40-50 students.
- Campus Ambassador, Pravega IISc Cultural Fest

(Dec'16 - Jan'17)

o Campus Ambassador for Indian Institute of Science Annual Cultural Fest Pravega.

KEY COURSES		
Robotics	Control Theory, Introduction to Robotics,	
	Reading Elective: Robotics and Feedback Control	
	Systems, Multi-Agent Systems	
Embedded Systems	Computer Architecture, Operating System,	
	Microprocessors and Microcontrollers,	
	Virtual Machines, Device Driver Development	
	Advance ARM Architecture, Real Time Operating	
	System	
Data Sciences	Machine Learning	
Network and communication	Computer Networks, Principles of Communication,	
	Digital Communication, Internet of Things	
Analog Systems design	Basic Electronics, Electronic Devices and Circuit	
	Theory, Analog Circuits and Systems	
Signal Processing	Signals and Systems, Digital Signal Processing,	
	Image Analysis, Speech Processing	