

↳ Griffiths MA: 111

- 1*. Calculate the curl and divergence of the following vector functions. If the curl turns out to be zero, construct a scalar function ϕ of which the vector field is the gradient:

- (a) $F_x = x + y$; $F_y = -x + y$; $F_z = -2z$
 (b) $G_x = 2y$; $G_y = 2x + 3z$; $G_z = 3y$
 (c) $H_x = x^2 - z^2$; $H_y = 2$; $H_z = 2xz$

$$\vec{F} = F_x \hat{i} + F_y \hat{j} + F_z \hat{k}$$

$$\nabla \times \vec{F} = 0 \quad \downarrow$$

$$\vec{F} = \nabla \phi$$

(a) $\operatorname{Div}(F) = \vec{\nabla} \cdot \vec{F}$

$$= \left(\frac{\partial}{\partial x} \hat{i} + \frac{\partial}{\partial y} \hat{j} + \frac{\partial}{\partial z} \hat{k} \right)$$

$$\cdot \left(F_x \hat{i} + F_y \hat{j} + F_z \hat{k} \right)$$

$$= 1 + 1 + (-2) = 0$$

(a) $\operatorname{curl}(F) = \vec{\nabla} \times \vec{F}$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ x+y & -x+y & -2z \end{vmatrix}$$

$$\hat{i} (0) - \hat{j} (0) + \hat{k} (-1 - 1) = -2 \hat{k}$$

(b) $\vec{\nabla} \cdot \vec{G} = 0$

$$\vec{\nabla} \times \vec{G}$$

$$= \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2y & 2x+3z & 3y \end{vmatrix}$$

$$= \hat{i} (0) - \hat{j} (0) + \hat{k} (2 - 2) = 0$$

$$\vec{\nabla} \times \vec{G} = 0$$

⇒ \vec{G} is a gradient field
 1st $\vec{G} = \vec{\nabla}(\phi) = \operatorname{grad}(\phi)$

111 flashback

Let $\vec{G} = \vec{\nabla}(\phi) = \text{grad } (\phi)$

where ϕ is a scalar function

$$\begin{aligned}\vec{G} &= \vec{\nabla}\phi \\ (2y)\hat{i} + (2x+3z)\hat{j} + (3y)\hat{k} &= \frac{\partial \phi}{\partial x}\hat{i} + \frac{\partial \phi}{\partial y}\hat{j} + \frac{\partial \phi}{\partial z}\hat{k}\end{aligned}$$

$$\frac{\partial \phi}{\partial x} = 2y$$

$$\Rightarrow \phi(u, y, z) = 2yu + f(y, z)$$

$$\frac{\partial \phi(u, y, z)}{\partial y} = 2u + \frac{\partial f(y, z)}{\partial y} = 2u+3z$$

$$\Rightarrow \frac{\partial f(y, z)}{\partial y} = 3z$$

$$f(y, z) = 3yz + g(z)$$

$$\phi(u, y, z) = 2uy + 3yz + g(z)$$

$$\frac{\partial \phi(u, y, z)}{\partial z} = 3y + \underline{g'(z)} = 3y$$

$$g'(z) = 0$$

$$g(z) = c$$

$$\boxed{\phi(u, y, z) = 2uy + 3yz + c}$$

$$\vec{F}_e = \vec{G} = \vec{A} \cdot \vec{V}$$

$$\begin{array}{l} \phi(u, y, z) = 2uy + 3yz + 1 \\ 2uy + 3yz + 2 \end{array}$$

We observe that for different

values of potential (due to our choice of c) we get same value of the field \vec{G} .

This freedom in choice of

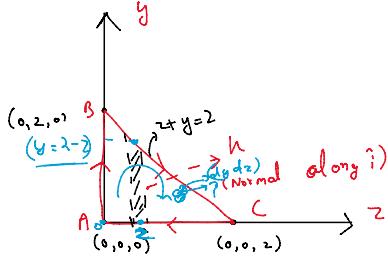
Potential ϕ is called

Gauge freedom

Potential
Gauge freedom

3. Test the Stokes theorem for the vector $\vec{v} = xy\hat{i} + 2yz\hat{j} + 3z\hat{k}$ using a triangular area with vertices at (0,0,0), (0,2,0) and (0,0,2).

Sol:



Stokes Theorem

$$\Rightarrow \iint (\vec{A} \times \vec{V}) \cdot d\vec{s} = \oint \vec{V} \cdot d\vec{l}$$

LHS RHS
integrated path

$$\vec{V} = xy\hat{i} + 2yz\hat{j} + 3z\hat{k}$$

$$\vec{A} \times \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xy & 2yz & 3z \end{vmatrix}$$

$$= \hat{i} (0 - 2y) - \hat{j} (0 - 0) + \hat{k} (-n)$$

$$= -2y\hat{i} - n\hat{k}$$

$$d\vec{s} = (dy dz \hat{i})$$

$$\text{LHS} = \int_0^2 \int_0^{2-z} (-2y\hat{i} - n\hat{k}) \cdot (dy dz \hat{i}) = \int_0^2 \int_0^{2-z} -2y dy dz = \int_0^2 -(2-z)^2 dz$$

$$= \int_0^2 (4z - 4z^2) dz$$

$$= 2 \times 1 - 4 \times 2 - \frac{8}{3}$$

$$= -\frac{8}{3}$$

$$\vec{E}(n\hat{s}) = \vec{0} + \hat{i} + 0\hat{k}$$

$$d\vec{l}(n\hat{s}) = dt\hat{j}$$

$$\text{RHS} = \int \vec{V} \cdot d\vec{l}_{AB} + \int \vec{V} \cdot d\vec{l}_{BC} + \int \vec{V} \cdot d\vec{l}_{CA}$$

$$= \int_0^2 ((ny\hat{i} + 2yz\hat{j} + 3z\hat{k}) \cdot (dt\hat{j})) + \int_2^0 ((ny\hat{i} + 2yz\hat{j} + 3z\hat{k}) \cdot (dt\hat{j} - dt\hat{k}))$$

$$+ \int_2^0 ((ny\hat{i} + 2yz\hat{j} + 3z\hat{k}) \cdot (dt\hat{k}))$$

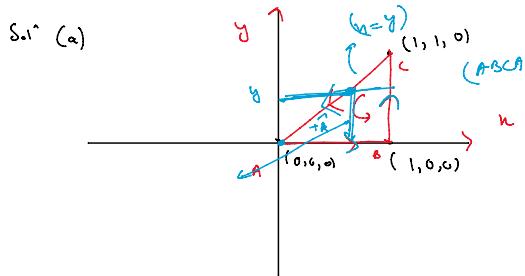
$$= \int_2^0 [2 + (2 - t) - 3(2 - t)] dt + \int_2^0 (3t \cdot dt)$$

$$\therefore \dots \therefore 2 \cdot 1 \cdot dt = 8(-4) - 2(-8) + 12$$

$$\begin{aligned}
 &= \int_2^0 [2 + (2-t) - 3(2-t)] \cdot a_1 + \int_2^0 (8t \cdot a_1) \\
 &= \int_2^0 (4t - 2t^2 - 6 + 6t) \cdot dt = \int_2^0 (10t - 2t^2 - 6) \cdot dt = 8(-4) - \frac{2}{3}(-8) + 12 \\
 &= -32 + \frac{16}{3} = -\frac{80}{3} = \underline{\underline{-\frac{80}{3}}}
 \end{aligned}$$

5. A force defined by $\vec{F} = A(y^2\hat{i} + 2x^2\hat{j})$ is exerted on a particle which is initially at the origin of the co-ordinate system. A is a positive constant. We transport the particle on a triangular path defined by the points (0,0,0), (1,0,0), (1,1,0) in the counterclockwise direction.

- (a) How much work does the force do when the particle travels around the path? Is this a conservative force?
- $\vec{F} = 0$ at origin
- (b) The particle is placed at rest right at the origin. Is this a stable situation? Give any argument (mathematical, physical, intuitive) to justify the stability (or instability) of this situation.



Conservative force
Work done along a closed path is zero

$$W = \oint \vec{F} \cdot d\vec{l} = \oint (\vec{A} \times \vec{F}) \cdot d\vec{s}$$

$$\vec{A} \times \vec{F} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y^2 & 2x^2 & 0 \end{vmatrix}$$

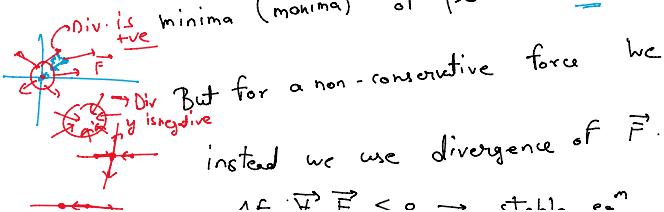
$$= \hat{i}(0) - \hat{j}(0) + \hat{k}(4n - 2y)$$

$$\begin{aligned}
 d\vec{s} &= +dx \hat{i} + dy \hat{k} \\
 W &= \int_0^1 \int_0^y \hat{k}(4n - 2y) \cdot (+dx dy) \hat{k} = \int_0^1 \int_0^y (2(1-y^2) - 2y(1-y)) \cdot dy \\
 &= \int_0^1 (2 - 2y) \cdot dy = 2 - \frac{2 \cdot 1}{2} = 0 \quad \text{①}
 \end{aligned}$$

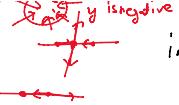
\vec{F} is non-conservative force

(b) A point of stability (instability) is a point of local minima (maxima) of potential ϕ corresponding to force \vec{F} .

We can't define a potential ϕ .



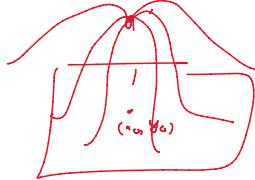
$$\nabla \cdot \vec{F} < 0 \rightarrow \text{at L1- eqn}$$

 instead we use divergence of \vec{F} .

$\nabla \cdot \vec{F} < 0 \rightarrow$ stable eqⁿ

\hookrightarrow (for a conservative force \vec{F} $\nabla \cdot \vec{F} = \nabla^2 \phi$)

Here $\nabla \cdot \vec{F} = 0$ so the particle is not in stable eqⁿ.



7. Suppose that the height of a certain mountain (in feet) is given by

$$h(x, y) = 10(2xy - 3x^2 - 4y^2 + 14x + 10y + 40), \quad \text{M102}$$

where x is the distance (in km) east, y the distance north of the closest town.

(a) Where is the top of the mountain located, and how high is it?

(b) How steep is the slope (in feet per km) at a point 1 km north and 1 km east of the town? In what direction is the slope steepest, at that point?

\hookrightarrow f function $h(x, y)$

Solⁿ (a) We need to find maxima

$$\nabla h = 0 \quad (\text{at maxima})$$

$$\frac{\partial h}{\partial x} \hat{i} + \frac{\partial h}{\partial y} \hat{j} = 0$$

$$(2y - 6x + 14)\hat{i} + (2x - 8y + 10)\hat{j} = 0$$

$$y - 3x + 7 = 0 \quad x - 4y + 5 = 0$$

$$\begin{aligned} -11y + 22 &= 0 \\ y &= 2 \\ x &= 3 \end{aligned}$$

$$h(3, 2) = 10(12 - 18 - 16 + 42 + 20 + 40) = 10(114 - 34) = \underline{800 \text{ ft}}.$$

$$(b) \nabla h(1, 1) = \frac{10\hat{i} + 4\hat{j}}{\sqrt{29}}$$

\hookrightarrow also gives the direction of steepest slope

$$\vec{F}_1 \rightarrow \vec{dl} \rightarrow \vec{F}_1 + d\vec{F}$$

$$d\vec{F} = \frac{\partial \vec{F}}{\partial x} dx + \frac{\partial \vec{F}}{\partial y} dy + \frac{\partial \vec{F}}{\partial z} dz$$

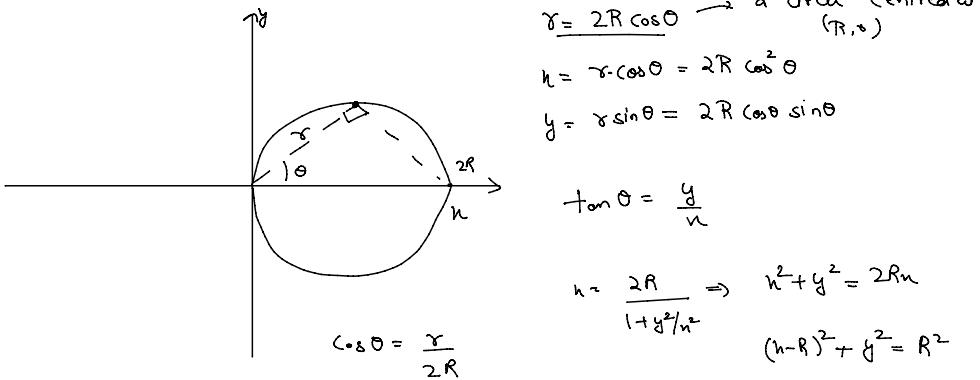
$$= \left(\frac{\partial \vec{F}}{\partial x} \hat{i} + \frac{\partial \vec{F}}{\partial y} \hat{j} + \frac{\partial \vec{F}}{\partial z} \hat{k} \right) (dx\hat{i} + dy\hat{j} + dz\hat{k})$$

$$= (\nabla \vec{F}) \cdot (d\vec{dl})$$

$d\vec{dl} \rightarrow \text{fixed}$
 $d\vec{dl}$ is in direction of $(\nabla \vec{F})$

6. The area bounded by the curve $r = 2R \cos \theta$ has a surface charge density $\sigma(r, \theta) = \frac{r}{R} \sin^4 \theta$. What is the total amount of charge?

Sol



$$d\sigma = \epsilon \cdot (r dr d\theta)$$

$$\begin{aligned} q_V &= \iint \epsilon \cdot r \cdot dr \cdot d\theta = \iint \epsilon \cdot \frac{r}{R} \sin^4 \theta \cdot r \cdot dr \cdot d\theta \\ &= \int_{-\pi/2}^{\pi/2} \int_0^{2R \cos \theta} \frac{\epsilon r^2 \sin^4 \theta}{R} dr \cdot d\theta \quad \text{for a given } \theta \text{ } r \in (0, 2R \cos \theta) \\ &\stackrel{=} {=} \int_{-\pi/2}^{\pi/2} \frac{\epsilon \sin^4 \theta}{R} \cdot \frac{8R^3 \cos^3 \theta}{3} \cdot d\theta \\ &= \frac{8 \epsilon R^2}{3} \int_{-\pi/2}^{\pi/2} \sin^4 \theta \cos^3 \theta \cdot d\theta \\ &= \frac{16 \epsilon R^2}{3} \int_0^{\pi/2} \sin^4 \theta \cos^3 \theta \cdot d\theta \end{aligned}$$

Using formula $\int_0^{\pi/2} \sin^m x \cos^n x dx = \begin{cases} \frac{[(m-1)(m-3)\cdots 1][(n-1)(n-3)\cdots 1]}{(m+n)(m+n-2)\cdots 2} \left(\frac{\pi}{2}\right) & m, n \text{ even} \\ \frac{[(m-1)(m-3)\cdots (2 \text{ or } 1)][(n-1)(n-3)\cdots (2 \text{ or } 1)]}{(m+n)(m+n-2)\cdots (2 \text{ or } 1)} & \text{otherwise} \end{cases}$

$$\Rightarrow q_V = \frac{16 \epsilon R^2}{3} \times \frac{(8 \times 1)(2)}{7 \times 5 \times 3 \times 1}$$

$$\boxed{q_V = \frac{32}{105} \epsilon R^2}$$