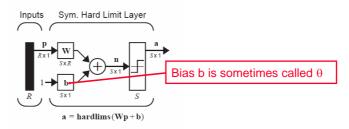


# The Perceptron and its Learning Rule

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With extracts from publications of :
M. Minsky, MIT, Demuth, U. of Colorado,
D.J. C. MacKay, Cambridge University

### Perceptron



- (i) Single layer ANN
- (ii) It works with continuous or binary inputs
- (iii) It stores pattern pairs  $(A_k, C_k)$  where:  $A_k = (a_1^k, ..., a_n^k)$  and  $C_k = (c_1^k, ..., c_n^k)$  are bipolar valued [-1, +1].
- (iv) It applies the perceptron error-correction procedure, which always converges.
- (v) A perceptron is a classifier.

# Perceptron convergence procedure (1)

- Step1: Initialize weights and thresholds: Set the  $w_{ij}$  and the  $b_j$  to small random values in the range [-1,+1].
- Step2: Present new continuous valued input  $p_0, p_1, \dots, p_n$  along with the desired output vector  $T = (t_0, \dots, t_n)$ .
- Step3: Calculate actual output:  $\mathbf{a}_j = \mathbf{f}(\Sigma \mathbf{w}_{ij} \mathbf{p}_i + \mathbf{b}_j)$  where  $\mathbf{f}(.) = \text{hardlim}(.) = \text{sgn}(.)$ .
- Step 5: Repeat by going to step 2 until no error.

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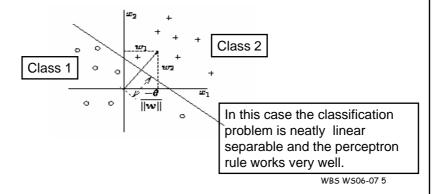
### The important propriety of the perceptron rule

The algorithm outlined in the precedent slide, will always converge to weights that solve the desired classification problem, assuming that such weights do exist. We will see, shortly, that such weights exist, as long as the classification problem is linearly separable.

## **Example**

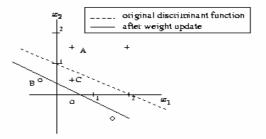
The discrimination line between two classes in a two input perceptron is determined by:  $w_1x_1 + w_2x_2 + \theta = 0$ .

We plot this line in a  $x_1$ ,  $x_2$  plane as:  $x_2 = -(w_1/w_2)x_1 - \theta/w_2$ 



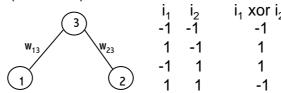
## **Example of perceptron learning rule**

A perceptron is initialized with the following weights:  $w_1=1$ ;  $w_2=2$ ;  $\theta=-2$ . The first point A:  $\mathbf{x}=(0.5, 1.5)$  and desired output  $t(\mathbf{x})=+1$  is presented to the network. From step 3, it can be calculated that the network output is +1, so no weights are adjusted. The same is the case for point B, with values  $\mathbf{x}=(-0.5, 0.5)$  and target value  $t(\mathbf{x})=-1$ . Point C:  $\mathbf{x}=(0.5, 0.5)$  gives an output -1, while the expected target is  $t(\mathbf{x})=+1$ . According to the learning rule we change the weights as follows:  $w_1=1.5$ ;  $w_2=2.5$ ;  $\theta=-1$ . ( $\eta=0.5$ ;  $p_C=0.5$ ;  $\to \Delta w_1=0.5$ ;  $\Delta w_2=0.5$ ;  $\Delta w_1=0.5$ ;  $\Delta w_2=0.5$ ;  $\Delta w_3=0.5$ ;  $\Delta w_4=0.5$ ;  $\Delta w_3=0.5$ ;  $\Delta w_4=0.5$ ;  $\Delta w_3=0.5$ ;  $\Delta w_4=0.5$ ;  $\Delta w_5=0.5$ ;



# Failure of the perceptron ANN to solve the XOR problem

The XOR-problem (see table):



Output<sub>i</sub> = 
$$\begin{pmatrix} 1 & \text{if } \sum w_{ij} i_i > h_i \\ -1 & \text{if } \sum w_{ii} i_i \leq h_i \end{pmatrix}$$

(i) 
$$i_1 = 1$$
,  $i_2 = 1$ :  $w_{13} + w_{23} \le h_3$ 

$$\begin{split} \text{(i) } i_1 &= 1, \ i_2 = 1 \colon w_{13} + \ w_{23} \leq h_3 \\ \text{(iii) } i_1 &= 1, \ i_2 = -1 \colon w_{13} + \ w_{23} \leq h_3 \\ \text{(iv) } i_1 &= 1, \ i_2 = 1 \colon w_{23} - w_{13} > h_3 \end{split}$$

(iii) 
$$i_1 = 1$$
,  $i_2 = -1$ :  $w_{13} - w_{23} > h_3$ 

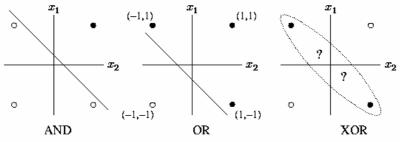
(iv) 
$$i_1 = -1$$
,  $i_2 = 1$ :  $W_{23} - W_{13} > h_3$ 

(i), (ii), (iii) and (iv) lead to a contradiction!

The xor-problem is not linearly separable

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# Linearly separable and not separable problems



XOR is not a linearly separable classification problem

# Perceptrons net with hidden layer Output Feedforward hidden layer Input

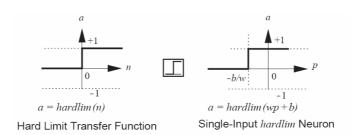
Now this perceptrons network can solve the XOR-problem!



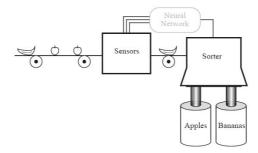
Show this.

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# **Transfer function for perceptron**



# A more complex example



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# **Prototype vectors**

We take 3 parameters to differentiate between a banana and a apple: shape, texture, weight.

Shape: {1: round; -1: elliptical} Texture: {1: smooth; -1: rough} Weight: {1: > 100 g; -1: < 100 g}

We can now define a prototype banana and apple:

$$p_1 = \begin{pmatrix} -1\\1\\-1 \end{pmatrix} \qquad p_2 = \begin{pmatrix} 1\\1\\-1 \end{pmatrix}$$

## Apple/banana example

Training set:

$$\left\{p_1 = \begin{pmatrix} -1 \\ 1 \\ -1 \end{pmatrix}, t_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}\right\} \qquad \left\{p_2 = \begin{pmatrix} 1 \\ 1 \\ -1 \end{pmatrix}, t_2 = \begin{pmatrix} 0 \\ \end{pmatrix}\right\}$$

Initial weights:

$$W = (0.5 - 1 - 0.5)$$
  $b = 0.5$ 

First iteration:

$$a = hardlim(Wp_1+b) = hardlim \left( (0.5 - 1 - 0.5) \times \begin{pmatrix} -1\\1\\-1 \end{pmatrix} + 0.5 \right)$$
$$a = hardlim(-0.5) = 0 \quad e = t_1 - a = 1 - 0 = 1$$

$$W^{new} = W^{old} + ep^T = (0.5 - 1 - 0.5) + (1)(-1 + 1 - 1) = (-0.5 + 0 - 1.5)$$

 $\eta = 1$  in this example

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### **Second iteration**

$$a = hardlim(Wp_2+b) = hardlim\left((-0.5 \ 0 \ -1.5) \times \begin{pmatrix} 1\\1\\-1 \end{pmatrix} + 1.5\right)$$

$$a = hardlim(2.5) = 1 \quad e = t_2 - a = 0 - 1 = -1$$

$$W^{new} = W^{old} + ep^T$$

$$W^{new} = (0.5 \ 0 \ -1.5) + (-1)(1 \ 1 \ -1)$$

$$W^{new} = (-1.5 \ -1 \ -0.5)$$

$$b^{new} = b^{old} + e = 1.5 + (-1) = 0.5$$

# **Checking the solution (test vectors)**

$$a = hardlim(Wp_1+b) = hardlim\left((-1.5 - 1 - 0.5) \times \begin{pmatrix} -1\\1\\-1 \end{pmatrix} + 0.5\right)$$
$$a = hardlim(1.5) = 1 = t_1$$

$$a = hardlim(Wp_2+b) = hardlim\left((-1.5 - 1 - 0.5) \times \begin{pmatrix} 1\\1\\-1 \end{pmatrix} + 0.5\right)$$
$$a = hardlim(-1.5) = 0 = t_2$$

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# Checking the solution (testing the network)

$$a = hardlim \left( (-1.5 - 1 - 0.5) \times \begin{pmatrix} -1 \\ 1 \\ -1 \end{pmatrix} + 0.5 \right)$$

$$a = hardlim(1) = 1(banana)$$

$$a = hardlim\left((-1.5 - 1 - 0.5) \times \begin{pmatrix} 1\\1\\-1 \end{pmatrix} + 0.5\right)$$

$$a = hardlim(-2) = -1(apple)$$

The net recovers the correct answer from noisy information:

$$a = hardlim \left( (-1.5 - 1 - 0.5) \times \begin{pmatrix} -1 \\ -1 \\ -1 \end{pmatrix} + 0.5 \right)$$

$$a = hardlim(3) = 1(banana)$$

# **Summary**

- A Perceptron net is:
- A feedforward network
- Which builds linear decision boundaries
- and uses one artificial neuron for each decision.