Homework-9

Resources - Notes, MIT open course. Collaboration - Nischal and Abhilash

Problem 1:

Part a

$$U = \begin{bmatrix} u_{11} & u_{12} & \dots & u_{1k} \\ u_{21} & u_{22} & \dots & u_{2k} \\ & \dots & & & \\ u_{n1} & u_{n2} & \dots & u_{nk} \end{bmatrix}_{n*k}$$

$$\sum = \begin{bmatrix} \sigma_1 & 0 \dots & 0 \\ 0 & \sigma_2 \dots & 0 \\ \dots & \dots & \\ 0 & \dots & 0 & \sigma_k \end{bmatrix}_{k*k}$$

$$V^{T} = \begin{bmatrix} v_{11} & v_{12} & \dots & v_{1d} \\ v_{21} & v_{22} & \dots & v_{2d} \\ & \dots & & & \\ v_{k1} & v_{k2} & \dots & v_{kd} \end{bmatrix}_{k*d}$$

$$A_{k} = \begin{bmatrix} u_{11} & u_{12} & \dots & u_{1k} \\ u_{21} & u_{22} & \dots & u_{2k} \\ \dots & \dots & \dots & \dots \\ u_{n1} & u_{n2} & \dots & u_{nk} \end{bmatrix}_{n*k} \begin{bmatrix} \sigma_{1} & 0 & \dots & 0 \\ 0 & \sigma_{2} & \dots & 0 \\ \dots & \dots & \dots & \dots \\ 0 & \dots & 0 & \sigma_{k} \end{bmatrix}_{k*k} \begin{bmatrix} v_{11} & v_{12} & \dots & v_{1d} \\ v_{21} & v_{22} & \dots & v_{2d} \\ \dots & \dots & \dots & \dots \\ v_{k1} & v_{k2} & \dots & v_{kd} \end{bmatrix}_{k*d}$$

$$A_{k} = \begin{bmatrix} u_{11}\sigma_{1} & u_{12}\sigma_{2} & \dots & u_{1k}\sigma_{k} \\ u_{21}\sigma_{1} & u_{22}\sigma_{2} & \dots & u_{2k}\sigma_{k} \\ \dots & & & & \\ u_{n1}\sigma_{1} & u_{n2}\sigma_{2} & \dots & u_{nk}\sigma_{k} \end{bmatrix}_{n*k} \begin{bmatrix} v_{11} & v_{12} & \dots & v_{1d} \\ v_{21} & v_{22} & \dots & v_{2d} \\ \dots & & & & \\ v_{k1} & v_{k2} & \dots & v_{kd} \end{bmatrix}_{k*d}$$

$$A_k(1,1) = u_{11} * \sigma_1 * v_{11} + u_{12} * \sigma_2 * v_{21} + \dots + u_{1k} * \sigma_k * v_{k1}$$

Generalizing for all rows(j) and columns(l) we can rewrite the above equation as follows:

$$A_k(j,l) = \sum_{i=1}^k \sigma_i * u_i(j) * v_i(l)$$

Part b

$$A_k = \begin{bmatrix} \sum_{i=1}^k \sigma_i * u_i(1) * v_i(l) & \sum_{i=1}^k sigma_i * u_i(1) * v_i(2) & \dots & \sum_{i=1}^k sigma_i * u_i(1) * v_i(l) \\ \sum_{i=1}^k \sigma_i * u_i(2) * v_i(1) & \sum_{i=1}^k sigma_i * u_i(2) * v_i(2) & \dots & \sum_{i=1}^k sigma_i * u_i(2) * v_i(l) \\ \sum_{i=1}^k \sigma_i * u_i(j) * v_i(l) & \sum_{i=1}^k sigma_i * u_i(j) * v_i(2) & \dots & \sum_{i=1}^k sigma_i * u_i(j) * v_i(l) \end{bmatrix}$$

$$=\sigma_1*\begin{bmatrix}u_1(1)*v_1(1) & u_1(1)*v_1(2) & \dots & u_1(1)*v_1(l)\\u_1(2)*v_1(1) & u_1(2)*v_1(2) & \dots & u_1(2)*v_1(l)\\u_1(j)*v_1(1) & u_1(j)*v_1(2) & \dots & u_1(j)*v_1(l)\end{bmatrix}+\sigma_2*\begin{bmatrix}u_2(1)*v_2(1) & u_2(1)*v_2(2) & \dots & u_2(1)*v_2(1)\\u_2(2)*v_2(1) & u_2(2)*v_2(2) & \dots & u_2(2)*v_2(l)\\u_2(j)*v_2(1) & u_2(j)*v_2(2) & \dots & u_2(j)*v_2(l)\end{bmatrix}+\sigma_2*\begin{bmatrix}u_1(1)*v_2(1) & u_2(1)*v_2(1) & u_2(1)*v_2(1) & u_2(1)*v_2(1)\\u_2(j)*v_2(1) & u_2(j)*v_2(2) & \dots & u_2(j)*v_2(l)\end{bmatrix}+\sigma_2*\begin{bmatrix}u_1(1)*v_2(1) & u_2(1)*v_2(1) & u_2(1)*v_2(1) & u_2(1)*v_2(1)\\u_2(j)*v_2(1) & u_2(j)*v_2(2) & \dots & u_2(j)*v_2(l)\end{bmatrix}+\sigma_2*\begin{bmatrix}u_1(1)*v_2(1) & u_2(1)*v_2(1) & u_2(1)*v_2(1) & u_2(1)*v_2(1)\\u_2(j)*v_2(1) & u_2(j)*v_2(2) & \dots & u_2(j)*v_2(l)\\u_2(j)*v_2(1) & u_2(j)*v_2(2) & \dots & u_2(j)*v_2(l)\\u_1(j)*v_2(1) & u_1(j)*v_2(1) & \dots & u_2(j)*v_2(l)\\u_2(j)*v_2(1) & u_2(j)*v_2(2) & \dots & u_2(j)*v_2(l)\\u_2(j)*v_2(j)*v_2(j) & \dots & u_2(j)*v_2(l)\\u_2(j)*v_2(j)*v_2(j)*v_2(j) & \dots & u_2(j)*v_2(l)\\u_2(j)*v_2(j)*v_2(j)*v_2(j)*v_2(j)*v_2(j)\\u_2(j)*v_2$$

$$= \sigma_1 * u_1 * v_1^T + \sigma_2 * u_2 * v_2^T + \dots + \sigma_k * u_k * v_k^T$$

$$A_k = \sum_{i=1}^k \sigma_i * u_i * v_i^T$$

Hence proved.

Part c

$$A_{k+1} = A_k + \sigma_{k+1} * \begin{bmatrix} u_{k+1}(1) * v_{k+1}(1) & u_{k+1}(1) * v_{k+1}(2) & \dots & u_{k+1}(1) * v_{k+1}(l) \\ u_{k+1}(2) * v_{k+1}(1) & u_{k+1}(2) * v_{k+1}(2) & \dots & u_{k+1}(2) * v_{k+1}(l) \\ u_{k+1}(j) * v_{k+1}(1) & u_{k+1}(j) * v_{k+1}(2) & \dots & u_{k+1}(j) * v_{k+1}(l) \end{bmatrix}$$

$$A_{k+1} = A_k + \sigma_{k+1} * u_{k+1} * v_{k+1}^T$$

Part d

$$A = \sum_{i=1}^{r} \sigma_i * u_i(j) * v_i(l)$$

$$A_k = \sum_{i=1}^{k} \sigma_i * u_i(j) * v_i(l)$$

$$A - A_k = \sum_{i=1}^{r} \sigma_i * u_i(j) * v_i(l) - \sum_{i=1}^{k} \sigma_i * u_i(j) * v_i(l) = \sum_{i=k+1}^{r} \sigma_i * u_i(j) * v_i(l)$$

$$R_k(j,l) = \sum_{i=k+1}^r \sigma_i * u_i(j) * v_i(l)$$

Part e

$$R_k(j, l) = \sum_{i=k+1}^r \sigma_i * u_i(j) * v_i(l)$$
$$R_k(j, l)^2 = \sum_{i=k+1}^r (\sigma_i * u_i(j) * v_i(l))^2$$

When we expand the above and multiply the terms we can write it

$$||R||_F^2 = \sum_{j,l} \sum_{i=k+1}^r \sigma_i^2 * u_i^2(j) * v_i^2(l)$$

The rest of terms in cases where a!=b

$$\sum_{i,l} \sigma_a * \sigma_b * u_a * u_b * v_a * v_b = 0$$

$$||R||_F^2 = \sum_{i,l} \sum_{i=k+1}^r \sigma_i^2 * u_i^2 * v_i^2$$

And as U and V are unit vectors and as individual components summation is 1 we can write

$$||A - A_k||_F^2 = \sum_{i=k+1}^r \sigma_i^2$$

Problem 2

- We can use JL lemma to reduce the dimensions. We've pairwise distances between points as $1 ||x_i x_j|| = 1$
- We are placing m points such that pairwise distance between points is in range 0.9 to 1.1 i.e $\varepsilon=0.1$
- Let $||y_i y_j||_{be}$ distance between points after Gaussian projection of original points in d dimensions.
- From JL lemma-1 let $d \geq \frac{8}{\varepsilon^2} ln(\frac{m}{\delta})$ Then for any $\varepsilon \in (0,1]$ with a probability $1-\delta$ that for all (i,j) pairs we can claim $(1-\varepsilon)||x_i-x_j|| \leq ||y_i-y_j|| \leq (1+\varepsilon)||x_i-x_j||$
- We now need a minimum value of d and we know $\varepsilon=0.1$ and if we substitute $\delta=0.1$

•
$$d = \frac{8}{0.1^2} ln(\frac{m}{0.1}) = 800(ln(m) - ln(0.1)) = 800 * ln(m) - 800 * ln(0.1)$$

$$O(d) = O(ln(m))$$

Hence,"I can place m points with all pairwise distances between 0:9 and 1:1, and I only need O (ln(m)) dimensions!"