## Colorado CSCI 5454: Algorithms Homework 9

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Due: Friday, November 22, 2019 at 11:59pm

Turn in electronically via Gradescope.

Remember to list the people you worked with and any outside sources used (if none, write "none").

## Problem 1 (12 points)

Suppose you have a database of movie recommendations stored as a matrix  $A \in \mathbb{R}^{n \times d}$ , where A(i, j) is person i's rating of movie j, a real number between zero and one.

There are n people and d movies, so A has n rows and d columns.

Now you take the singular value decomposition,

$$A = U D V^{\mathsf{T}}$$

where (updated), when r is the rank of A:

- $U \in \mathbb{R}^{n \times r}$  is an orthogonal matrix<sup>1</sup>.
- $D \in \mathbb{R}^{r \times r}$  is a diagonal matrix<sup>2</sup>, and the entries are sorted from largest to smallest.
- $V \in \mathbb{R}^{d \times r}$  is an orthogonal matrix, and  $V^{\intercal}$  is its transpose.

Recall that the columns  $u_1, \ldots, u_n$  of U are the *left singular vectors*, the diagonal entries  $\sigma_1, \ldots, \sigma_r$  of D are the *singular values*, and the columns  $v_1, \ldots, v_d$  of V are the *right* singular vectors.

Recall that we obtain a rank-k approximation by taking the first k columns of U and V, along with the first k rows of D. This gives us  $U_k \in \mathbb{R}^{n \times k}$ ,  $D_k \in \mathbb{R}^{k \times d}$ , and  $V_k \in \mathbb{R}^{d \times k}$ , with

$$A_k := U_k \ D_k \ V_k^{\mathsf{T}}.$$

In this problem, we'll show that  $A_k$  is a sum of k rank-one matrices, from "most important" to "least". We will also bound how much accuracy is lost by dropping the "unimportant" matrices from the sum.

Part a (4 points) Show that  $A_k(j,\ell) = \sum_{i=1}^k \sigma_i u_i(j) v_i(\ell)$ .

<sup>&</sup>lt;sup>1</sup>Every row is a unit vector, and the rows are all pairwise orthogonal; and this is also true of the columns.

<sup>&</sup>lt;sup>2</sup>All entries are zero except the (i, i) entries.

**Solution.** Let  $B = U_k D_k$ . Then by the rules of matrix multiplication,  $B(j,i) = \sum_{o=1}^k U_k(j,o) D_k(o,i)$ . Note  $U_k(j,o) = u_o(j)$ , where  $u_o$  is the oth column. Since  $D_k(o,i) = 0$  unless o = i, in which case it is  $\sigma_i$ , we have  $B(j,i) = u_i(j)\sigma_i$ .

Then  $A_k = BV_k^{\mathsf{T}}$ . Note  $V_k^{\mathsf{T}}(i,\ell) = V_k(\ell,i) = v_i(\ell)$  where  $v_i$  is the *i*th column of  $V_k$ . So

$$A_k(j,\ell) = \sum_{i=1}^k B(j,i) V_k^{\mathsf{T}}(i,\ell)$$
$$= \sum_{i=1}^k B(j,i) v_i(\ell)$$
$$= \sum_{i=1}^k u_i(j) \sigma_i v_i(\ell).$$

**Part b (2 points)** Recall that if u and v are vectors, then their outer product  $uv^{\dagger}$  is a matrix whose  $(j, \ell)$  entry is  $u(j)v(\ell)$ . Using this and the previous part, show the following identity:

$$A_k = \sum_{i=1}^k \sigma_i u_i v_i^{\mathsf{T}}$$

That is,  $A_k$  is the sum of these k matrices, one for each set of singular value+vectors.

**Solution.** Let us define  $C = \sum_{i=1}^k \sigma_i u_i v_i^{\mathsf{T}}$ . We just need to show  $C(j,\ell) = A_k(j,\ell)$  for all entries  $j,\ell$ . If we look at the matrix  $u_i v_i^{\mathsf{T}}$ , then its  $j,\ell$  entry is  $u_i(j)v_i(\ell)$ . So  $C(j,\ell) = \sum_{i=1}^k \sigma_i u_i(j)v_i(\ell)$ , which equals  $A_k(j,\ell)$  by the previous part.

**Part c (2 points)** Suppose you have computed the SVD and listed all the singular values and vectors of A. You used these to compute the approximation  $A_k$ . Using the previous part, what is a quick way to now compute the better approximation  $A_{k+1}$ ?

**Solution.** By the previous part, we can write  $A_{k+1} = A_k + \sigma_{k+1} u_{k+1} v_{k+1}^{\mathsf{T}}$ . So we just need to add this rank-one matrix to  $A_k$ .

**Part d (2 points)** When we approximate A by  $A_k$ , let the remainder be  $R_k := A - A_k$ . Show that  $R_k(j,\ell) = \sum_{i=k+1}^r \sigma_i u_i(j) v_i(\ell)$ .

**Solution.** If we set k = r in the previous parts, we get all of A, i.e.  $A = \sum_{i=1}^{r} \sigma_i u_i v_i^{\mathsf{T}}$ . So  $A - A_k = \sum_{i=k+1}^{r} \sigma_i u_i v_i^{\mathsf{T}}$ , which implies the claim.

**Part e (2 points)** Use the previous part to argue that  $||A - A_k||_F^2 \le \sum_{i=k+1}^r \sigma_i^2$ . In other words, the total error in the approximation of  $A_k$  is bounded by the small singular values that are dropped.

(Recall that for a matrix R,  $||R||_F^2 := \sum_{j,\ell} R(j,\ell)^2$ . Also recall that each  $u_i$  and  $v_i$  are unit vectors.)

**Solution.** We also need to recall that  $u_i$  is orthogonal to all  $u_{i'}$  for  $i \neq i'$ , and similarly the columns of V are orthogonal. So we can take a "brute-force" approach of expanding it out:

$$\sum_{j,\ell} R_k(j,\ell)^2$$

$$= \sum_{j,\ell} \sum_{i=k+1}^r \sum_{i'=k+1}^r \sigma_i \sigma_{i'} u_i(j) u_{i'}(j) v_i(\ell) v_{i'}(\ell)$$

$$= \sum_{i=k+1}^r \sum_{i'=k+1}^r \sigma_i \sigma_{i'} \sum_j u_i(j) u_{i'}(j) \sum_{\ell} v_i(\ell) v_{i'}(\ell)$$

$$= \sum_{i=k+1}^r \sigma_i^2.$$

The key is that  $\sum_{\ell} v_i(\ell) v_{i'}(\ell) = v_i \cdot v_{i'}$ , so it is zero if  $i \neq i'$ , otherwise it is one. The same goes for  $u_i$  and  $u_{i'}$ .

Note we actually get equality.

## Problem 2 (4 points)

Your friend is boasting about the following construction. "In *m*-dimensional space," she says, "I put a point at  $(\frac{1}{\sqrt{2}}, 0, \dots, 0)$ . Then I put one at  $(0, \frac{1}{\sqrt{2}}, 0, \dots, 0)$ . And so on. Eventually, I have placed *m* points in just *m* dimensions, such that the distance between any pair of points is exactly one!"

"That's nothing," you say. "I can place m points with all pairwise distances at between 0.9 and 1.1, and I only need O(\_\_\_\_\_) dimensions!"

(Fill in the blank and carefully justify your answer.)

**Solution.** We can put ln(m) in the blank.

There are m points in our friend's construction. The Johnson-Lindenstrauss lemma says that, if we start from our friend's construction, we can take  $\epsilon = 0.1$  and any  $\delta < 1$  and get, with probability at least  $1 - \delta$ , all the projected points will have pairwise distance in [0.9, 1.1], for any choice of dimension  $d \ge \frac{8}{\epsilon^2} \ln \left( \frac{m}{\delta} \right) = 800 \ln(m/\delta)$ .

Now, this holds for any  $\delta$ . So if we pick any  $\delta < 1$ , there is positive probability of being able to place the points in this manner. So there will be some way to place the points in any dimension  $d > 800 \ln(m)$ .