

Pramodkumar Choudhary

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Education

- Oct. 2021 - **M. Sc., Informatics**, *Technical University of Munich(TUM)*, Munich
Nov. 2024 Grade: 1.9, *German scale*
Focus Area: Machine Learning, Robotics, Scientific Computing and High Performance Computing(HPC).
Aug. 2016 - **B. Eng., Computer Engineering**, *University of Mumbai*, Mumbai
Oct. 2020 Grade: 8.38/10, *CGPA*

Research Experience

- Jan. 2024 - **Robot-adaptive Neural Inverse Kinematics**, *TUM*, Munich
Jun. 2024 **Master thesis**, Supervisor: Prof. Dr. Matthias Althoff
 - Use of self-supervised learning to design a single, robot-adaptive model that generalises across arbitrary serial kinematic chains (2-6 DOF), eliminating the need for robot-specific models and pre-computation.
 - Demonstrate a unified approach for generating diverse, collision-aware inverse kinematics (IK) solutions for manipulators in complex, unseen environments with obstacles.

May 2023 - **Benchmarking Hybrid Reinforcement Learning for Robot Morphology Optimization**, *TUM*, Munich
Nov. 2023 **Guided research**, Supervisor: Prof. Dr. Matthias Althoff
Continuation work of Master practical course.
 - Perform a systematic benchmark of multiple deep reinforcement learning algorithms based on parameterized action space for the task of robot morphology optimization.
 - Analyze algorithm performance in terms of convergence speed, final reward, and computational cost, providing insights into their suitability for complex design synthesis problems.

Nov. 2022 - **Optimizing temperature controllers of Multi-stage continuous Adiabatic Demagnetization**, *TUM and Kiutra GmbH*, Munich
Jun. 2023 **Interdisciplinary project**, Supervisor: Prof. Dr. Christian Pfleiderer & Dr. Alexander Regnat
 - Design control parameters of an adiabatic demagnetisation refrigeration(ADR) process as a sequential Markov Decision Process(MDP) to precisely control temperature setpoints to replace manually tuned PID controllers.
 - Conduct a systematic study to mitigate policy-induced noise caused by deep reinforcement learning to ensure a stable and robust control required for sub-kelvin temperature regulation.

Oct. 2022 - **Hybrid Reinforcement Learning for Robot Morphology Optimization**, *TUM*, Munich
Mar. 2023 **Master practical course**, Supervisor: Prof. Dr. Matthias Althoff
 - Formulate the robot design problem as a Markov Decision Process(MDP) with a hybrid discrete-continuous action space to simultaneously select robot modules and their parameters.
 - Implement a search heuristic to construct task-specific robot morphologies in 2D and 3D environments while satisfying reachability and obstacle-avoidance constraints.

Apr. 2022 - **NeRF based Kinematic Calibration**, *TUM*, Munich
Sep. 2022 **Course project: Advanced deep learning for Robotics**
 - Extend Neural Radiance Fields (NeRFs) to learn camera parameters and the noisy configuration of a robot arm within the scene.
 - Couple a robot's forward kinematic chain as a differentiable component within the neural rendering optimization to calibrate camera parameters and robot joint angles.

Aug. 2019 - **Trail Tracker: Anti-Poaching Intelligence**, *University of Mumbai*, Mumbai
Oct. 2020 **Bachelors project**, Supervisor: Asst. Prof. Vidya Zope
 - Train a computer vision model to predict and identify poaching activities from sensor data, optimized for low-power edge deployment.
 - Define and deploy edge-computing architecture using IoT that enables AI inference for operational robustness in remote environments.

Work Experience

- Dec. 2024 - **Software developer**, *Kiutra GmbH*, Munich
current Design, develop, and maintain the software lifecycle for cryogenic control systems, from architecture and automation to CI/CD and release management.

- Mar. 2022 - **Working student software developer**, *Kiutra GmbH*, Munich
- Nov. 2024 Build a centralized control software with integrated real-time visualization backed by high-frequency data storage and communication systems.
- May 2020 - **Web development intern**, *Indian Institute of Technology - Bombay*, Mumbai
- Jun. 2020 Collaborate on a data-driven media platform featuring user personalization, an analytics dashboard, and an integrated AWS video-on-demand pipeline.
- Jun. 2019 - **Deep learning intern**, *Konsultera Solutions Pvt. Ltd.*, Mumbai
- Jul. 2019 Discover a lightweight emotion recognition model by applying transfer learning over existing architectures and analyze optimizations achieved.
- Jun. 2018 - **Deep learning intern**, *Konsultera Solutions Pvt. Ltd.*, Mumbai
- Jul. 2018 Build and deploy an object detection model for automated attendance tracking integrated into a real-time system.

Publications

- IJCRT 2020 V. Zope, S. Relekar, **P. Choudhary**, M. Ochaney, & R. Bhagtani. *Trail-tracker: Anti-poaching Intelligence Using AI and IoT*. In IJCRT Vol. 8, No. 4, 2020.

Seminars and Workshops

- Mar. 2023 **Beyond Deep Learning: Selected Topics on Novel Challenges**, *TUM*, Munich
Topic: Continual Learning
- Nov. 2019 **Object Detection API using TensorFlow**, *Mumbai*
Conducted as part of the Computer Society of India
- Oct. 2019 **React workshop**, *Mumbai*
Conducted as part of the Computer Society of India
- Feb. 2019 **Python workshop**, *Mumbai*
Conducted as part of the Computer Society of India

Extra Curricular Activities

- Jun. 2019 - Teaching Volunteer in U&I Organization at Vision Rescue, Kalwa Center
- Mar. 2020
- Jul. 2019 - Senior technical member: Computer Society of India(CSI)-VESIT Council
- Apr. 2020
- Jul. 2018 - Executive committee member: Computer Society of India(CSI)-VESIT Council
- Apr. 2019

Technical skills

- Programming Python, C++, Bash
- ML Concepts Deep learning, Reinforcement learning, Self-supervised learning
 - HPC PyTorch Distributed Data Parallel(DDP), CUDA
 - Web React, Next.js, Node.js, Redux, Webpack, Flask, Quart
 - Data Pandas, SQL, MongoDB
- Miscellaneous Git, Docker, Redis, Ansible, Proxmox
 - API REST, Websockets, GraphQL