EX8 190144D

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Exercise 8

```
import numpy as np
import matplotlib.pyplot as plt
import cv2 as cv
from scipy.linalg import null_space
```

## 1

```
In []:
    f = open(r'templeSparseRing/templeSR_par.txt', 'r')
    assert f is not None
    n = int(f.readline())
    # Reading the information of the first image
    l = f.readline().split()
    im1_fn = 1[0]
    K1 = np.array([float(i) for i in 1[1:10]]).reshape ((3,3))
    R1 = np.array([float(i) for i in 1[10:19]]).reshape((3,3))
    t1 = np.array([float(i) for i in 1[19:22]]).reshape((3,1))
    # Reading the information of the second image
    l = f.readline().split()
    im2_fn = 1[0]
    K2 = np.array([float(i) for i in 1[1:10]]).reshape((3,3))
    R2 = np.array([float(i) for i in 1[10:19]]).reshape((3,3))
    t2 = np.array([float(i) for i in 1[19:22]]).reshape((3,1))
```

## 2

```
im1 = cv.imread(r'templeSparseRing/' + im1_fn, cv.IMREAD_COLOR)
 im2 = cv.imread(r'templeSparseRing/' + im2_fn, cv.IMREAD_COLOR)
 assert im1 is not None
assert im2 is not None
# Compute P1 and P2
P1 = K1 @ np.hstack((R1, t1)) # P = K^*[R/t]
P2 = K2 @ np.hstack((R2, t2)) # P = K^*[R|t]
print('P1 = \n', P1)
 print('P2 = \n', P2)
P1 =
 [[ 4.80251845e+01 1.44011271e+03 -5.71648932e+02 7.53293366e+01]
 [ 1.53577034e+03 -6.41434324e+01 -1.63127843e+02 1.85810055e+02]
 [ 4.88387837e-02 -1.81568392e-01 -9.82164799e-01 6.14604846e-01]]
P2 =
[[-1.55882371e+02 1.44377186e+03 -5.42436214e+02 6.81806220e+01]
 [ 1.34928131e+03 -8.41979541e+01 -7.49443961e+02 1.99929996e+02]
 [-3.40999743e-01 -1.74474039e-01 -9.23730472e-01 6.00850565e-01]]
```

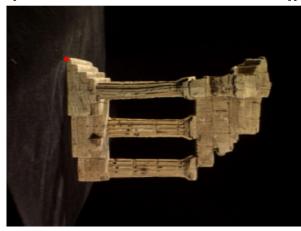
## 3

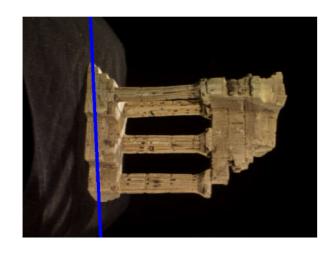
```
In [ ]:
    def skew(x):
        x = x.ravel()
        return np.array([[0, -x[2], x[1]], [x[2], 0, -x[0]], [-x[1], x[0], 0]])
    C = null_space(P1)
    C = C * np.sign(C[0, 0])
    e2 = P2 @ C
    e2x = skew(e2)
    F = e2x @ P2 @ np.linalg.pinv(P1)
    print('F = \n', F)
    x = np.array([130, 115, 1])
    cv.circle(im1, (x[0], x[1]), 5, (0, 0, 255), -1)
    12 = F @ x.T
    p1 = np.array([0, (12[0]*0 + 12[2])/12[1]]).astype(int)
```

4/4/22, 10:36 PM EX8\_190144D

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p2 = np.array([500, (12[0]*500 + 12[2])/12[1]]).astype(int)
cv.line(im2, (p1[0], p1[1]), (p2[0], p2[1]), (255,0, 0), 5)
fig, ax = plt.subplots(1, 2, figsize=(18, 18))
ax[0].imshow(cv.cvtColor(im1, cv.COLOR_BGR2RGB))
ax[0].axis('off')
ax[1].imshow(cv.cvtColor(im2, cv.COLOR_BGR2RGB))
ax[1].axis('off')
plt.show()
```

F = [[-2.87071497e-04 -3.96261289e-02 2.94221686e+02] [-3.55039713e-02 1.65329260e-04 1.78860854e+01] [-2.76702814e+02 2.12942175e+01 -9.06669374e+03]]





4

```
In [ ]:
         image1 = cv.imread (r'templeSparseRing/'+im1_fn,0)
         image2 = cv.imread (r'templeSparseRing/'+im2_fn,0)
         sift = cv.SIFT_create()
         kp1, desc1 = sift.detectAndCompute(image1, None)
         kp2, desc2 = sift.detectAndCompute(image2, None)
         FLANN_INDEX_KDTREE = 1
         indx_para = dict(algorithm = FLANN_INDEX_KDTREE, trees = 5)
         search_para = dict (checks = 50)
         flann = cv.FlannBasedMatcher(indx_para, search_para)
         matches = flann.knnMatch(desc1, desc2, k=2)
         points1, points2 = [],[]
         for i, (m,n) in enumerate (matches):
             if m.distance < 0.8*n.distance:</pre>
                 points2.append (kp2 [m.trainIdx].pt)
                 points1.append (kp1 [m.queryIdx] .pt)
         points1= np.int32 (points1)
         points2 = np.int32 (points2)
         F ,mask = cv. findFundamentalMat(points1, points2, cv.FM_LMEDS)
         points1 = points1[mask.ravel () == 1]
         points2 = points2 [mask.ravel () == 1]
         def drawlines (img1, img2, lines, pts1,pts2):
             r,c = img1. shape
             img1 = cv.cvtColor (img1, cv. COLOR_GRAY2BGR)
             img2 = cv.cvtColor (img2, cv.COLOR_GRAY2BGR)
             for r,pt1, pt2 in zip (lines, pts1, pts2) :
                 color = tuple(np. random.randint(0, 255, 3).tolist())
                 x0,y0 = map(int, [0,-r[2]/r[1]])
                 x1,y1 = map (int, [c,-(r[2]+r[0]*c)/r[1]])
                 img1 = cv.line (img1,(x0, y0), (x1, y1), color, 1)
                 img1 = cv.circle (img1, tuple (pt1), 5, color, -1)
                 img2 = cv.circle (img2, tuple (pt2) , 5, color, -1)
             return img1, img2
         lins1 = cv.computeCorrespondEpilines (points2.reshape(-1, 1, 2),2,F)
         lins1 = lins1.reshape (-1, 3)
         image3, image4 = drawlines (image1, image2, lins1, points1, points2)
```

4/4/22, 10:36 PM EX8\_190144D

```
lins2 = cv.computeCorrespondEpilines (points2.reshape (-1,1,2) , 2, F)
lins2 = lins2.reshape (-1, 3)
image5, image6 = drawlines (image2, image1, lins2, points2, points1)
plt. figure (figsize=(20, 20) )
plt. subplot (121), plt. imshow (image3)
plt. subplot (122), plt. imshow (image5)
plt.show()
```

