Parallel Computing with GPUs: Visual Studio Guide for CUDA

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Compiling a CUDA program

☐ CUDA C Code is compiled using **nvcc** e.g.

☐ Will compile host AND device code to produce an executable

nvcc -o example example.cu

☐ We will be using Visual Studio to build our CUDA code so we will not need to compile at the command line (unless you are running on ShARC)



Creating a CUDA Project

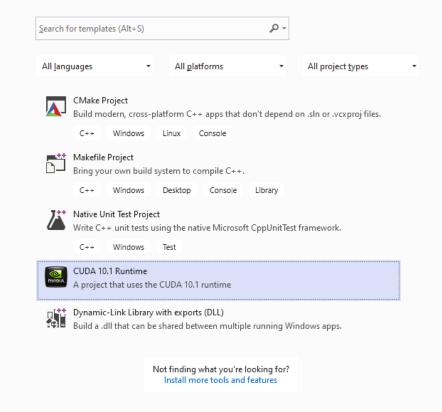
- ☐ Create New CUDA Project
 - □Select NVIDIA -> CUDA 11.1
 - ☐ This will create a project with a default kernels.cu file containing a basic vector addition example

Create a new project

Recent project templates

Empty Project

C++

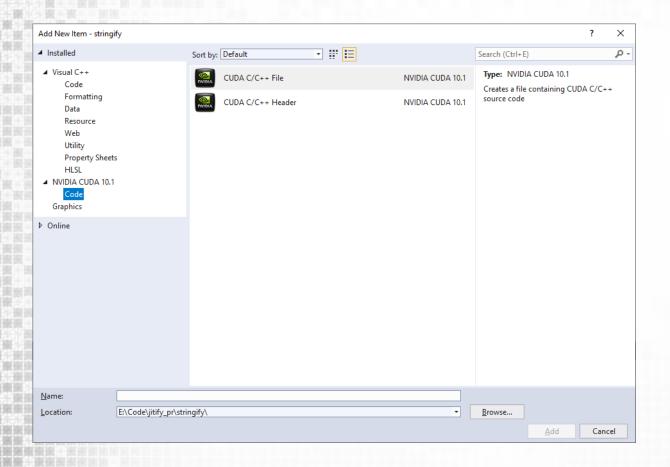


Preferred Method!



<u>N</u>ext

Adding a CUDA source file

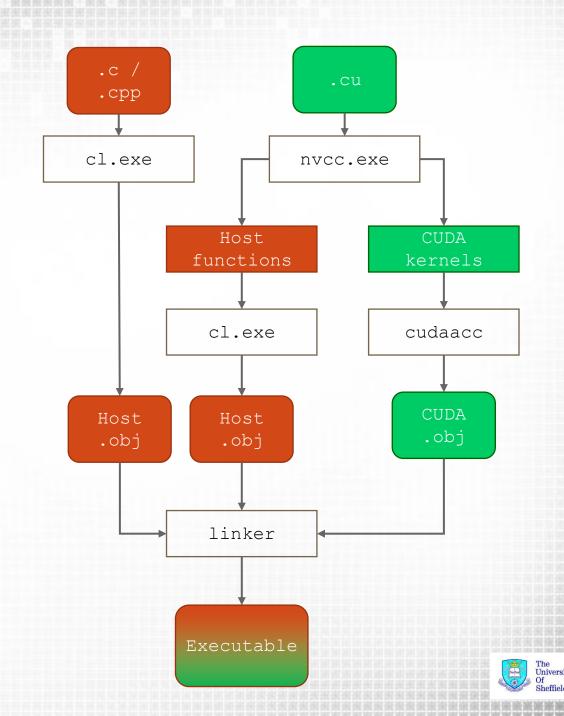


- ☐ Alternatively add a CUDA source file to an existing application
- ☐ If you do this you must modify the project properties to include CUDA build customisations
 - http://developer.downlo
 ad.nvidia.com/compute/c
 uda/6 5/rel/docs/CUDA
 Getting Started Window
 s.pdf (section 3.4)



Compilation

- □CUDA source file (*.cu) are compiled by nvcc
- ☐ An existing cuda.rules file creates property page for CUDA source files
 - □Configures nvcc in the same way as configuring the C compiler
 - □Options such as optimisation and include directories can be inherited from project defaults
- ☐ C and C++ files are compiled with cl (MSVCC compiler)



Device Versions

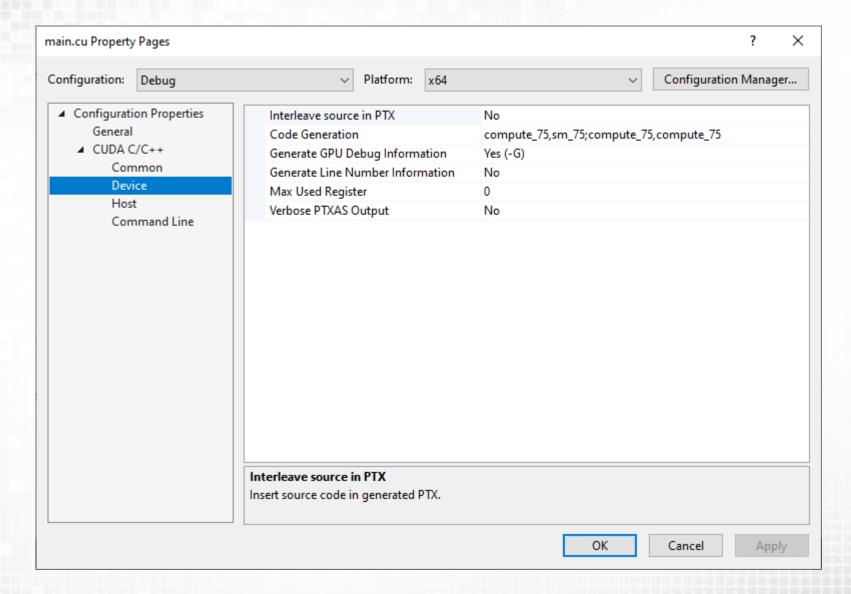
Device Versions of Available GPUs

☐ Diamond Machines

☐ Pascal Architecture

 \square compute_60,sm_60;

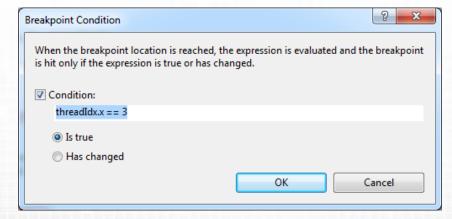
CUDA Properties





Debugging

- □NSIGHT is a GPU debugger for debugging GPU kernel code
 - ☐ It does not debug breakpoints in host code
- ☐ To launch select insert a breakpoint and select NSIGHT-> Start CUDA Debugging
 - ☐You must be in the debug build configuration.
 - ☐ When stepping all warps except the debugger focus will be paused
- ☐ Use conditional breakpoints to focus on specific threads
 - ☐ Right click on break point and select Condition







Error Checking

- ☐ cudaError_t: enumerator for runtime errors
 ☐ Can be converted to an error string (const char *) using cudaGetErrorString (cudaError t)
- ☐ Many host functions (e.g. cudaMalloc, cudaMemcpy) return a cudaError_t which can be used to handle errors gracefully

```
cudaError_t cudaStatus;

cudaStatus = cudaMemcpy(dev_a, a, size * sizeof(int), cudaMemcpyHostToDevice);
if (cudaStatus != cudaSuccess) {
    //handle error
}
```

☐ Kernels do not return an error but if one is raised it can be queried using the cudaGetLastError() function

```
addKernel<<<1, size>>>(dev_c, dev_a, dev_b);
cudaStatus = cudaGetLastError();
```

