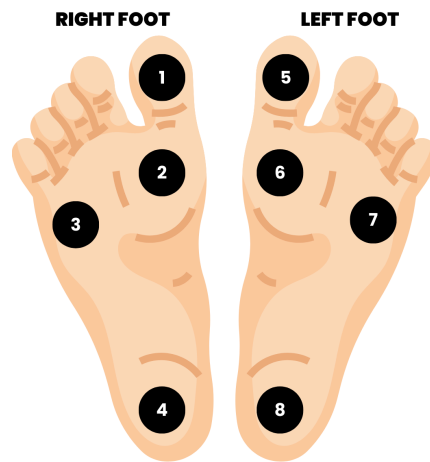


Sensor's positioning



Data sent as: Timestamp; Sensor1, Sensor2, Sensor3, Sensor4 ; Sensor5, Sensor6, Sensor7, Sensor8\n