

# pumpMaster 1.0.0

**pumpMaster** is an application which predicts the imminent failure of pumps and comparable turbomachines. Preemptive warnings or alerts prevent catastrophic failure by triggering timely operator/controller intervention. Such an intervention is crucial for safety and reliability of operators and high value critical systems. **pumpMaster** is able to make these predictions because it continuously listens to sensor data streams and identifies signal patterns which predict failure. At its heart is a simple linear regression model trained on time series sensor data. Section 1 details the data set and the motivations behind it.

## 1. Data Set

**pumpMaster** is trained with and demonstrated on the [Pump Sensor Dataset](#) from Keggles. The DataSet consists of indices, time-stamped signals from 52 sensors and machine status as NORMAL, BROKEN or RECOVERING. There are three motivations to use this data-set.

1. It is a very realistic data-set as this is how industrial logs are also maintained.
2. The data is raw, signal is noisy and it contains 7 different failures.
3. Though the sensors are not annotated, they provide sufficient indication for failure (taking one example in Figure 1) thus, are sufficient to build a predictor.

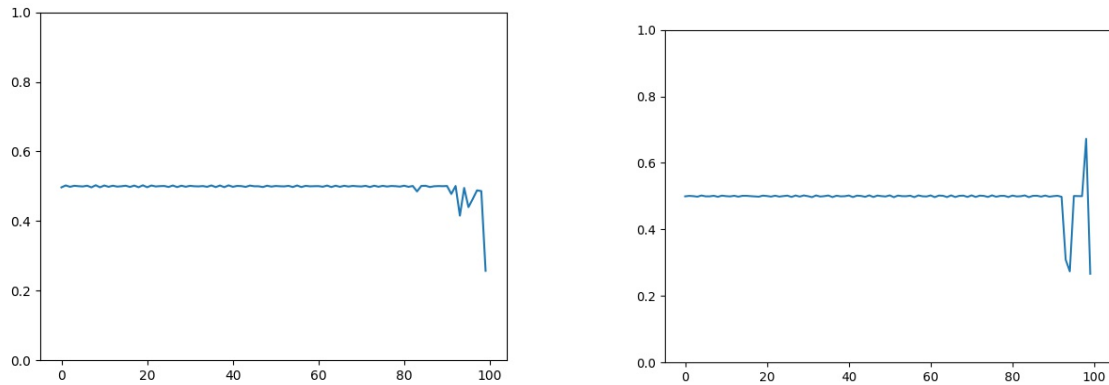


Figure 1: Sensor data preempting failure about 10 minutes before actual failure

## 2. Formulation

At first glance the machine state labels make it seem like a classification problem, however, pumps are not typically designed to work with a lot of variations in parameters speaking from my experiences in Mechanical, Aerospace, Maritime industries. A good measure for how well it is performing is:

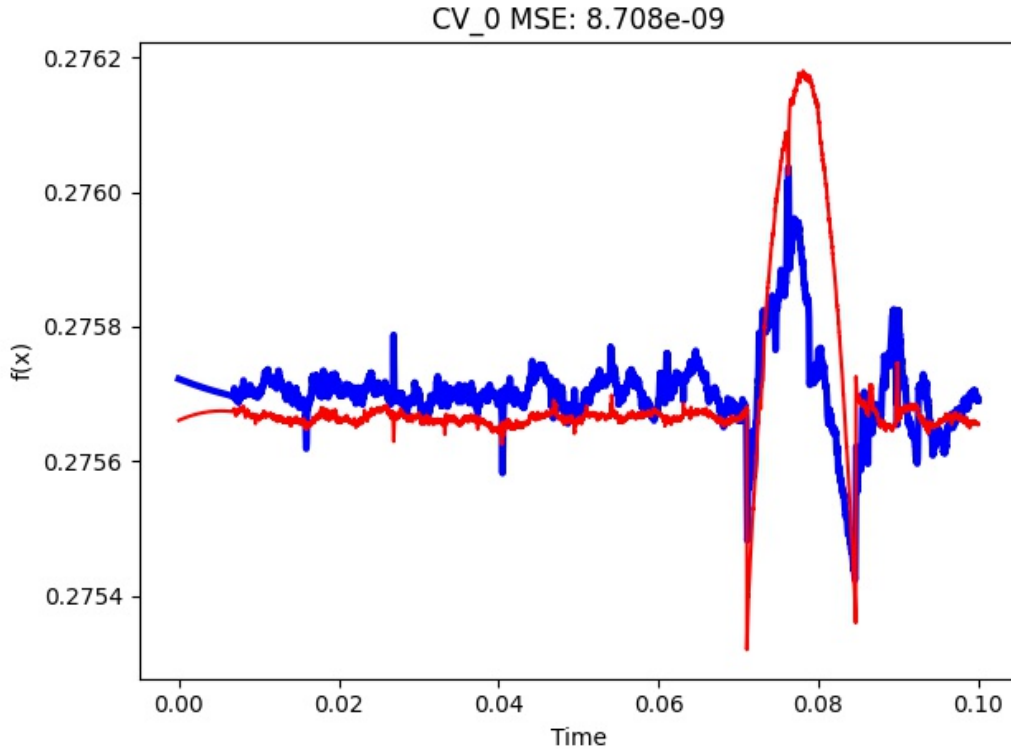
$$y_t = \frac{1}{52} \sum_{i=1}^{52} \frac{\partial s_i(t)}{\partial t} + y_c; \text{ Where } y_c \in \{0,1\}, 0 - \text{Normal/Recovering, Broken, } s_i \text{ is } i\text{-th signal}$$

This function is now continuous and with Exponentially Weighted Moving Averages, we would be able to make predictions of the form:

$$y'_t = f\left(\text{ewm}\left(\frac{\partial s_0}{\partial t}\right), \dots, \text{ewm}\left(\frac{\partial s_{52}}{\partial t}\right)\right)$$

### 3. Regression

An ordinary least square regression is now sufficient as seen from cross-validation results.



Cross Validation studies