```
moteus::IcPz::Status
  + bool active
  + bool err
  + bool warn
  + uint32_t value
  + uint8 t nonce
  + uint8 t cmd
  + uint8 t cmd stat
  + float ai_phases
  + float ai scales
  + bool dig sat
  + bool led cur low
  + bool temp not steady
  + bool vddio low
  + bool interp err
  + bool abz not ready
  + bool uvw not ready
  + bool pos alpha
  + bool pos omega
 + bool dig_not_steady
 + bool prc_sync_failed
  + bool ana bound
  + bool dig bound
 + bool temp1
 + bool temp2
  + uint8 t adi
  + uint8 t dig
 + void Serialize(Archive *a)
                +status
         moteus::lcPz
+ IcPz(const Options
&options, MillisecondTimer
*timer)
+ void SetExtraRead(uint8
t bitfield)
+ void StartCommand(uint8
t cmd)
+ void ReadRegisters
(uint8 t reg, mjlib
::base::string_span output)
+ void WriteRegisters
```

(uint8_t reg, std::string

+ void PollMillisecond()
 + void DoOperating()
 + void ISR_StartSample
 () MOTEUS_CCM_ATTRIBUTE
 + void ISR_MaybeFinishSample
 () MOTEUS_CCM_ATTRIBUTE
 + const Status & status()

view data)