

moteus::MotorPosition
::Status

- + Error error
- + std::array< SourceStatus,
kNumSources > sources
- + uint8_t epoch
- + bool position_relative
_valid
- + int64_t position_relative_raw
- + float position_relative
- + int64_t position_relative
_modulo
- + int64_t position_raw
- + float position
- + Homed homed
- + float velocity
- + bool theta_valid
- + float electrical_theta

+ void Serialize(Archive *a)