

moteus::BldcServo::Impl

```
+ Impl(micro::PersistentConfig
  *persistent_config, micro
  ::TelemetryManager *telemetry
  _manager, MillisecondTimer *millisecond
  _timer, MotorDriver *motor_driver,
  AuxADC *aux_adc, AuxPort *aux1_port,
  AuxPort *aux2_port, MotorPosition *motor
  _position, const Options &options)
+ void Start()
+ ~Impl()
+ void Command(const
  CommandData &data)
+ const Status &status
  () const
+ const Config &config
  () const
+ const Control &control
  () const
+ const AuxPort::Status
  &aux1() const
+ const AuxPort::Status
  &aux2() const
+ const MotorPosition
  ::Status &motor_position
  () const
+ MotorPosition::Config
  *motor_position_config()
+ const MotorPosition
  ::Config *motor_position
  _config() const
+ bool is_torque_constant
  _configured() const
+ float current_to_torque
  (float current) const
+ float torque_to_current
  (float torque) const
+ MOTEUS_CCM_ATTRIBUTE
+ float torque_to_current
  (float torque) const
+ MOTEUS_CCM_ATTRIBUTE
+ void UpdateConfig()
+ void PollMillisecond()
+ void SetOutputPositionNearest
  (float position)
+ void SetOutputPosition
  (float position)
+ void RequireReindex()
```