```
moteus::Vec3
  + float a
  + float b
  + float c
  + void Serialize(Archive *ar)
                  +phase v
                   +pwm
moteus::BldcServoCommandData

    + BldcServoMode mode

    float theta

+ float voltage
+ float theta rate
+ float d V
+ float q V
+ float i d A
+ float i q A
+ float position
+ float velocity
+ std::optional < int64
t > position relative raw
+ float max torque Nm
+ float stop position
+ std::optional < int64
t > stop position relative raw
+ float feedforward Nm
+ float kp scale
+ float kd scale
+ float velocity limit
+ float accel limit
+ float fixed voltage
override
+ float timeout s
+ float bounds min
+ float bounds max
+ int8 t meas ind period
+ void Serialize(Archive *a)
```