moteus::BldcServo

+ BldcServo(mjlib::micro
::Pool *, mjlib::micro
::PersistentConfig *, mjlib
::micro::TelemetryManager
 *, MillisecondTimer *, MotorDriver
 *, AuxADC *, AuxPort *, AuxPort
 *, MotorPosition *, const Options &)
+ ~BldcServo()
+ void PollMillisecond()
+ void Start()
+ void Command(const
 CommandData &)
+ const Status & status
() const
+ const Config & config
() const
+ const Control & control
() const
+ const AuxPort::Status
 & aux1() const
+ const AuxPort::Status
 & aux2() const
+ const MotorPosition
::Status & motor_position
() const
+ MotorPosition::Config
 * motor_position_config()
+ const MotorPosition
::Config * motor_position
_config() const
+ void SetOutputPositionNearest
(float position)
+ void SetOutputPosition
(float position)
+ void RequireReindex()