

moteus::MotorPosition
::SourceConfig

- + uint8_t aux_number
- + Type type
- + uint8_t i2c_device
- + int8_t incremental_index
- + uint32_t cpr
- + float offset
- + int8_t sign
- + int32_t debug_override
- + Reference reference
- + float pll_filter_hz
- + std::array< float, kCompensationSize > compensation_table

+ void Serialize(Archive *a)