

moteus::BldcServoMotor

- + uint8_t poles
- + uint8_t phase_invert
- + float resistance_ohm
- + float v_per_hz
- + std::array< float, 64 > offset
- + float rotation_current_cutoff_A
- + float rotation_current_scale
- + float rotation_torque_scale
- + float cogging_dq_scale
- + std::array< int8_t, 1024 > cogging_dq_comp

+ void Serialize(Archive *a)