

moteus::MotorPosition  
::SourceStatus

- + bool active\_velocity
- + bool active\_theta
- + bool active\_absolute
- + uint32\_t raw
- + float time\_since\_update
- + uint8\_t nonce
- + uint32\_t offset\_value
- + float compensated\_value
- + float filtered\_value
- + float velocity

+ void Serialize(Archive \*a)