

moteus::PID::State

- + float integral
- + float desired
- + float error
- + float error_rate
- + float p
- + float d
- + float pd
- + float command

- + void Clear() MOTEUS_CCM_ATTRIBUTE
- + void Serialize(Archive *a)
- + void Clear() MOTEUS_CCM_ATTRIBUTE
- + void Serialize(Archive *a)