

::Response &response, const std::string_view &message)

+ BldcServo(mjlib::micro ::Pool *, mjlib::micro ::PersistentConfig *, mjlib ::micro::TelemetryManager *, MillisecondTimer *, MotorDriver *, AuxADC *, AuxPort *, AuxPort *, MotorPosition *, const Options &) + ~BldcServo() + void PollMillisecond() + void Start() + void Command(const CommandData &) + const Status & status () const + const Config & config () const + const Control & control () const + const AuxPort::Status

moteus::BldcServo

::Status & motor_position
() const
+ MotorPosition::Config
* motor_position_config()
+ const MotorPosition
::Config * motor_position
_config() const

+ const AuxPort::Status

& aux1() const

& aux2() const + const MotorPosition

+ void SetOutputPositionNearest (float position)
+ void SetOutputPosition

(float position)
+ void RequireReindex()

+bldc_