| multiplex::MicroServer |
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| ::Server |
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| moteus::MoteusController |
| ::Impl |
| + AuxADC aux_adc_ + AuxPort aux1_port_ + AuxPort aux2_port_ + MotorPosition motor _position_ + Drv8323 drv8323_ + BldcServo bldc_ + ClockManager *const clock_manager_ + SystemInfo *const system _info_ |
| + FirmwareInfo *const firmware_ + bool command_valid_ + BldcServo::CommandData command_ |
| + Impl(micro::Pool *pool, micro::PersistentConfig *persistent_config, micro ::CommandManager *command _manager, micro::TelemetryManager *telemetry_manager, multiplex ::MicroServer *multiplex_protocol, ClockManager *clock_manager, SystemInfo *system_info, MillisecondTimer *timer, FirmwareInfo *firmware) + void Start() + void Poll() + void PollMillisecond() + uint32_t Write(multiplex ::MicroServer::Register reg, const multiplex::MicroServer ::Value &value) overrideattribute((optimize("O3"))) + const MotorPosition ::SourceStatus & encoder _value(int index) const + const MotorPosition ::SourceConfig & encoder _config(int index) const + multiplex::MicroServer ::ReadResult Read(multiplex ::MicroServer::Register reg, size_t type) const overrideattribute((optimize("O3"))) |