```
moteus::MotorPosition
::Config::Output

+ int8_t source
+ float offset
+ int8_t sign
+ int8_t reference_source

+ void Serialize(Archive *a)
```

moteus::MotorPosition
::Config

+ std::array < SourceConfig,
kNumSources > sources

+ int8_t commutation
_source
+ float rotor_to_output
ratio

+ Config() + void Serialize(Archive *a)