moteus::MotorDriver

+ virtual void Enable
(bool)=0
+ virtual void Power
(bool)=0
+ virtual bool fault()=0

moteus::Drv8323

+ Drv8323(mjlib::micro
::Pool *, mjlib::micro
::PersistentConfig *persistent
_config, mjlib::micro::TelemetryManager
 *telemetry_manager, MillisecondTimer
 *timer, const Options &)
+ ~Drv8323()
+ void Enable(bool) override
+ void Power(bool) override
+ bool fault() override
+ void PollMillisecond()
+ const Status * status
() const