## moteus::PID

State \*state)

State \*state)

+ float Apply(float measured,

+ PID(const Config \*config,

float input desired, float measured rate, float input desired rate, int rate hz,

+ PID(const Config \*config,

+ float Apply(float measured, float input desired, float measured rate, float input desired rate, int rate hz, ApplyOptions apply options= {}) MOTEUS CCM ATTRIBUTE

ApplyOptions apply options=

{}) MOTEUS CCM ATTRIBUTE