# Pranav Kumar

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# Education

Virginia Tech

Virginia, USA

MS in Computer Engineering

**UIET**, Panjab University

B.E in Electronics and Communication Engineering

3.9/ 4 GPA August 2024 - May 2026 Chandigarh, IN

May 2016 - Sept. 2020

Job / Research Experience

## SSRG Lab @Virginia Tech

Docker, Compilers, LLVM, indirect Call

Graduate Student Researcher

Dec 2024 - Present, VA, USA

- Developing an indirect call mechanism for binary decompilation under Prof. Binoy Ravindran.
- Exploring kernel-level instrumentation and low-level code optimization for enhanced performance.

## ARTPARK @IISc, Bangalore

Emb. Linux, ARM, STM32, BLDC, CAN, ROS

Embedded System Engineer

May 2023 – July 2024, Bangalore, IN

- Designed low-level drivers and communication stacks for quadruped robotics.
- Developed custom firmware for motor controllers (FOC, BLDC), optimizing real-time performance.
- Implemented high-speed CAN protocols for real-time control in embedded Linux systems.

#### Flux Auto Pvt. Ltd.

ARMm7, FreeRTOS, STM32, TI MCUs, CAN

Embedded System Engineer

June 2021 – March 2023, Bangalore, IN

- Built low-level peripheral drivers for autonomous vehicle retrofit kits (tractors, industrial machinery).
- $\bullet \ \ {\rm Designed\ real\text{-}time\ firmware\ for\ multi-node\ CAN\ networks,\ ensuring\ robust\ distributed\ control.}$
- Developed RTOS-based bootloader and system diagnostics for seamless firmware updates.

## Futuristic Labs Pvt. Ltd.

Emb. Linux, RTOS, OpenCV, Docker, MQTT

Embedded Firmware Engineer

Jan. 2020 - May 2021, Hyderabad, IN

- $\bullet$  Created device drivers and firmware abstraction layers for IoT-integrated autonomous systems.
- Developed kernel-space and user-space communication bridges for real-time data exchange.
- Optimized interrupt-driven firmware to enhance system responsiveness and efficiency.

### Technical Skills

Languages: C, C++, Python, C, Linux, LLVM, Compiler

Hardware Protocols: ARM, I2C, SPI, CAN, UART, BeagleBone, Raspberry Pi ESP32

Developer Tools: Git, Docker, MqTT, ROS, FreeRTOS, AUTOSAR

Hardware: STM32H7x, TI, Steppers, BLDC, FOC, Xilinx FPGA Spartan etc.

Familiar: Algorithms, LATEX, Shell

## Long Term Project

## Google Summer Of Code(GSOC)

Device Tree, Kernel Module, PRU, ARMa8, Embedded C

BeagleBoard.Org(Open Source Contributer)

June – Aug. 2019, Chandigarh, IN

• Using BeagleBone and 74hc299 shift Register, provided a reference design for bi-directional commincation for multiple peripherials see Project <u>Page</u> and Beaglebone official blog <u>Page</u>, <u>Playlist</u> and <u>Github Repo</u>.

#### Research Work

• "Autonomous System of Heavy Vehicle Using CAN Networking" <u>Link</u> at **ICDEMI**, Bangalore through Springer - Nov 2024

### Achievements And Awards

- 2019 Robot Operating System Conference ROSCon-19, Macau, China Scholarship Holder.
- 2019 Awardee for excellence in Technology field by Mrs. Kirron Kher (MP, Chandigarh).
- 2019 Got 1st Award at Design and Idea Competition by IIC, Panjab University at Chandigarh.
- 2019 Mentor of winning team at Smart India Hackathon-2019 by Kokuyo Camlin at IIT Hyd.
- 2021-2022 Three times winner of Best Employee per Quarter at Flux Auto.

Note: All the <u>Underline</u> text are Clickable Links.