

# Person Detection in Aerial Images

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## **Abstract:**

To detect human presence in aerial imagery. Variety of applications available, particularly in the area of Search and Rescue Operations(SAR ops)

## **Motivation:**

- India ranks 89th in disaster management according to the World Risk Index (WRI) 2020, even lower than Sri Lanka, Bhutan & Maldives.
- Search and Rescue Missions (SAR) missions in India are generally limited to Coast Guard or military operations only. (ISRO's intervention in SAR missions has been a very recent trend, but mostly in case of high profile military operations like Indo-China border rescue missions etc.)
- Local bodies(say Municipality) which have more statistics and information about the region have very limited resources and/or access to execute SAR missions during calamities or otherwise.
- But all is not gloomy, as the procurement & setup cost of UAVs has significantly decreased.
- However, automation in this domain is more/less not explored(Indian context).
- To start with, I want to detect persons in aerial images in imagery that has been captured during calamity-like scenarios.

## **Datasets Details (HERIDAL DATASET ) [1]**

### **Patch Data**

Positive and Negative Samples

Image Size : 81 \* 81

Channels : 3

+ve Images : ~29,000

-ve Images : ~32,000

Images are taken with a high resolution camera on the DJI Phantom 3, vertically at a 50 m altitude with the selected

### **Actual Data**

Image Size : 4000 \* 3000

Channels : 3

No. of Images : ~1500

Note : The dataset originally contains Train and Test images - But I've merged all of them and made my own splits as the splits they gave were skewed

**Train, Val, Test** - 64%, 18%, 18%

### **Models Used :**

- 1) **Classification** (using Patch Data)
  - a) Machine Learning - **SVM**
  - b) Deep Learning - **Custom Network**
- 2) **Detection** - using Actual Images
  - a) YOLO v5

## Deep Learning Network [3]



Figure 1. Classification network architecture.

### Tweaks to the above model

Changed final Activation fn. To sigmoid instead of softmax

Trainable params: 522,561

Epochs = 20

Batch Size = 32

Loss Fn. = Binary Cross Entropy

Optimizer = Adam

Used Dropout Layer - 0.5

*This network is used for classification of patch data*

## YOLO v5 [2]

Q: **Why this model?**

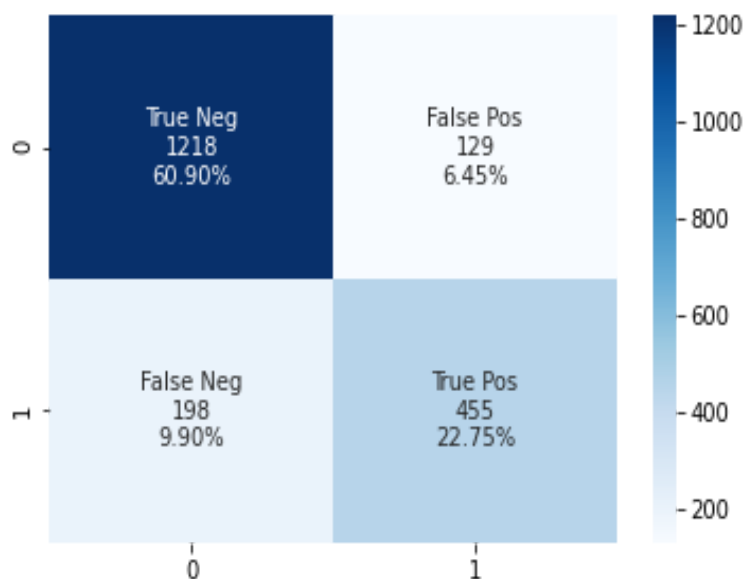
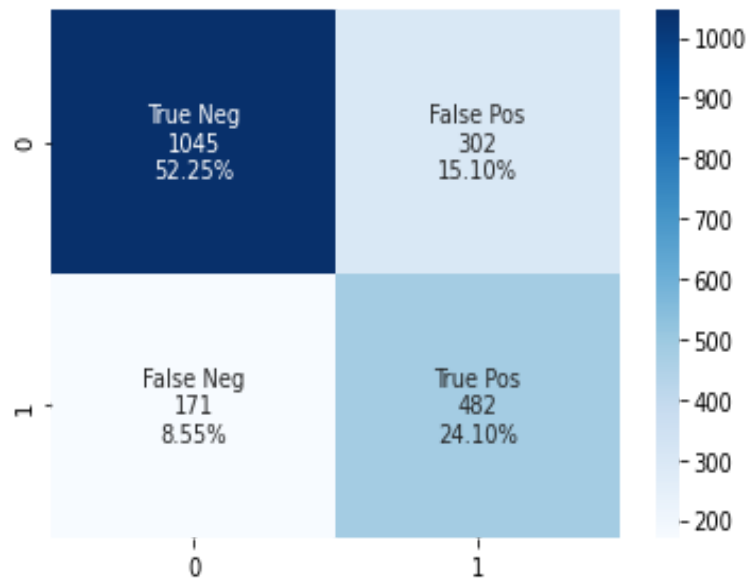
- a) It has a **distributed aspect ratio** which makes it more robust for various aspect ratios
- b) **Automatic new anchors** - The model can generate new anchors if the given anchors < threshold
- c) It uses models like K-Means, Genetic Algorithm to generate anchors
- d) Uses a **Dense Network** with Body, Head and Neck
- e) **Head** captures most of the major features
- f) **Neck** captures the minor features
- g) **Data Augmentation:**
  - h) a) High degree of scaling augmentation
  - i) b) Good Color-Space Augmentation
  - j) Image Size (pixel) is the same as that of the image size - thereby increasing the volume of the batch.
  - k) This increases **variation**
  - l) Overall, this architecture makes the computation(time+memory) very efficient.

## Results (Classification)

|                     | Linear SVM | Polynomial SVM | DL Classifier |
|---------------------|------------|----------------|---------------|
| Training Accuracy   | 100%       | 96.7 %         | 98.769 %      |
| Validation Accuracy | NA         | NA             | 98.86 %       |
| Testing Accuracy    | 76.35 %    | 83.65 %        | 98.86 %       |
| Precision           | 61.5 %     | 77.9 %         | 98.68 %       |
| Recall              | 73.8%      | 69.7 %         | 97.36 %       |

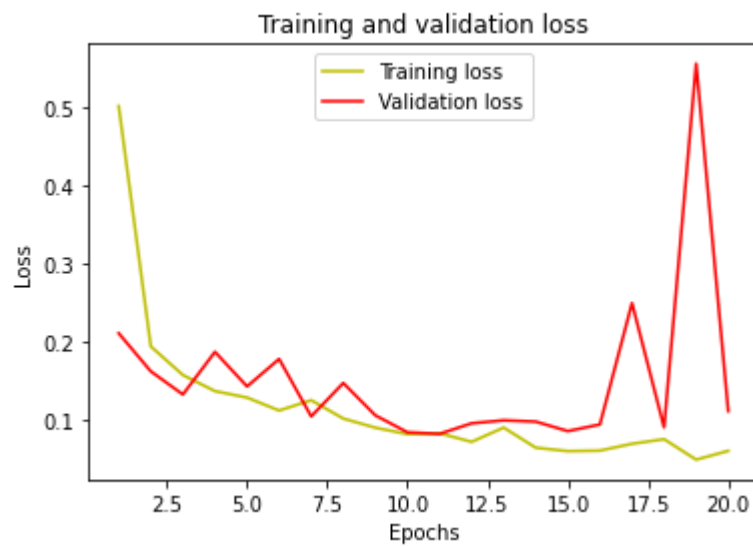
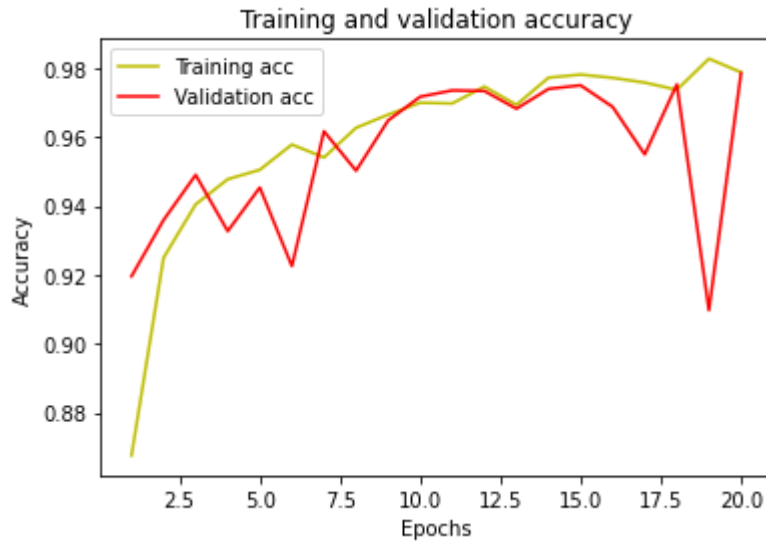
## SVM Confusion Matrices

*Linear SVM*



*Polynomial SVM*

## DL Model's Plots

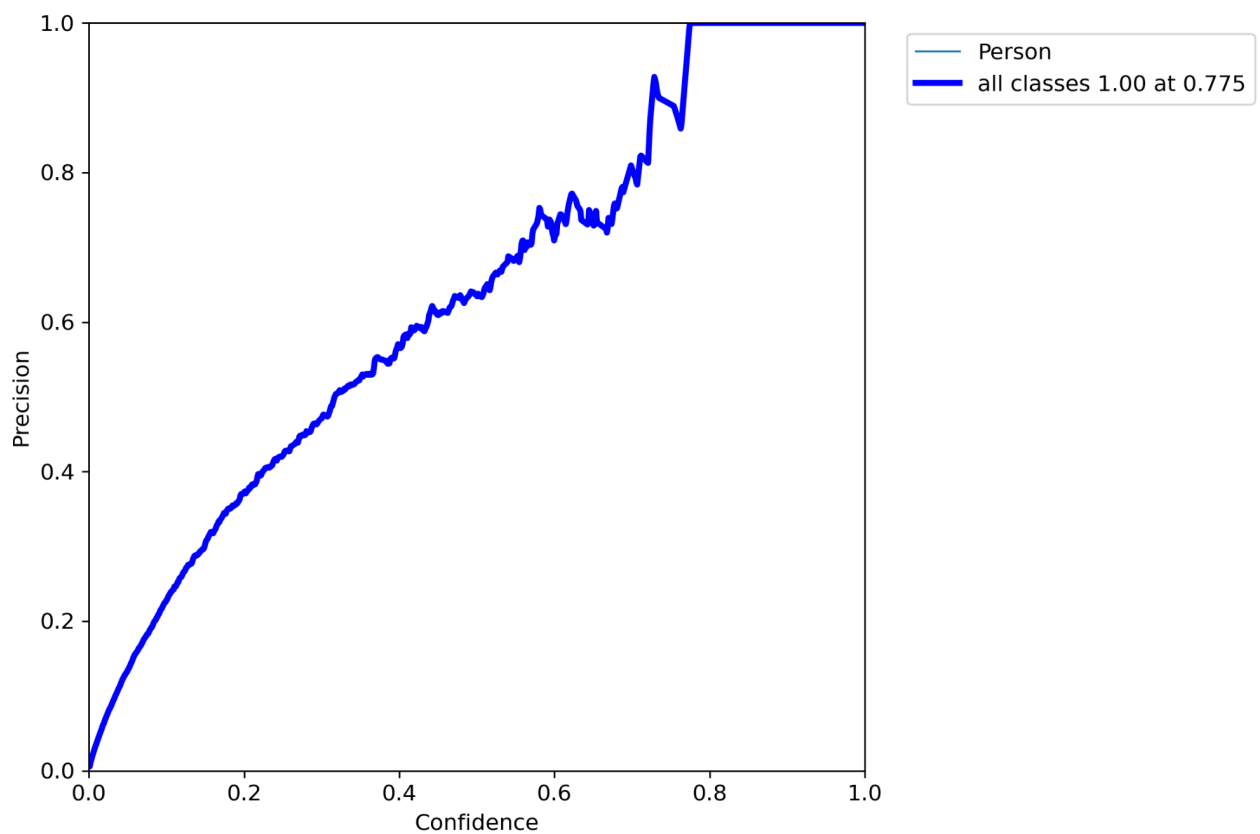
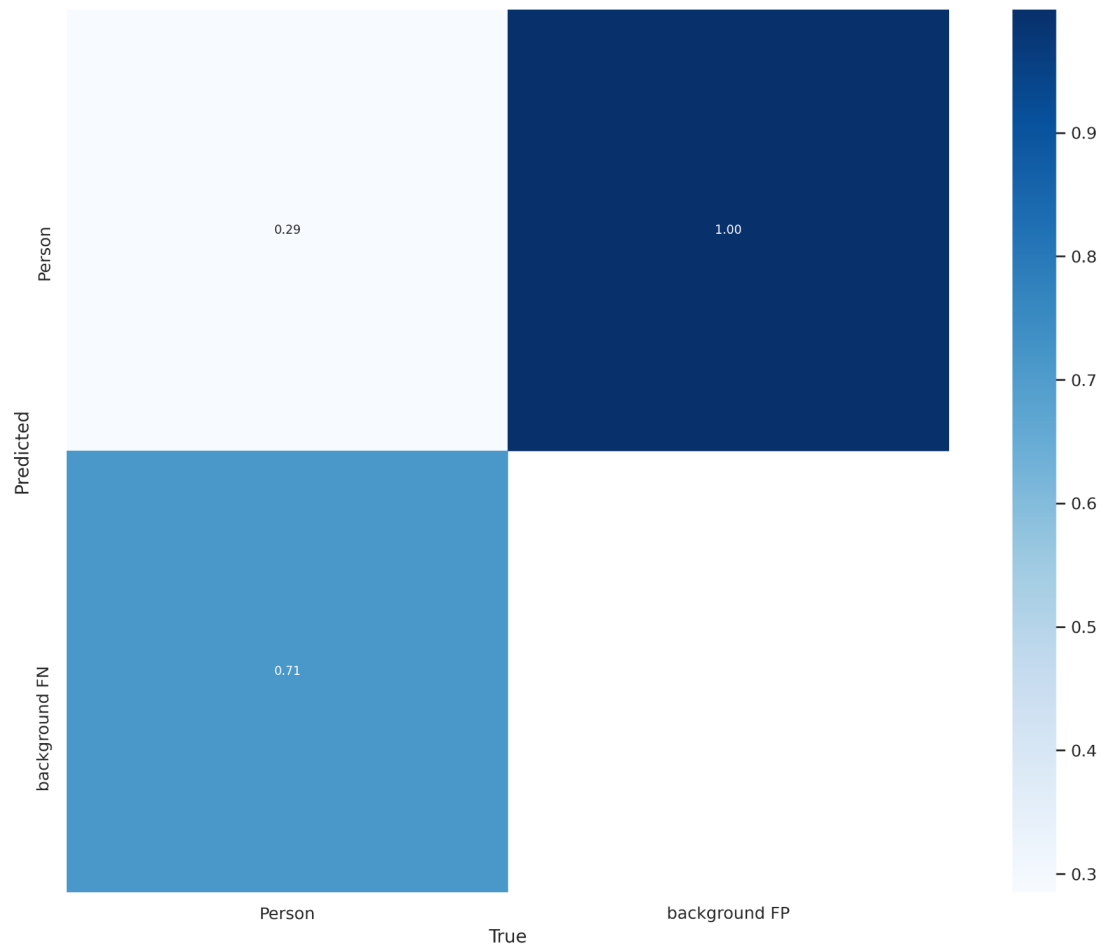


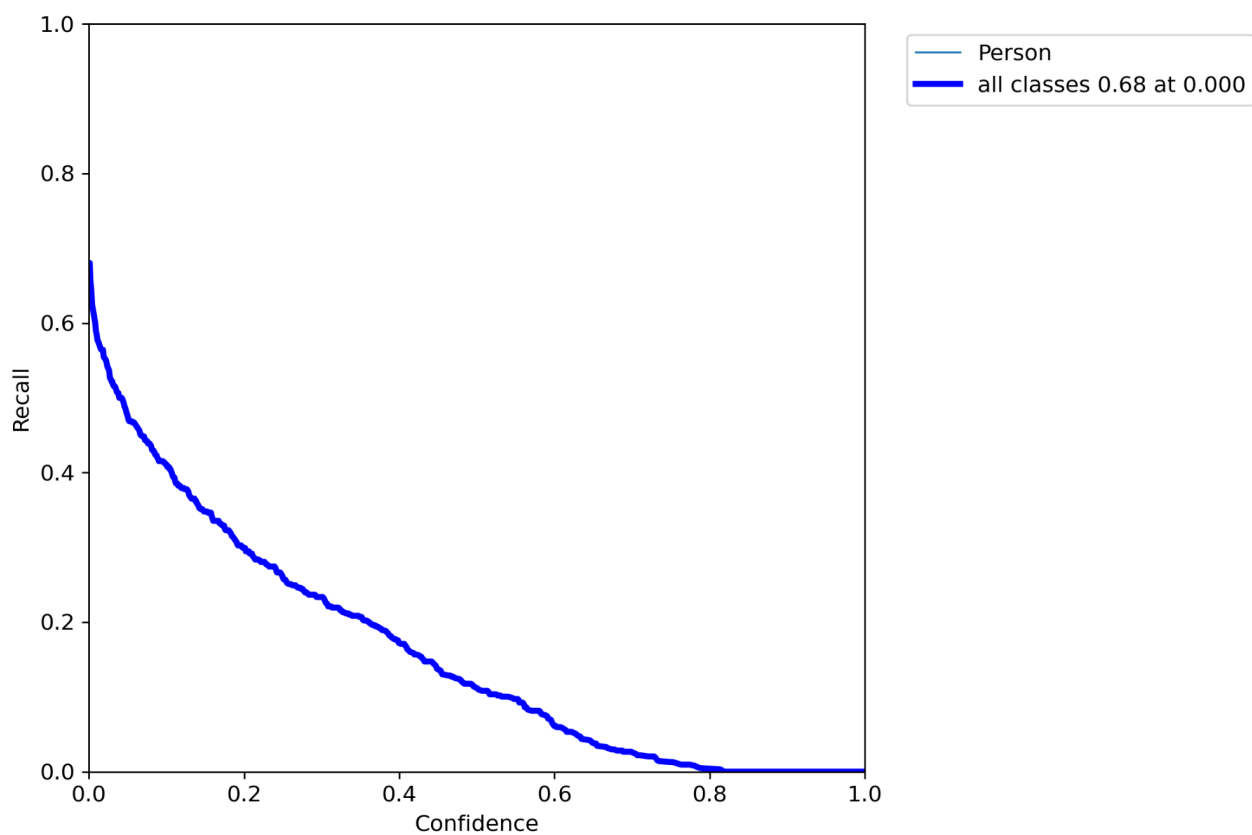
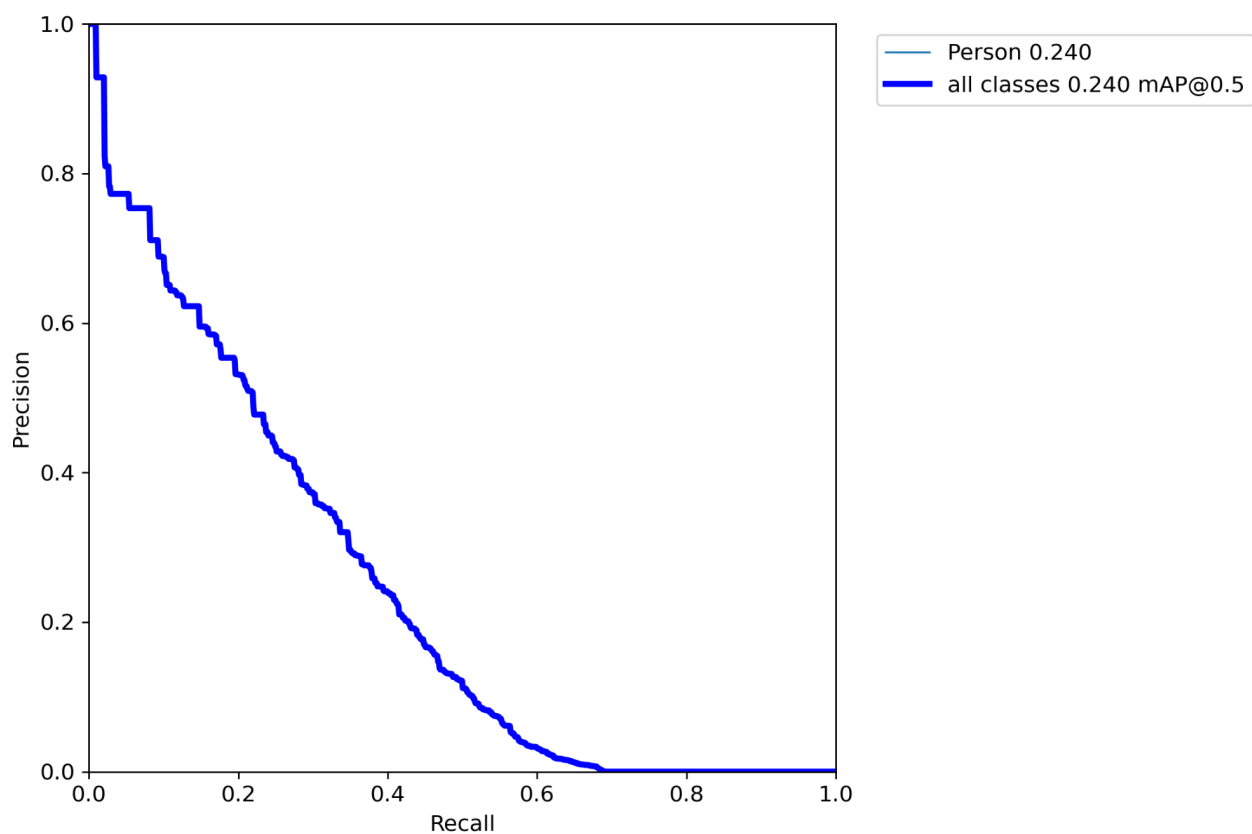
## YOLO v5

### Hyper Parameters for Yolo v5

|               |                 |
|---------------|-----------------|
| Learning Rate | 0.01            |
| No. of Epochs | 200             |
| Batch_Size    | 16              |
| Optimizer     | SGD (+Momentum) |
| Momentum      | 0.937           |
| Weight Decay  | 0.0005          |

## Plots:







## Outputs:



## Conclusion:

Very good performance for the classifier. Objection Detection's performance is performing poorly. Image size (4000,3000) was a huge problem. Dividing the image into blocks of 4-5 and implementing RetinaNET can be a future scope

## References:

- 1) Dunja Božić-Štulić, Željko Marušić, Sven Gotovac: Deep Learning Approach on Aerial Imagery in Supporting Land Search and Rescue Missions, International Journal of Computer Vision, 2019. - [Link](#)
- 2) Official Implementation of YOLO v5 - [Link](#)
- 3) Kundid Vasić, M.; Papić, V. Multimodel Deep Learning for Person Detection in Aerial Images. Electronics 2020, 9, 1459. - [Link](#)