```
{VK} → set of linearly independed readers
      AV_{K} = \lambda_{K}V_{K} \lambda_{1} > \lambda_{2} > \lambda_{3} - \cdots > \lambda_{N}
Any rector by superpolition;
                               Xo = C, V, + C2V2 + C3V3 + .... + CNVN
                          A_{N_0}^{2} = c_1 \lambda_1 V_1 + c_2 \lambda_2 V_2 + \cdots + c_N \lambda_N V_N
A_{N_0}^{2} = c_1 \lambda_1^2 V_1 + c_2 \lambda_2^2 V_2 + \cdots + c_N \lambda_N^2 V_N
                         A^{M}_{\lambda_0} = c_1 \lambda_1 V_1 + c_2 \lambda_2 V_2 + \cdots + c_N \lambda_N V_N
                       \frac{A^{m}\chi_{0}}{\lambda_{i}^{m}} = C_{i}V_{i} + C_{2}\left(\frac{\lambda_{2}}{\lambda_{i}}\right)^{m} + \cdots + C_{N}\left(\frac{\lambda_{m}}{\lambda_{i}}\right)^{N}V_{N}
                     \frac{A^{m} \chi_{0} \cdot y = C_{1} Y_{1} y}{\lambda_{1}^{m+1} \chi_{0} \cdot y} = C_{1} Y_{1} y}
\frac{A^{m+1} \chi_{0} \cdot y}{\lambda_{1}^{m+1}} \cdot y} = C_{1} Y_{1} y}
\frac{A^{m} \chi_{0} \cdot y}{\lambda_{1}^{m+1}} \cdot y} = C_{1} Y_{1} y}
\frac{A^{m} \chi_{0} \cdot y}{\lambda_{1}^{m+1}} \cdot y} = C_{1} Y_{1} y}{\lambda_{1}^{m}} \cdot y}
\frac{A^{m} \chi_{0} \cdot y}{\lambda_{1}^{m}} \cdot y} = C_{1} Y_{1} y}{\lambda_{1}^{m}} \cdot y}
              Works for non-degenerate matrices
               · Convergence depends ~ h2/21 lim 21 > 2
                - sating {Am Xo} -> {a1,2a2 -- . an}x 1
mox {ai}
```

Power Method: Dominant Eigenvalue of a motion.

Method of Defloction: finding the non-dominant eigenvolve

A > (1), Yi) is known by power method

Define  $Y_1 = \frac{Y_1}{\|Y_1\|}$  and construed  $\hat{A} = A - \lambda_1 Y_1 Y_1^T$ 

 $A = \{\lambda_1, \lambda_2, \lambda_3, \dots, \lambda_N\} \qquad \hat{A} = \{0, \lambda_2, \lambda_3, \dots, \lambda_N\}$   $\{\psi_1, \psi_2, \psi_3, \dots, \psi_N\} \qquad \{\psi_1, \hat{\psi}_2, \hat{\psi}_3, \dots, \hat{\psi}_N\}$ 

# ÂY, = AY, - \(\lambda\) \(\text{Y}\) \(\text{TY}\) = 0 \(\text{O'} -> \text{eigenvolume}\)

## ÂYk 2 AYk " (Y, Yk) = O orthsnormal set

## Gram - Schmidt Process

$$A = \begin{bmatrix} a_1 & a_2 & --- & a_N \end{bmatrix}$$

a2-(a2.61)61

$$u_2 = a_2 - (a_2, e_1)e_1$$
  $e_2 = \frac{u_2}{||u_2||}$ 

$$\frac{1}{||\mathbf{u}_{\kappa}||} = \frac{||\mathbf{v}_{\kappa}||}{||\mathbf{v}_{\kappa}||}$$

$$\frac{1}{||\mathbf{v}_{\kappa}||}$$

$$a_1 = (e_1, a_1)e_1$$

$$a_2 = (e_1, a_2) e_1 + (e_2, a_2) e_2$$

$$\dot{\alpha}_{K} = \sum_{j=1}^{K} (e_{j}, \alpha_{K}) e_{j}$$

In matrix form

$$A = Q \cdot R \rightarrow QR$$
 decomposition

	QR Algorithm: Eigenvalues of a months.
	QR factorize: A= A= Q, R, ksteps Ax = QxRx
	Define: $A_2 = R_1 Q_1$ $A_{k+1} = R_k Q_k$
	for K>>1 Ax converges to a triangular matrix diag(Ax) = { \lambda \lam
A	
	$\Rightarrow Q_1^* A_1 Q_1 = Q_1^* Q_1 P_1 Q_1$
	= P(Q)
	$ \begin{array}{ll}                                    $
	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$
	(XK AKKK - AK+1 -> MK, AK+1
A	Proof of Ax convergen to a triangula, martin see notes balow

## Useful Identities

= PKA, PK

AKHI = PWA, PK from (1)  $P_{\kappa}A_{\kappa+1}=A_{1}P_{\kappa}$ - Pr-, Ak = A, Pk-,

```
Proof of convergence of Ax to a triangular matrix=
       \Delta d, A = X \wedge X^{-1} \Lambda = \{\lambda_1, \lambda_2 - \cdots \lambda_n\}
             X = Q_x R_x
                                 Qx - orthogonal Rx - upper tranqular
                                 Ly - lower triangular Ry - upper thangular
             XT = Ly Ry
      P_{x}T_{x} = A^{k} = \chi_{\Lambda}^{k}\chi^{-1}
= Q_{x}R_{x}\Lambda^{k}L_{y}R_{y}
= Q_{x}R_{x}(\Lambda^{k}L_{y}\Lambda^{-k})(\Lambda^{k}R_{y})
                          = QxRx (I+ Ex) 1 Ry From (3)
                          =Qx[I+ Rx Ex Rx] Rx 1 Ry
                           = Qx [I + Gx] Rx 1k Ry
= Qx [I + Ze] [I + Wx] Rx 1k Ry
                                       QR factorization of Gx
     QR factoraction is unique PR = Qx [I+Zx]
limit K > 2 => Ex > 0 => Gx > 0 => Zx > 0 => Px > Qx
    A_{x} = P_{x}^{-1} A P_{x} \longrightarrow Q_{x}^{-1} A Q_{x} = Q_{x}^{-1} X \Lambda X^{-1} Q_{x}
= Q_{x}^{-1} Q_{x} R_{x} \Lambda R_{x}^{-1}
                                          = RXXRx -> upper triangua
     En 1/2 / > I
                                                         1/4 L1-4 = I + EK (3)
```