# **Packaging**

### How to package

First and foremost clone the verilator github repo and compile the program's stable version. Follow the link for instructions.

Once the repo is cloned cd into the repo and set up a virtual environment

```
cd linux_package_management_system # The repo
python3 -m venv env
source env/bin/activate
pip install -r requirements.txt
```

Once the virtual environment is set move into the src folder use cx\_freeze to make our program a stand alone executable.

```
cd src
cxfreeze -c main.py --target-dir=dist
```

Now from the directory where verilator was built, copy the bin and include directories into the dist directory which was created using  $cx_freeze$ .

After copy bin and include into the dist directory compress it using tar

```
tar cJvf program.tar.xz dist
```

Now move back to the root directory of the repo and use the template shell script stored in there to create the required installer

```
cd .. #cd to the repo
cp installer_template_script.sh installer.sh
```

This installer.sh (or installer\_template\_script.sh) has an bash script written in it.

It has a marker called \_\_ARCHIVE\_\_ to which we will soon mark our compressed tar file using cat whose line number from which it is stored would be stored in a variable named ARCHIVE using some awk and using it the actual file would read using tail and piping its output to tar to extract the file into a directory which we mention inside the sh file (Here it is \${HOME}/verilator\_gui)

Now we concatenate the compressed tar.xz file to installer.sh and make it executable. cat src/program.tar.xz >> installer.sh chmod +x installer.sh This is the packaging process of the installer.

```
installer\_template\_script.sh
```

```
#!/bin/bash
echo ""
echo "Verilog GUI Installer"
echo ""
```

```
# Create destination folder
DESTINATION="${HOME}/verilator_gui"
mkdir -p ${DESTINATION}
# Find __ARCHIVE__ maker, read archive content and decompress it
ARCHIVE=$(awk '/^_ARCHIVE__/ {print NR + 1; exit 0; }' "${0}")
tail -n+${ARCHIVE} "${0}" | tar xpJv -C ${DESTINATION}
# Put your logic here (if you need)
chmod +x ${HOME}/verilator_gui/dist/bin/*
export VERILATOR_ROOT=${HOME}/verilator_gui/dist
export PATH=$VERILATOR ROOT/bin:$PATH
echo ""
echo "Installation complete."
echo ""
# Exit from the script with success (0)
exit 0
__ARCHIVE__
```

#### Reason for the packaging approach

After doing some investigation, I discovered that <code>cx\_freeze</code> can create a standalone Python executable. I tested its performance by installing it on an Ubuntu 22.04 and running it on an MX Linux, and I was really pleased with its output.In addition, the produced executable resembled a straight executable and was independent of any distribution. After going through its documentation for some time, I gained enough faith in the <code>cx\_freeze</code>'s cross-platform execution. Then, I desired a unique kind of packaging that was independent of a particular distro. Actually, I was looking for a packaging technique that would allow me to give my final product a <code>.run</code> extension. In , I wasn't sure whether I needed to make separate <code>.deb</code> or <code>.rpm</code> packages in addition to the <code>.run</code>. But fortunately, I stumbled into this website, which I adored, by accident. The link for the website is:

```
https://tinyurl.com/2p9x4djp
```

I was able to create a .sh file using the website's script that contained both the installer script and the whole application in a compressed format.

Once I noticed this was possible I copied the bin and include directory from the verilator build and pasted it in the dist directory which was created by cx freeze on making the python program executable (The executable is located in a directory that we named dist). Then the file was compressed into a tar.xz file

Now I had to edit the installer shell script found in the previously mentioned website. So, I did the following with the file.

- Changed the installation directory to \${HOME}/verilator\_gui
- changed permission for all files inside \${HOME}/verilator\_gui/dist/bin as executable
- Set the path variable for verilator for a proper installation

Now the installer script was only missing the actual software which was in the tar.gz file which is the concatenated to the file via

cat program.tar.gz >> installer.sh

### A note on dependency

Here I have compiled verilator in my computer and is using an OS-distributed Verilator in the program.

While compiling I've used GLIBC\_2.31 which was released in 2020. This enables me to run the program with later versions of GLIBC as well.

## Installation

Download the installer.sh file.

You can do this either by cloning the repo or directly downloading it from Google Drive.

https://drive.google.com/file/d/1HVtLxvJNPOGXQtFQGIPhE60VPPJTsd62/view?usp=share\_link

#### Note

An alternate download link is provided because the installer.sh is somewhat of a big file and GitHub doesn't allow files above 100 MiB

So, the file was uploaded using git-lfs and hence has this bandwidth restriction of 1 GiB. So, once the 1 GiB monthly bandwidth is used, downloading the file would not be possible. This Google Drive link was provided to ensure that the <code>installer.sh</code> file would be accessible even amidst a wear out of the monthly free bandwidth that <code>git-lfs</code> provides.

Once downloaded open a terminal in the directory in which the installer file has been downloaded.

Then:

chmod +x installer.sh
./installer.sh

This will now install the program in a folder named verilator\_gui inside your home directory.

The program is accessible from the dist directory inside the verilator\_gui directory

```
cd ~/verilator_gui/dist
```

One could now simply open up the program by

./main

### **Dependencies**

The software Verilator does comes packaged inside this program and is installed when running the installer.sh.

The stable version inside the Verilator GitHub repo was compiled along with a GLIBC 2.31 so that it would support a wide variety of distros especially the Debian based ones that still hasn't moved on to the later versions such as GLIBC 2.35 or GLIBC 2.34. Additional dependency warnings if any will be displayed in the dialogue box that opens up once the Build button is pressed inside the program.

### Usage

Once properly installed open the program from the directory at which the program was installed.

```
cd ~/verilator_gui/dist
./main
```

Now, the GUI build using PyQt5 will open up.

In the program there will be 3 text fields associated with each, a button as well. Along with the first field is a button with Input written inside it.

Clicking that button will open a dialogue box that helps to pick a verilog file. Along with the second field is a button with Input written inside it.

Clicking that button will open a dialogue box that helps to pick a wrapper file.

Along with the first field is a button with Output written inside it.

Clicking that button will open a dialogue box that helps to pick a directory to where the compiled simulation is to be saved.

Inside the directory mentioned in the Output field there will be a directory named obj\_dir inside which the simulation will be present.

It can be executed as follows:

```
cd <output dir>
obj_dir/Vour
```

Along with this there is a radio button that helps to pick whether to use a C++ execution or a SystemC execution.

The spinbox helps to set the number of cores that will go into the make command for compilation.  $\,$