#### 1

# EE5609: Matrix Theory Assignment-5

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Abstract—This document contains a proof for Affine transformation of a given ellipse equation

Download the python codes from

https://github.com/pranaya14014/EE5609/tree/master/Assignment5/code

and latex-tikz codes from

https://github.com/pranaya14014/EE5609/tree/master/Assignment5

### 1 PROBLEM

Show that, by a change of origin and the directions of the coordinate axes, the equation

$$\mathbf{x}^{T} \begin{pmatrix} 5 & 1 \\ 1 & 5 \end{pmatrix} \mathbf{x} - \begin{pmatrix} 14 & 22 \end{pmatrix} \mathbf{x} + 27 = 0$$
 (1.0.1)

can be transformed to

$$\mathbf{x}^T \begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix} \mathbf{x} = 1 \tag{1.0.2}$$

or

$$\mathbf{x}^T \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix} \mathbf{x} = 1 \tag{1.0.3}$$

## 2 SOLUTION

The general second order equation can be expressed as follows,

$$\mathbf{x}^{\mathbf{T}}\mathbf{V}\mathbf{x} + 2\mathbf{u}^{\mathbf{T}}\mathbf{x} + f = 0 \tag{2.0.1}$$

Comparing (1.0.1) with (2.0.1),

$$\mathbf{V} = \begin{pmatrix} 5 & 1 \\ 1 & 5 \end{pmatrix} \tag{2.0.2}$$

$$\mathbf{u} = \begin{pmatrix} -7 \\ -11 \end{pmatrix} \tag{2.0.3}$$

$$f = 27$$
 (2.0.4)

Let  $\mathbf{c}$  be the change in the origin. The equation (2.0.1) can be modified as

$$(\mathbf{x} + \mathbf{c})^{\mathrm{T}} \mathbf{V} (\mathbf{x} + \mathbf{c}) + 2\mathbf{u}^{\mathrm{T}} (\mathbf{x} + \mathbf{c}) + f = 0$$
 (2.0.5)

Considering (2.0.5)

$$\implies (\mathbf{x} + \mathbf{c})^{\mathrm{T}} \mathbf{V} (\mathbf{x} + \mathbf{c}) \tag{2.0.6}$$

$$\implies \mathbf{x}^{\mathbf{T}}\mathbf{V}\mathbf{x} + \mathbf{c}^{\mathbf{T}}\mathbf{V}\mathbf{x} + \mathbf{x}^{\mathbf{T}}\mathbf{V}\mathbf{c} + \mathbf{c}^{\mathbf{T}}\mathbf{V}\mathbf{c}$$
 (2.0.7)

In the above equation

$$\mathbf{c}^{\mathbf{T}}\mathbf{V}\mathbf{x} = \mathbf{x}^{\mathbf{T}}\mathbf{V}\mathbf{c} \tag{2.0.8}$$

From (2.0.7) and (2.0.8) then (2.0.5) becomes

$$\mathbf{x}^{\mathbf{T}}\mathbf{V}\mathbf{x} + 2\mathbf{c}^{\mathbf{T}}\mathbf{V}\mathbf{x} + \mathbf{c}^{\mathbf{T}}\mathbf{V}\mathbf{c} + 2\mathbf{u}^{\mathbf{T}}\mathbf{x} + 2\mathbf{u}^{\mathbf{T}}\mathbf{c} + f = 0$$
(2.0.9)

Comparing (1.0.2) and (2.0.9)

$$2\mathbf{c}^{\mathrm{T}}\mathbf{V}\mathbf{P}\mathbf{y} + 2\mathbf{u}^{\mathrm{T}}\mathbf{P}\mathbf{y} = 0 \tag{2.0.10}$$

$$\mathbf{c}^{\mathbf{T}}\mathbf{V}\mathbf{P}\mathbf{y} = -\mathbf{u}^{\mathbf{T}}\mathbf{P}\mathbf{y} \tag{2.0.11}$$

$$\mathbf{c} = -\mathbf{V}^{-1}\mathbf{u} \tag{2.0.12}$$

Substituting (2.0.2) and (2.0.3) in (2.0.12)

$$\mathbf{c} = \frac{-1}{24} \begin{pmatrix} 5 & -1 \\ -1 & 5 \end{pmatrix} \begin{pmatrix} -7 \\ -11 \end{pmatrix} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$
 (2.0.13)

Hence (2.0.9) becomes

$$\mathbf{x}^{\mathbf{T}}\mathbf{V}\mathbf{x} + \mathbf{c}^{\mathbf{T}}\mathbf{V}\mathbf{c} + 2\mathbf{u}^{\mathbf{T}}\mathbf{c} + f = 0$$
 (2.0.14)

Substituting (2.0.2), (2.0.3) and (2.0.13) the above equation becomes

$$\mathbf{x}^{\mathsf{T}} \begin{pmatrix} 5 & 1 \\ 1 & 5 \end{pmatrix} \mathbf{x} + \begin{pmatrix} 1 & 2 \end{pmatrix} \begin{pmatrix} 5 & 1 \\ 1 & 5 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + 2 \begin{pmatrix} -7 & -11 \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} + 27 = 0$$
(2.0.15)

$$\mathbf{x}^{\mathrm{T}} \begin{pmatrix} 5 & 1 \\ 1 & 5 \end{pmatrix} \mathbf{x} + 29 - 58 + 27 = 0$$
 (2.0.16)

$$\mathbf{x}^{\mathbf{T}}\mathbf{V}\mathbf{x} - 2 = 0 \tag{2.0.17}$$

With change in the origin to point  $\mathbf{c} = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$  but the Substituting (2.0.25) and (2.0.32) in (2.0.19) V doesn't change.

$$\begin{vmatrix} \mathbf{V} \end{vmatrix} = \begin{vmatrix} 5 & 1 \\ 1 & 5 \end{vmatrix} = 24 \tag{2.0.18}$$

As |V| > 0 it represents a ellipse. Hence V can be written as,

$$\mathbf{V} = \mathbf{P}\mathbf{D}\mathbf{P}^{\mathbf{T}} \tag{2.0.19}$$

The characteristic equation of V is given by

$$|\mathbf{V} - \mathbf{I}\lambda| = 0 \tag{2.0.20}$$

$$\begin{vmatrix} 5 - \lambda & 1 \\ 1 & 5 - \lambda \end{vmatrix} = 0 \tag{2.0.21}$$

$$\implies \lambda^2 - 10\lambda + 24 = 0 \tag{2.0.22}$$

Hence the eigen vales are,

$$\lambda_1 = 4 \tag{2.0.23}$$

$$\lambda_2 = 6 \tag{2.0.24}$$

Hence diagonal vector is given by,

$$\mathbf{D} = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix} = \begin{pmatrix} 4 & 0 \\ 0 & 6 \end{pmatrix} \tag{2.0.25}$$

The eigen vector **p** is given by

$$\mathbf{Vp} = \lambda \mathbf{p} \tag{2.0.26}$$

$$(\mathbf{V} - \lambda \mathbf{I})\mathbf{p} = 0 \tag{2.0.27}$$

For  $\lambda_1 = 4$  the eigenvector is,

$$\mathbf{V} - \lambda_1 \mathbf{I} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \stackrel{R_2 \leftarrow R_2 - R_1}{\longleftrightarrow} \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix} \tag{2.0.28}$$

$$\mathbf{p_1} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{-1}{\sqrt{2}} \end{pmatrix} \qquad (2.0.29)$$

For  $\lambda_1 = 6$  the eigenvector is,

$$\mathbf{V} - \lambda_1 \mathbf{I} = \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} \stackrel{R_2 \leftarrow R_2 + R_1}{\longleftrightarrow} \begin{pmatrix} -1 & 1 \\ 0 & 0 \end{pmatrix} \quad (2.0.30)$$

$$\mathbf{p_1} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix}$$
 (2.0.31)

Hence,

$$\mathbf{P} = \begin{pmatrix} \mathbf{p_1} & \mathbf{p_2} \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{-1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$
 (2.0.32)

$$\mathbf{V} = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{-1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 6 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix}$$
(2.0.33)

Hence substituting (2.0.33) in (2.0.17)

$$\mathbf{x}^{\mathbf{T}} \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{-1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 4 & 0 \\ 0 & 6 \end{pmatrix} \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \end{pmatrix} \mathbf{x} = 2 \qquad (2.0.34)$$

$$\mathbf{y}^{\mathrm{T}} \begin{pmatrix} 4 & 0 \\ 0 & 6 \end{pmatrix} \mathbf{y} = 2 \qquad (2.0.35)$$

$$\mathbf{y}^{\mathrm{T}} \begin{pmatrix} 2 & 0 \\ 0 & 3 \end{pmatrix} \mathbf{y} = 1 \qquad (2.0.36)$$

where y is given by Affine transformation

$$\mathbf{x} = \mathbf{P}\mathbf{y} \tag{2.0.37}$$

$$\mathbf{y} = \mathbf{P}^{\mathbf{T}}\mathbf{x} \tag{2.0.38}$$

The rotation matrix  $\mathbf{P}$  can be given by,

$$\mathbf{P} = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \tag{2.0.39}$$

Comparing (2.0.32) and (2.0.39)

$$\cos \theta = \frac{1}{\sqrt{2}} \tag{2.0.40}$$

$$\theta = \frac{\pi}{4} \tag{2.0.41}$$

But given the direction of coordinate axes changes

$$\theta = \pi + \frac{\pi}{4} \tag{2.0.42}$$

Subtituting (2.0.42) in (2.0.39) we get

$$\mathbf{P} = \begin{pmatrix} \cos\left(\pi + \frac{\pi}{4}\right) & \sin\left(\pi + \frac{\pi}{4}\right) \\ -\sin\left(\pi + \frac{\pi}{4}\right) & \cos\left(\pi + \frac{\pi}{4}\right) \end{pmatrix}$$
 (2.0.43)

$$\mathbf{P} = \begin{pmatrix} \frac{-1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \end{pmatrix} \tag{2.0.44}$$

From (2.0.19) we find the diagonal matrix

$$\mathbf{p_1} = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \end{pmatrix} \quad (2.0.31) \qquad \mathbf{D} = \mathbf{P^T V P} = \begin{pmatrix} \frac{-1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{-1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 5 & 1 \\ 1 & 5 \end{pmatrix} \begin{pmatrix} \frac{-1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \end{pmatrix} \quad (2.0.45)$$

$$\mathbf{D} = \begin{pmatrix} 6 & 0 \\ 0 & 4 \end{pmatrix} \quad (2.0.46)$$

Hence using (2.0.44), (2.0.46) and (2.0.19) in (2.0.17) we get.

$$\mathbf{x}^{\mathbf{T}} \begin{pmatrix} \frac{-1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \end{pmatrix} \begin{pmatrix} 6 & 0 \\ 0 & 4 \end{pmatrix} \begin{pmatrix} \frac{-1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{-1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} \end{pmatrix} \mathbf{x} = 2 \qquad (2.0.47)$$

using (2.0.38) the above equation becomes,

$$\mathbf{y}^{\mathrm{T}} \begin{pmatrix} 6 & 0 \\ 0 & 4 \end{pmatrix} \mathbf{y} = 2 \tag{2.0.48}$$

$$\mathbf{y}^{\mathrm{T}} \begin{pmatrix} 3 & 0 \\ 0 & 2 \end{pmatrix} \mathbf{y} = 1 \tag{2.0.49}$$

Hence from (2.0.36) and (2.0.49) proved that change of origin and the directions of the coordinate axes (1.0.1) can be transformed to (1.0.2) or (1.0.3)

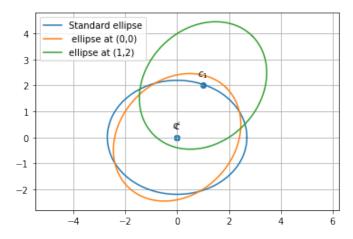


Fig. 0: Ellipse