

# EE5609: Matrix Theory

## Assignment-19

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### Abstract

This document contains a solution for a quadratic form of given matrix.

Download the latex-tikz codes from

<https://github.com/pranaya14014/EE5609/blob/master/Assignment19>

### 1 PROBLEM

Let

$$\mathbf{A} = \begin{pmatrix} 1 & 2 & 0 \\ 0 & 0 & -2 \\ 0 & 0 & 1 \end{pmatrix} \quad (1)$$

and define for  $x, y, z \in \mathbb{R}$

$$\mathbf{Q}(x, y, z) = \begin{pmatrix} x & y & z \end{pmatrix} \mathbf{A} \begin{pmatrix} x \\ y \\ z \end{pmatrix} \quad (2)$$

Which of the following are True?

1. The matrix of second order partial derivatives of the quadratic form of  $\mathbf{Q}$  is  $2\mathbf{A}$ .
2. The rank of the quadratic form of  $\mathbf{Q}$  is 2
3. The signature of the quadratic form  $\mathbf{Q}$  is  $(+, +, 0)$
4. The quadratic form  $\mathbf{Q}$  takes the value 0 for some non-zero vector  $(x, y, z)$

### 2 SOLUTION

Quadratic Form of a matrix	Let $\mathbf{V}$ be a vector space over $\mathbb{R}$ . $\mathbf{A}$ be a symmetric matrix $n \times n$ . Quadratic form on $\mathbf{V}$ is a real function, $(\mathbf{F} : \mathbf{V} \rightarrow \mathbb{R})$ defined as $F(\mathbf{x}) = \mathbf{x}\mathbf{A}\mathbf{x}^T = \sum_{i,j=1}^n a_{ij}x_i x_j$ where $\mathbf{x} \in \mathbf{V}$
Signature of Quadratic form	The signature of quadratic form is $(n_+, n_-, n_0)$ where $n_+$ is the number of positive entries, $n_-$ is number of negative entries and $n_0$ is number of zero's in $a_{ii}$
Rank of quadratic form	Rank of quadratic form is the rank of its matrix which is maximum number of linearly independent rows/columns of a matrix

TABLE 1: Definitions

<b>Option 1</b>	The matrix of second order partial derivatives of the quadratic form of <b>Q</b> is <b>2A</b> .
Solution	$\mathbf{Q}(x, y, z) = \begin{pmatrix} x & y & z \end{pmatrix} \mathbf{A} \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x & y & z \end{pmatrix} \begin{pmatrix} x+2y \\ -2z \\ z \end{pmatrix} = x^2 + z^2 + 2xy - 2yz$ <p>First order partial derivatives: <math>\frac{\partial \mathbf{Q}}{\partial x} = 2x + 2y</math> <math>\frac{\partial \mathbf{Q}}{\partial y} = 2x - 2z</math> <math>\frac{\partial \mathbf{Q}}{\partial z} = 2z - 2y</math></p> <p>Second order partial derivatives of: <math>\frac{\partial^2 \mathbf{Q}}{\partial x^2} = 2</math> <math>\frac{\partial^2 \mathbf{Q}}{\partial y^2} = 0</math> <math>\frac{\partial^2 \mathbf{Q}}{\partial z^2} = 2</math></p> $\frac{\partial^2 \mathbf{Q}}{\partial x \partial y} = \frac{\partial^2 \mathbf{Q}}{\partial y \partial x} = 2 \quad \frac{\partial^2 \mathbf{Q}}{\partial x \partial z} = \frac{\partial^2 \mathbf{Q}}{\partial z \partial x} = 0 \quad \frac{\partial^2 \mathbf{Q}}{\partial y \partial z} = \frac{\partial^2 \mathbf{Q}}{\partial z \partial y} = -2$ <p>Matrix of second order partial derivatives <b>Q</b>: <math>\begin{pmatrix} \frac{\partial^2 \mathbf{Q}}{\partial x^2} &amp; \frac{\partial^2 \mathbf{Q}}{\partial x \partial y} &amp; \frac{\partial^2 \mathbf{Q}}{\partial x \partial z} \\ \frac{\partial^2 \mathbf{Q}}{\partial y \partial x} &amp; \frac{\partial^2 \mathbf{Q}}{\partial y^2} &amp; \frac{\partial^2 \mathbf{Q}}{\partial y \partial z} \\ \frac{\partial^2 \mathbf{Q}}{\partial z \partial x} &amp; \frac{\partial^2 \mathbf{Q}}{\partial z \partial y} &amp; \frac{\partial^2 \mathbf{Q}}{\partial z^2} \end{pmatrix} = \begin{pmatrix} 2 &amp; 2 &amp; 0 \\ 2 &amp; 0 &amp; -2 \\ 0 &amp; -2 &amp; 2 \end{pmatrix} \neq 2\mathbf{A}</math></p> <p>Hence, <b>Option 1</b> is not correct.</p>

TABLE 2: Solution for Option 1

<b>Option 2</b>	The rank of the quadratic form of <b>Q</b> is 2
Solution	<p>From above we have quadratic form of <b>Q</b> = <math>\begin{pmatrix} 2 &amp; 2 &amp; 0 \\ 2 &amp; 0 &amp; -2 \\ 0 &amp; -2 &amp; 2 \end{pmatrix}</math></p> <p>Echelon form reduction: <math>\begin{pmatrix} 2 &amp; 2 &amp; 0 \\ 2 &amp; 0 &amp; -2 \\ 0 &amp; -2 &amp; 2 \end{pmatrix} \xrightarrow{R_1 = \frac{1}{2}R_1} \begin{pmatrix} 1 &amp; 1 &amp; 0 \\ 2 &amp; 0 &amp; -2 \\ 0 &amp; -2 &amp; 2 \end{pmatrix} \xrightarrow{R_2 \rightarrow R_2 - 2R_1} \begin{pmatrix} 1 &amp; 1 &amp; 0 \\ 0 &amp; -2 &amp; -2 \\ 0 &amp; -2 &amp; 2 \end{pmatrix}</math></p> $\xrightarrow{R_2 \rightarrow \frac{-1}{2}R_2} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & -2 & 2 \end{pmatrix} \xrightarrow{R_3 \rightarrow R_3 + 2R_2} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 4 \end{pmatrix} \xrightarrow{R_3 \rightarrow \frac{1}{4}R_3} \begin{pmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix}$ $\xrightarrow{R_1 \rightarrow R_1 - R_2} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_2 \rightarrow R_2 - R_3} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$ <p>Rank = Number of non-zero rows = 3 <math>\neq</math> 2</p> <p>Hence, <b>Option 2</b> is not correct.</p>

TABLE 3: Solution for Option 2

<b>Option 3</b>	The signature of the quadratic form <b>Q</b> is (+ + 0)
Solution	<p>From above we have quadratic form of <b>Q</b> = <math>\begin{pmatrix} 2 &amp; 2 &amp; 0 \\ 2 &amp; 0 &amp; -2 \\ 0 &amp; -2 &amp; 2 \end{pmatrix}</math></p> <p>Finding eigen values: <math> \mathbf{Q} - \lambda \mathbf{I}  = \begin{vmatrix} 2-\lambda &amp; 2 &amp; 0 \\ 2 &amp; -\lambda &amp; -2 \\ 0 &amp; -2 &amp; 2-\lambda \end{vmatrix}</math></p> $\Rightarrow (2-\lambda)(-2\lambda + \lambda^2 + 4) + 8 = 0$ $\Rightarrow \lambda^3 - 4\lambda^2 - 4\lambda + 16 = 0$ $\lambda_1 = 4 \quad \lambda_2 = 2 \quad \lambda_3 = -2$ <p>Signature = <math>(n_+, n_-, n_0) = (2, 1, 0) \neq (+ + 0)</math></p> <p>Hence, <b>Option 3</b> is not correct.</p>

TABLE 4: Solution for Option 3

<b>Option 4</b>	The quadratic form <b>Q</b> takes the value 0 for some non-zero vector $(x, y, z)$
Solution	<p>From above we have quadratic form of <math>\mathbf{Q} = \begin{pmatrix} 2 &amp; 2 &amp; 0 \\ 2 &amp; 0 &amp; -2 \\ 0 &amp; -2 &amp; 2 \end{pmatrix}</math></p> <p>we can see that few elements are zero even though the vectors are non-zero.</p> <p>Therefore, <b>Option 4</b> is correct.</p>

TABLE 5: Solution for Option 4