High Performance Computing (HPC) MCQs [set-11]

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|--------------|-----------------|------|----|---------|------------|------|--------------|-------|--------|-----------|------|
| <i>2</i> 51 | wnat | 1C 1 | ne | average | riinning | time | \mathbf{o} | annck | SULT 5 | algorithm | 17 |
| 4 J1. | v v mat | 19 (| | avciago | I WIIIIIII | | or a | quick | SOLL | ugumum | .⊥ • |
| | | | | U | U | | | - | | O | |

- A. o(n)
- B. o(n log n)
- C. o(n2)
- D. o(log n)

Answer: B

252. Odd-even transposition sort is a variation of Mate.com

- A. quick sort
- B. shell sort
- C. bubble sort
- D. selection sort

Answer: C

253. What is the average case time complexity of odd-even transposition sort?

- A. o(n log n)
- B. o(n)
- C. o(log n)
- D. o(n2)

Answer: D

254. Shell sort is an improvement on

- A. quick sort
- B. bubble sort
- C. insertion sort
- D. selection sort

Answer: C

255. In parallel Quick Sort Pivot is sent to processes by

- A. broadcast
- B. multicast

| C. selective multic | ast |
|---------------------------|---|
| D. unicast Answer: A | |
| 256. In parallel Q | uick Sort each process divides the unsorted list into |
| A. n lists | |
| B. 2 lists | |
| C. 4 lists | |
| D. n-1 lists Answer: B | |
| 257. Time Compl | exity of DFS is? (V – number of vertices, E – number of edges) |
| A. $o(v + e)$ | |
| B. o(v) | |
| C. o(e) | |
| D. o(v*e) Answer: A | |
| · · | till it finishes from one vertex, backtracks and then explore other vertex. What algorithm he should use? |
| | ray of n elements and p processes, in the message-passing version icksort, each process storeselements of array |
| B. n-p | |
| C. p/n | |
| D. n/p Answer: D | |
| 260. In parallel q | uick sort Pivot selecton strategy is crucial for |
| A. maintaing load | balance |

| B. maintaining uniform distribution of elements in process groups | |
|--|----|
| C. effective pivot selection in next level | |
| D. all of the above | |
| Answer: D | |
| 261. In execution of the hypercube formulation of quicksort for d = 3, split along | |
| dimention to partition sequence into two big blocks, one greater than piv | ot |
| and other smaller than pivot as shown in diagram | |
| A. first | |
| B. scond | |
| C. third | |
| D. none of above | |
| Answer: C | |
| 262. Which Parallel formulation of Quick sort is possible | |
| A. shared-address-space parallel formulation | |
| B. message passing formulation | |
| C. hypercube formulation | |
| D. all of the above | |
| Answer: D | |
| 263. Which formulation of Dijkstra's algorithm exploits more parallelism | |
| A. source-partitioned formulation | |
| B. source-parallel formulation | |
| C. partitioned-parallel formulation | |
| D. all of above | |
| Answer: B | |
| 264. In Dijkstra's all pair shortest path each process compute the single-source | |
| shortest paths for all vertices assigned to it in SOURCE PARTITIONED | |
| FORMULATION | |
| A. true | |
| B. false | |
| Answer: A | |
| 265. A complete graph is a graph in which each pair of vertices is adjacent | |
| A. true | |
| B. false | |
| | |

B. false Answer: A

| 266. The space required to store the adjacency matrix of a graph with n vertices is |
|---|
| A. in order of n |
| B. in order of n log n |
| C. in order of n squared |
| D. in order of n/2 Answer: C |
| 267. Graph can be represented by |
| A. identity matrix |
| B. adjacency matrix |
| C. sprse list |
| D. sparse matrix Answer: B |
| 268. to solve the all-pairs shortest paths problem which algorithm's is/are used a) Floyd's algorithm |
| b) Dijkstra's single-source shortest paths |
| c) Prim's Algorithm |
| d) Kruskal's Algorithm |
| A. a) and c) |
| B. a) and b) |
| C. b) and c) |
| D. c) and d) Answer: B |
| 269. Simple backtracking is a depth-first search method that terminates upon |
| finding the first solution. |
| A. true |
| B. false Answer: A |
| 270. Best-first search (BFS) algorithms can search both graphs and trees. |
| A. true |

| 271. A* algorithm is a | |
|--------------------------------------|---|
| A. bfs algorithm | |
| B. dfs algorithm | |
| C. prim\s algorithm | |
| D. kruskal\s algorithm Answer: A | |
| 272. identify Load-Balancing Schen | ne/s |
| A. asynchronous round robin | |
| B. global round robin | |
| C. random polling | |
| D. all above methods Answer: D | |
| 273. important component of best-f | irst search (BFS) algorithms is |
| A. open list | |
| B. closed list | |
| C. node list | |
| D. mode list Answer: A | |
| 274. A CUDA program is comprised | d of two primary components: a host and |
| a | |
| A. gpu kernel | |
| B. cpu kernel | |
| C. os | |
| D. none of above Answer: A | |
| 275. The kernel code is dentified by | thequalifier with void return type |
| Ahost_ | |
| Bglobal | |
| Cdevice_ | |
| D. void Answer: B | |