

Interaction protocol

For $t = 1, \dots, T$

- learner picks $w_t \in \mathbb{R}^d$, $\|w_t\|_2 = 1$, in randomized fashion
- environment picks $L_t \in \mathbb{R}^{d \times d}$, $\|L_t\|_2 \leq 1$
- learner observes $\text{loss } \langle w_t w_t^\top, L_t \rangle = \text{tr}(w_t w_t^\top L_t)$

Note: - L_t is loss matrix
 - allowed to depend on entire history (except w_t).
 - thus, adaptive adversaries allowed.

Goal: minimize regret,

$$R_T = \max_{u: \|u\|_2=1} \sum_{t=1}^T E[\langle w_t w_t^\top - u u^\top, L_t \rangle] \quad \hookrightarrow \text{over randomization of learner}$$

Algorithm Online mirror descent

Param: $\eta > 0$ (learning rate), $\gamma \in [0, 1]$ (exploration rate)

$$\text{Init: } W_1 = \frac{1}{d} I_d$$

for $t = 1, \dots, T$

$$W_t \stackrel{\text{EVD}}{=} \sum_{i=1}^d \lambda_i u_i u_i^\top$$

$$\underline{\lambda} = (1-\gamma)\underline{\lambda} + \gamma(1/d, \dots, 1/d) \rightarrow \text{controls exploration, exploitation trade-off}$$

$$\tilde{L}_t = \underbrace{\text{sample}(\lambda, \{u_i\}_{i=1}^d)}$$

\hookrightarrow 2 possible sub-routines

$$w_{t+1} = (W_t^{-1} + \eta \tilde{L}_t + \beta I)^{-1} \text{ with } \beta \text{ s.t. } \text{tr}(W_{t+1}) = 1$$

$$W_{t+1} = (W_t^{-1} + \eta \tilde{L}_t + \beta I)^{-1} \text{ with } \beta \text{ s.t. } \text{tr}(W_{t+1}) = 1$$

Note: $W \triangleq (1-\gamma)W_t + \frac{\gamma}{d}I_d$ here

A. Dense Sampling

Sample $(\lambda, \{u_i\}_{i=1}^d)$

$$B \sim \text{bern}(1/2)$$

to est. if $B=1$
diag. elements $I \sim \lambda$, $w_t \leftarrow u_I$

- sample one eigvect s.t $P(I=i) = \lambda_i$
 $E[W_t w_t^T] = E\left[\sum_{i=1}^d \mathbb{1}_{\{I=i\}} u_i u_i^T\right] = \sum_i \lambda_i u_i u_i^T = W$

to estimate off-diag
elements

else $s \in \{-1, 1\}^d$ i.i.d uniformly

$$w_t \leftarrow \sum_i s_i \sqrt{\lambda_i} u_i$$

play w_t , observe $\langle w_t w_t^T, l_t \rangle = l_t$

if $B=1$

$$\tilde{L}_t \leftarrow 2l_t W_t^{-1/2} w_t w_t^T W_t^{-1/2}$$

else

$$\tilde{L}_t \leftarrow l_t (W_t^{-1} w_t w_t^T W_t^{-1} - W_t^{-1})$$

return \tilde{L}_t

$$E[W_t w_t^T] = E_s \left[\sum_{i,j} s_i s_j \sqrt{\lambda_i} u_i u_j^T \right] = \sum_{i,j} s_i s_j \sqrt{\lambda_i} u_i u_j^T = W$$

$$\langle u_i u_i^T, l_t \rangle = \text{tr}(u_i u_i^T l_t) = u_i^T l_t u_i$$

intuitively, observe we can
estimate $\approx u_i^T l_t u_i$

↳ lemma $\rightarrow E[\tilde{L}_t] = L_t$

Bounding regret

$$(R_T = \max_{u: \|u\|_2=1} \sum_{t=1}^T E[\langle w_t w_t^T - uu^T, l_t \rangle])$$

Theorem 3: Let $n < \frac{1}{2d}$, $\gamma = 0$. Then,

$$R_T \leq d \frac{\log T}{n} + n(d+1) \sum_{t=1}^T E[l_t^2] + 2$$

{ not so necessary
for first round
II think }

Corollary: Let $n = \min \left\{ \sqrt{\frac{\log T}{dT}}, \frac{1}{2d} \right\}$, $\gamma = 0$

$$R_T \leq O(d^{3/2} \sqrt{T \log T})$$

T^*

$$R_T \leq O(d^{3/2} \sqrt{T \log T})$$

- if assume that $L_t \succeq 0$, $\min_{\text{null } L_t} \sum_t \text{tr}(u u^\top L_t) \leq \bar{L}_t^*$

then with $\eta = \min \left\{ \sqrt{\frac{\log T}{d \bar{L}_t^*}}, \frac{1}{4d^2} \right\}$

$R_T = O \left(d^{3/2} \sqrt{\bar{L}_t^* \log T} + d^3 \log T \right)$

approx. says if $\forall t, \|L_t\| = O_T(1)$
then it gives better bound

B. Sparse Sampling

sample $(\Sigma, \{u_i\}_{i=1}^d)$

draw $I, J \sim \lambda$

if $I = J$

$$w_t \leftarrow u_I$$

else

$s \in \{-1, 1\}$ uniformly

$$w_t \leftarrow \frac{1}{\sqrt{2}} (u_I + s u_J)$$

play w_t , observe $d_t = \langle w_t w_t^\top, L_t \rangle$

if $I = J$

$$\tilde{L}_t = \frac{d_t}{\lambda_I^2} u_I u_I^\top$$

else

$$\tilde{L}_t = \frac{s d_t}{2 \lambda_I \lambda_J} (u_I u_J^\top + u_J u_I^\top)$$

little more work, but can show

$$E[w_t w_t^\top] = I$$

lemma 2 shows
that $E[\tilde{L}_t] = L_t$

Bounding regret

Thm 6: $\eta \leq 1/2d$, $\gamma = \eta d$.

$$R_T \leq d \frac{\log T}{n} + 2nd + 2 + 8nd \sum E[\|L_t\|_F^2]$$

$$\dots - r \dots r \dots r \quad \text{if } \eta = \min \left\{ \sqrt{\frac{\log T}{nT}}, \frac{1}{2d} \right\}$$

For: let $\frac{1}{T} \sum E[\|L_t\|_F^2] \leq r$. if $\eta = \min \left\{ \sqrt{\frac{\log T}{rT}}, \frac{1}{2d} \right\}$

$$\gamma = nd \text{ . then }$$

$$R_T = O(d \sqrt{rT \log T})$$

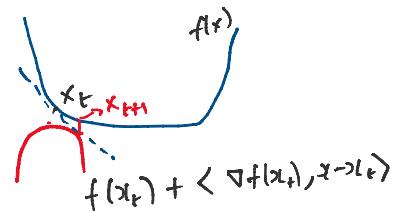
Note: since $\|L_t\|_2 \leq 1$, $\|L_t\|_F \leq \text{rank}(L_t)$

$$\Rightarrow \text{for } L_t = x_t x_t^T \text{ (online PCA) , } R_T \leq O(d \sqrt{T \log T})$$

Understanding the algorithm (Online mirror descent)

(aside) mirror descent ! [from Yuxin's slides]

proximal viewpoint of projected G-D



$$x_{t+1} = \arg \min_{x \in \mathcal{C}} \underbrace{f(x_t) + \langle \nabla f(x_t), x - x_t \rangle}_{\text{linear approx}} + \underbrace{\frac{1}{2\eta_t} \|x - x_t\|_2^2}_{\text{prox}}$$

- the proximal term is based on geometry of problem

- e.g. if \mathcal{C} is probability simplex, better idea to use

- KL divergence, T.V. distance, ...

mirror descent

$$x_{t+1} = \arg \min_{x \in \mathcal{C}} \left\{ f(x_t) + \langle \nabla f(x_t), x - x_t \rangle + \frac{1}{\eta_t} D_\Psi(x, x_t) \right\}$$

Bregman divergence

$$D_\psi(x, y) = \psi(x) - \psi(y) - \langle \nabla \psi(y), x-y \rangle$$

essentially the difference in first order approximation!

- key point: choice of regularization and associated Bregman is crucial

Back to Bandit PCA:

- Consider differentiable, convex $R: S \rightarrow \mathbb{R}$, $S \rightarrow$ dxd symmetric, PSD

- associated $D_R: S \times S \rightarrow \mathbb{R}_+$

$$D_R(W||W') = R(W) - R(W') - \langle \nabla R(W), W-W' \rangle$$

- in Algo 1, initialize $W_1 = \frac{1}{d} I_d$

$$W_{t+1} = \arg \min_{W \in S} \left\{ \eta \langle W, L_t \rangle + D_R(W||W^t) \right\}$$

$W \in S \text{ with } \text{tr}(W) = 1$

- choose $R(W) = -\log \det(W)$

another aside

$$\frac{\partial (-\log \det W)}{\partial W_{ij}} = -\frac{1}{\det(W)} \cdot \frac{\partial \det W}{\partial W_{ij}} = -\frac{1}{\det(W)} \cdot \text{adj}(W)_{ij} = -(W^{-1})_{ij}$$

$$\text{then, } D_R(W||U) = -\log \det(W) + \log \det(U) + \underbrace{\langle U^T, W-U \rangle}_{= \text{tr}(U^T W) - \text{tr}(U)}$$

$$= -\log \det(W) + \log \det(U) + \text{tr}(U^T W) - d$$

$$= \log \det(UW^*) + \text{tr}(U^T W) - d$$

$$= \text{tr}(U^T W) - \log \det(U^T W) - d \quad \square$$

- Alg 1 iterates can be rewritten as

$$\tilde{W}_{t+1} = \arg \min_{W} \left\{ \eta \text{tr}(W \tilde{L}_t) + D_R(W \| W_t) \right\} \quad (\text{update})$$

$$W_{t+1} = \arg \min_{W \in \mathcal{W}} D_R(W \| \tilde{W}_{t+1})$$

- \tilde{W}_{t+1} satisfies [not verified yet]

$$\nabla R(\tilde{W}_{t+1}) = \nabla R(W_t) - \eta \tilde{L}_t$$

$$\Rightarrow \tilde{W}_{t+1}^{-1} = W_t^{-1} + \eta \tilde{L}_t$$

$$\Rightarrow \tilde{W}_{t+1} = (W_t^{-1} + \eta \tilde{L}_t)^{-1} = W_t^{1/2} \left(I + \eta W_t^{1/2} \tilde{L}_t W_t^{1/2} \right)^{-1} W_t^{1/2}$$

Lemma 9: (from an older reference) for any $n > 0$, $y \in [0, 1]$

$$R_T \leq \frac{d \log T}{n} + 2yT + 2 + (1-y) \underbrace{\sum_{t=1}^T \mathbb{E}[\langle W_t - \tilde{W}_{t+1}, \tilde{L}_t \rangle]}_{+1}$$

Let $B_t = W_t^{1/2} \tilde{L}_t W_t^{1/2}$, then

$$\tilde{W}_{t+1} = W_t^{1/2} (I + \eta B_t) W_t^{1/2} = W_t - \eta W_t^{1/2} \underbrace{B_t (I + \eta B_t)^{-1}}_{B_t} W_t^{1/2}$$

$$\begin{aligned} \text{use } (I+A)^{-1} &= I + (I+A)^{-1} - I \\ &= I + (I+A)^{-1} - (I+A)^{-1} (I+A)^{-1} \\ &= I + (I - I - A)(I+A)^{-1} \\ &= I - A(I+A)^{-1} \end{aligned}$$

$$\langle W_t - \tilde{W}_{t+1}, L_t \rangle = \eta \text{tr} \left(W_t^{1/2} B_t (I + \eta B_t)^{-1} W_t^{1/2} \tilde{L}_t \right)$$

$$\begin{aligned}
 & - n \operatorname{tr} (B_t (I + \eta B_t)^{-1} B_t) \\
 & = n \sum_{t=1}^n \frac{b_{ti}^2}{1 + \eta b_{ti}}
 \end{aligned}$$

b_{ti} - eig vals of B_t

- these are bounded separately for dense, sparse cases
- lemma 10 bounds $T\mathbf{1}_t \leq n(d^2 + t) L_t^2$ (dense)
- lemma 11 bounds $T\mathbf{1}_t \leq 8nd \|L_t\|_F^2$ (sparse)

Running time:

<ul style="list-style-type: none"> - Dense - Sparse 	<ul style="list-style-type: none"> - $\tilde{O}(d^3)$ per trial - $\tilde{O}(d)$ per trial
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Possible extensions

- what about non-square loss matrices?
- does looking at $w_t \in \mathbb{R}^{d \times r}$ make sense?
- can we look at sparse PCA?
- some other structure on $w_t / L_t \dots$?
- missing data?? ie if we only see $\operatorname{tr}(w_t w_t^\top P_{\text{sr}}(L_t))$? or other places for $P_{\text{sr}}(\cdot)$ as well
- check contaminated data paper by Nwokoro for "good" models.