

Complex Analysis Using Python

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Contents

1	Introduction	3
2	Introduction to CMath 2.1 Read complex number & apply some CMath functions 2.2 Verifying commutativity & associativity 2.3 Magnitude of complex number 2.4 Phase of a complex number 2.5 Polar coordinates of a complex number 2.5.1 Representing in polar form 2.5.2 Polar coordinates to rectangular coordinates 2.6 Conjugate	3 4 4 5 5 6 6 6
3	Complex expressions equations 3.1 Euler's formula to evaluate e^{x+iy} 3.2 Finding point furthest from origin 3.3 Solving simple complex equations	7 7 7 8
4	Plotting complex numbers roots of unity 4.1 Plotting single complex number	8 9 9 11 13
5	Limits of complex sequences 5.1 Limit of $i\frac{n^2}{n^2+1}$ as n approaches infinity	16 16 17 18 20 20 22
6	Cauchy-Riemann equations6.1 Necessary libraries	23 23 23 24 25
7	Harmonic functions & conjugates 7.1 Harmonic conjugates	25 27
8	Milne-Thompson method	28

	8.1	With user input	29
9	Pow	er series	30
	9.1	Taylor series expansion	30
			31
10	Elen	nentary transformations	32
	10.1	Translation	33
	10.2	Rotation	34
	10.3	Inversion	35
	10.4	Reflection	36
11	Con	formity of transformations	38
	11.1	Introduction	38
		11.1.1 Notes	39
	11.2	Checking if the transformation is analytic	39
			41
			42
			44
		1	46

1 Introduction

In this course, i.e. Complex Analysis using Python programming, we learn to use Python programming concepts and libraries to apply and verify Complex Analysis concepts that we have learnt in our theory classes.

2 Introduction to CMath

AIM: CMath module for dealing with complex numbers.

```
[11]:
               import cmath as cm
               dir(cm)
[11]: ['__doc__',
        '__file__',
        '__loader__',
        '__name__',
        '__package__',
        '__spec__',
        'acos',
        'acosh',
        'asin',
        'asinh',
        'atan',
        'atanh',
        'cos',
        'cosh',
        'e',
        'exp',
        'inf',
        'infj',
        'isclose',
        'isfinite',
        'isinf',
        'isnan',
        'log',
        'log10',
        'nan',
        'nanj',
        'phase',
        'pi',
        'polar',
        'rect',
```

```
'sin',
'sinh',
'sqrt',
'tan',
'tanh',
'tau']
```

Note that the 'a' in acos, asin, atan, etc. means 'arc' i.e. acos is arccosine, asin is arcsine, etc.

2.1 Read complex number & apply some CMath functions

```
[13]: # A valid complex number string must be in the form a+bj
# a and b must be numeric values, and j represents sqrt(-1)
# No spaces must be between the complex number characters
# Spaces may be put before and after the complex number
z = complex(input(">>> "))

>> 3+8j

[29]: print("Sine:", cm.sin(z))
    print("Cosine:", cm.cos(z))
    print("Square root: ", cm.sqrt(z))

Sine: (210.3364312489715-1475.5628538734973j)
    Cosine: (-1475.5631859789817-210.33638390848276j)
    Square root: (2.402499089002692+1.6649329934441104j)
```

2.2 Verifying commutativity & associativity

(of addition and multiplication of complex numbers)

```
[34]: print("Input three complex numbers:")
   z1 = complex(input(">> "))
   z2 = complex(input(">> "))
   z3 = complex(input(">> "))

Input three complex numbers:
   >> 3-7j
   >> 2-9j
   >> 3+6j

[35]: print("Commutative w.r.t. addition?", z1+z2 == z2+z1)
   print("Commutative w.r.t. multiplication?", z1*z2 == z2*z1)
```

```
Commutative w.r.t. addition? True

Commutative w.r.t. multiplication? True

[38]: print("Associative w.r.t. addition?", z1+(z2+z3) == (z1+z2)+z3)

print("Associative w.r.t. multiplication?", z1*(z2*z3) == (z1*z2)*z3)

Associative w.r.t. addition? True

Associative w.r.t. multiplication? True
```

2.3 Magnitude of complex number

```
[27]: z = complex(4, -8)
    print("Complex number:", z)
#-----
print("Magnitude (using 'abs' function):", abs(z))
from math import sqrt
print("Magnitude (using formula):", sqrt(z.real**2 + z.imag**2))
```

Complex number: (4-8j)
Magnitude (using 'abs' function): 8.94427190999916
Magnitude (using formula): 8.94427190999916

2.4 Phase of a complex number

Phase of a complex number is simply the argument of the complex number, i.e. the angle between the vector representing the complex number in the complex plane and the real number axis in the same plane. For a complex number x + iy, the phase i.e. argument is given by $tan^{-1}(\frac{y}{x})$ i.e. $tan^{-1}(\frac{im(z)}{re(z)})$.

```
[28]: z = complex(3, 4)
print("Complex number:", z)
#-----
print("Phase (using 'phase' function):", cm.phase(z))
from numpy import arctan
# (Using purely numeric arctan function for demo purposes, though CMathuralso offerns arctan).
print("Phase (using arctan(im(z)/re(z))):", arctan(z.imag/z.real))
```

```
Complex number: (3+4j)
Phase (using 'phase' function): 0.9272952180016122
Phase (using arctan(im(z)/re(z))): 0.9272952180016122
```

2.5 Polar coordinates of a complex number

2.5.1 Representing in polar form

Polar coordinates represent a complex number using the complex number's magnitude and argument (i.e. phase). For a complex number z, if the magnitude is r and the argument is θ , then the polar coordinates of z are (r, θ) .

2.5.2 Polar coordinates to rectangular coordinates

For a complex number z = x + iy, its rectangular coordinates are (x, y). Rectangular coordinates are simply the Cartesian representation of the complex number, by giving the real and imaginary parts as the x and y coordinates respectively.

```
[47]: p = (2, 4)
# For this complex number, magnitude is 2 and argument is 4.
print("Complex number (polar coordinates):", z)
#-----
print("Rectangular coordinates (using 'rect'):", cm.rect(p[0], p[1]))

Complex number (polar coordinates): (1+7j)
Rectangular coordinates (using 'rect'):
(-1.3072872417272239-1.5136049906158564j)
```

2.6 Conjugate

Conjugate of a complex number can be found by simply inverting the sign of the imaginary part. In Python, we have an in-built attribute method for complex numbers '.conjugate()' that evaluates the conjugate of a given complex number.

```
[1]: z = complex(1, 7)
print("Complex number:", z)
```

```
print("Conjugate:", z.conjugate())

Complex number: (1+7j)
Conjugate: (1-7j)
```

3 Complex expressions equations

AIM: Learning to work with and evaluate complex expressions and equations.

3.1 Euler's formula to evaluate e^{x+iy}

Euler's formula states that $e^{iy} = cos(y) + isin(y)$ Hence, by Euler's formula $e^{x+iy} = e^x e^{iy} = e^x (cos(y) + isin(y))$.

```
e^z (using inbuilt CMath function): (-22.72084741761923-49.64595733458056j)
e^z (Euler's formula): (-22.72084741761923-49.64595733458056j)
```

3.2 Finding point furthest from origin

print("e^z (Euler's formula):", eulersFormula(z))

The magnitude of a complex number gives its distance from the origin. Hence, to see which point is furthest from the origin, we must see which point has the greatest magnitude.

QUESTION: Out of the three points, $z_1 = 2.5 + 1.9j$, $z_2 = 1.5 - 2.9j$ and $z_3 = -2 + 2.2j$, find the point which is farthest away from the origin

```
[24]: complexNumbers = [complex(2.5, 1.9), # z1
complex(1.5, 2.9), # z2
complex(-2, 2.2)] # z3
```

```
[42]: # METHOD 1
# Finding complex number with largest magnitude
zmax = complexNumbers[0]
for z in complexNumbers:
    if abs(z) > abs(zmax):
        zmax = z
print("Complex number with most distance from origin:", zmax)
```

Complex number with most distance from origin: (1.5+2.9j)

```
[47]: # METHOD 2
# List of magnitudes
magnitudes = list(map(abs, complexNumbers))
zmax = complexNumbers[magnitudes.index(max(magnitudes))]
print("Complex number with most distance from origin:", zmax)
```

Complex number with most distance from origin: (1.5+2.9j)

3.3 Solving simple complex equations

```
If a + ib = \frac{3-i}{2+3i} + \frac{2-2i}{1-5i}, find a and b.
```

```
[49]: # First, we must compute the complex expression.

# Here, a is the real part and b is the imaginary part of this complex

□ expression.

complexExpression = complex(3, 1) / complex(2, 3) + complex(2, -2) /

□ complex(1, -5)

print("a =", complexExpression.real)

print("b =", complexExpression.imag)
```

```
a = 1.153846153846154

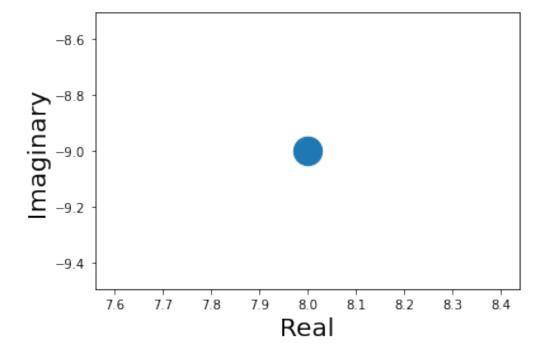
b = -0.23076923076923084
```

4 Plotting complex numbers roots of unity

AIM: Learning to plot complex numbers and functions, as well as finding and plotting the nth roots of unity.

```
[1]: import cmath import matplotlib.pyplot as plt
```

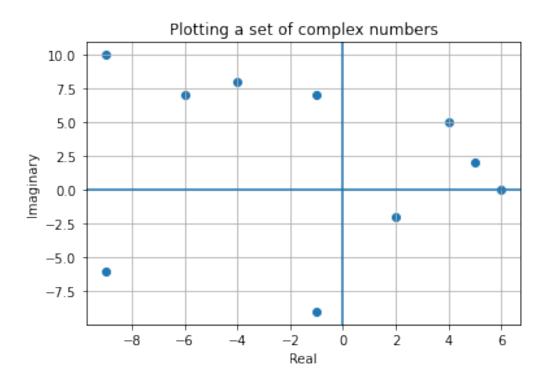
4.1 Plotting single complex number



4.2 Plotting a set of complex numbers

```
[3]: # Generating a random set of ten complex numbers
from random import randint
Z = []
for i in range(0, 10):
    Z.append(complex(randint(-10, 10), randint(-10, 10)))
# Printing the list of complex numbers
```

```
print(Z)
    [(-9+10j), (6+0j), (-4+8j), (-6+7j), (-1+7j), (-1-9j), (-9-6j), (4+5j),
     \hookrightarrow (5+2j),
    (2-2j)]
[4]: # Functions to return the real and imaginary parts of a complex number
     # (Functions are created to use in the 'map' function)
     def real(z): return z.real
     def imag(z): return z.imag
     \# Creating x and y values
     re = list(map(real, Z))
     im = list(map(imag, Z))
     # Plotting the complex numbers
     plt.scatter(re, im, marker = 'o')
     plt.title("Plotting a set of complex numbers")
     plt.xlabel("Real")
     plt.ylabel("Imaginary")
     # To show grid and axes
     plt.plot(0, 0)
     plt.grid()
     plt.axvline()
     plt.axhline()
     # Displaying the plot alone
     plt.show()
```



4.3 Plotting cube roots of unity

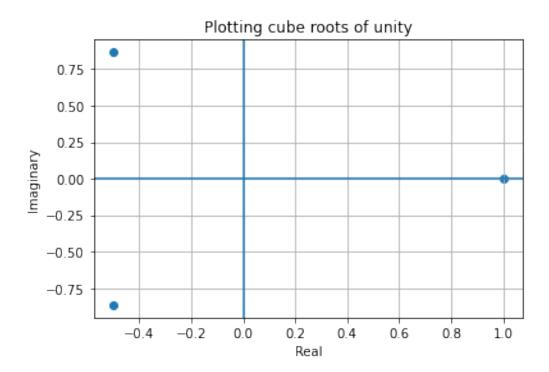
Cube roots of unity are the solutions of the equation $a^3 = 1$. We will find these solutions using SymPy, then use these solutions to plot points on the complex plane.

```
[7]: # FINDING CUBE ROOTS OF UNITY
#------
# Obtaining cube roots of unity (denoted here as cbou)
import sympy as sp
a = sp.Symbol('a')
equation = sp.Eq(a**3, 1)
cbou = sp.solve(equation, a)

# Printing the cube roots of unity obtained
print("\nObtained cube roots of unity:")
for r in cbou: print(r)

# Converting the list of cube roots of unity to complex numbers
cbou = list(map(complex, cbou))
print("\nCube roots of unity as complex numbers:")
```

```
for r in cbou: print(r)
    Obtained cube roots of unity:
    -1/2 - sqrt(3)*I/2
    -1/2 + sqrt(3)*I/2
    Cube roots of unity as complex numbers:
    (1+0j)
    (-0.5-0.8660254037844386j)
    (-0.5+0.8660254037844386j)
[6]: # PLOTTING THE ROOTS
     #-----
     # Finding the list of real and imaginary parts separately
     def real(z): return z.real
     def imag(z): return z.imag
     re, im = list(map(real, cbou)), list(map(imag, cbou))
     # Plotting the cube roots of unity
     plt.scatter(re, im)
     # Adding additional plot elements
     plt.title("Plotting cube roots of unity")
    plt.xlabel("Real")
    plt.ylabel("Imaginary")
     # To show grid and axes
    plt.grid()
    plt.axvline()
    plt.axhline()
     # Displaying the plot alone
     plt.show()
```



4.4 Plotting nth roots of unity

```
[121]: # FINDING N ROOTS OF UNITY
#-----
# Inputting n
n = abs(int(input("n = ")))

# Obtaining cube roots of unity (denoted here as cbou)
import sympy as sp
a = sp.Symbol('a')
equation = sp.Eq(a**n, 1)
cbou = sp.solve(equation, a)

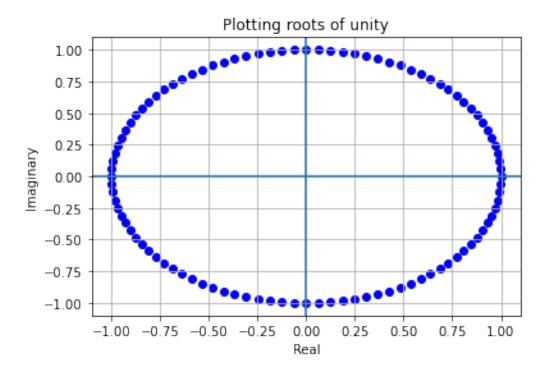
# Converting the list of cube roots of unity to complex numbers
cbou = list(map(complex, cbou))
```

```
n = 100
```

```
# Finding the list of real and imaginary parts separately
def real(z): return z.real
def imag(z): return z.imag
re, im = list(map(real, cbou)), list(map(imag, cbou))

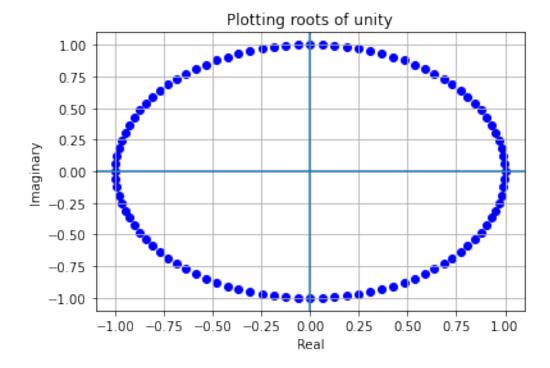
# Plotting the cube roots of unity
plt.scatter(re, im, color = "blue")
plt.title("Plotting roots of unity")
plt.xlabel("Real")
plt.ylabel("Imaginary")

# To show grid and axes
plt.grid()
plt.axvline()
plt.axvline()
# Displaying the plot alone
plt.show()
```



NOTE ON PLOTTING METHOD: You could use the above method, where you gener-

ate the corresponding lists of real and imaginary parts for each root of unity, then plot the lists, Or, you could plot each complex number separately, as shown below. The latter method is notably more time consuming, which becomes apparent for larger values of n.



5 Limits of complex sequences

AIM: Find limit of a complex function / sequence

```
[1]: import cmath as c
import math as m
import sympy as sp
import matplotlib.pyplot as plt
```

Syntax of the limit function in SymPy is **limit(exp, var, c)** where exp is the expression in terms of symbols var is the symbol denoting the variable approaching a constant c is the constant being approached

5.1 Limit of $i \frac{n^2}{n^2+1}$ as n approaches infinity

```
[2]: n = sp.Symbol('n')
im_exp = n**2 / (n**2 + 1)

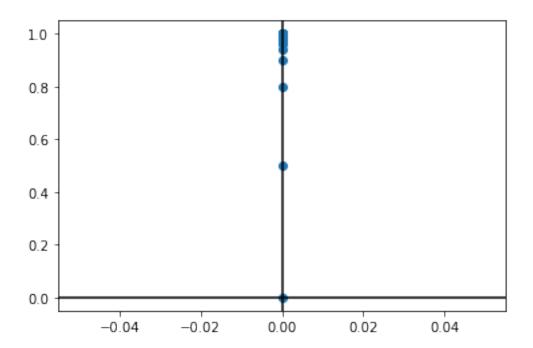
# Since we have only imaginary part, real part is 0
complex(0, sp.limit(im_exp, n, float('inf')))
```

[2]: 1j

5.1.1 Plotting the above function

```
[3]: lower, upper = 0, 100
re, im = [], []
for x in range(lower, upper):
    re.append(0)
    im.append(x**2 / (x**2 + 1))

# Plotting the graph
plt.scatter(re, im)
plt.axvline(color = "black")
plt.axhline(color = "black")
plt.show()
```



5.2 Limit of $(1 + \frac{4}{n})^n + i\frac{7n}{n+4}$ as n approaches infinity

```
[4]: n = sp.Symbol('n')
re_exp = (1 + 4/n)**n
im_exp = 7*n/(n + 4)
inf = float('inf')

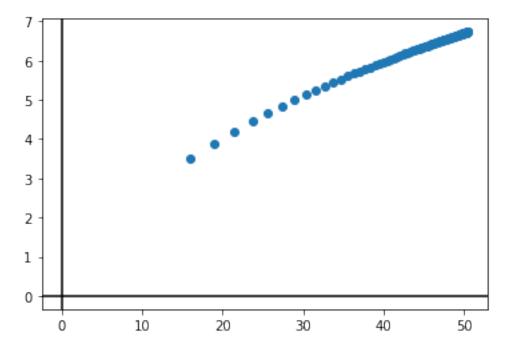
# Since we have only imaginary part, real part is 0
complex(sp.limit(re_exp, n, inf), sp.limit(im_exp, n, inf))
```

[4]: (54.598150033144236+7j)

```
[5]: lower, upper = 4, 100
re, im = [], []
for x in range(lower, upper):
    re.append((1 + 4/x)**x)
    im.append(7*x/(x + 4))

# Plotting the graph
plt.scatter(re, im)
plt.axvline(color = "black")
```

```
plt.axhline(color = "black")
plt.show()
```



5.2.1 Plotting the above using polar plot

```
[6]: # Obtaining polar coordinate expressions
# Modulus
r = sp.sqrt(re_exp**2, im_exp**2)
# Argument
theta = sp.atan(im_exp/re_exp)
```

```
[7]: # Finding limit in polar form

# z = re^(i*theta)

inf = float('inf')

limr = float(sp.limit(r, n, inf))

limtheta = float(sp.limit(theta, n, inf))

print("lim(r): ", limr)

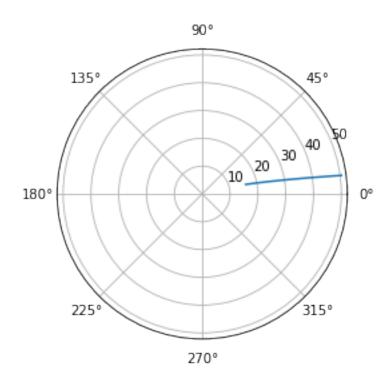
print("lim(theta) (in radians):", limtheta)

print("lim(theta) (in degrees):", 180*limtheta/m.pi)
```

lim(r): 54.598150033144236

plt.show()

```
lim(theta) (in radians): 0.1275138319828531
    lim(theta) (in degrees): 7.306004402157776
[8]: # Obtaining polar coordinates for different values of n
    lower, upper = 4, 100
    rs, thetas = [], []
    for x in range(lower, upper):
        rs.append(eval(str(r.subs({n: x}))))
        thetas.append(eval(str(theta.subs({n: x})), {'atan': m.atan}))
     Here, I have associated the word 'atan' with the atan function from the \sqcup
     \hookrightarrow Math module.
     \hookrightarrow second argument.
     The second argument is a dictionary associating various strings with \Box
     \hookrightarrow their values.
     This is done since atan is not available in default Python.
     NOTE: eval only accepts strings
     11 11 11
     # Plotting the graph
     # Syntax of polar plot: polar(theta, r, etc.)
     plt.polar(thetas, rs)
     # NOTE: thetas i.e. arguments must be given in radians
```



5.3 Limit properties verification

5.3.1 Limit of sum of sequences = Sum of limits of sequences

Confirm for $\frac{1}{n} + i \frac{n-1}{n}$ and $i \frac{n^2}{n^2+1}$

```
[23]: # Sequence 1:
    n = sp.Symbol('n')
    re_exp_1 = 1/n
    im_exp_1 = (n-1)/n

# Sequence 2:
    n = sp.Symbol('n')
    re_exp_2 = 0
    im_exp_2 = (n**2)/(n**2 + 1)

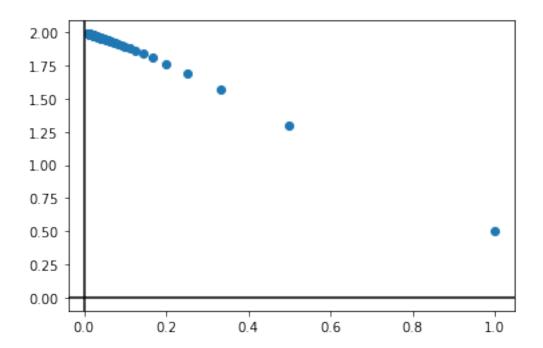
# Sum of sequences:
    re_exp_sum = re_exp_1 + re_exp_2
    im_exp_sum = im_exp_1 + im_exp_2
```

Limit of sum of sequences...

plt.axhline(color = "black")

plt.show()

```
[24]: inf = float('inf')
      re_limit = sp.limit(re_exp_sum, n, inf)
      im_limit = sp.limit(im_exp_sum, n, inf)
     print(complex(re_limit, im_limit))
     2j
     Sum of limits of sequences
[22]: # Limit of sequence 1:
      lim_1 = complex(sp.limit(re_exp_1, n, inf), sp.limit(im_exp_1, n, inf))
      print("Limit of sequence 1: ", lim_1)
      # Limit of sequence 2:
      lim_2 = complex(sp.limit(re_exp_2, n, inf), sp.limit(im_exp_2, n, inf))
      print("Limit of sequence 2: ", lim_2)
      # Sequence 1:
     print("Sum of limits of sequences: ", lim_1 + lim_2)
     Limit of sequence 1: 1j
     Limit of sequence 2: 1j
     Sum of limits of sequences: 2j
     Plotting sum of sequences
[37]: lower, upper = 1, 100
      re, im = [], []
      for x in range(lower, upper):
          re.append(eval(str(re_exp_sum.subs({n: x}))))
          im.append(eval(str(im_exp_sum.subs({n: x}))))
      # Plotting the graph
      plt.scatter(re, im)
      plt.axvline(color = "black")
```



5.3.2 $k \cdot limit of of sequence = limit of k \cdot sequence (k is a constant)$

Confirm for $\frac{1}{n} + i \frac{n-1}{n}$

```
[48]: # Real and imaginary expressions
n = sp.Symbol('n')
re_exp = 1/n
im_exp = (n-1)/n

# Inputting complex constant
k = complex(input("k = "))

# k * limit of sequence
lim_1 = k * complex(sp.limit(re_exp, n, inf), sp.limit(im_exp, n, inf))
print("k • limit of sequence:", lim_1)

# Limit of k • sequence
lim_2 = complex(sp.limit(k*re_exp, n, inf), sp.limit(k*im_exp, n, inf))
print("Limit of k • sequence:", lim_2)
```

k • limit of sequence: 3j

```
Limit of k ● sequence: 3j
```

6 Cauchy-Riemann equations

AIM: Verifying analytic functions using Caucy-Riemann equations

A complex function f(z) = u(x,y) + iv(x,y) (where z = x + iy) is analytic if and only if the following equations are satisfied: $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$ and $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$. These are the Cauchy-Riemann equations.

6.1 Necessary libraries

```
[1]: import sympy as sp
```

6.2 Check if $f(z) = x^2 - y^2 + 2xyi$ is analytic

```
[2]: # Defining variable symbols
x = sp.Symbol('x')
y = sp.Symbol('y')

# Defining u(x, y) (real part) and v(x, y) (imaginary part)
u = x**2 - y**2
v = 2*x*y
```

```
print("Partial derivative of v w.r.t. x:")
print(dv_dx)
print("Partial derivative of v w.r.t. x:")
print(dv_dy)
print("-----")
#------"
# Confirming Cauchy-Riemann equations
print("Cauchy-Riemann equations are satisfied?", end = " ")
print(du_dx == dv_dy and du_dy == -dv_dx)
```

```
[4]: isAnalytic(u, v, x, y)
```

```
Partial derivative of u w.r.t. x:

2*x

Partial derivative of u w.r.t. y:

-2*y

------

Partial derivative of v w.r.t. x:

2*y

Partial derivative of v w.r.t. x:
```

Cauchy-Riemann equations are satisfied? True

Since the Cauchy-Riemann equations are satisfied, we can conclude that f(z) is analytic.

6.3 Check if f(z) = 2xy + 2xi is analytic

```
[5]: # Defining variable symbols
x = sp.Symbol('x')
y = sp.Symbol('y')

# Defining u(x, y) (real part) and v(x, y) (imaginary part)
u = 2*x*y
v = 2*x

# Checking if Cauchy-Riemann equations are satisfied
isAnalytic(u, v, x, y)

Partial derivative of u w.r.t. x:
2*y
Partial derivative of u w.r.t. y:
```

Since the Cauchy-Riemann equations are not satisfied, we can conclude that f(z) is not analytic.

6.4 Check if $f(z) = \frac{x - iy}{x^2 + y^2}$ is analytic

```
[6]: # Defining variable symbols
x = sp.Symbol('x')
y = sp.Symbol('y')

# Defining u(x, y) (real part) and v(x, y) (imaginary part)
u = x/(x**2 + y**2)
v = -y/(x**2 + y**2)

# Checking if Cauchy-Riemann equations are satisfied
isAnalytic(u, v, x, y)
```

Since the Cauchy-Riemann equations are not satisfied, we can conclude that f(z) is not analytic.

7 Harmonic functions & conjugates

A function u(x,y) is said to be harmonic if it satisfies the Laplace equation i.e. $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x^2} = 0$

```
[1]: import sympy as sp
     def isHarmonic(function, variables):
         summation = 0
         print("-----\nFunction:")
         print(f)
         for var in variables:
             # Calculating the partial derivative of order 2
             partialDerivative = function.diff(var, 2)
             print("Partial derivative w.r.t.", var, end = ":\n")
             print(partialDerivative)
             # Adding to the cumulative
             summation = summation + partialDerivative
         # Forcing expression evaluation through 'sp.simplify'
         summation = sp.simplify(summation)
         # Returning a Boolean
         return summation == 0
[2]: x, y, = sp.Symbol('x'), sp.Symbol('y')
     functions = [
         2*x*y,
         sp.log(sp.sqrt(x**2 + y**2)),
         sp.atan(y/x)]
     for f in functions:
         print("Harmonic?", isHarmonic(f, (x, y)))
    Function:
    2*x*y
    Partial derivative w.r.t. x:
    Partial derivative w.r.t. y:
    Harmonic? True
    Function:
    log(sqrt(x**2 + y**2))
    Partial derivative w.r.t. x:
    (-2*x**2/(x**2 + y**2) + 1)/(x**2 + y**2)
    Partial derivative w.r.t. y:
    (-2*y**2/(x**2 + y**2) + 1)/(x**2 + y**2)
    Harmonic? True
```

```
Function:
atan(y/x)
Partial derivative w.r.t. x:
2*y*(1 - y**2/(x**2*(1 + y**2/x**2)))/(x**3*(1 + y**2/x**2))
Partial derivative w.r.t. y:
-2*y/(x**3*(1 + y**2/x**2)**2)
Harmonic? True
```

7.1 Harmonic conjugates

If u(x,y) is a harmonic function, its harmonic conjugate is another harmonic function v(x,y) such that they satisfy the Cauchy-Riemann equations in the following manner: $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$, $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$

```
[14]: | # Redefining the 'isHarmonic' function without the print statements
      def isHarmonic(function, variables):
          summation = 0
          for var in variables:
              # Calculating the partial derivative of order 2
              partialDerivative = function.diff(var, 2)
              # Adding to the cumulative
              summation = summation + partialDerivative
          # Forcing expression evaluation through 'sp.simplify'
          summation = sp.simplify(summation)
          # Returning a Boolean
         return summation == 0
      #==========
      # Finding harmonic conjugate
      def harmonicConjugate(function, variables):
          if not isHarmonic(function, variables):
              return "Given function is not harmonic!"
          # Finding partial derivatives of 'function'
          du_dx = function.diff(x)
          du_dy = function.diff(y)
          # Applying Cauchy-Riemann equations for an unknown function v
          dv_dx = -du_dy
          dv_dy = du_dx
```

```
The above assignment operations are merely done for conceptual \sqcup
        \hookrightarrow clarity.
            They are not practically necessary, and these steps can be reduced.
            # Obtaining and simplifying v
            v = (dv_dx.integrate(x) + dv_dy.integrate(y)) / 2
            The integrals are divided by 2 based on what led to the correct_{\sqcup}
        \rightarrow results.
            The exact reasoning is yet unknown to me.
            v.simplify()
            return v
[15]: x, y, z = sp.Symbol('x'), sp.Symbol('y'), sp.Symbol('z')
       u = sp.log(x**2+y**2)/2
       u
[15]: \log (x^2 + y^2)
[17]: harmonicConjugate(u, (x, y))
[17]: \frac{i \log (x - iy)}{4} - \frac{i \log (x + iy)}{4} - \frac{i \log (-ix + y)}{4} + \frac{i \log (ix + y)}{4}
```

8 Milne-Thompson method

This is a method to find the complex function (in terms of z) whose real or imaginary part is given. If real part u(x,y) is given, we use the equation $f'(z) = \frac{\partial u}{\partial x} - i \frac{\partial u}{\partial y}$. If imaginary part v(x,y), we use the equation $f'(z) = \frac{\partial v}{\partial y} + i \frac{\partial v}{\partial x}$

```
[1]: import sympy as sp
def milne_thompson(function, variables, isReal):
    if isReal: df_dz = sp.diff(function, x) - sp.I*sp.diff(function, y)
    else: df_dz = sp.diff(function, y) + sp.I*sp.diff(function, x)
    # Substituting x = z and y = 0
    df_dz = df_dz.subs({x:z, y:0})
    # Obtaining f(z)
    f = df_dz.integrate(z)
    return f
```

```
[2]: x, y, z = sp.Symbol('x'), sp.Symbol('y'), sp.Symbol('z')
u = sp.log(sp.sqrt(x**2 + y**2))
milne_thompson(u, (x, y), True)
[2]: log(z)
```

8.1 With user input

```
[3]: def milne_thompson_with_input():
         function = input("Enter function:\n")
         isReal = input("For f(z) = u + iv, is the above function u or v? ")
         if isReal == "u": isReal = True
         elif isReal == "v": isReal = False
         else:
             print("Invalid inputs!")
             return
         # Recognising variables...
         variables = []
         for c in function:
             if c.isalpha() and c not in variables: variables.append(sp.
      →Symbol(c))
         # It seems that you can apply SymPy functions on strings as well.
         # (as long as the required symbols are defined)
         # Applying Milne-Thompson method...
         print("The above function in terms of z:")
         print(milne_thompson(function, variables, isReal))
```

```
[4]: milne_thompson_with_input()
```

```
Enter function: x**2-y**2
For f(z) = u + iv, is the above function u or v? u
The above function in terms of z: z**2
```

9 Power series

9.1 Taylor series expansion

The *n*th degree Taylor's series expansion for f(z) is given by $\sum_{0}^{n} \frac{f^{k}(z_{0})(z-z_{0})^{k}}{k!}$, which is an approximation of f(z) around the point $z=z_{0}$.

```
[1]: from sympy import *
     # HELPER FUNCTION
     def expression(expansion):
         expansion = '+'.join(list(map(str, expansion)))
         expansion = sympify(expansion)
         return expansion
     # MAIN FUNCTION
     def taylor(f, z, c, n, returnType):
         z = Symbol(z)
         expansion, prevDiff, factorial = [], f, 1
         # prevDiff contains the previous derivative of f.
         # So, if we are at the kth iteration, prevDiff contains the (k-1)th_{\sqcup}
      \rightarrow derivate of f.
         # This is to reduce computational cost.
         # factorial contains the factorial of the previous k value.
         # This is also to reduce computational cost.
         for i in range(0, n+1):
             tmp = prevDiff.subs({z:c})
             if float(tmp) != 0: expansion.append((tmp*(z-c)**i)/factorial)
             prevDiff = prevDiff.diff()
             factorial = factorial*(i+1)
         # Processing expansion based on return type option
         return {"expression": expression,
                  "list": list,
                  "tuple": tuple}[returnType](expansion)
[2]: taylor(exp('z'), 'z', 0, 5, 'expression')
```

```
[2]: taylor(exp('z'), 'z', 0, 5, 'expression')

[2]: \frac{z^5}{120} + \frac{z^4}{24} + \frac{z^3}{6} + \frac{z^2}{2} + z + 1

[3]: taylor(sin('z'), 'z', pi, 5, 'expression')

[3]:
```

$$-z - \frac{(z-\pi)^5}{120} + \frac{(z-\pi)^3}{6} + \pi$$

9.2 Radius of convergence

An infinite series of the form $S = \sum_{i=0}^{n} a_{i}(z-z_{0})^{k}$ is called a power series centred at z_{0} (centre of the series). The circle $|z-z_0|=r\in R_+$ such that S converges for every set of points within this crcle is called the circle of convergence of the series, and its radius is called the radius of convergence of the series.

For the series $S = \sum_{k=0}^{\infty} a_k (z - z_0)^k$, the radius of convergence R can be evaluated as follows...

- If $\lim_{n\to\infty} \left| \frac{a_{n+1}}{a_n} \right| = L \neq 0$, then $R = \frac{1}{L}$ If $\lim_{n\to\infty} \left| \frac{a_{n+1}}{a_n} \right| = 0 \neq 0$, then $R = \infty$ If $\lim_{n\to\infty} \left| \frac{a_{n+1}}{a_n} \right| = \infty \neq 0$, then R = 0

Alternatively, if $\lim_{n\to\infty} \sqrt[n]{a_n} = L$, then $R = \frac{1}{L}$

```
[28]: # Function to find radius of convergence
      def roc(a_k, method):
          n n n
          a_k is the expression of the kth coefficient of the series.
          Note that it must be defined considering
          k as the iterating variable.
          NOTE: a_k must b given as an expression string.
          method is a number that specifies whether you want the
          program to evaluate the radius of convergence using
          the 1st formula or the 2nd formula
          a_k = sympify(a_k)
          k = Symbol('k')
          # Limit expression: a_k / a_(k-1)
          if method == 1: a = abs(a_k/a_k.subs(\{k:k-1\}))
          # Limit expression: (a_k)^(1/k)
          elif method == 2: a = (a_k)**(1/k)
          # Trying to evaluate limit
          try: L = limit(a, k, float("inf"))
          except: return "Could not calculate!"
```

```
return 1/L

Applying the above function...

[32]: roc("1/(1-2*I)^(k+1)", 1)

[32]: √5

[33]: roc("1/(1-2*I)^(k+1)", 2)

[33]: 'Could not calculate!'

[36]: roc("((6*k+1)/(2*k+5))^k", 1)
```

```
[36]: \frac{1}{3}
[37]: \operatorname{roc}("((6*k+1)/(2*k+5))^k", 2)
```

[37]: 1/3

As we can see, both methods can be used if many cases, though in some cases, using one may lead to a computational error. Hence, in the actual implementation of this radius of convergence finder, we can simply try one method, and if it does not work, try the other...

10 Elementary transformations

```
[1]: from random import randint
  from matplotlib.pyplot import scatter, plot, show, axhline, axvline, axis

[2]: def inputComplex(prompt):
    try: return complex(input(prompt))
    except:
        print("Not a complex number! Defaulting to 0.")
        return complex(0, 0)

def inputReal(prompt):
    try: return float(input(prompt))
    except:
        print("Not a real number! Defaulting to 0.")
        return 0

def graph(z, w):
```

```
scatter([z.real, w.real], [z.imag, w.imag])
    axhline()
    axvline()
    axis('square')
    show()
def graphWithConnection(z, w):
    scatter([z.real, w.real], [z.imag, w.imag])
    plot([z.real, w.real], [z.imag, w.imag])
    axhline()
    axvline()
    axis('square')
    show()
def graphWithOriginVectors(z, w):
    scatter([z.real, w.real], [z.imag, w.imag])
    plot([0, z.real], [0, z.imag], color = "red")
    plot([0, w.real], [0, w.imag], color = "blue")
    axhline()
    axvline()
    axis('square')
    show()
```

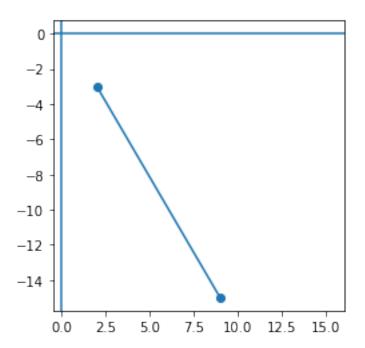
10.1 Translation

```
w = z + k, k \in R
```

```
[3]: def translate(z, k): return z + k
[4]: z1 = inputComplex("Preimage = ")
    k = inputComplex("Translate by: ")
    w1 = translate(z1, k)
    print("Image =", w1)

Preimage = 2-3j
    Translate by: 7-12j
    Image = (9-15j)

[6]: graphWithConnection(z1, w1)
```



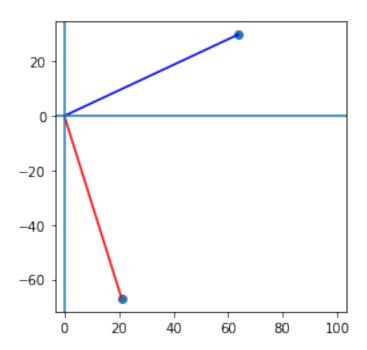
10.2 Rotation

```
[8]: from numpy import e
    def rotate(z, theta): return z*(e**(complex(0, 1)*theta))

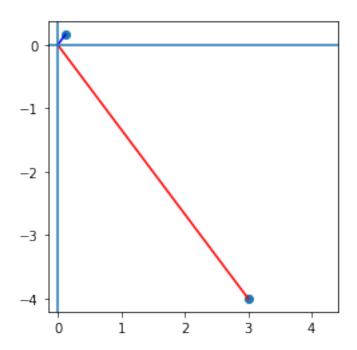
[9]: z2 = inputComplex("Preimage = ")
    k = inputReal("Rotate by: ")
    w2 = rotate(z2, k)
    print("Image =", w2)

Preimage = 21-67j
    Rotate by: 1.705
    Image = (63.58772412718167+29.775851630565278j)

[11]: graphWithOriginVectors(z2, w2)
```



10.3 Inversion



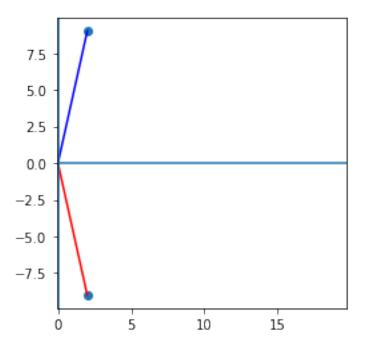
10.4 Reflection

```
[7]: def reflect(z, option):
    """
    option = "re" => reflect along the real axis
    option = "im" => reflect along the imaginary axis
    """
    try:
        return {
        "im": z.conjugate(),
        "re": complex(-z.real, z.imag)}[option]
        except: return
```

```
[10]: z4 = inputComplex("Preimage = ")
  option = input("Option = ")
  w4 = reflect(z4, option)
  print("Image =", w4)
```

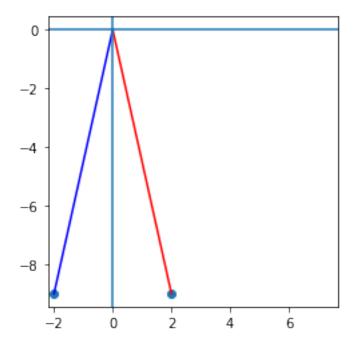
```
Preimage = 2-9j
Option = im
Image = (2+9j)
```

[13]: graphWithOriginVectors(z4, w4)



```
[14]: z4 = inputComplex("Preimage = ")
    option = input("Option = ")
    w4 = reflect(z4, option)
    print("Image =", w4)

Preimage = 2-9j
    Option = re
    Image = (-2-9j)
[15]: graphWithOriginVectors(z4, w4)
```



11 Conformity of transformations

11.1 Introduction

A transformation is said to be conformal if it preserves the orientation and magnitude of the angle of intersubsection between any two curves. In other words, consider curves c_1 and c_2 that are transformed to c_1' and c_2' respectively, under some transformation w = f(z). Then, this transformation is conformal if and only if the angle of intersubsection at a certain direction between c_1 and c_2 is the same as the angle of intersubsection at the same direction between c_1' and c_2' .

According to a result, at each point where the function f(z) is analytic and $f'(z) \neq 0$, the mapping between z and f(z) is conformal. Using this result, we will check if a given transformation is conformal within a certain range. Note that to test if a function f is analytic for a given point z = x + iy, $x, y \in R$, then $\frac{\partial u}{\partial x} = \frac{\partial v}{\partial y}$ and $\frac{\partial u}{\partial y} = -\frac{\partial v}{\partial x}$ i.e. the Cauchy-Riemann equations are satisfied.

To check if the derivative of a transformation f(z) is ever zero, we can solve for the equation f'(z)=0. If the number of solutions is zero, we will know that the derivative of the transformation is never zero. If the number of solutions is greater than 0, we can return the solutions so that the user can identify at what point(s) is the transformation non-conformal.

11.1.1 Notes

We define the following notations for this file...

- z = x + iy, $x, y \in R$ is a complex number in the domain of the transformation
- w = f(z) = u + iv, $u, v \in R$ is a complex number in the range of the transformation

Note that f(z) is essentially a complex function, and like all complex functions, maps one set of complex numbers to another set of complex numbers.

11.2 Checking if the transformation is analytic

```
[2]: from sympy import Symbol, I, sympify
     def isAnalytic(u, v, val=[]): # u and v are strings of expressions\Box
      \rightarrow containing x and y
         Notes:
         1.
         z = u + iv, where u and v are real valued functions.
         val is a list of two lists.
         The 1st list is the range of the real part.
         The 2nd list is the range of the imaginary part.
         11 11 11
         x, y, pd = Symbol('x'), Symbol('y'), []
         # Obtaining partial derivatives
         pd.append(u.diff(x))
         pd.append(v.diff(y))
         pd.append(u.diff(y))
         pd.append(v.diff(x))
         # If we need to check at given points...
         if len(val) == 2:
             # Setting last index as minimum length of the given sublists
             top = min(len(val[0]), len(val[1]))
             # Iterating through each set of real and imaginary parts given
             for i in range(0, top):
                 re, im = val[0][i], val[1][i]
                 tmp = []
                 for j in range(0, 4):
                     tmp.append(pd[j].subs({x:re, y:im}))
```

```
# If not analytic at even one point, return false
if not (tmp[0]==tmp[1] and tmp[2]==-tmp[3]): return False
return True

# If we need to check in general...
return pd[0]==pd[1] and pd[2]==-pd[3]
```

Testing above function...

```
[3]: print("\nEXAMPLE 1")
     u = sympify("x^2-y^2")
     v = sympify("2*x*y")
     # NOTE: sympify recognizes both '^' and '**' for power operator.
     print("u:", u)
     print("v:", v)
     print("Analytic in general?", isAnalytic(u, v))
     print("Analytic at (3, -3)?", isAnalytic(u, v, [[3], [-3]]))
     print("\nEXAMPLE 2")
     print("(Analytic at a point)")
     u = sympify("x^3")
     v = sympify("y^3")
     print("u:", u)
     print("v:", v)
     print("Analytic in general?", isAnalytic(u, v))
     print("Analytic at (0, 0)?", isAnalytic(u, v, [[0], [0]]))
```

```
EXAMPLE 1
u: x**2 - y**2
v: 2*x*y
Analytic in general? True
Analytic at (3, -3)? True

EXAMPLE 2
(Analytic at a point)
u: x**3
v: y**3
Analytic in general? False
Analytic at (0, 0)? True
```

11.3 Checking the derivative of transformation i.e. f'(z)

To obtain the derivative of the complex function (call it f(z)) using the real part alone, we use the equation $f'(z) = \frac{\partial u}{\partial x} + i \frac{\partial u}{\partial y}$

```
[4]: from sympy import Symbol, I, sympify, solve, Eq
     def derivative(u):
         # u is the real part of a complex function f(z)
         return u.diff(Symbol('x'))-I*u.diff(Symbol('y'))
     def willDerivativeBeNonZero(u, val=[]):
         # u is the real part of a complex function f(z)
         Notes (as before):
         z = u + iv, where u and v are real valued functions.
         2.
         val is a list of two lists.
         The 1st list is the range of the real part.
         The 2nd list is the range of the imaginary part.
         # Defining symbols
         x, y = Symbol('x'), Symbol('y')
         # Obtaining f'(z)
         df_dz = derivative(u)
         # If we need to check at given points...
         if len(val) == 2:
             # Setting last index as minimum length of the given sublists
             top = min(len(val[0]), len(val[1]))
             # Iterating through each set of real and imaginary parts given
             for i in range(0, top):
                 re, im = val[0][i], val[1][i]
                 tmp = df_dz.subs({x:re, y:im})
                 if tmp == 0: return False
             return True
         # If we need to check in general...
         if df_dz == 0: return False
```

```
# Checking if df/dz = 0 has any solutions i.e. if derivative is everu

⇒zero

if len(solve(Eq(df_dz, 0))) == 0: return True

return False
```

Testing the above functions...

```
[5]: derivative(sympify("x**2-y**2"))
[5]: 2x + 2iy
[6]: derivative(sympify("log(sqrt(x**2 + y**2))"))
[6]:
    \frac{x}{x^2+y^2} - \frac{iy}{x^2+y^2}
[7]: print("Will derivative of x**2-y**2 be non-zero...")
     print("For all?")
     print(willDerivativeBeNonZero(sympify("x**2-y**2")))
     print("For the point (0, 3)?")
     print(willDerivativeBeNonZero(sympify("x**2-y**2"), [[0], [3]]))
     print("For the point (0, 0)?")
     print(willDerivativeBeNonZero(sympify("x**2-y**2"), [[0], [0]]))
     print("For both points (0, 1) and (1, -2)?")
     print(willDerivativeBeNonZero(sympify("x**2-y**2"), [[0, 1], [1, -2]]))
    Will derivative of x**2-y**2 be non-zero...
    For all?
    False
    For the point (0, 3)?
    True
    For the point (0, 0)?
    False
    For both points (0, 1) and (1, -2)?
    True
```

11.4 Checking if the transformation is conformal

We could merge the above two functionalities into a single function...

```
[12]: from sympy import Symbol, I, sympify def isConformal(u, v, val=[]): # u and v are strings of expressions

→containing x and y

Notes:
```

```
1.
z = u + iv, where u and v are real valued functions.
2.
val is a list of two lists.
The 1st list is the range of the real part.
The 2nd list is the range of the imaginary part.
x, y, pd = Symbol('x'), Symbol('y'), []
# Obtaining partial derivatives
pd.append(u.diff(x))
pd.append(v.diff(y))
pd.append(u.diff(y))
pd.append(v.diff(x))
# Obtaining complete derivative
df_dz = u.diff(x)-I*u.diff(y)
# If we need to check at given points...
if len(val) == 2:
    # Setting last index as minimum length of the given sublists
    top = min(len(val[0]), len(val[1]))
    # Iterating through each set of real and imaginary parts given
    for i in range(0, top):
        re, im = val[0][i], val[1][i]
        # If f'(z) = 0, transformation f(z) is not conformal
        if df_dz.subs({x:re, y:im}) == 0: return False
        # If f'(z) = -0, checking if analytic
        tmp = []
        for j in range(0, 4):
            tmp append(pd[j] subs({x:re, y:im}))
        # If not analytic at even one point, return false
        if not (tmp[0]==tmp[1] and tmp[2]==-tmp[3]): return False
    return True
# If we need to check in general...
# Handling the obvious cases...
```

```
if df_dz == 0: return False
  if not (pd[0]==pd[1] and pd[2]==-pd[3]): return False
#_______
# Handling the less obvious cases...
# Checking if df/dz = 0 has any solutions i.e. if derivative is ever_
⇒zero
  solutions = solve(Eq(df_dz, 0))
  if len(solutions) == 0: return True
# The solutions for x and y show where the transformation is_
⇒non-conformal
  return solutions
```

Testing the above function...

[13]: $[\{x: -I*y\}]$

Hence, we can see that the transformation is non-conformal when x = -iy. Since x and y are real numbers, this equation can only be true if x = y = 0. Hence, the transformation is non-conformal at (0,0).

11.5 Input functions

```
[14]: from numpy import linspace
      def getBound(prompt, default):
          s, flag = input(prompt).strip(), 0
          # Checking for * in the end
          if s[-1] == "*": s, flag = s[:-1], 1
          try: s = float(s)
          except:
              print("Couldn't convert " + s + " to float.")
              print("Defaulting to " + str(default) + "...\n")
              s = default
          return [s, flag]
      def inputInterval():
          print("(Append * to the bound value to exclude from the interval)")
          flag = 0
          lower = getBound("Lower bound: ", 0)
          upper = getBound("Upper bound: ", 0)
          # If lower bounds exceeds upper bound, switch
```

```
if upper[0] < lower[0]:</pre>
        tmp = upper
        upper = lower
        lower = tmp
    # Obtaining divisions for the interval
    divs = input("Divisions: ")
    try: divs = abs(int(divs))
    except:
        print("Couldn't convert " + divs + " to int.")
        print("Defaulting to 0...")
        divs = 10
    # If inclusive, we get flag = 0,
    # and add 0 to the bound.
    # If exclusive, we get flag = 1,
    # and add (upper[0]-lower[0])/divs to the bound.
    lower[0] = lower[0] + lower[1]*float(upper[0]-lower[0])/divs
    upper[0] = upper[0] + upper[1]*float(upper[0]-lower[0])/divs
    # Obtaining interval
    return linspace(lower[0], upper[0], divs)
def inputComplexFunction():
   try:
        u = sympify(input("Re(f(z)): "))
        v = sympify(input("Im(f(z)): "))
    except:
        print("Invalid expressions!")
        return
    X, Y = [], []
    option = input("Give specifics? (y/n) ")
    if option == "v":
        print("\nInput desired real part range:")
        X = inputInterval()
        print("\nInput desired imaginary part range:")
        Y = inputInterval()
    D = [X, Y]
    if len(X) == 0 \text{ or } len(Y) == 0: D = []
    return [u, v, D]
```

Testing the above functions...

```
[240]: inputComplexFunction()
      Re(f(z)): y*x+23
      Im(f(z)): x-y
      Give specifics? (y/n) n
[240]: [x*y + 23, x - y, [[], []]]
[241]: inputComplexFunction()
      Re(f(z)): 2**x
      Im(f(z)): y*x
      Give specifics? (y/n) n
[241]: [2**x, x*y, [[], []]]
[242]: inputComplexFunction()
      Re(f(z)): x**2
      Im(f(z)): y-x
      Give specifics? (y/n) y
      Input desired real part range:
      (Append * to the bound value to exclude from the interval)
      Lower bound: 1
      Upper bound: 3
      Divisions: 3
      Input desired imaginary part range:
      (Append * to the bound value to exclude from the interval)
      Lower bound: 2*
      Upper bound: 4
      Divisions: 5
[242]: [x**2, -x + y, [array([1., 2., 3.]), array([2.4, 2.8, 3.2, 3.6, 4.])]]
```

11.6 Application

We will use the following functions and their dependencies...

- inputComplexFunction
- isConformal

```
[28]: def checkConformity():
          s = isConformal(*inputComplexFunction())
              print("Inputted mapping is conformal for the given range.")
          else:
              print("Inputted mapping is not conformal for the given range.")
              print("Reasons for non conformity:")
              if s == False:
                  print("- Function is not analytic for the given range.")
              else:
                  print("- Function is non-conformal given following...")
                  print(" ", s)
[23]: checkConformity()
     Re(f(z)): x
     Im(f(z)): y
     Give specifics? (y/n) n
     Inputted mapping is conformal for the given range.
[26]: checkConformity()
     Re(f(z)): x**2
     Im(f(z)): y**3
     Give specifics? (y/n) n
     Inputted mapping is not conformal for the given range.
     Reasons for non conformity:
     - Function is not analytic for the given range.
[29]: checkConformity()
     Re(f(z)): x**2-y**2
     Im(f(z)): 2*x*y
     Give specifics? (y/n) n
     Inputted mapping is not conformal for the given range.
     Reasons for non conformity:
     - Function is non-conformal given following...
       [\{x: -I*y\}]
[30]: checkConformity()
     Re(f(z)): x**2-y**2
     Im(f(z)): 2*x*y
     Give specifics? (y/n) y
```

Input desired real part range:

(Append * to the bound value to exclude from the interval)

Lower bound: -1 Upper bound: 30 Divisions: 500

Input desired imaginary part range:

(Append * to the bound value to exclude from the interval)

Lower bound: 3 Upper bound: 60 Divisions: 500

Inputted mapping is conformal for the given range.