## **Complexity of PR - An Example**

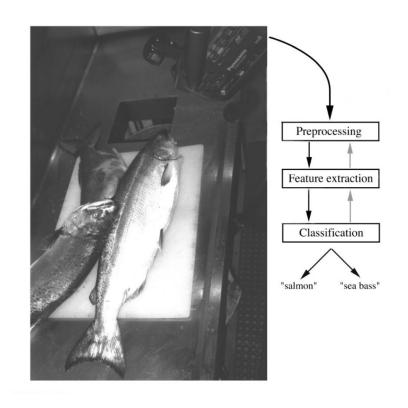
**Problem:** Sorting incoming fish on a conveyor belt.

**Assumption:** Two

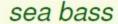
kind of fish:

(1) sea bass

(2) salmon

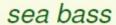


salmon



salmon











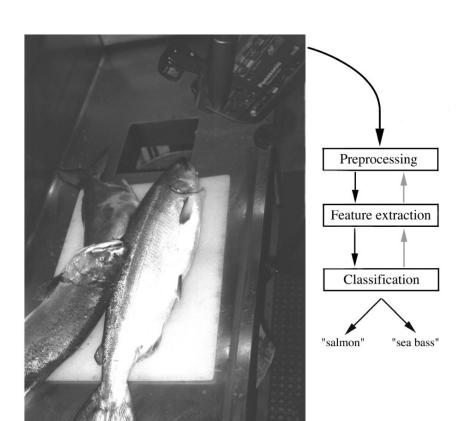








## **Pre-processing Step**



#### **Example**

- (1) Image enhancement
- (2) Separate touching or occluding fish
- (3) Find the boundary of each fish

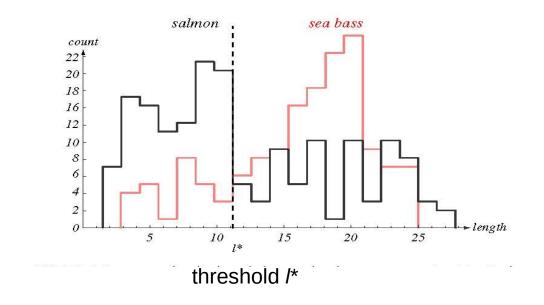
#### **Feature Extraction**

 Assume a fisherman told us that a sea bass is generally longer than a salmon.

 We can use length as a feature and decide between sea bass and salmon according to a threshold on length.

How should we choose the threshold?

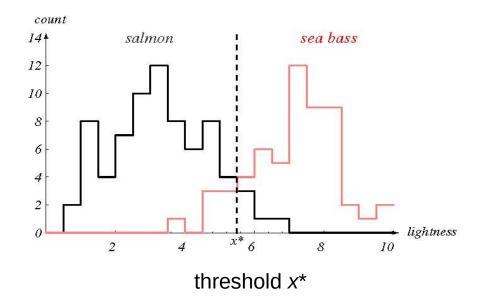
# "Length" Histograms



 Even though sea bass is longer than salmon on the average, there are many examples of fish where this observation does not hold.

# "Average Lightness" Histograms

 Consider a different feature such as "average lightness"



 It seems easier to choose the threshold X\* but we still cannot make a perfect decision.

## **Multiple Features**

- To improve recognition accuracy, we might have to use more than one features at a time.
  - Single features might not yield the best performance.
  - Using combinations of features might yield better performance.

 $\begin{bmatrix} X_1 \\ X_2 \end{bmatrix}$  •  $x_1$ : length •  $x_2$ : lightness

How many features should we choose?

#### **How Many Features?**

- Does adding more features always improve performance?
  - It might be difficult and computationally expensive to extract certain features.
  - Correlated features might not improve performance.
  - "Curse" of dimensionality.

#### **Feature Extraction**

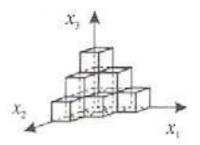
- How to choose a good set of features?
  - Discriminative features



- Invariant features (e.g., translation, rotation and scale)
- Are there ways to automatically learn which features are best?

#### **Curse of Dimensionality**

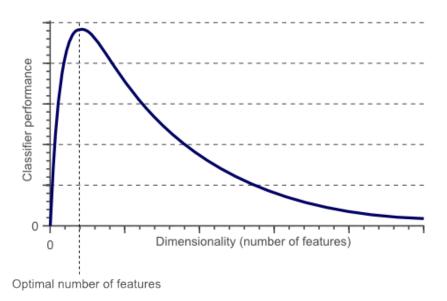
- Adding too many features can, paradoxically, lead to a worsening of performance.
  - Divide each of the input features into a number of intervals, so that the value of a feature can be specified approximately by saying in which interval it lies.



- If each input feature is divided into M divisions, then the total number of cells is M<sup>d</sup> (d: # of features).
- Since each cell must contain at least one point, the number of training data grows exponentially with d.

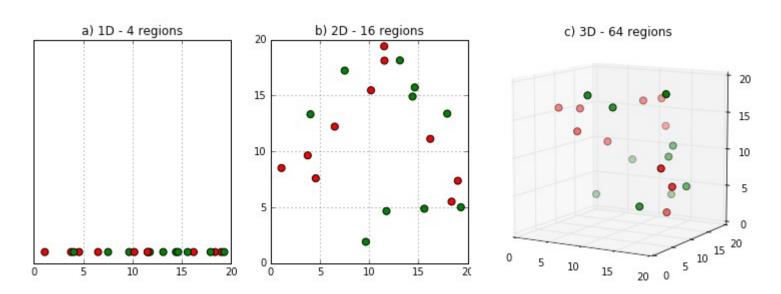
# Curse of Dimensionalitydefinition

- As the number of features or dimensions grows, the amount of data we need to generalize accurately grows exponentially."
- In applied maths, COD refers to the problem caused by the exponential increase in volume associated with adding extra dimensions to a mathematical space.



# **Curse of Dimensionality-(contd)**

• Fig. 1 (a) shows 10 data points in one dimension i.e. there is only one feature in the data set. It can be easily represented on a line with only 10 values, x=1, 2, 3... 10.



# **Curse of Dimensionality-(contd)**

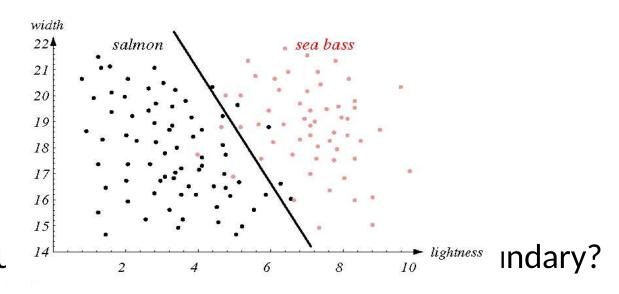
- But if we add one more feature, same data will be represented in 2 dimensions (Fig.1 (b)) causing increase in dimension space to 10\*10 = 100.
- And again if we add 3rd feature, dimension space will increase to 10\*10\*10 = 1000. As dimensions grows, dimensions space increases exponentially.
- $10^{1} = 10$
- $10^2 = 100$
- 10<sup>3</sup> = 1000 and so on...

## **Missing Features**

- Certain features might be missing (e.g., due to occlusion).
- How should we train the classifier with missing features?
- How should the classifier make the best decision with missing features?

#### Classification

 Partition the feature space into two regions by finding the decision boundary that minimizes the error.



How shot

## **Main Classification Approaches**

**x**: input vector (pattern)

y: class label (class)

#### Generative

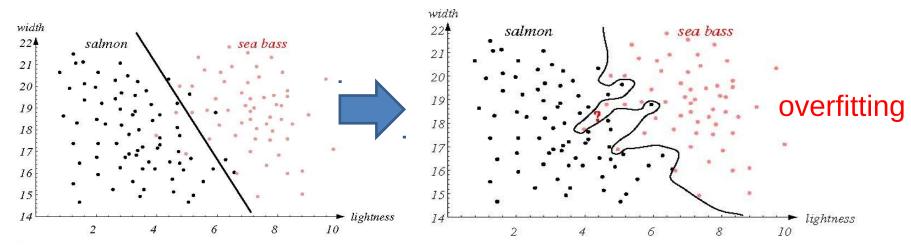
- Model the joint probability, p(x, y)
- Make predictions by using Bayes rules to calculate p(ylx)
- Pick the most likely label y

#### Discriminative

- Estimate p(ylx) directly (e.g., learn a direct map from inputs x to the class labels y)
- Pick the most likely label y

# Complexity

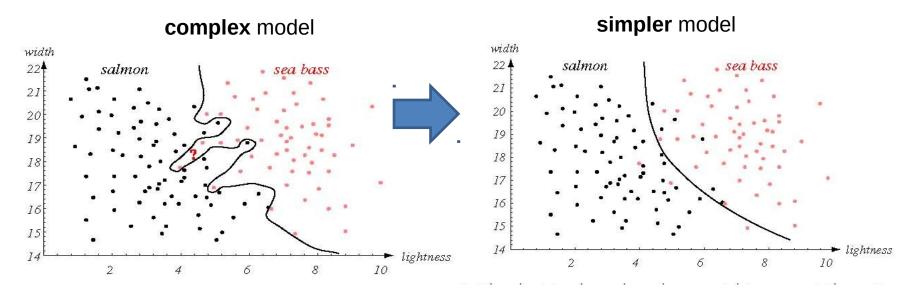
- We can get perfect classification performance on the training data by choosing complex models.
- Complex models are tuned to the particular training samples, rather than on the characteristics of the true model.



How well can the model generalize to unknown samples?

#### Generalization

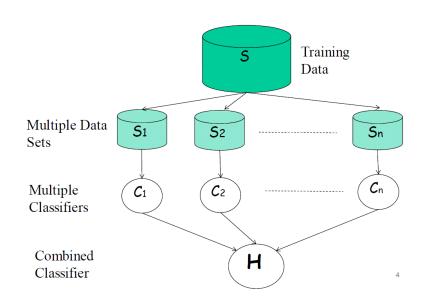
- Generalization is defined as the ability of a classifier to produce correct results on novel patterns.
- How can we improve generalization performance?
  - More training examples (i.e., better model estimates).
  - Simpler models usually yield better performance.



#### **Ensembles of Classifiers**

 Performance can be improved using a "pool" of classifiers.

 How should we build and combine different classifiers?



# Would it be possible to build a "general purpose" PR system?

- Humans have the ability to switch rapidly and seamlessly between different pattern recognition tasks.
- It is very difficult to design a system that is capable of performing a variety of classification tasks.
  - Different decision tasks may require different features.
  - Different features might yield different solutions.
  - Different tradeoffs exist for different tasks.