CS315: Principles of Database Systems Indexing

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Basics

- Indexing is used to speed up search
- A search key is used
- An index file consists of records or index entries which has two fields
 - Search key: Attribute that is used for searching
 - Pointer to the entire object or tuple
- Index files should be smaller than data files

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 - Search time
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- Two basic types of indices
 - Ordered index: search keys are organized according to some order
 - 4 Hash index: search keys are organized according to a hash function

Static hashing

- A hash function maps a key to a bucket
- A bucket is a unit of storage
- It is typically a disk block
- A key may need to be searched sequentially inside a bucket
- Results in hash file organization
- Example: mod n where n is the number of buckets

Hash function

- Two important qualities of an ideal hash function
- Uniform: Total number of keys from the domain is spread uniformly over all the buckets
- Random: Number of keys in each bucket is same irrespective of the actual distribution of keys

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- Changing size of a database is a problem
- Periodic re-hashing is the only solution
- Dynamic hashing: h changes dynamically but deterministically

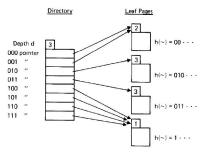
Dynamic hashing

- Organize overflow buckets as binary trees
- m binary trees for m primary pages
- $h_0(k)$ produces index of primary page
- Particular access structure for binary trees
- Family of functions $g(k) = \{h_1(k), \dots, h_i(k), \dots\}$
- Each $h_i(k)$ produces a bit
- At level i, if $h_i(k) = 0$, take left branch, otherwise right branch
- Example: bit representation

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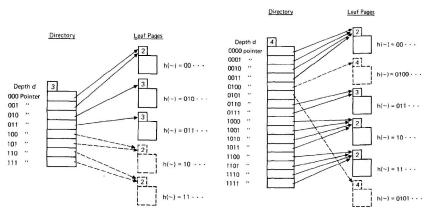
Extendible hashing

- Directory of pointers to buckets (leaf pages)
- Directory has global depth d
- 2^d pointers to leaf pages
- Pointer i contains keys starting with bit string i
- Leaf page has local depth I ≤ d
- Leaf page j contains keys starting with bit string j



Insertion

- When leaf page overflows
 - If I < d, leaf page split into two and I is incremented for both new leaf pages
 - If l = d, directory doubles in size, d is incremented and leaf page splits



Linear hashing

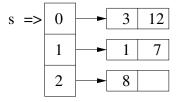
- Number of buckets grow by at most 1
 - Linear growth
- Both primary and overflow buckets
 - Overflow buckets are chained
- Family g of hash functions $\{h_0, \ldots, h_i, \ldots\}$
 - $h_i(k) = h(k) \mod (2^i n)$
 - n is initial number of buckets
 - h_{i+1} doubles the range of h_i

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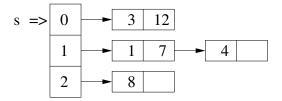
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- Load factor decides when to split
- Split pointer s decides which bucket to split
 - s is independent of overflowing bucket
 - At level i, s is between 0 and 2ⁱ 1
 - s is incremented and if at end, is reset to 0
- Records in splitting bucket are rehashed using h_{i+1}
 - Equal chance of being in old and new buckets

- Full buckets are not necessarily split
- Buckets split are not necessarily full

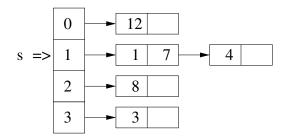
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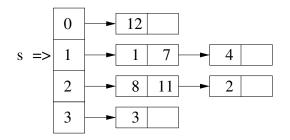
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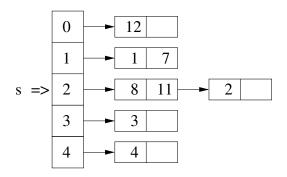
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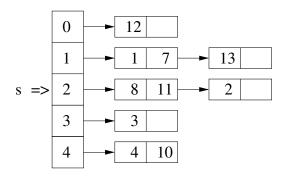
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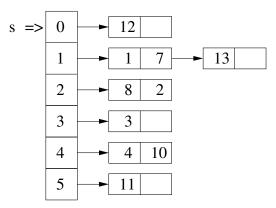
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Searching

- Searching key r
- Find bucket $b = h_l(r)$, l being final level
- If b > s, then bucket b has not been split and r must be here
- Otherwise r may be in b or $b + 2^l$
- Apply $h_{l+1}(r)$ to find out

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- Multilevel index: primary index does not fit in memory
 - Outer index: Sparse primary index
 - Inner index: Dense primary index file



B-tree

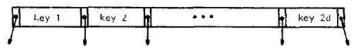
- A B-tree of order m has the following properties:
 - Leaf nodes are in same level (balanced) and contain no data
 - Internal nodes (not the root) have between m and 2m keys
 - Root has at least 1 key
 - 4 An internal node with r keys have r + 1 children
 - Ohild pointers in leaf nodes are null
- Branching factor = m + 1

B+-tree

- Balanced
- All data are in the leaf nodes
- Leaf nodes have $m \le r \le 2m$ keys and r + 1 data pointers
- Internal nodes contain $m \le r \le 2m$ keys and r + 1 child pointers
- Keys define range of values for children
- Often siblings are connected by pointers to avoid parent traversal

Order

 Branching factor or order determined by page size, size of key and size of pointer



- Page size = 4 kB
- Size of key = 8 bytes
- Size of pointer = 4 bytes
- If order is m, then $8 \times 2m + 4 \times (2m + 1) = 4 \times 1024$
- Therefore, *m* = 170
- A tree of height 3 can, therefore, store 5×10^6 records and that of height 4 can store 8×10^8 records

Index on multiple attributes

- Search keys having more than one attribute are called composite search keys
- Separate indices may be used
 - Union, intersection, etc. of individual results
- Multi-dimensional indexing
 - Quadtree: Extension of BST
 - R-tree: Extension of B+-tree
 - Indexing is specified by hyper-rectangles

Bitmap index

- Attribute domain consists of a small number of distinct values
- A bitmap or a bit vector is an array of bits
- Each distinct value has an array of the size of the number of tuples
 - If the *i*-th bit is 1, tuple *i* has that value

Gender	Grade
Male	С
Female	Α
Female	С
Male	D
Male	Α

- Two sets of bit vectors
 - Male = (10011), Female = (01100)
 - A = (01001), B = (00000), C = (10100), D = (00010)

Bitmap operations

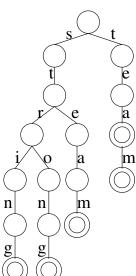
- Queries are answered using bitmap operations
- Example: Find the male student who got 'D'
 - Bitmap(Male) AND Bitmap(D)
- Null values require a special bitmap for null
- O/S allows efficient bitmap operations when they are packed in word sizes

Tries

- Comes from the word retrieval
- Mostly used for strings
- Structure
 - Root represents null string
 - Each edge defines the next character
 - Each node stores a string or a prefix of a string
 - Strings with same prefix share the path
- Advantages over binary search trees
 - Search time is O(m) where m is the length of the query
 - Size is generally less
 - Independent of database size
- Related structures: prefix tree, radix tree, suffix tree

Example

string, strong, steam, team



Indices in SQL

- create index i on r (a) creates an index named i on the attribute a of the relation r
 create index bindex on branch (bname)
- Index will be used implicitly whenever attribute a of relation r is queried
- drop index i deletes the index
 drop index bindex