

Pranshu Malik

Robotics Enthusiast



pranshumalik14



pranshu-malik

pranshu.malik@mail.utoronto.ca

Interests

Robotic Systems & Automation · Medical Devices · Computer Vision · Signal Processing · Circuit Design

Education

University of Toronto

Toronto, ON

Bachelor of Applied Science in Electrical Engineering; GPA: 3.87/4.0 Sept. '17 – June '21 (Exp.)

- Engineering International Scholar: Received full tuition-fee waiver for the entire duration of the program
- Key Courses: Digital Systems, Signals & Systems, Intro. Electronics, E&M Fields II, Dynamics, Linear Algebra
- Minoring in Robotics and Mechatronics; candidate for Certificate in Artificial Intelligence Engineering

Research & Professional Experience

Software Engineering Intern, Rocscience Inc.

Toronto, ON

Geotechnical Software Tools Design

May '19 – Present

- Introduced a new CAD model querying tool to allow users to efficiently filter through and operate on complex models by designing a seamless API and general implementation that allows the tool to be reused in several CAE products.
- Created a heavily client-requested schedule-view panel to give users a contextual display of multi-staged CAD models
- Improved synergy between products by integrating engine into other software. Generating interactive reports for more effective CAE project data visualization

Hardware Team Member, aUToronto

Toronto, ON

University of Toronto's Self Driving Car Team

Feb. '19 – Present

- powering all the sensors and our Intel compute server in a safe and efficient manner. The Electrical sub-team is also in charge of routing data from all the sensors to the server.
- Help build and assemble test equipment. (Software switch for the autonomous mode indicator lights) Designed controller PCB for based on the activation of autonomy mode of the car.

Vice President, Biomedical Engineering Competition 2019

Toronto, ON

Club for Undergraduate Biomedical Engineering

July '18 – Present

- Planned logistics and budget while effectively communicating with club members, judges, and sponsors
- Composed and evaluated problem statements to ensure design feasibility, and tested potential solutions
- Revamped competition's concept with hopes to promote innovation and improve learning experience

Teaching Assistant, Calculus 1A (MAT 135)

Toronto, ON

Department of Mathematics

Sept. '18 – Dec. '18

- Held weekly tutorials and office hours to help students learn various concepts in calculus
- Graded weekly assignments and midterm examinations; also assisted with exam invigilating duties

Undergrad. Research Assistant, Rehabilitation Engineering Lab, TRI

Toronto, ON

Advisors: Prof. Kei Masani and Prof. Paul Yoo

May '18 – Aug. '18

- Developed finite element models (FEMs) of lower leg for computational study of neurostimulation applications
- Streamlined workflow for developing FEMs using Autodesk Inventor, COMSOL Multiphysics, and MATLAB
- Documented the framework for developing FEMs from (Magnetic Resonance Imaging) MRI data sets, with a view of adaptability for other bio-electric studies

Projects

CollabBots: Is a collaborative robotic system, consisting of two independent robotic arms built from scratch. The two arms stack blocks to make a structure, controlled solely by vision. Currently, completed arm and work is going on for the vision and planning modules.

OpenPSU: A portable and programmable dual channel benchtop power supply unit (PSU) that can be powered using USB C/A, battery, or a power socket. Continuous current and voltage graphing. The project is still in the design phase.

Object-tracking robotic arm: Programmed to locate a cup in its radius and drop a coin into it; video from a camcorder, mounted on the arm, is processed in real-time by an FPGA which communicates with an Arduino to control the robot's actions. The system allows for calibration of thresholds to suit any environment.

TRAECY: Traffic and Emission Control System, aims to conjoin traffic management with real-time vehicle emission tracking & regulation, to ultimately reduce air pollution; it comprises of 3 disparate devices embedded in vehicles and street infrastructure that collect data for traffic-light control & traffic rerouting algorithms, and update users' quota.

Skills

Programming Languages:

Proficient: C, C++, C#, MATLAB, Verilog, Arduino

Intermediate: Python, Java, ARMv7, Visual Basic, L^AT_EX, PHP, HTML, CSS, JavaScript

Packages and Libraries: OpenCV, ROS, Git, CMake, .NET, WPF, GTK, Eyeshot, ParaView, DevExpress

Softwares:

EDA and Simulation Tools: KiCad, EAGLE, LTspice, Pspice, NI Multisim, ModelSim, Quartus Prime

3D CAD and CAE: SolidWorks, Autodesk Inventor, Autodesk Fusion 360, ANSYS, COMSOL Multiphysics, CATIA

Graphic design: Photoshop, Illustrator, Inkscape, GIMP

Hardware familiarity:

Modules and Sensors: PCA-9685 (12bit-PWM servo driver), TB6600 and A4988 (stepper motor drivers), HC-05 (serial Bluetooth transceiver), MQ-135 (gas sensor), LTC-3108 (ultra-low voltage step-up), LTC-3588 (nano-power harvesting)

Hardware Development Platforms and Boards: DE1-SoC, ESP-8266, ESP-32, Arduino (Due, Mega/Uno/Nano, MKR-1000, Intel Galileo Gen-2), Raspberry Pi 3B, STEM-Du RDC-102 MCU

Data Acquisition and Computing Platforms: Muse headband, NI myDAQ, redpitaya, Hantek 6022-BL

Professional Development & Certifications

Fundamentals of Image and Video Processing, Coursera: 2D signals and systems, sampling and filtering, motion estimation, color representation and processing; image enhancement, recovery, and compression

A Hands-on Introduction to Engineering Simulations, edX: Finite-element analysis and computational fluid dynamics simulations on ANSYS for real-world problems; verification and validation of results

Mechanical CAD Certification (in SolidWorks), CadZone India: Solid and sheet-metal modeling, advanced modeling tools, assembly modeling, SolidWorks Motion and Simulation tools

CATIA Certification, Institute for Multidisciplinary Design & Innovation, UoFT: Solid part design, assembly design, and drafting workbench for models

Basic, Advanced Machining, & Machining III, George Brown College: Machine shop safety; use of hand tools, lathe, mill, grinder, drill press, band saw; machine feed rates and cutting speeds

Introduction to Welding, George Brown College: Oxy-acetylene, manual-arc (stick), and gas-metal-arc (MIG) welding techniques; safety training

Awards & Achievements

First Place

First Year Summer Research Fellowship

Runner Up

Pete Conrad Scholar Finalist

First Prize (Grade XI, Large Team)

First

Second

GM/SAE Autodrive Challenge

2019

Faculty of Applied Science and Engineering

2018

NASA Space Apps Hackathon, New Delhi

2017

Conrad Spirit of Innovation Challenge

2016

NASA Ames Space Settlement Contest

2016

Intel Make-a-thon, New Delhi

2015

Google Developers Group (GDG) College Hack

2014

Other Interests & Activities

Sports: Love playing cricket and racket sports like squash and badminton; enjoy cycling, hiking, camping activities, and going on long walks. Have also played cricket competitively, at the state level.

Spiritualism/Culture: Have been attending Bhagavad Gita classes each week at ISKCON Temple for the past 12 years. Also associated with the Institute for Science and Spirituality at ISKCON; actively contribute to the newsletter and attend scientific conferences on the matter.