

Day 5 : 19th January, 2026

5.1. Wedge sum and smash product The disjoint union of two spaces is geometrically exactly what it sounds like: you just imagine the two spaces side by side.

Definition 5.1: (Disjoint union)

Let X and Y be two topological space. The *disjoint union*, $X \sqcup Y$, is defined by

$$X \sqcup Y := \text{disjoint union of } X \text{ and } Y.$$

A subset $U \subseteq X \sqcup Y$ is open if $U \cap X$ and $U \cap Y$ are open in X and Y , respectively.

Exercise 5.2: (Disjoint union on any indexed set)

Let $\{X_\alpha : \alpha \in \Lambda\}$ be a collection of topological space indexed by Λ . Let

$$X := \bigsqcup_{\alpha \in \Lambda} X_\alpha$$

denote the disjoint union of X_α 's. For each $\alpha \in \Lambda$, we have the natural inclusion map

$$f_\alpha : X_\alpha \hookrightarrow X.$$

Show that the above defined topology is the strongest topology on X such that each f_α is continuous.

Definition 5.3: (Based or pointed space)

A *based space* or *pointed space* is a pair (X, x_0) , where X is a topological and $x_0 \in X$ is a chosen *basepoint*.

If (X, x_0) and (Y, y_0) are based spaces, then a continuous map $f : (X, x_0) \rightarrow (Y, y_0)$ is called a *based map* if $f(x_0) = y_0$.

Definition 5.4: (Wedge sum)

Let (X, x_0) and (Y, y_0) be two based spaces. Then the *wedge sum*, denoted by $X \vee Y$, is defined as the quotient space of the disjoint union of X and Y by the identification $x_0 \sim y_0$.

$$X \vee Y := (X \sqcup Y) / \sim, \text{ where } x_0 \sim y_0.$$

Similarly, the wedge sum of collection of pointed spaces is defined as

$$\bigvee_{\alpha \in \Lambda} (X_\alpha, x_\alpha) := \left(\bigsqcup_{\alpha \in \Lambda} (X_\alpha, x_\alpha) \right) / \sim.$$

Definition 5.5: (Smash product)

Let (X, x_0) and (Y, y_0) be two based spaces. The *smash product*, denoted by $X \wedge Y$, is defined as the quotient space of $X \times Y$ with the identifications $(x, y_0) \sim (x_0, y)$ for all $x \in X$ and $y \in Y$.

Note that the wedge sum of X and Y be viewed as $X \vee Y = X \times \{y_0\} \cup \{x_0\} \times Y$ and hence

$$X \wedge Y = \frac{X \times Y}{X \vee Y}.$$

5.2. Category theory

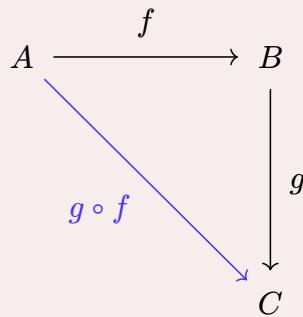
Definition 5.6: (Category)

A **category** \mathcal{C} consists of following:

- i) A collection of **objects** denoted by $\text{Ob}(\mathcal{C})$.
- ii) For any two objects $A, B \in \text{Ob}(\mathcal{C})$, a set $\text{Hom}_{\mathcal{C}}(A, B)$ called a **morphism**.
- iii) For any three objects $A, B, C \in \text{Ob}(\mathcal{C})$, we have a **composition**

$$\circ : \text{Hom}_{\mathcal{C}}(A, B) \times \text{Hom}_{\mathcal{C}}(B, C) \rightarrow \text{Hom}_{\mathcal{C}}(A, C),$$

$$(f, g) \mapsto g \circ f$$



satisfying the following properties.

- a) **(Associativity)** Let $A, B, C, D \in \text{Ob}(\mathcal{C})$. For morphisms $f \in \text{Hom}_{\mathcal{C}}(A, B), g \in \text{Hom}_{\mathcal{C}}(B, C)$ and $h \in \text{Hom}_{\mathcal{C}}(C, D)$, we have

$$h \circ (g \circ f) = (h \circ g) \circ f.$$

- b) **(Identity)** For each object A , there is a morphism $1_A \in \text{Hom}_{\mathcal{C}}(A, A)$ such that for any $g \in \text{Hom}_{\mathcal{C}}(A, B)$ and any $h \in \text{Hom}_{\mathcal{C}}(C, A)$, we have

$$g \circ 1_A = g, \quad 1_A \circ h = h.$$

When the context is clear, we will write $\text{Hom}(A, B)$ instead of $\text{Hom}_{\mathcal{C}}(A, B)$.

Remark 5.7:

- i) The only restriction on Hom is that it be a set. In particular, $\text{Hom}(A, B) = \emptyset$ is allowed, although the identity axiom shows that $\text{Hom}(A, A) \neq \emptyset$ as it contains 1_A .
- ii) Instead of writing $f \in \text{Hom}(A, B)$, we usually write $f : A \rightarrow B$.

Example 5.8: (Examples of category)

Categories are everywhere in mathematics (and even in computer science). We will list some of them here.

- i) $\mathcal{C} = \text{Sets}$. Here

$\text{Ob}(\mathcal{C})$ = all sets,

$\text{Hom}(A, B) = \{\text{all functions } f : A \rightarrow B\}$

◦ = composition is the usual function composition

ii) $\mathcal{C} = \mathbf{Top}$. Here

$\text{Ob}(\mathcal{C})$ = all topological spaces,

$\text{Hom}(X, Y) = \{\text{all continuous functions } f : X \rightarrow Y\}$

◦ = composition is the usual function composition

iii) $\mathcal{C} = \mathbf{Top}_*$. Here

$\text{Ob}(\mathcal{C}) = \{(X, *_X) : X \text{ is a topological space and } *_X \in X\}$

$*_X \in X$ is called the basepoint,

$\text{Hom}((X, *_X), (Y, *_Y)) = \{\text{all continuous functions } f : (X, *_X) \rightarrow (Y, *_Y) \text{ with } f(*_X) = *_Y\}$

this is called basepoint preserving functions

◦ = composition is the usual function composition

iv) $\mathcal{C} = \mathbf{Groups}$: Category of groups and group homomorphisms.

v) $\mathcal{C} = \mathbf{Ab}$: Category of abelian groups and group homomorphisms.

Example 5.9: (Discrete Category)

Let X be a nonempty set. Consider a category \mathcal{C} ,

$\text{Ob}(\mathcal{C})$ = elements of X

$$\text{Hom}(x, y) = \begin{cases} \emptyset & \text{if } x \neq y \\ 1_x & \text{if } x = y. \end{cases}$$

This is called a *discrete category*.