Write down the construction, principle, working of 0 poles of permanent magner it experiences the force by the principle of Faraday's law of electromagnetic induction and that force is called deflecting force (or) deflecting torque Aus: Construction: Pointer Balance Scale weight pial plate > Permanent magnet Tewel hearing. A current carrying coil is placed between the poles of permanent magnets. of poles is fixed outside of the Coll, that Colls gives the Stationary magnetic féllids. control torque is provided by two phospher boon te hair Springs. These springs also serve as leads to today current damping is produced by the movement of allminium former moving in the magnetic X bields of the permanent magnet. The pointer is carried by the Spindle and moves over a graduated scale. Working: A permanent magnet creates a Stationary magnetic field. When a current from the source blows through a Coil suspended with in this field, it experiences a torce based on the Fleming's left X hand rule. Deflection torque. The torque which is required to move the pointer is called deflecting torque. Controlling Torque - The opposition force given to the pointer to stand at steady point. Equilibrium - The pointer stops moving Deflection is equal to the When Deflection Controlling torque. then meaning the readings. X

dwi Q. 25 \* Describe wall Directiful. \* 75% ning the readings of two wattmeteres. Motor 750 method ment D 8 & power wing

Summing the readings of two Waterners with the current with the current with the waterness, which is placed in any two lines, and the potential coils are broady 5 Calculated 1 70 1000 A A A (000 third line. S 11 W, + W2. The total ES V VRN DAMON X

\* To 3 The three voltages VRN, VyN and VRN was displaced by our angle of 120°. had "a considered (loo).

X NOW. The Given as current flowing through the of the unstimeter, w, will be

Je potential Thoro to E. Jore difference a Cross the WI = VRB = VRN - VBN Potential bo

tore the power measured W, = VRB IR (08 (30°- ф).

Similary, we found the Wo Value is W2 = VyB Ty COS (30°+ Ф). since the load is in balanced condition, here × IR = Iy = IB = IL and VRY = VyB = VBR = VL  $\Rightarrow$   $W_1 = V_L I_L \cos(30^\circ - \phi)$  and  $W_2 = V_L I_L \cos(30^\circ + \phi)$ Now, the scum of two watemeter readings will be given as  $W_1 + W_2 = V_2 I_L \left[ \cos(30^\circ - \phi) + \cos(30^\circ + \phi) \right]$ W, +W2 = V\_ I\_ [ Cos30 Cos0 + sin 30 sin 0 + cos300 COSA - Sin 30° sin A ]  $W_1 + W_2 = V_L I_L (2 \cos 30^\circ \cos \phi)$ W, +W2 = VL IL [2 \frac{13}{2} \cos 0] W1+W2 = V3 VL IL COS \$ W,+W2 = P

Explain the digital storage oscilloscope (DSO), With block diagram.