

# Introduction to Deep Learning

Notes

# Human Visual System

- The human visual system is one of the wonders of the world. Consider the following sequence of handwritten digits:

504192

- Most people effortlessly recognize those digits as 504192
- In **each hemisphere of our brain**, humans have a **primary visual cortex**, also known as **V1, containing 140 million neurons, with tens of billions of connections between them**
- And yet human vision involves not just V1, but an entire series of visual cortices - V2, V3, V4, and V5 - doing progressively more complex image processing
- We carry in our heads a supercomputer, tuned by evolution over hundreds of millions of years, and superbly adapted to understand the visual world
- Recognizing handwritten digits isn't easy. Rather, we humans are stupendously, astoundingly good at making sense of what our eyes show us

# Challenges in visual pattern recognition

- The difficulty of visual pattern recognition becomes apparent if you attempt to write a computer program to recognize digits like those above
- What seems easy when we do it ourselves suddenly becomes extremely difficult
- Simple intuitions about how we recognize shapes - "a 9 has a loop at the top, and a vertical stroke in the bottom right" - turn out to be not so simple to express algorithmically
- When you try to make such rules precise, you quickly get lost in a morass of exceptions and caveats and special cases
- It seems hopeless.

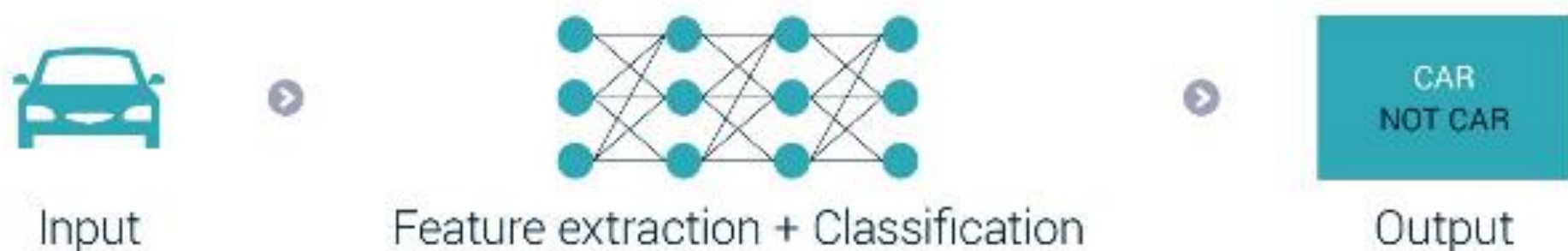
# Machine Learning vs Deep Learning

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## Machine Learning



## Deep Learning



# ML vs DL

- ML

- Flow     Input -> Feature Engineering -> Classification(Model) -> Output
- Feature Engineering
  - EDA
  - Feature Elimination
    - Missing Value Ratio
    - Low Variance Filter
    - Random Forest Classifier
    - High Co-relation filter
  - Feature Extraction
    - Extracting the variability into a fewer variables
    - PCA works on co-related variables and creates un-corelated variables

- DL

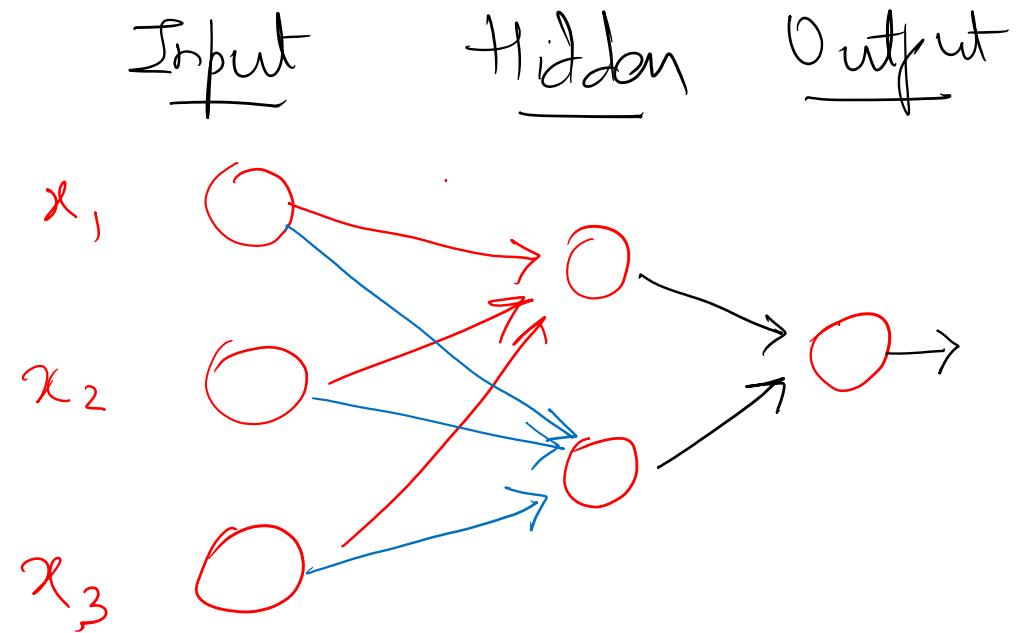
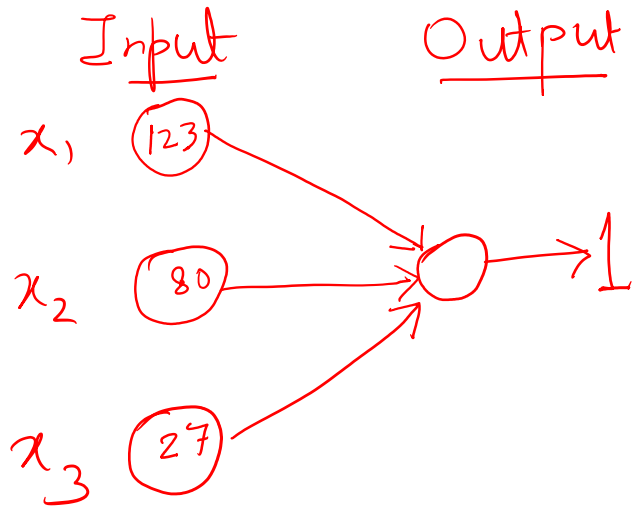
- Flow     Input -> (Feature Engineering + Classification) -> Output
- DL handles Feature Engineering by itself...you don't need to do that..

# ML vs DL

- ML
  - Mostly used with structured data
- DL
  - Mostly used with unstructured data – images, videos, text

# Neural Network Representation

|   | <u>X</u> |       |       | <u>Y</u> |
|---|----------|-------|-------|----------|
|   | $x_1$    | $x_2$ | $x_3$ |          |
| 1 | 123      | 80    | 27    | 1        |
| 2 | -        | -     | -     | 0        |
| : |          |       |       | :        |



# Perceptron & Neural Networks

- The **perceptron** is an algorithm for supervised learning of binary classifiers
- A binary classifier is a function which can decide whether or not an input, represented by a vector of numbers, belongs to some specific class
- It is a type of linear classifier, i.e. a classification algorithm that makes its predictions based on a linear predictor function combining a set of weights with the feature vector
- ***Perceptron is a single layer neural network and a multi-layer perceptron is called Neural Networks.***



# DNN

$$h_1 = w_{11}^{(1)}x_1 + w_{12}^{(1)}x_2 + w_{13}^{(1)}x_3$$

$$h_2 = w_{21}^{(1)}x_1 + w_{22}^{(1)}x_2 + w_{23}^{(1)}x_3$$

$$(1) X = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$

$$(2) H = \begin{bmatrix} h_1 \\ h_2 \end{bmatrix}$$

$$*X = \begin{bmatrix} w_{11}^{(1)} & w_{12}^{(1)} & w_{13}^{(1)} \\ w_{21}^{(1)} & w_{22}^{(1)} & w_{23}^{(1)} \end{bmatrix} * \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} w_{11}x_1 + w_{12}x_2 + w_{13}x_3 \\ w_{21}x_1 + w_{22}x_2 + w_{23}x_3 \end{bmatrix} = \begin{bmatrix} h_1 \\ h_2 \end{bmatrix}$$

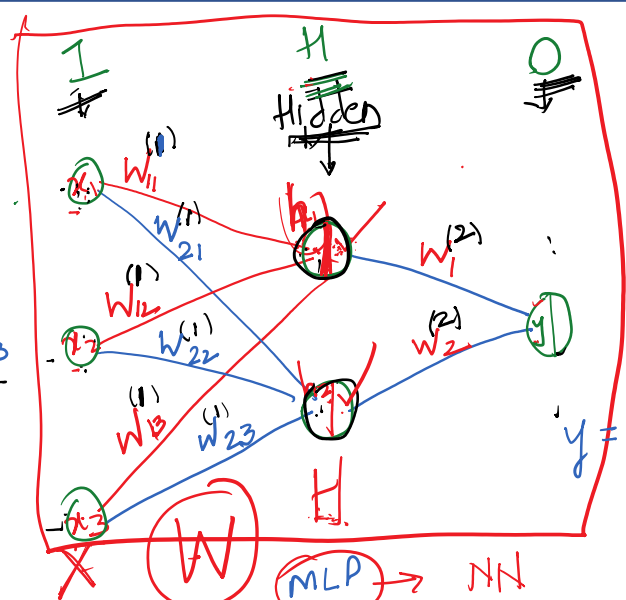
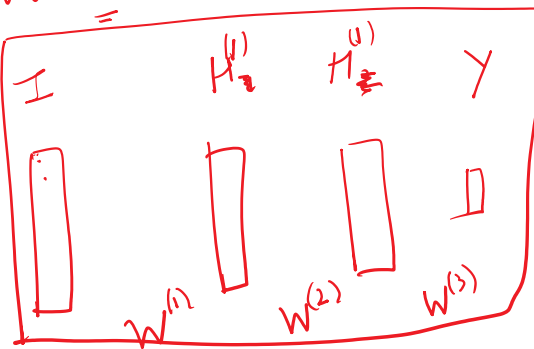
$$H = W * X$$

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$$\begin{aligned} H^{(1)} &= W^{(1)} * X \\ H^{(2)} &= W^{(2)} * H^{(1)} \\ Y &= W^{(3)} * H^{(2)} \end{aligned}$$

$$H^{(k)} = W^{(k)} * H^{(k-1)}$$

where  $H^{(0)} = X$



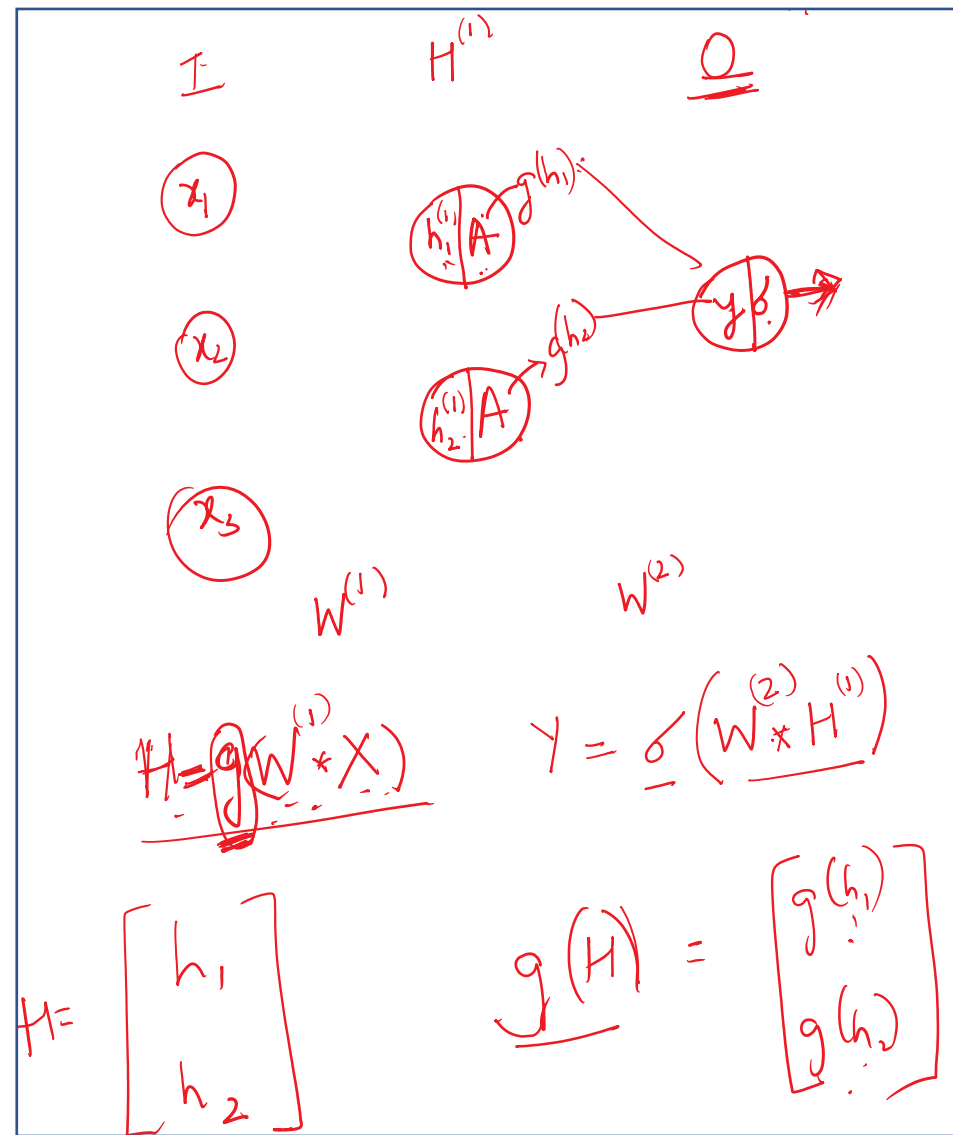
HN  
Neural

$$y = w_1^{(2)}h_1 + w_2^{(2)}h_2$$

$h_1, h_2, \dots$

MLP  $\rightarrow$  NN  
 $\uparrow$   
SLP

DNN



$$H = g(W^{(1)} * X)$$

$$Y = \sigma(W^{(2)} * H^{(1)})$$

$$H = \begin{bmatrix} h_1 \\ h_2 \end{bmatrix}$$

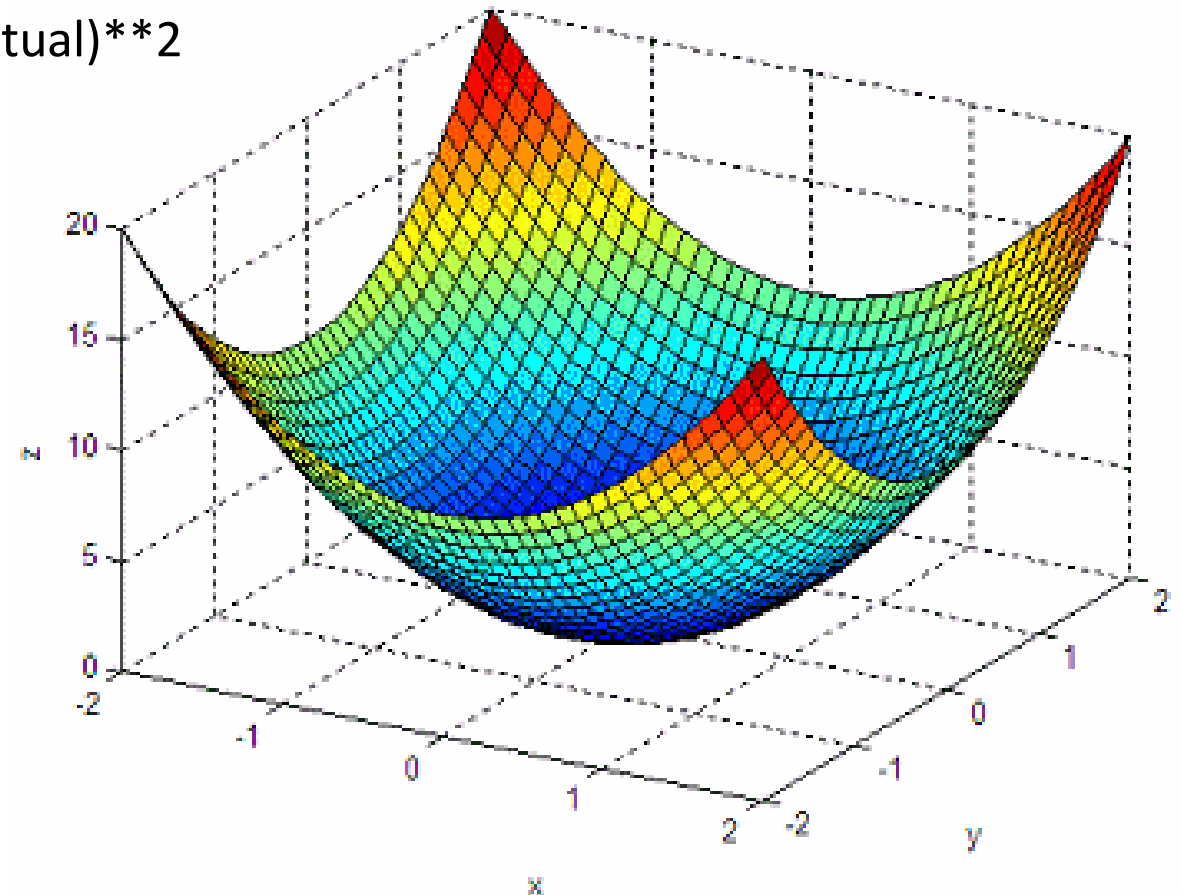
$$g(H) = \begin{bmatrix} g(h_1) \\ g(h_2) \end{bmatrix}$$

# Forward and Backward propagation

- Go through the Perceptron stages: Input, Summation, Activation and calculate the Loss (based on the Target)
- This is forward propagation
- Based on the Loss, adjust the only thing you can...the Weights/Bias
- This is backward propagation
- Multiple such forward and backward passes need to reduce the Loss
- This is the learning process

# Gradient Descent

- $Y = m_1x_1 + m_2x_2 + c$
- Loss v/s  $m_1, m_2, c$
- $\text{Loss} = (\text{Pred} - \text{Actual})^2 = ((m_1x_1 + m_2x_2 + c) - \text{Actual})^2$
- Find  $m_1, m_2, c$  such that Loss is minimum
- Use Gradient descent for this
- Derivative to find minima:



# Representation Learning

- Representation learning is learning representations of input data typically by transforming it or extracting features from it(*by some means*), that makes it easier to perform a task like classification or prediction.

