

03-Mar-2021 10:27:16 am

RESPONSE SHEET FOR Online Assessment - Mar - 2021

Department: Information Technology

Date: 03-03-2021

Name of Student: Satyam Abhishek

Scholar Number: 19V03068

Semester: 4th

Regular/ Supply:
Subject Code: IT-221

Subject Name: Analog and Digital Communication

Signature of Student: Satyam

Subject Coordinator Name: Dr. Praveen Pawar

Page -1

Q.1.

DSB- FC

- It is a double side band along with carrier AM.
- Band width = 2 fm
- Less no. of channels in a given frequency range.
- More power consumption.
- More redundant data.
- No need of synchronization.

DSB- SC

- It is a double side band without carrier AM.
- Band width = 2 fm
- Less number of channels in a given frequency range.
- Moderate power consumption.
- Moderately redundant data
- Tracking might be required.

SSB- SC

- It is only one side band AM, without carrier.
- Band width = fm
- More number of channels in a given frequency range.
- Least power consumption.
- Least redundant data.
- Synchronization or tracking is essential.

03-Mar-2021 10:27:30 am

Scholar Number 19U03068

Page No: 2

Date 03-03-21

Signature satyam

Q. No.

Rough Work
Required

ii) Here, we have to calculate the modulation index of the AM wave.

given,

$$m(t) = A \sin 45\pi t$$

$$c(t) = 4 \cos 800\pi t$$

Let's calculate the value of A , as given in question.

My scholar no. = 68

As the scholar no. is even, so the value of

$$\boxed{A = 2}$$

So, as we know that, Modulation index (m) = $\frac{A_m}{A_c}$

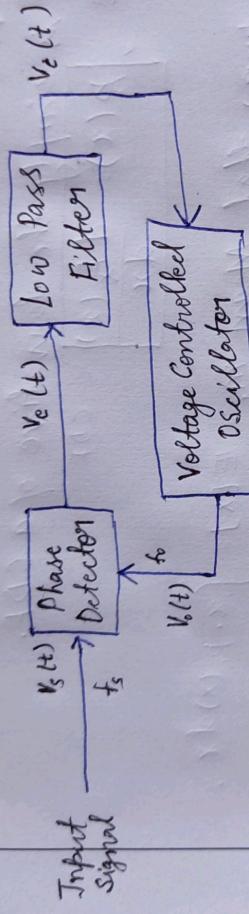
And Here, $A_m = 2$ & $A_c = 4$.

$$\therefore m = \frac{2}{4} = 0.5 \Rightarrow \boxed{m = 0.5}$$

Q.No.

Rough Work (if Required)

2. FM waves are detected using Phase-Locked Loop (PLL).
 It is a feedback control system with 3 basic components :-
 → i) Phase detector , ii) Low Pass Filter & iii) Voltage Controlled oscillator .



Let's have a look at the working of PLL :-
 If an input signal V_s of frequency f_s is applied to the PLL, the phase detector compares the phase and frequency of incoming signal to V_o of VCO .
 If the two signals differs in frequency and/or phase, an error V_e is generated .

The phase-detector is basically a multiplier and produces the sum and difference components at its output .

→ The high frequency component is removed by low pass filter and difference frequency component is then V_e to VCO .

→ The signal V_e shifts the VCO frequency in a direction to reduce the frequency difference between f_s and f_o .

→ And once the action starts we say that the signal is in capture range .

→ The Voltage Controlled oscillator continues to change frequency till output frequency is exactly the same as input signal frequency , And when its achieved the circuit is then set to be locked and thus we are able to detect the FM waves .

03-Mar-2021 11:02:26 am

Scholar Number 19V03068

Page No: 4

Date 03-03-2021

Signature Satyam

Q. No.

3.

Rough Work (If Required)

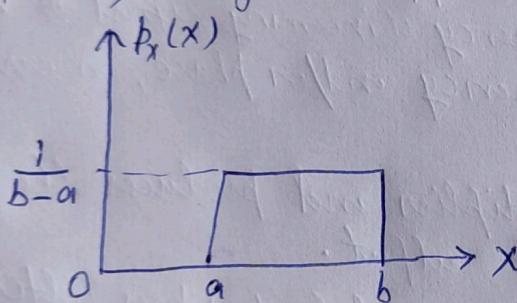
i) The Central limit theorem states that whenever a random sample of size n is taken from any distribution with mean, variance, then the sample mean will be approx. normally distributed with mean & variance.

ii) A PDF is simply the derivative of a CDF.

$$\text{i.e. } p_x(x) = \frac{d(F_x(x))}{dx} \leftarrow \text{CDF}$$

iii) As we know that Mean, $m_x = E[x] = \int_{-\infty}^{\infty} x \cdot p_x(x) dx$.

Here, the given pulse is as:-



$$\therefore m_x = E[x] = \int_a^b x \cdot \frac{1}{b-a} dx = \frac{1}{2(b-a)} [b^2 - a^2]$$

$$m_x = \cancel{a+b} \cdot \frac{a+b}{2}$$

As stated in question,

a is smallest digit of my mob. no., i.e $a = 0$

b is largest digit of my mob. no., i.e $b = 9$

$$\therefore m_x = \frac{0+9}{2} = 4.5$$

$$\boxed{m_x = 4.5}$$

So, the mean of the rectangular pulse is 4.5.

03-Mar-2021 11:29:12 am

Scholar Number 19U03068

Date 03-03-2021

Page No: 5

Signature Satyam,

Q. No.

4. Noise may be defined as any unwanted form of energy tending to interfere with proper and easy reception and reproduction of wanted signal.

Rough Work (If Required)

→ Depending upon whether noise is external or internal to the signal, there are two types of noise.

i) External noise: The noise which is generated externally to the system is known as external noise.
eg. Atmosphere Noise, extra-terrestrial noise, etc.

ii) Internal noise: The noise which is generated within the system is known as internal noise.

Some types of internal noise are :-

- i) Thermal Noise.
- ii) Flicker Noise.
- iii) Shot Noise.

→ The thermal noise in electronic systems is usually modeled as a white gaussian Noise process. It is usually assumed that it has zero mean $\mu_x = 0$, and is gaussian.

So, its power spectral density is given

$$\text{as, } S_x(f) = \frac{N_0}{2} ; \text{ for all } f$$

