



STEREO VISION

INPUT IMAGES

IMAGE SET 1



(L)

(R)

IMAGE SET 2



(L)

(R)

DETECTED CORNERS

IMAGE SET 1

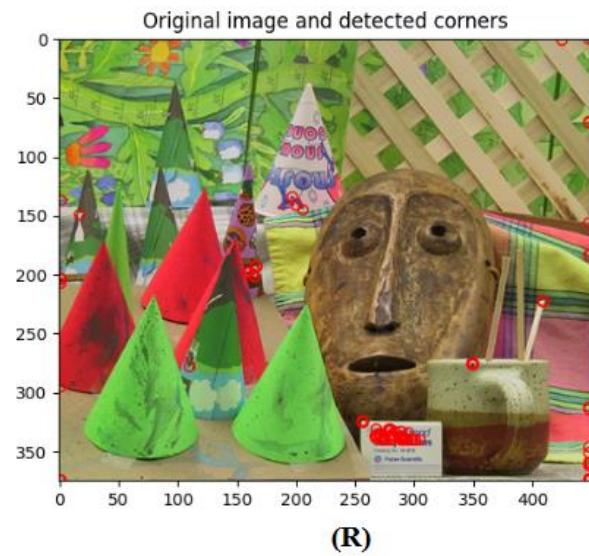
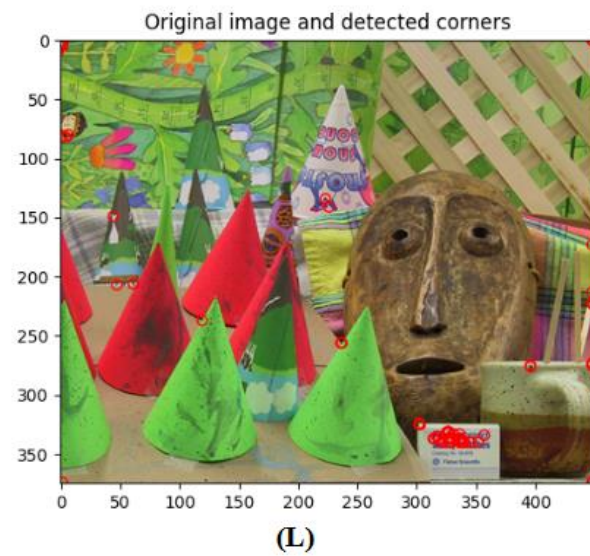
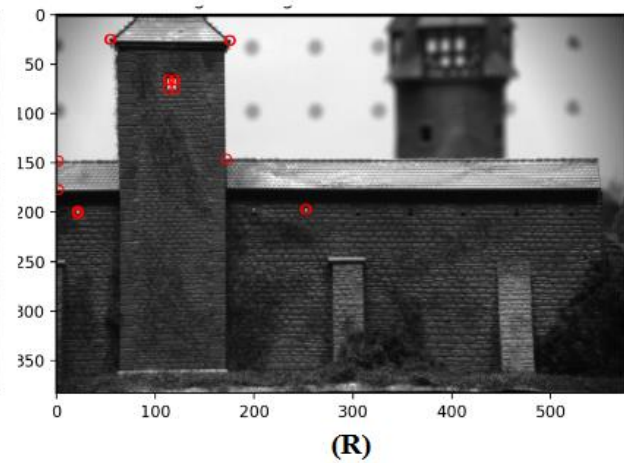
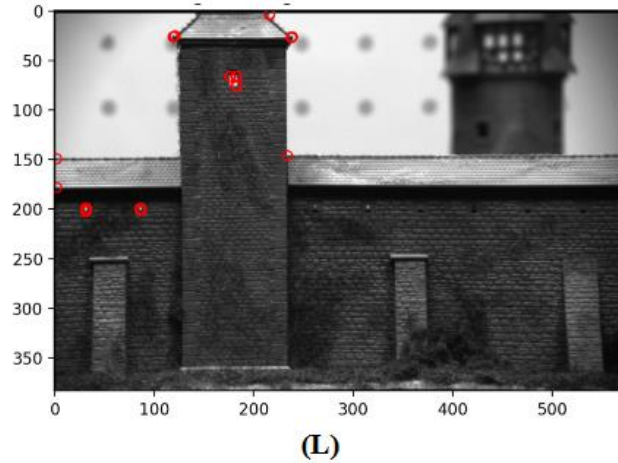


IMAGE SET 2



NCC CORNER
MATCHES
(BEFORE
THRESHOLDING)

IMAGE SET 1

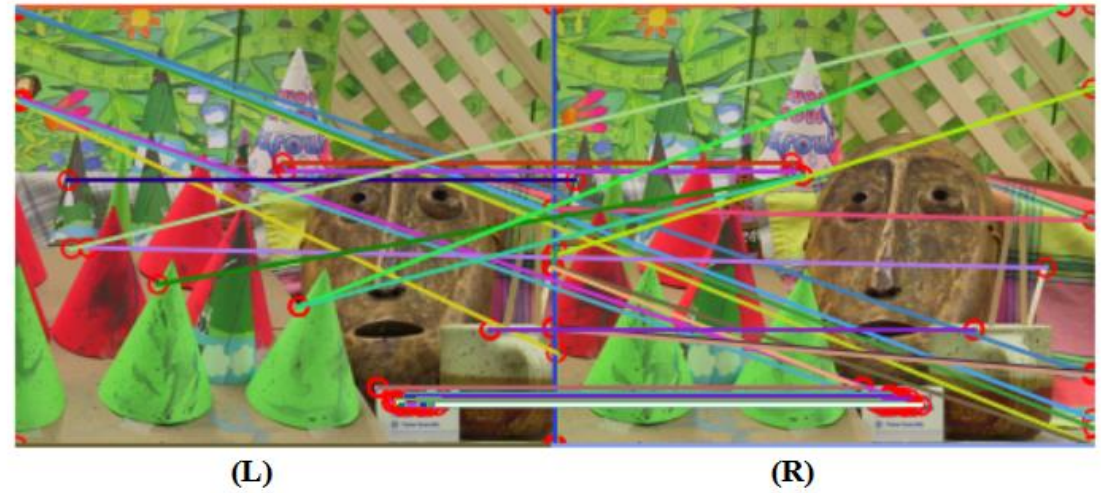
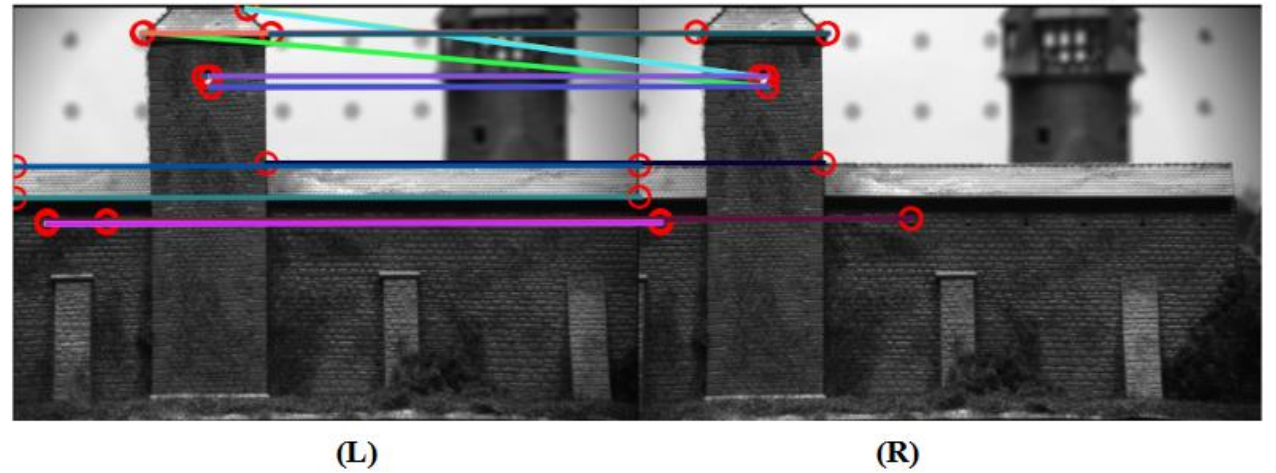


IMAGE SET 2



NCC CORNER
MATCHES (AFTER
THRESHOLDING)

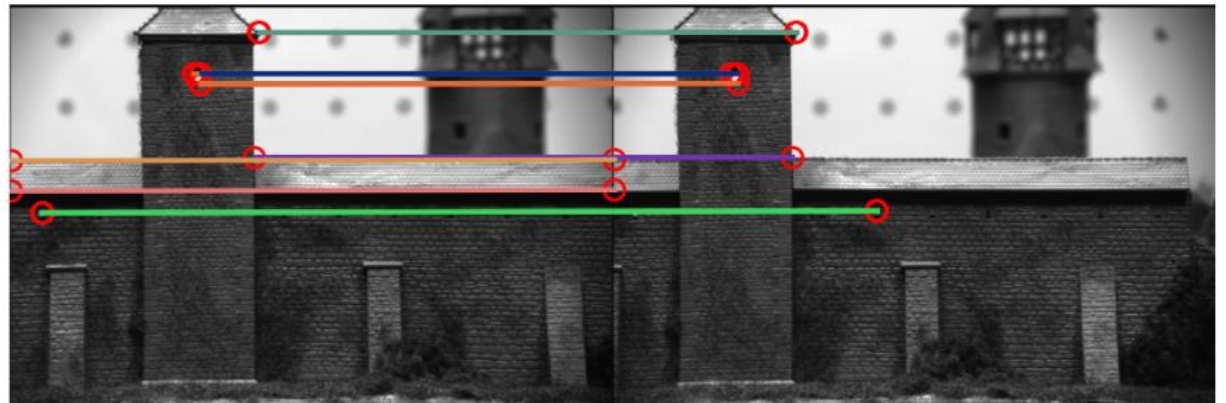
IMAGE SET 1



(L)

(R)

IMAGE SET 2



(L)

(R)

INLIER CORRESPONDENCES

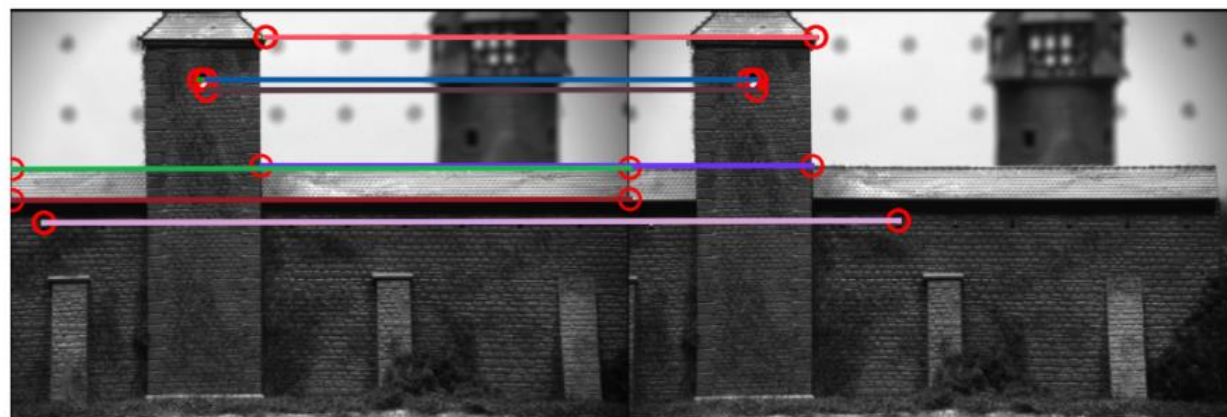
IMAGE SET 1



(L)

(R)

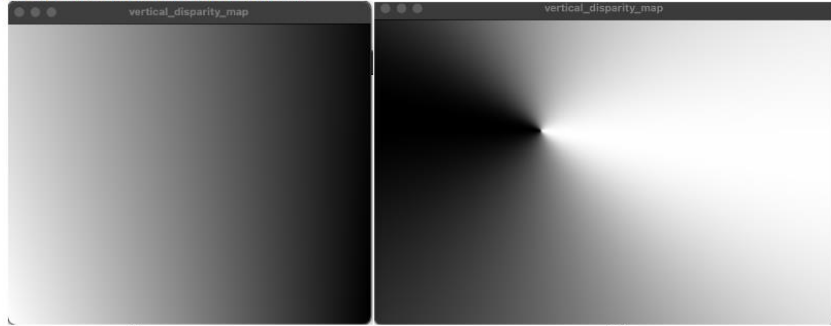
IMAGE SET 2



(L)

(R)

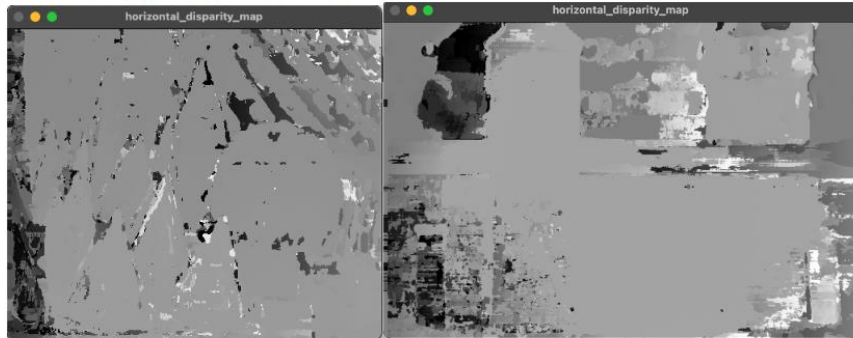
VERTICAL DENSE DISPARITY MAP



(1)

(2)

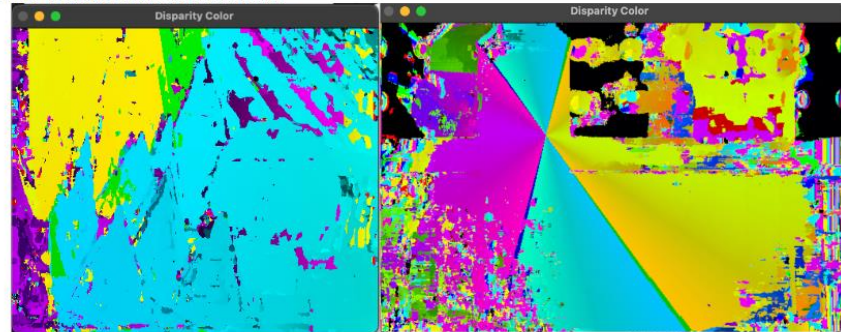
HORIZONTAL DENSE DISPARITY MAP



(1)

(2)

COLOR DENSE DISPARITY MAP



(1)

(2)

DISPARITY MAPS
