

Unit II

Introduction to Finite Automata

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Introduction to Finite Automata

- A finite automaton is a mathematical (model) abstract machine that has a set of “states” and its “control” moves from state to state in response to external “inputs”.
- The control may be either “deterministic” meaning that the automation can’t be in more than one state at any one time
- or “non deterministic”, meaning that it may be in several states at once.
- This distinguishes the class of automata as DFA or NFA.

Applications

- The finite state machines are used in applications in computer science and data networking.
- For example, finite-state machines are basis for programs for spell checking, indexing, grammar checking, etc
- network protocols that specify how computers communicate.

Introduction of Finite State Machine

- a machine that can, at any point in time, be in a specific state from a finite set of possible states
- It can move (transition) to another state by accepting an input.
- The simplest machine is the finite state automaton

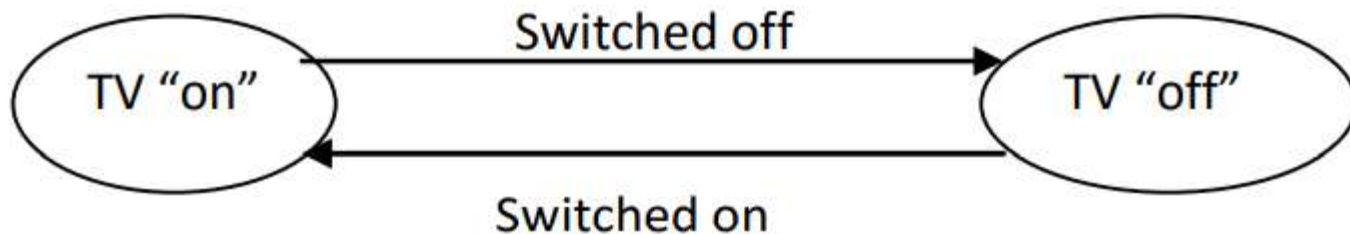


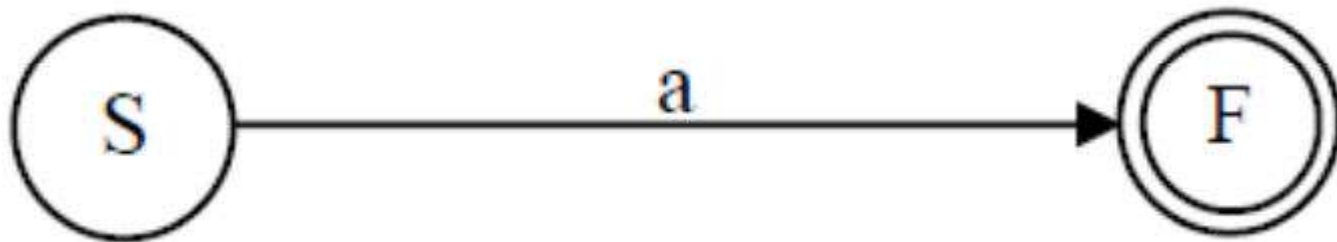
Fig: state diagram for TV on/off state

Deterministic Finite Automata (DFA)

- A deterministic finite automaton is defined by a quintuple (5-tuple) as $(Q, \Sigma, \delta, q_0, F)$.
 - Where,
 - Q = Finite set of states,
 - Σ = Finite set of input symbols,
 - δ = A transition function that maps $Q \times \Sigma \rightarrow Q$
 - q_0 = A start state; $q_0 \in Q$
 - F = Set of final states; $F \subseteq Q$.
- A transition function δ that takes as arguments a state and an input symbol and returns a state.

Deterministic Finite Automata (DFA)

- For example:



- If 'S' is a state and 'a' is an input symbol then $\delta(S,a)$ is that state F such that there are arcs labeled 'a' from S to F.

How a DFA process strings?

- The first thing we need to understand about a DFA is how DFA decides whether or not to “accept” a sequence of input symbols.
- The “language” of the DFA is the set of all symbols that the DFA accepts.
- Suppose a_1, a_2, \dots, a_n is a sequence of input symbols.
- We start out with the DFA in its start state, q_0 .
- We consult the transition function δ also for this purpose.

How a DFA process strings? (Contd...)

- Say $\delta(q_0, a_1) = q_1$ to find the state that the DFA enters after processing the first input symbol a_1 .
- We then process the next input symbol a_2 , by evaluating $\delta(q_1, a_2)$; suppose this state be q_2 .
- We continue in this manner, finding states q_3, q_4, \dots, q_n such that $\delta(q_{i-1}, a_i) = q_i$ for each i .
- if q_n is a member of F , then input a_1, a_2, \dots, a_n is accepted & if not then it is rejected.

Notations for DFA

- There are two preferred notations for describing this class of automata
 - **Transition Diagram**
 - Which is a graph
 - **Transition Table**
 - which is a tabular listing of the δ function, which by implication tells us the set of states and the input alphabet.

Notations for DFA

Transition Diagram

- A transition diagram of a DFA is a graphical representation where; (or is a graph)
- For each state in Q , there is a node represented by circle,
- For each state q in Q and each input a in Σ , if $\delta(q, a) = p$ then there is an arc from node q to p labeled a in the transition diagram.
- If more than one input symbol cause the transition from state q to p then arc from q to p is labeled by a list of those symbols.
- The start state is labeled by an arrow written with “start” on the node.
- The final or accepting state is marked by double circle.

Notations for DFA

Transition Diagram Example

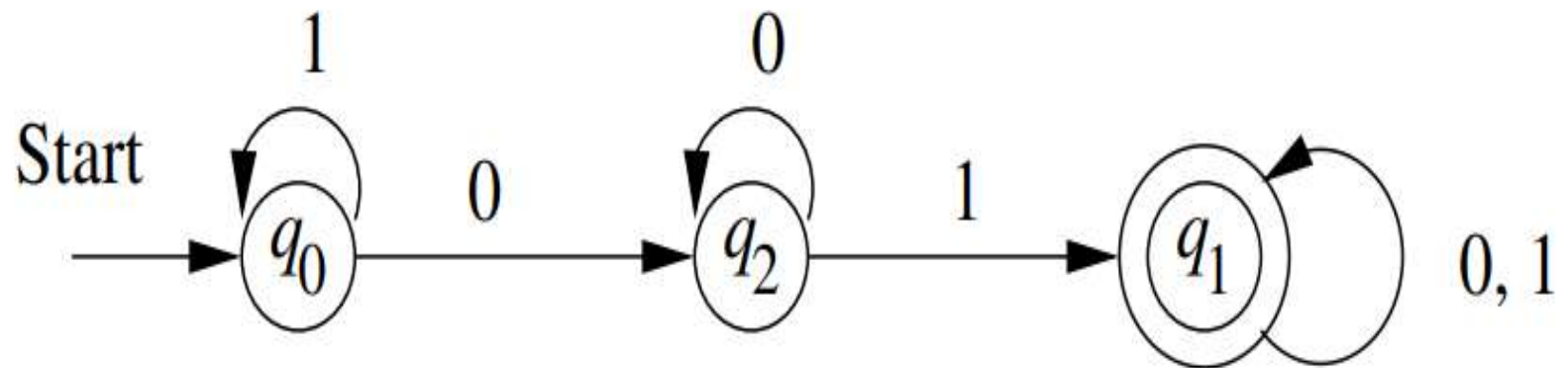


Fig: The transition diagram for the DFA accepting all strings with a substring 01

Notations for DFA

Transition Table

- Transition table is a conventional, tabular representation of the transition function δ that takes the arguments from $Q \times \Sigma$ & returns a value which is one of the states of the automation.
- The row of the table corresponds to the states while column corresponds to the input symbol.
- The starting state in the table is represented by \rightarrow followed by the state i.e. $\rightarrow q$, for q being start state, whereas final state as $*q$, for q being final state.

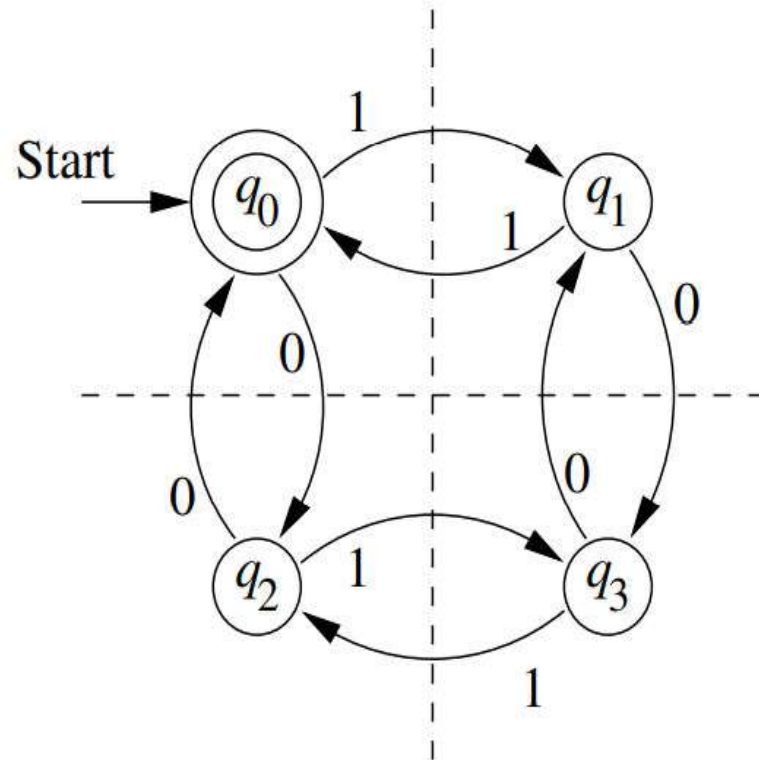
Notations for DFA

Transition Table Example

	0	1
$\rightarrow q_0$	q_2	q_0
$*q_1$	q_1	q_1
q_2	q_2	q_1

Fig: The transition table for the DFA accepting all strings with a substring 01

Example 2



	0	1
* \rightarrow q_0	q_2	q_1
q_1	q_3	q_0
q_2	q_0	q_3
q_3	q_1	q_2

Fig: The state diagram & transaction table for the DFA accepting all strings with even number of 0's & even number of 1's

Extended Transition Function of DFA

- The extended transition function of DFA, denoted by $\hat{\delta}_1$ is a transition function that takes two arguments as input, one is the state q of Q and another is a string $w \in \Sigma^*$, and generates a state $p \in Q$.
- This state p is that the automaton reaches when starting in state q & processing the sequence of inputs w .
- i.e. $\hat{\delta}_1(q, w) = p$

Extended Transition Function of DFA

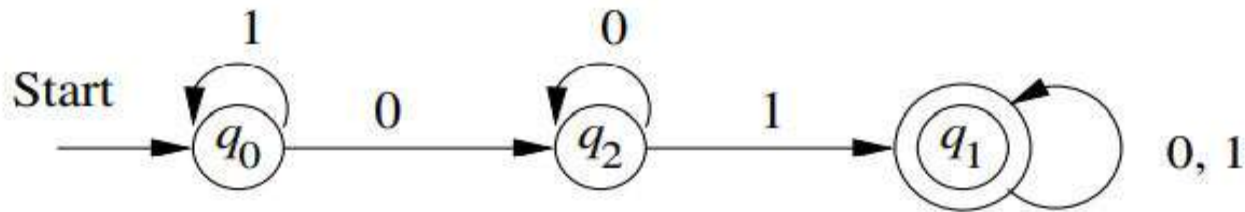
- Let us define by induction on length of input string as follows:
- **Basis step:** $\hat{\delta}_|(q, \epsilon) = q$. i.e. from state q , reading no input symbol stays at the same state.
- **Induction:** Let w be a string from Σ^* such that $w = xa$, where x is substring of w without last symbol and a is the last symbol of w , then $\hat{\delta}_|(q, w) = \delta(\hat{\delta}_|(q, x), a)$.
- Thus, to compute $\hat{\delta}_|(q, w)$, we first compute $\hat{\delta}_|(q, x)$, the state the automaton is in after processing all but last symbol of w . let this state is p , i.e. $\hat{\delta}_|(q, x) = p$.
- Then, $\hat{\delta}_|(q, w)$ is what we get by making a transition from state p on input a , the last symbol of w . i.e. $\hat{\delta}_|(q, w) = \delta(p, a)$

Extended Transition Function of DFA

- Compute $\hat{\delta}_|(q_0, w)$ for each prefix w of 110101, starting at ϵ and going in increasing size.
 - $\hat{\delta}(q_0, \epsilon) = q_0$.
 - $\hat{\delta}(q_0, 1) = \delta(\hat{\delta}(q_0, \epsilon), 1) = \delta(q_0, 1) = q_1$.
 - $\hat{\delta}(q_0, 11) = \delta(\hat{\delta}(q_0, 1), 1) = \delta(q_1, 1) = q_0$.
 - $\hat{\delta}(q_0, 110) = \delta(\hat{\delta}(q_0, 11), 0) = \delta(q_0, 0) = q_2$.
 - $\hat{\delta}(q_0, 1101) = \delta(\hat{\delta}(q_0, 110), 1) = \delta(q_2, 1) = q_3$.
 - $\hat{\delta}(q_0, 11010) = \delta(\hat{\delta}(q_0, 1101), 0) = \delta(q_3, 0) = q_1$.
 - $\hat{\delta}(q_0, 110101) = \delta(\hat{\delta}(q_0, 11010), 1) = \delta(q_1, 1) = q_0$.

Since, q_0 is final state in example 2 so it is accepted

Extended Transition Function of DFA (Assignment- 2)



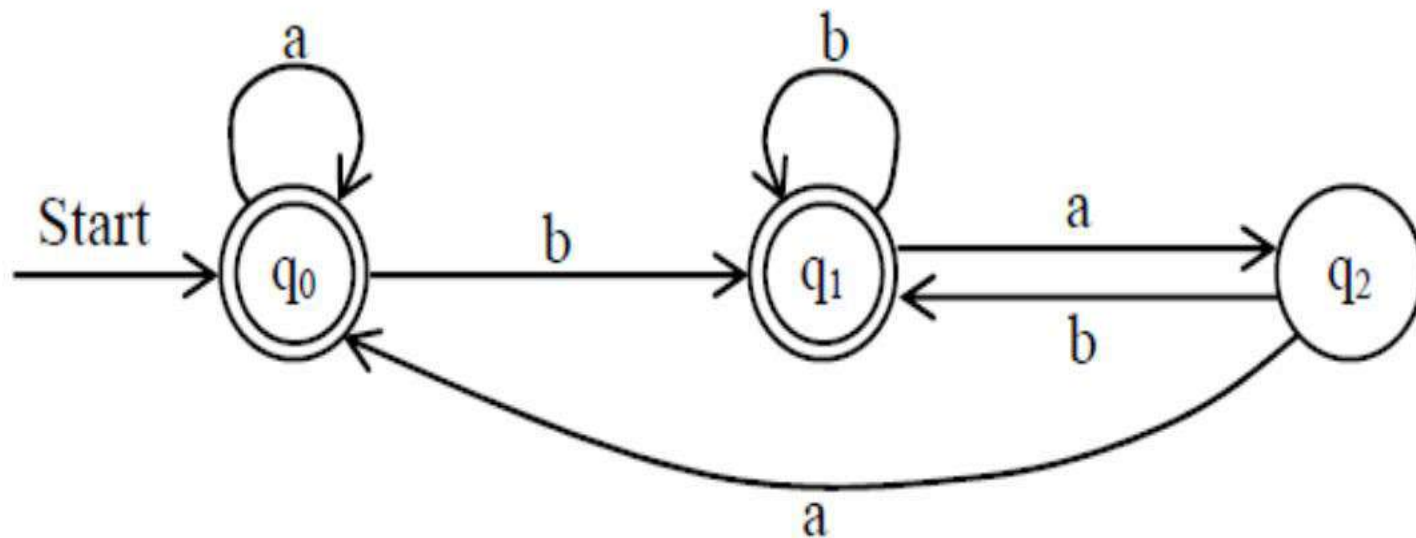
- Compute $\hat{\delta}(q_0, 1001)$
- Compute $\hat{\delta}_i(q_0, 100)$

Language of DFA

- The language of DFA $M = (Q, \Sigma, \delta, q_0, F)$ denoted by $L(M)$ is a set of strings over Σ^* that are accepted by M .
- i.e; $L(M) = \{w / \hat{\delta}_1(q_0, w) = p \in F\}$
- i.e. the language of a DFA is the set of all strings w that take DFA starting from start state to one of the accepting states.
- The language of DFA is called regular language.

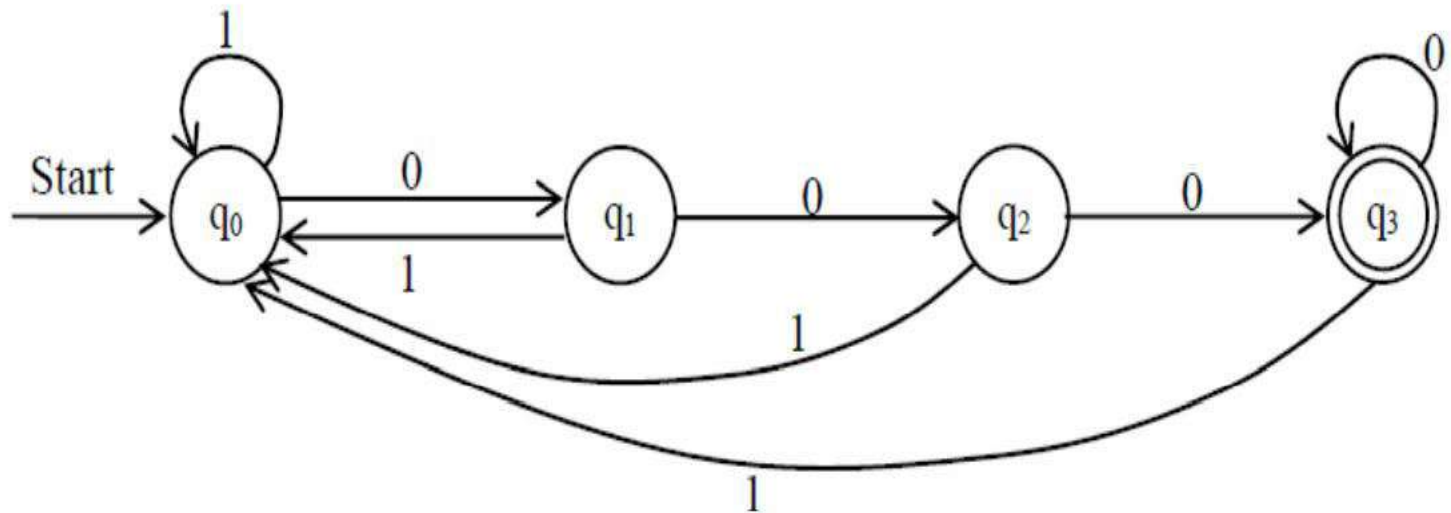
Examples

- Construct a DFA, that accepts all the strings over $\Sigma = \{a, b\}$ that do not end with ba .



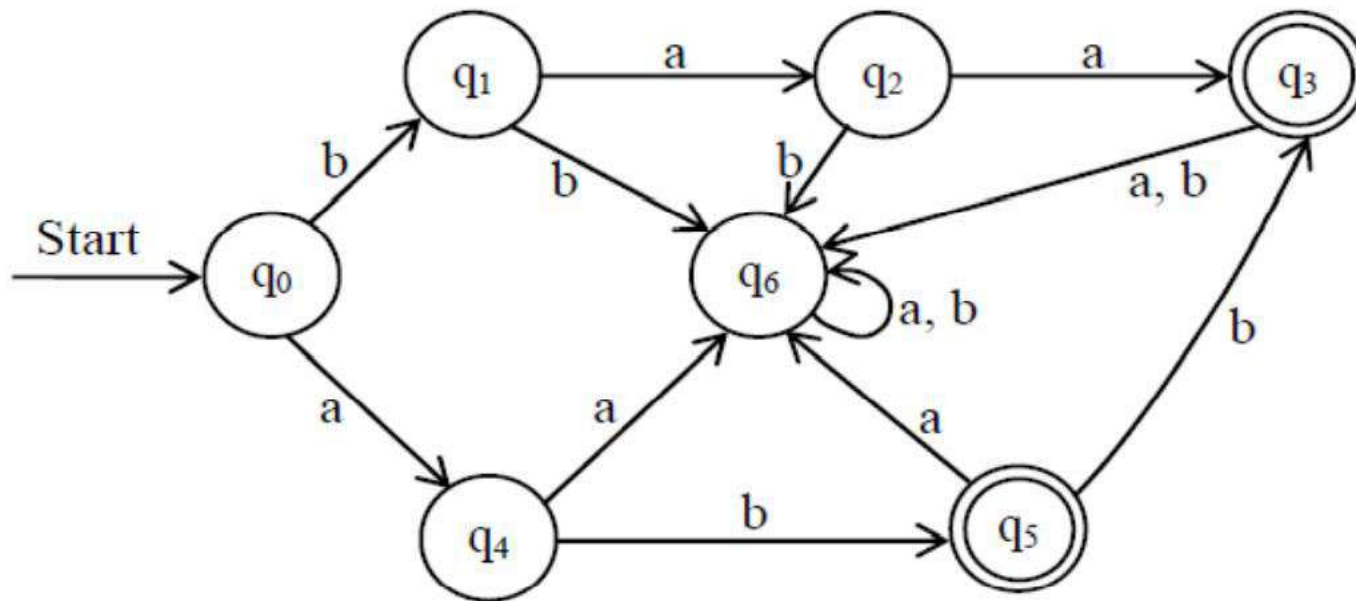
Examples

- DFA accepting all string over $\Sigma = \{0, 1\}$ ending with 3 consecutive 0"s.



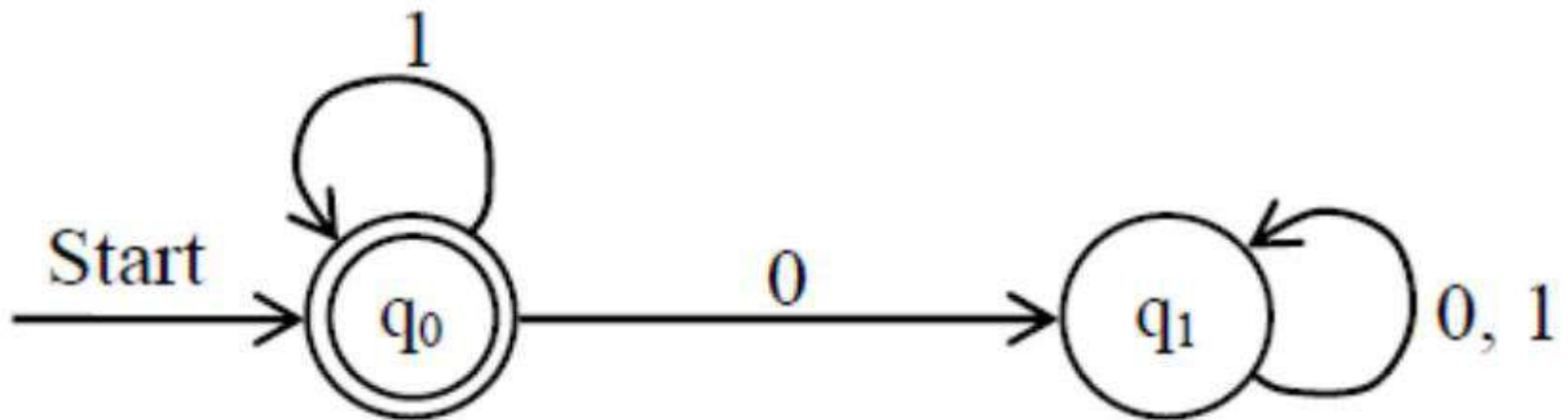
Examples

- DFA over $\{a, b\}$ accepting $\{baa, ab, abb\}$



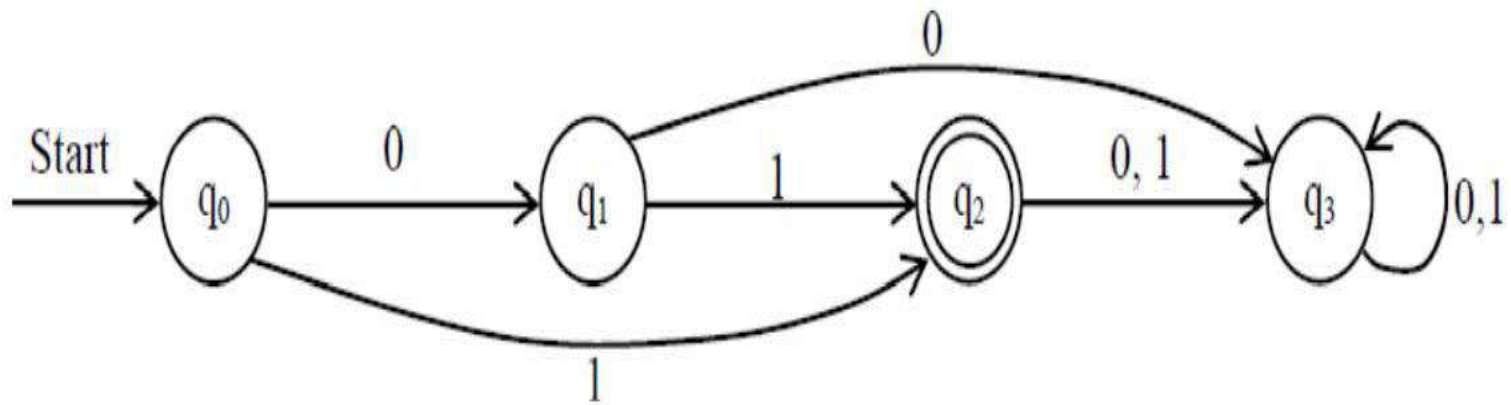
Examples

- DFA accepting zero or more consecutive 1's. i.e. $L(M) = \{1^n \mid n = 0, 1, 2, \dots\}$



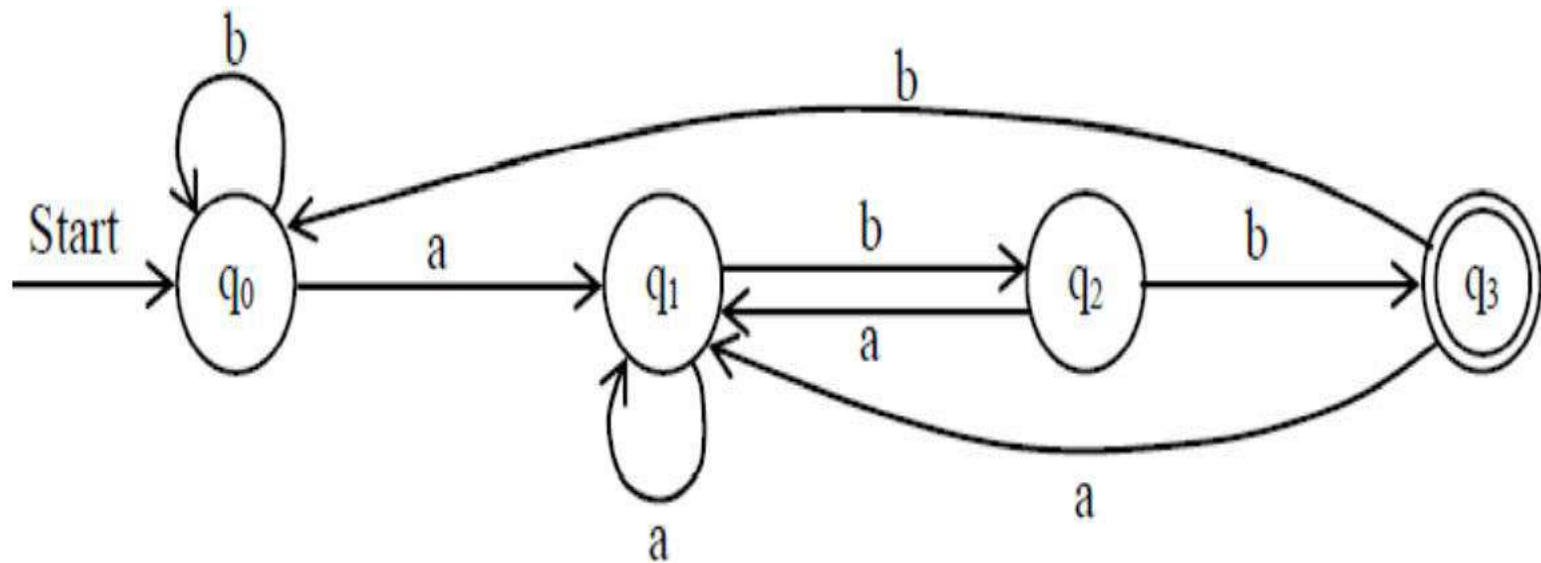
Examples

- DFA over $\{0, 1\}$ accepting $\{1, 01\}$



Examples

- DFA over $\{a, b\}$ that accepts the strings ending with abb.



Assignment-3

- Give the DFA for the language of string over $\{0,1\}$ in which each string end with 11
- Give the DFA accepting the string over $\{a,b\}$ such that each string does not end with ab.
- Give the DFA for the language of string over $\{a,b\}$ such that each string contain aba as substring
- Give the DFA for the language of string over $\{0,1\}$ such that each string start with 01
- Give the DFA for the language of string over $\{0,1\}$ such that set of all string ending in 00.
- Give the DFA for the language of string over $\{0,1\}$ such that set of strings with 011 as a substring.

Non-Deterministic Finite Automata (NFA)

- NFA can also be interpreted by a quintuple; $(Q, \Sigma, \delta, q_0, F)$
 - Where,
 - Q = A finite set of states
 - Σ = A finite set of input symbols, (alphabets)
 - δ = A transition function that maps state symbol pair to sets of states i.e. δ is $Q \times \Sigma \rightarrow 2^Q$
 - A state $q_0 \in Q$, that is distinguished as a start (initial) state.
 - A set of final states F distinguished as accepting (final) state. $F \subseteq Q$.
- Unlike DFA, a transition function in NFA takes the NFA from one state to several states just with a single input.

Non-Deterministic Finite Automata (NFA)

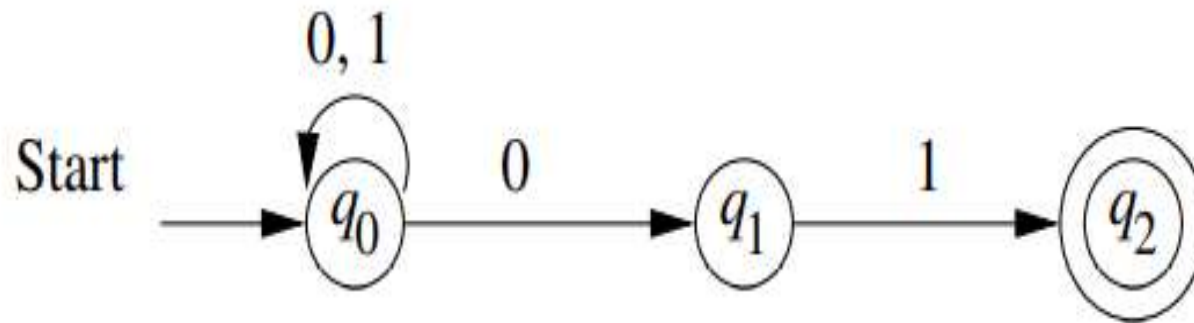
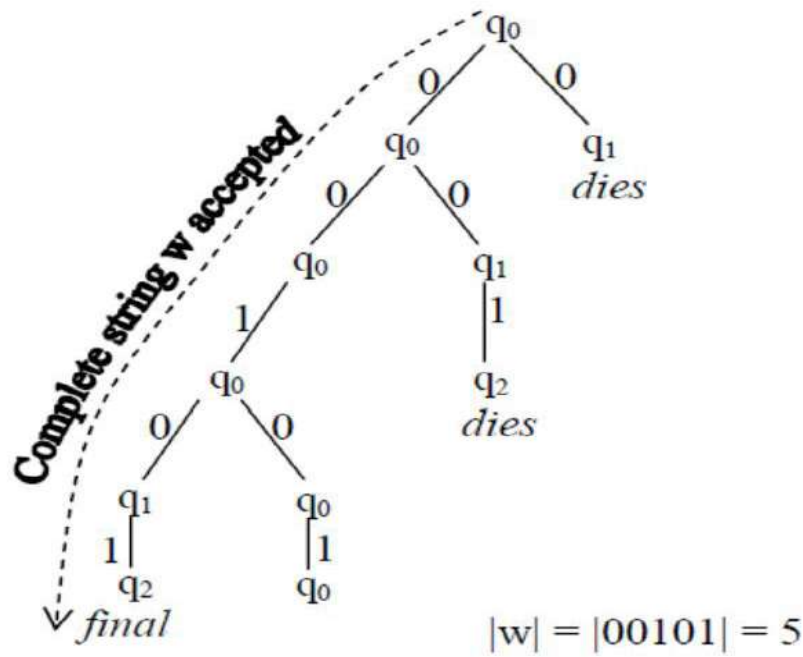


Fig: NFA accepting all strings that end in 01

Non-Deterministic Finite Automata (NFA)

- For input sequence $w = 00101$, the NFA can be in the states during the processing of the input are as:



$Q = \{q_0, q_1, q_2\}$

$\Sigma = \{0, 1\}$

$q_0 = \{q_0\}$

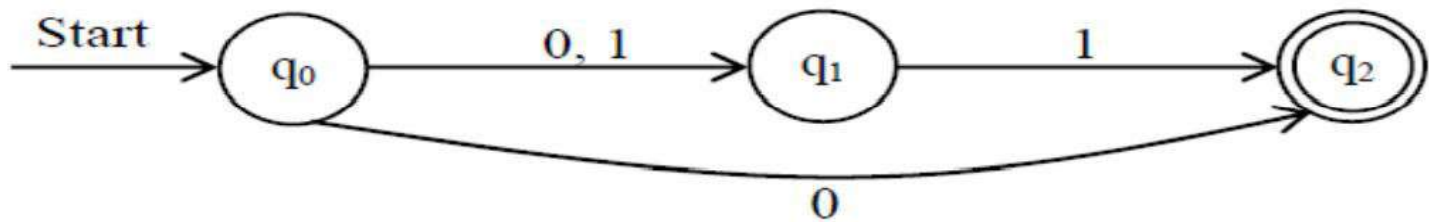
$F = \{q_2\}$

Transition table:

$\delta:$	0	1
$\rightarrow q_0$	$\{q_0, q_1\}$	$\{q_0\}$
q_1	$\{\phi\}$	$\{q_2\}$
$*q_2$	$\{\phi\}$	$\{\phi\}$

Non-Deterministic Finite Automata (NFA)

- NFA over $\{0, 1\}$ accepting strings $\{0, 01, 11\}$

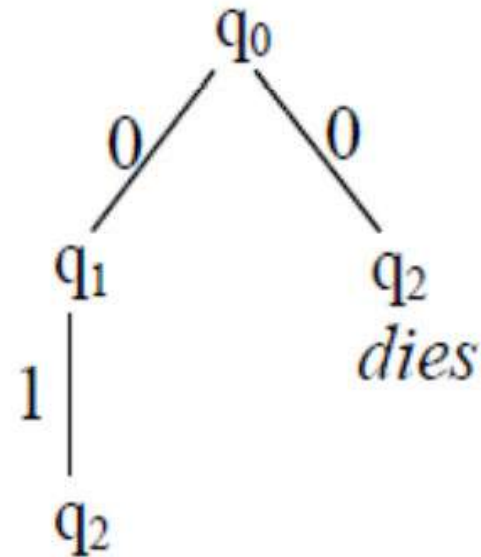


Transition table:

$\delta:$	0	1
$\rightarrow q_0$	$\{q_0, q_2\}$	$\{q_1\}$
q_1	$\{\phi\}$	$\{q_2\}$
$*q_2$	$\{\phi\}$	$\{\phi\}$

Non-Deterministic Finite Automata (NFA)

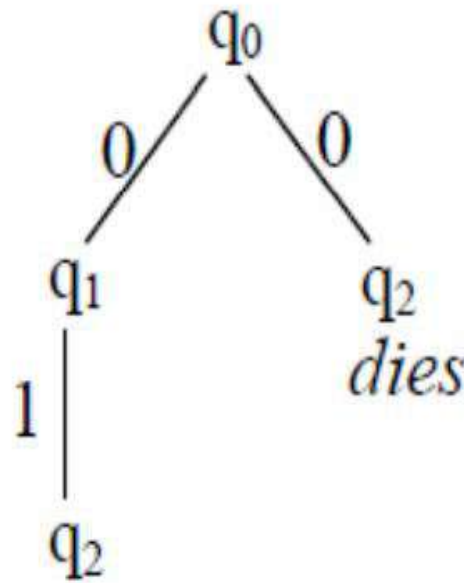
Computation tree for 01;



Final, so 01 is accepted

Non-Deterministic Finite Automata (NFA)

Computation tree for 0110



dies, so 0110 is not accepted

The Extended transition function of NFA

Definition by Induction:

- **Basis Step:**

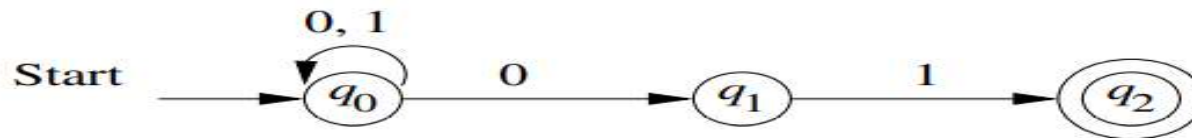
- $\hat{\delta}(q, \epsilon) = \{q\}$ i.e. reading no input symbol remains into the same state.

- **Induction:**

- Let w be a string from Σ^* such that $w = xa$, where x is a substring of without last symbol a .
- Also let, $\hat{\delta}(q, x) = \{p_1, p_2, p_3, \dots, p_k\}$
- and $\bigcup_{i=1}^k \delta(p_i, a) = \{r_1, r_2, \dots, r_m\}$
- Then, $\hat{\delta}(q, w) = \{r_1, r_2, r_3, \dots, r_m\}$
- Thus, to compute $\hat{\delta}(q, w)$ we first compute $\hat{\delta}(q, x)$ & then following any transition from each of these states with input a .

The Extended transition function of NFA

- Use of $\hat{\delta}$ for the processing of input 00101 by NFA



1. $\hat{\delta}(q_0, \epsilon) = \{q_0\}$.
2. $\hat{\delta}(q_0, 0) = \delta(q_0, 0) = \{q_0, q_1\}$.
3. $\hat{\delta}(q_0, 00) = \delta(q_0, 0) \cup \delta(q_1, 0) = \{q_0, q_1\} \cup \emptyset = \{q_0, q_1\}$.
4. $\hat{\delta}(q_0, 001) = \delta(q_0, 1) \cup \delta(q_1, 1) = \{q_0\} \cup \{q_2\} = \{q_0, q_2\}$.
5. $\hat{\delta}(q_0, 0010) = \delta(q_0, 0) \cup \delta(q_2, 0) = \{q_0, q_1\} \cup \emptyset = \{q_0, q_1\}$.
6. $\hat{\delta}(q_0, 00101) = \delta(q_0, 1) \cup \delta(q_1, 1) = \{q_0\} \cup \{q_2\} = \{q_0, q_2\}$.

Assignment-4

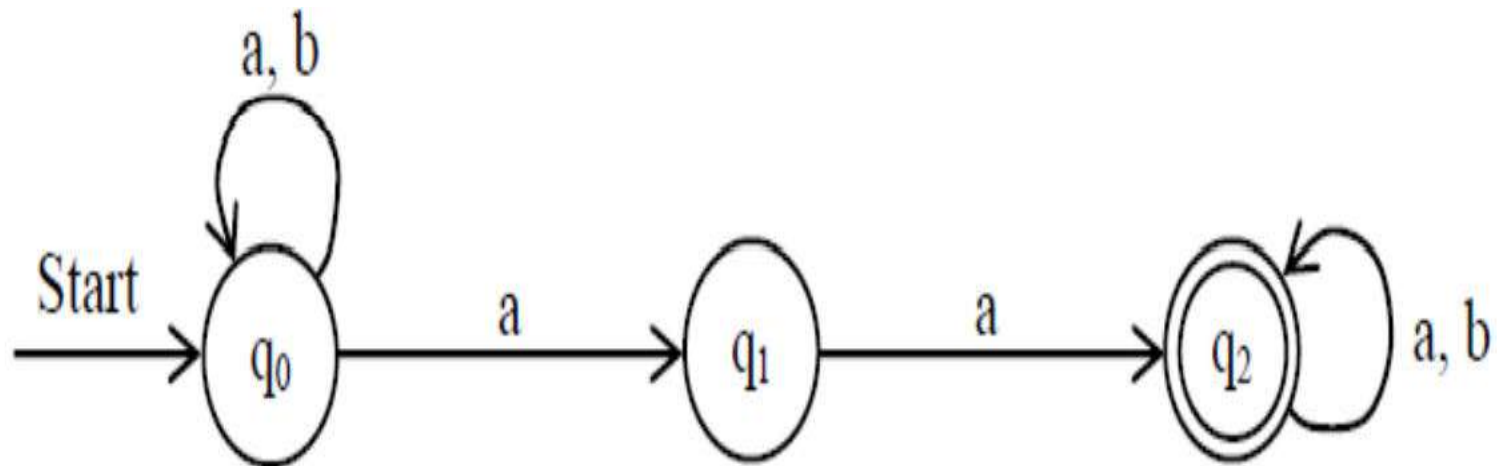
- compute for $\hat{\delta}(q_0, 01101)$
- Compute for $\hat{\delta}(q_0, 1101011)$
- Compute for $\hat{\delta}(q_0, 1010101)$

Language of NFA

- The language of NFA, $M = (Q, \Sigma, \delta, q_0, F)$, denoted by $L(M)$ is;
 - $L(M) = \{w / \hat{\delta}(q_0, w) \cap F \neq \varnothing\}$
 - i.e. $L(M)$ is the set of strings w in Σ^* such that $\hat{\delta}(q_0, w)$ contains at least one state accepting state.

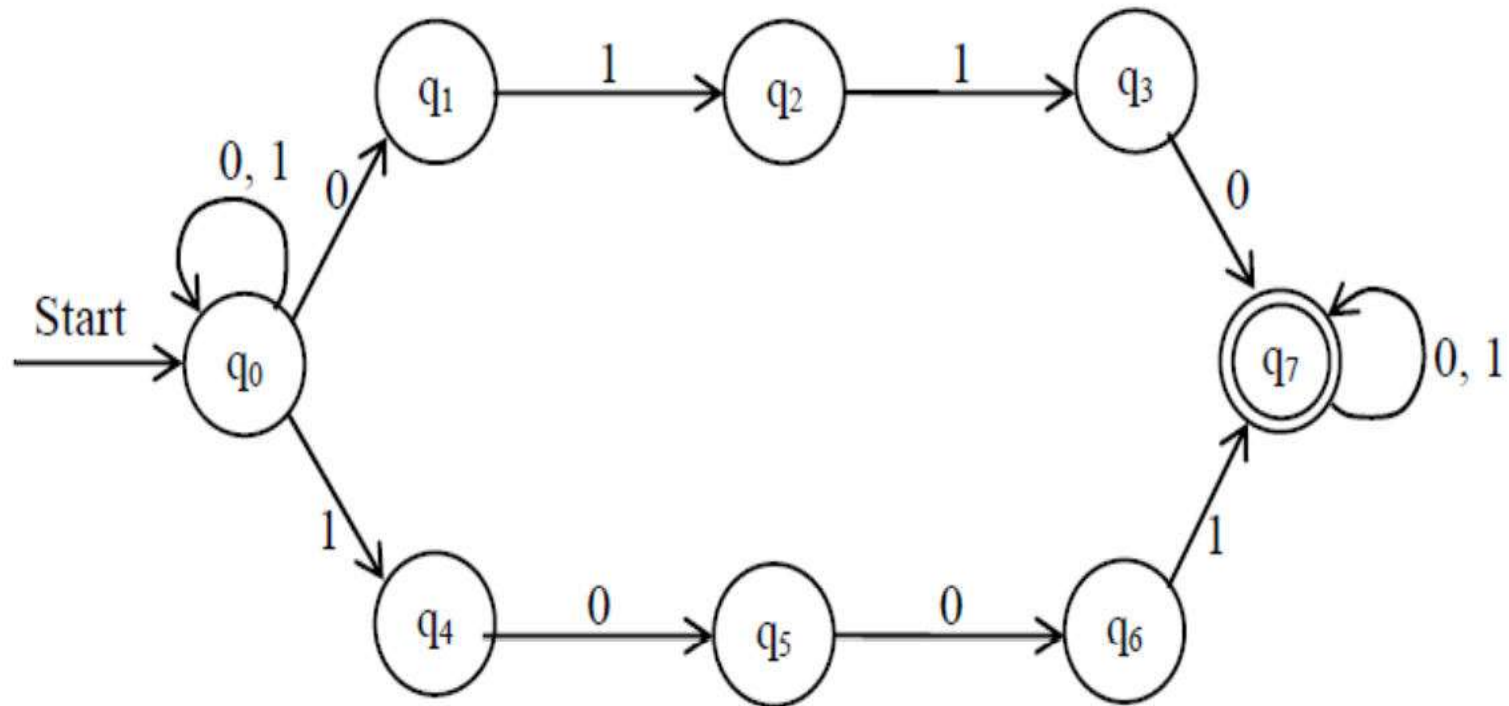
Examples

- Construct a NFA over $\{a, b\}$ that accepts strings having aa as substring.



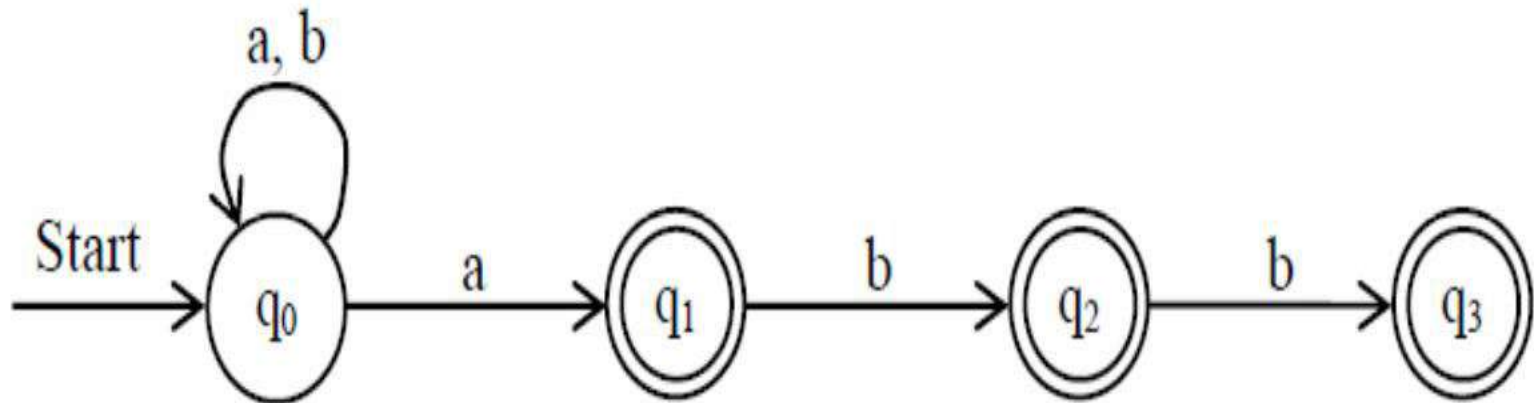
Examples

- NFA for strings over $\{0, 1\}$ that contain substring 0110 or 1001



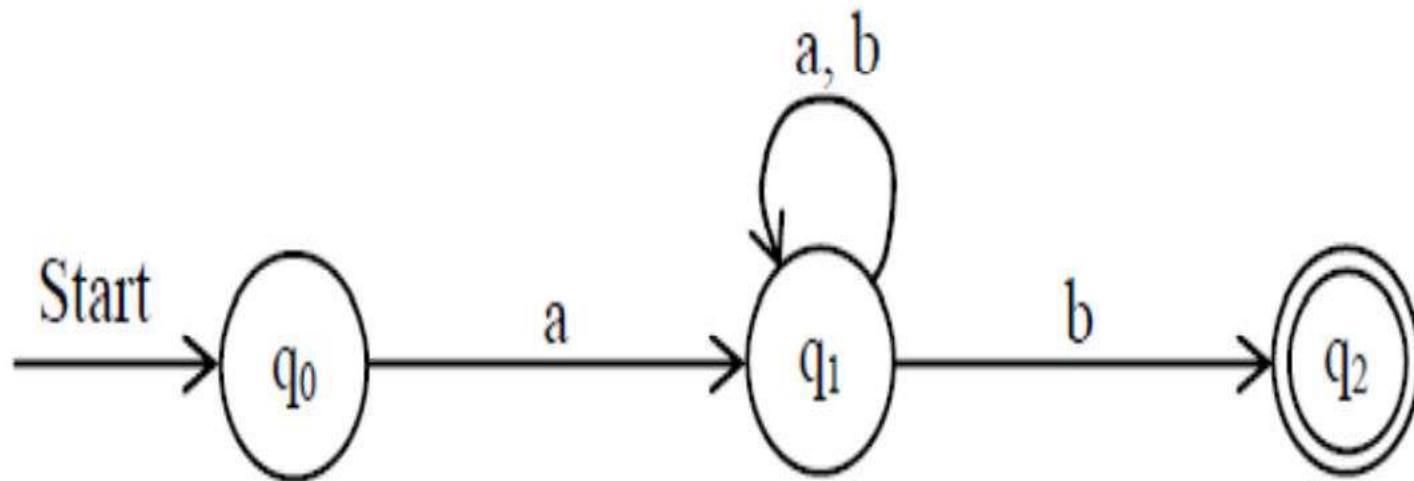
Examples

- NFA over $\{a, b\}$ that have “a” as one of the last 3 characters.



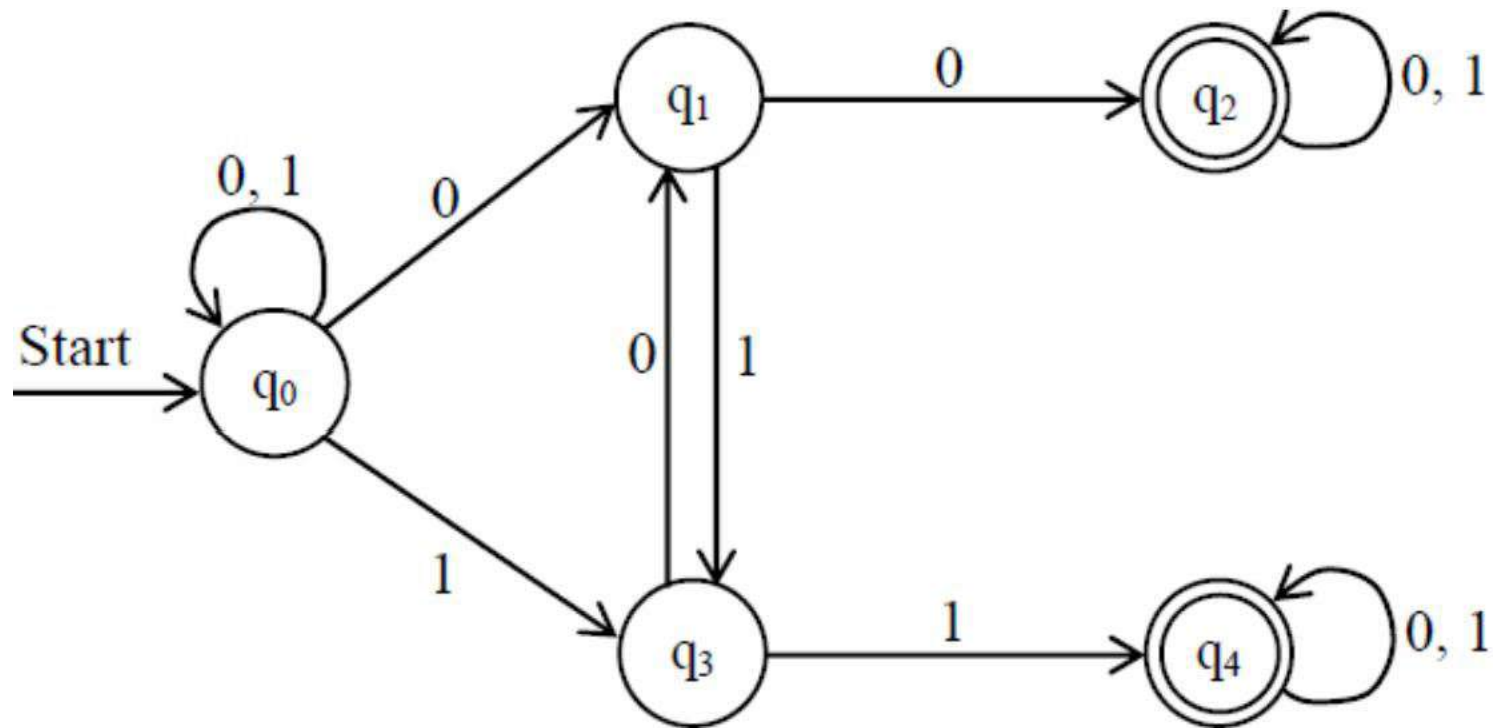
Examples

- NFA over $\{a, b\}$ that accepts strings starting with a and ending with b.



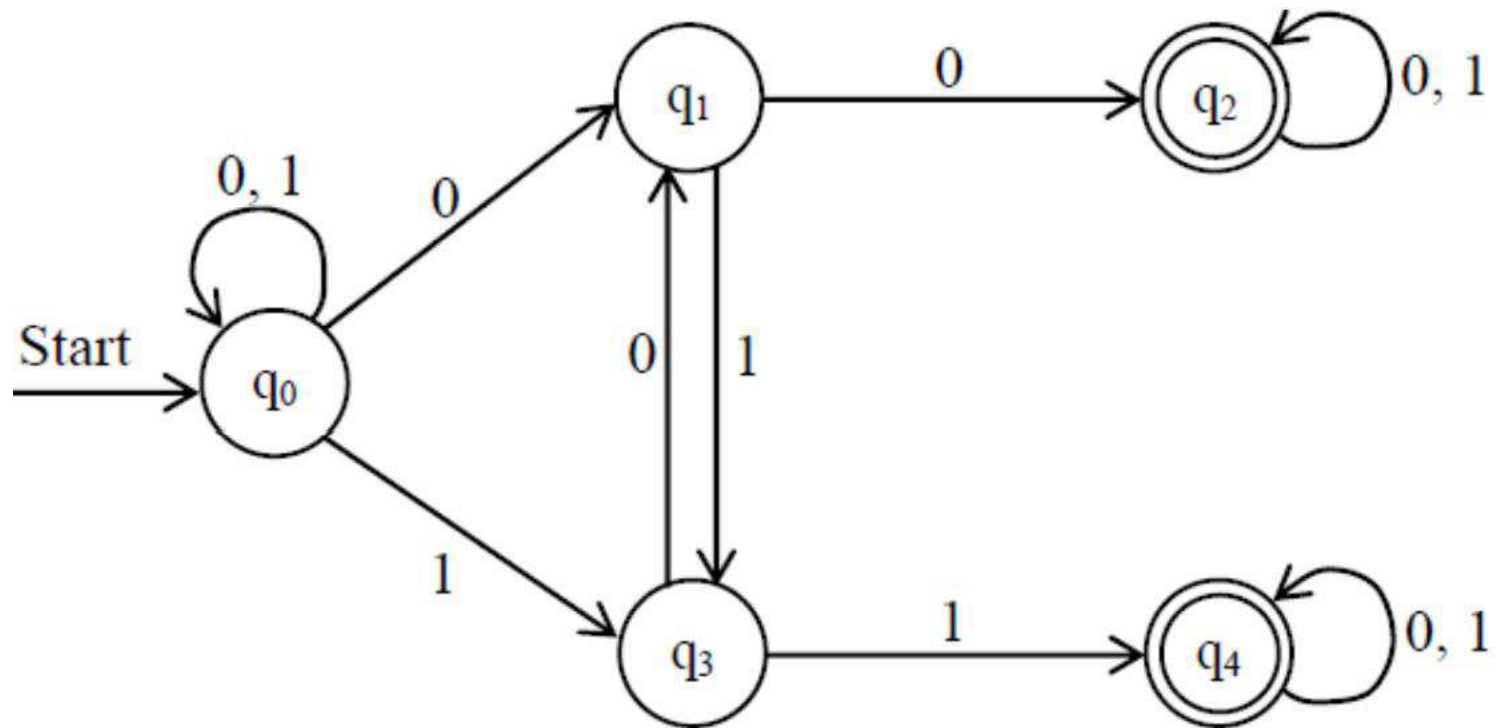
Examples

- Design a NFA for the language over $\{0, 1\}$ that have at least two consecutive 0's or 1's



Examples

- Design a NFA for the language over $\{0, 1\}$ that have at least two consecutive 0's or 1's



Assignment-5

- Give a NFA to accept the language of string over $\{a.b\}$ in which each string contain abb as substring.
- Give a NFA which accepts binary strings which have at least one pair of „00“ or one pair of „11“

Equivalence of DFA and NFA

- every language that can be described by some NFA can also be described by some DFA
- The proof that DFA's can do whatever NFA's can do involves an important construction called **subset construction** because it involves constructing all subsets of the set of states of the NFA.
- If NFA has n -states, the DFA can have 2^n states (at most), although it usually has many less.

Subset Construction Algorithm

- To convert a NFA, $N = (Q_N, \Sigma, \delta_N, q_0, F_N)$ into an equivalent DFA $D = (Q_D, \Sigma, \delta_D, q_0, F_D)$, we have following steps.
- The start state of D is the set of start states of N i.e. if q_0 is start state of N then D has start state as $\{q_0\}$.
- Q_D is set of subsets of Q_N i.e. $Q_D = 2^{Q_N}$. So, Q_D is power set of Q_N . So if Q_N has n states then Q_D will have 2_n states. However, all of these states may not be accessible from start state of Q_D so they can be eliminated. So Q_D will have less than 2_n states.

Subset Construction Algorithm

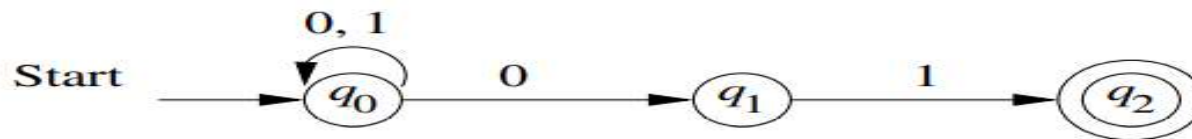
(Contd...)

- F_D is set of subsets S of Q_N such that $S \cap F_N \neq \emptyset$ i.e. F_D is all sets of N 's states that include at least one final state of N .
- For each set $S \subseteq Q_N$ & each input $a \in \Sigma$,

$$\delta_D(S, a) = \bigcup_{p \text{ in } S} \delta_N(p, a)$$

- i.e. to compute $\delta_D(S, a)$ we look all the states p in S , see what states N goes to from p on input a , and take the union of all those states.

Subset Construction Algorithm (Contd...)



	$\delta:$	0	1
A	ϕ	ϕ	ϕ
B	$\rightarrow \{q_0\}$	$\{q_0, q_1\}$	$\{q_0\}$
C	$\{q_1\}$	ϕ	$\{q_2\}$
D	$*\{q_2\}$	ϕ	ϕ
E	$\{q_0, q_1\}$	$\{q_0, q_1\}$	$\{q_0, q_2\}$
F	$*\{q_0, q_2\}$	$\{q_0, q_1\}$	$\{q_0\}$
G	$*\{q_1, q_2\}$	ϕ	$\{q_2\}$
H	$*\{q_0, q_1, q_2\}$	$\{q_0, q_1\}$	$\{q_0, q_2\}$

Table: Complete Subset construction of above NFA

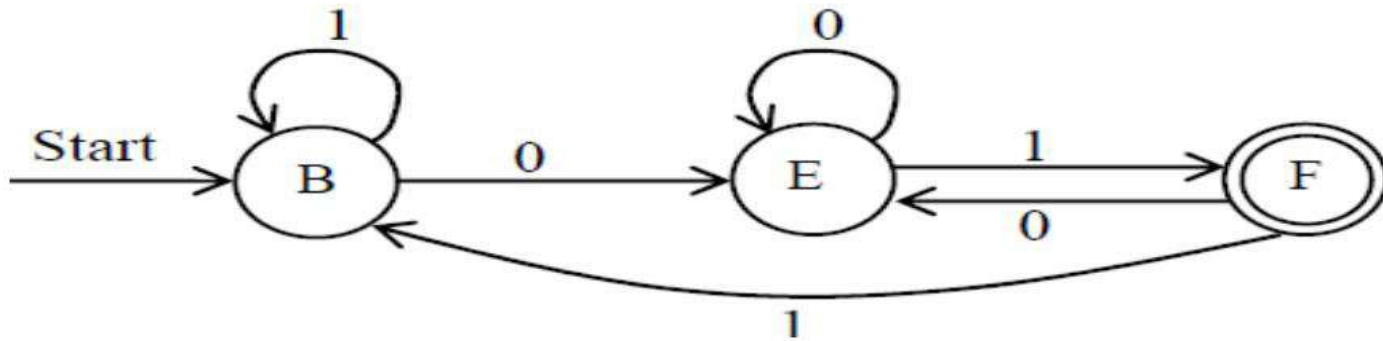
Reduction of NFA to DFA

- The same table(Previous slide) can be represented with renaming the state on table entry as

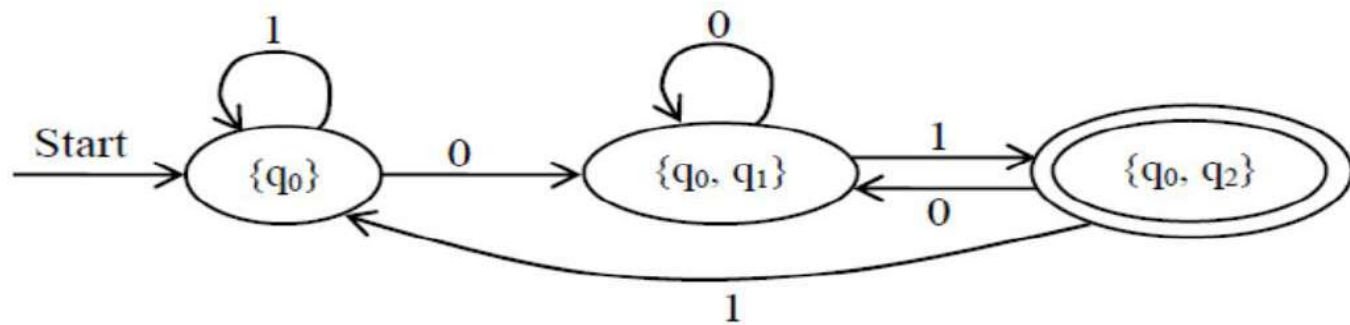
$\delta:$	0	1
A	A	A
$\rightarrow B$	E	B
C	A	D
*D	A	A
E	E	F
*F	E	B
*G	A	D
*H	E	F

Reduction of NFA to DFA

- The equivalent DFA is

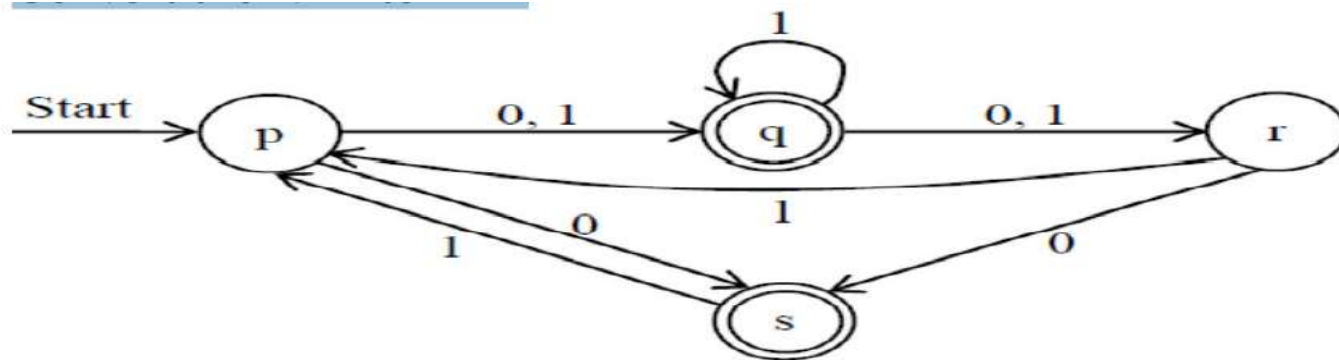


OR

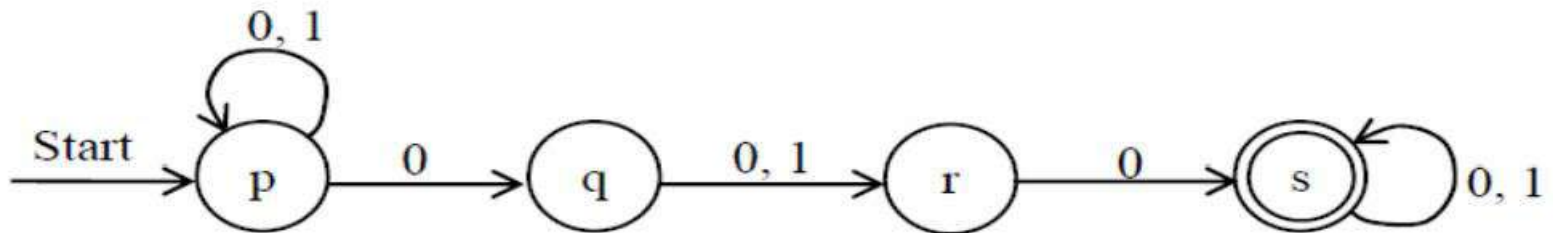


Assignment-6

- Convert the NFA to DFA

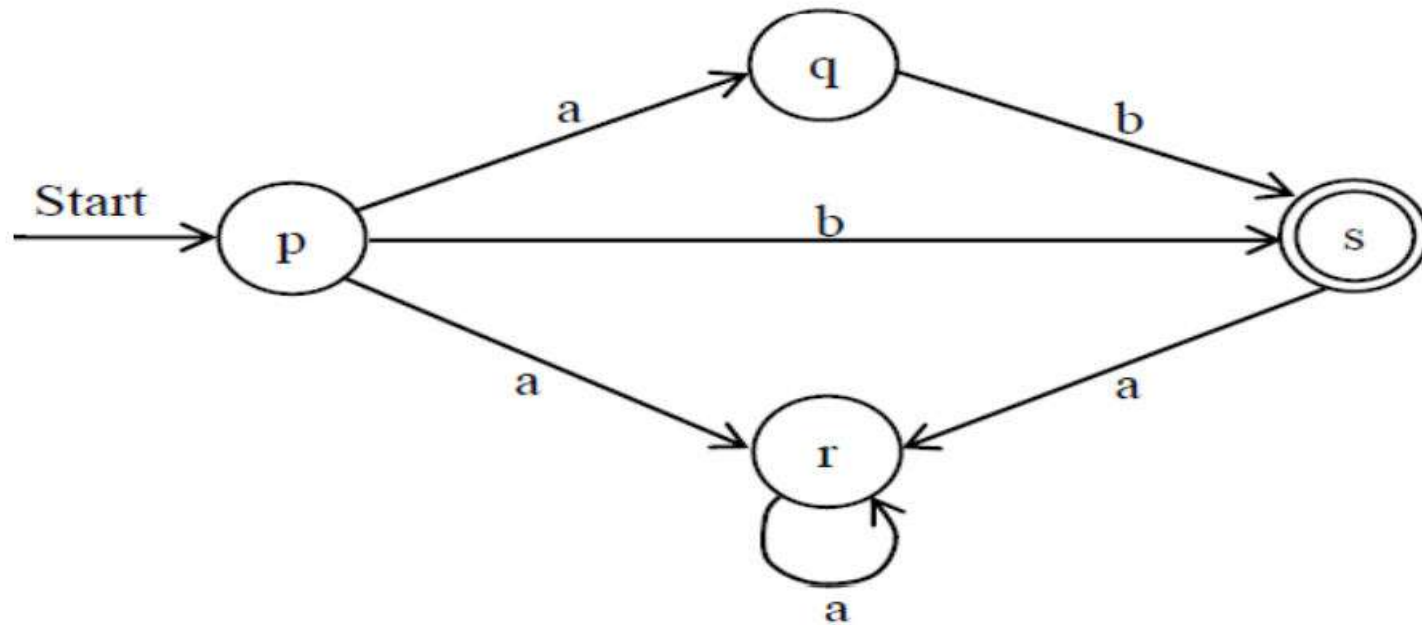


- Convert the NFA to DFA



Assignment-6

- Convert the NFA to DFA



Theorem 1

For any NFA, $N = (Q_N, \Sigma, \delta_N, q_0, F_N)$ accepting language $L \subseteq \Sigma^*$ there is a DFA $D = (Q_D, \Sigma, \delta_D, q_0', F_D)$ that also accepts L i.e. $L(N) = L(D)$.

Proof:

- The fact that D accepts the same language as N is as; for any string $w \in \Sigma^*$;

$$\hat{\delta}_N(q_0, w) = \hat{\delta}_D(q_0, w)$$

- Thus, we prove this fact by induction on length of w .

Theorem 1

- **Basis Step:**

- Let $|w| = 0$, then $w = \varepsilon$,

$$\hat{\delta}_N(q_0, \varepsilon) = \{q_0\} = q_0 = \hat{\delta}_D(q_0, \varepsilon)$$

- **Induction step:**

- Let $|w| = n + 1$ is a string such that $w = xa$ & $|x| = n$, $|a| = 1$; a being last symbol.
- Let the inductive hypothesis is that x satisfies.
- Thus,
 - $\hat{\delta}_D(q_0, x) = \hat{\delta}_N(q_0, x)$, let these states be $\{p_1, p_2, p_3, \dots p_k\}$

Theorem 1

Now,

$$\begin{aligned}
 \hat{\delta}_N(q_0, w) &= \hat{\delta}_N(q_0, xa) \\
 &= \delta_N(\hat{\delta}_N(q_0, x), a) \\
 &= \delta_N(\{p_1, p_2, p_3, \dots p_k\}, a) \text{ [Since, from inductive step]} \\
 &= \bigcup \delta_N(p_i, a) \dots \dots \dots (1)
 \end{aligned}$$

Also

$$\begin{aligned}
 \hat{\delta}_D(q_0', w) &= \hat{\delta}_D(q_0', xa) \\
 &= \delta_D(\hat{\delta}_D(q_0', x), a) \\
 &= \delta_D(\hat{\delta}_N(q_0, x), a) \text{ [Since, by the inductive step as it is true for x]} \\
 &= \delta_D(\{p_1, p_2, p_3, \dots p_k\}, a) \text{ [Since, from inductive step]}
 \end{aligned}$$

Theorem 1

- Now, from subset construction, we can write,
 - $\delta_D(\{p_1, p_2, p_3, \dots, p_k\}, a) = \cup \delta_N(p_i, a)$
- so, we have
 - $\hat{\delta}_D(q_0, w) = \cup \delta_N(p_i, a) \dots \dots \dots (2)$
- Now we conclude from 1 and 2 that
$$\hat{\delta}_N(q_0, w) = \hat{\delta}_D(q_0', w)$$
- Hence, if this relation is true for $|x| = n$, then it is also true for $|w| = n + 1$.

\therefore DFA D & NFA N accepts the same language.

i.e. $L(D) = L(N)$ Proved.

Theorem 2

A language L is accepted by some DFA if and only if L is accepted by some NFA.

Proof:

- **“if” part** (A language is accepted by some DFA if L is accepted by some NFA):
 - It is the subset construction and is proved in previous theorem.
- **Only if part** (a language is accepted by some NFA if L is accepted by some DFA):
 - Here we have to convert the DFA into an identical NFA.
 - To show if L is accepted by D then it is also accepted by N
 - it is sufficient to show, for any string $w \in \Sigma^*$,
 - $\hat{\delta}_D(q_0, w) = \hat{\delta}_N(q_0, w)$

Theorem 2

- We can proof this fact using induction on length of the string
- **Basis step:**
 - Let $|w| = 0$ i.e. $w = \varepsilon$
 - $\therefore \hat{\delta}_D(q_0, w) = \hat{\delta}_D(q_0, \varepsilon) = q_0$
 - $\hat{\delta}_N(q_0, w) = \hat{\delta}_N(q_0, \varepsilon) = \{q_0\}$
 - $\therefore \hat{\delta}_D(q_0, w) = \hat{\delta}_N(q_0, w)$ for $|w| = 0$ is true.
- **Induction:**
 - Let $|w| = n + 1$ & $w = xa$. Where $|x| = n$ & $|a| = 1$; a being the last symbol.
 - Let the inductive hypothesis is that it is true for x .
 - \therefore if $\hat{\delta}_D(q_0, x) = p$, then $\hat{\delta}_N(q_0, x) = \{p\}$
 - i.e. $\hat{\delta}_D(q_0, x) = \hat{\delta}_N(q_0, x)$

Theorem 2

Now,

$$\begin{aligned}\hat{\delta}_D(q_0, w) &= \hat{\delta}_D(q_0, xa) \\ &= \delta_D(\hat{\delta}_D(q_0, x), a) \\ &= \delta_D(p, a) \text{ [from inductive step } \hat{\delta}_D(q_0, x)=p] \\ &= r, \text{ say}\end{aligned}$$

Now,

$$\begin{aligned}\hat{\delta}_N(q_0, w) &= \hat{\delta}_N(q_0, xa) \\ &= \delta_N(\hat{\delta}_N(q_0, x), a) \text{ [from inductive steps]} \\ &= \delta_N(\{p\}, a) \\ &= r \text{ [from the rule that define } \delta_N]\end{aligned}$$

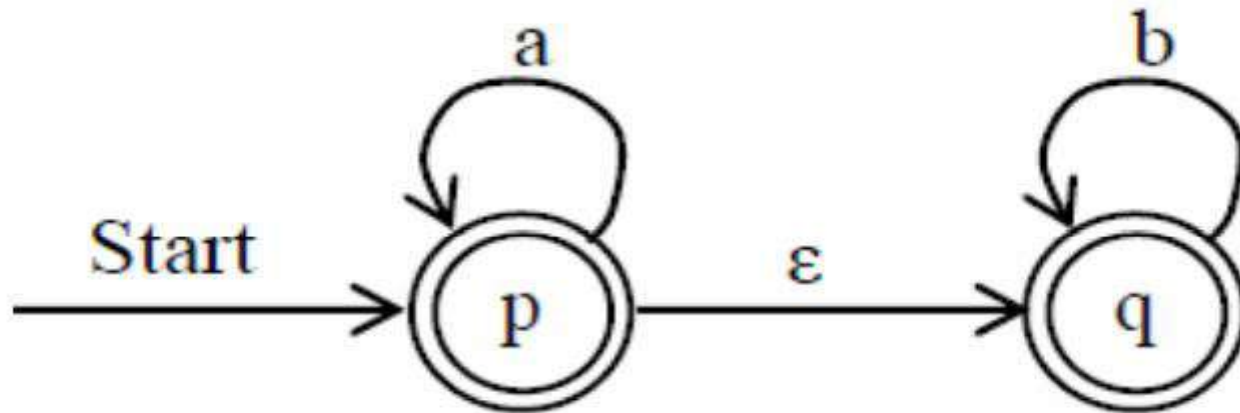
Hence proved. i.e. $\hat{\delta}_D(q_0, w) = \hat{\delta}_N(q_0, w)$

Finite Automaton with Epsilon Transition (ϵ - NFA)

- A NFA with ϵ -transition is defined by five tuples $(Q, \Sigma, \delta, q_0, F)$, where;
 - Q = set of finite states
 - Σ = set of finite input symbols
 - q_0 = Initial state, $q_0 \in Q$
 - F = set of final states; $F \subseteq Q$
 - δ = a transition function that maps; $Q \times \Sigma \cup \{\epsilon\} \rightarrow 2^Q$

Finite Automaton with Epsilon Transition (ϵ - NFA)

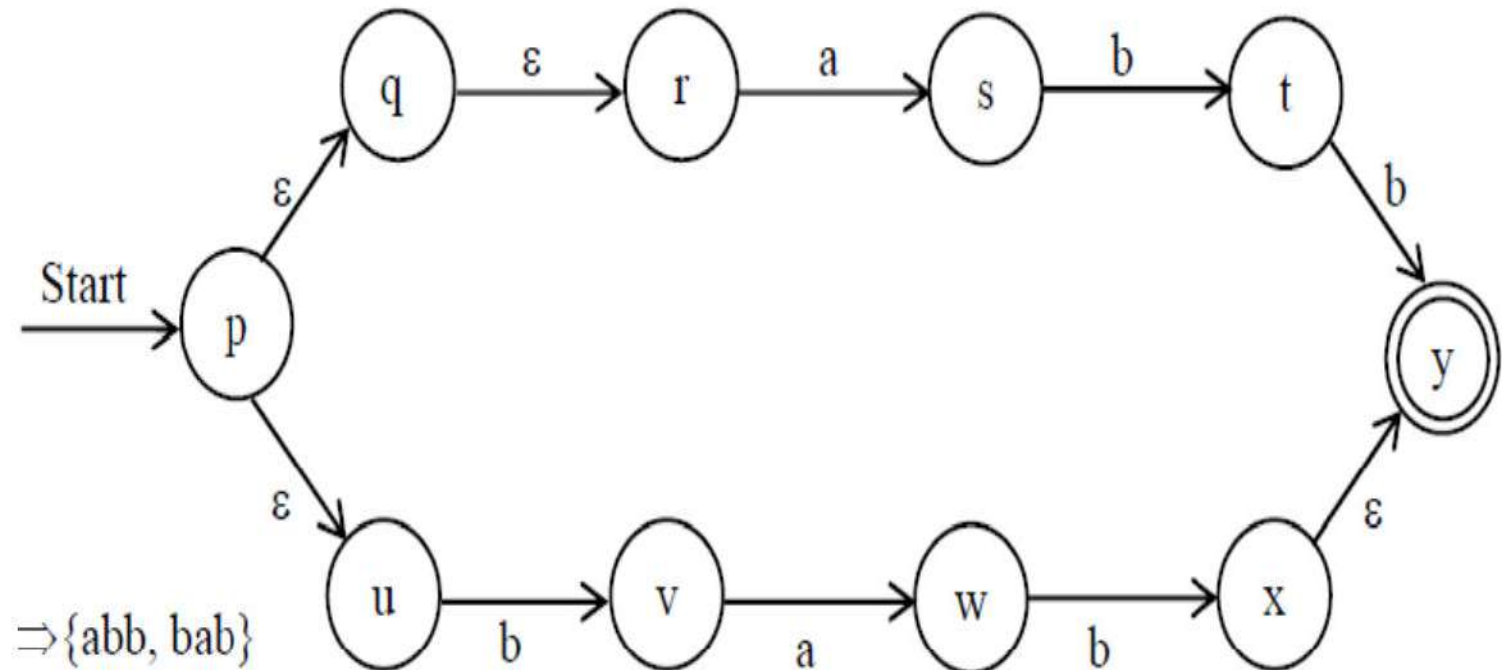
- **Examples:**



- This accepted the language
 $\{a, aa, ab, abb, b, bbb, \dots\}$

Finite Automaton with Epsilon Transition (ϵ - NFA)

- **Examples**



Exercise

- Design ϵ -NFA for the following languages
 - The set of strings consisting of zero or more a's followed by zero or more b's , followed by zero or more c's.
 - The set of strings that consists of either 01 repeated one or more times or 010 repeated one or more times.

Epsilon Closure of a State

- ϵ -closure of a state 'q' can be obtained by following all transitions out of q that are labeled ϵ .
- Formally, we can define ϵ -closure of the state q as;
- **Basis:** state q is in ϵ -closure (q).
- **Induction:** If state q is reached with ϵ -transition from state p then, p is in ϵ -closure (q). And if there is an arc from p to r labeled ϵ , then r is in ϵ -closure (q) and so on.
- If δ is the transition function of ϵ -NFA involved, and p is in ϵ -closure (q), then ϵ -closure (q) also contains all the states in $\delta(p, \epsilon)$.

Epsilon Closure of a State

- Example:

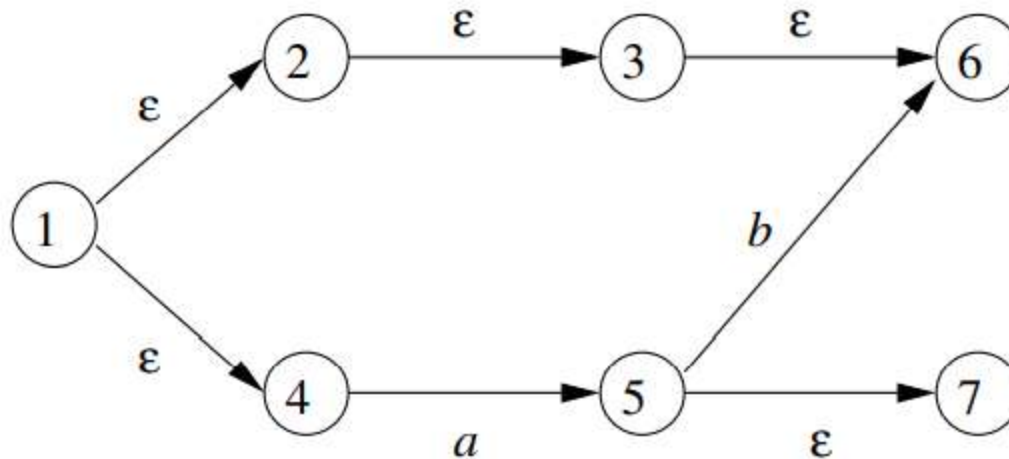


Fig: Some states and transitions

- $\epsilon\text{-closure}(1) = \{1, 2, 3, 4, 6\}$

Extended Transition Function of ϵ -NFA

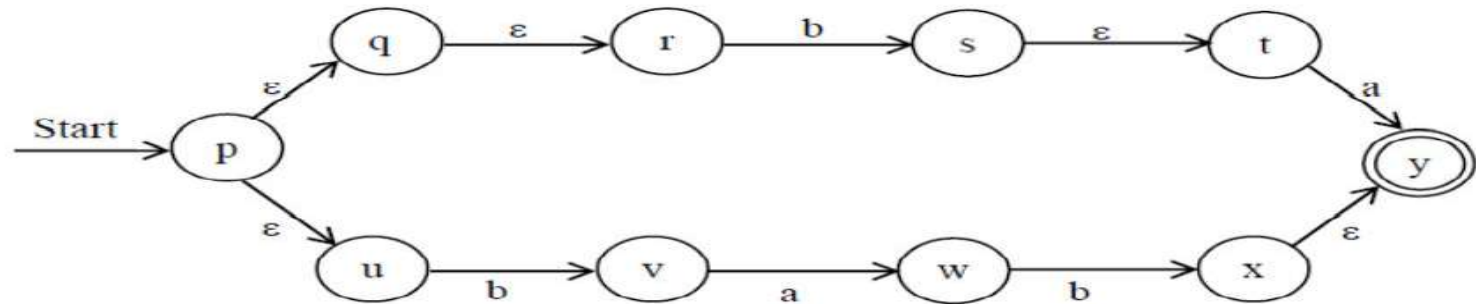
- **BASIS STEP**

- $\hat{\delta}(q, \epsilon) = \epsilon\text{-closure}(q)$

- **INDUCTION STEP**

- Let $w = xa$ be a string, where x is substring of w without last symbol a and $a \in \Sigma$ but $a \neq \epsilon$.
- Let $\hat{\delta}(q, x) = \{p_1, p_2, \dots, p_k\}$ i.e. p_i 's are the states that can be reached from q following path labeled x which can end with many ϵ & can have many ϵ .
- Also Let, $\bigcup_{i=1}^k \delta(p_i, a)$ be the set $\{r_1, r_2, r_3, \dots, r_m\}$
- Then, $\hat{\delta}(q, w) = \epsilon\text{-closure}(\{r_1, r_2, r_3, \dots, r_m\})$

Extended Transition Function of ϵ -NFA



compute for string ba

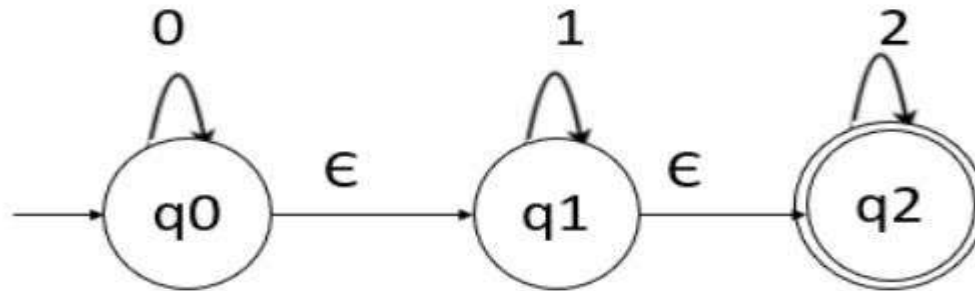
- $\hat{\delta}(p, \epsilon) = \epsilon\text{-closure}(p) = \{p, q, r, u\}$
- Compute for b
 - i.e. $\delta(p, b) \cup \delta(q, b) \cup \delta(r, b) \cup \delta(u, b) = \{s, v\}$
 - $\epsilon\text{-closure}(s) \cup \epsilon\text{-closure}(v) = \{s, t, v\}$
- Computer for next input 'a'
 - $\delta(s, a) \cup \delta(t, a) \cup \delta(v, a) = \{y, w\}$
 - $\epsilon\text{-closure}(y) \cup \epsilon\text{-closure}(w) = \{y, w\}$
- The final result set contains the one of the final state so the string is accepted.

Removing Epsilon Transition using the concept of Epsilon Closure

- **Step 1** – Find out all the ϵ -transitions from each state from Q . That will be called as ϵ -closure(q_i) where, $q_i \in Q$.
- **Step 2** – Then, δ^1 transitions can be obtained. The δ^1 transitions means an ϵ -closure on δ moves.
- **Step 3** – Step 2 is repeated for each input symbol and for each state of given NFA.
- **Step 4** – By using the resultant status, the transition table for equivalent NFA without ϵ can be built.
- NFA with ϵ to without ϵ is as follows –
 - $\delta^1(q, a) = \epsilon\text{-closure}(\delta(\delta^*(q, \epsilon), a))$
where, $\delta^*(q, \epsilon) = \epsilon\text{-closure}(q)$

Removing Epsilon Transition using the concept of Epsilon Closure

- Convert the given NFA with epsilon to NFA without epsilon.



- We will first obtain ϵ -closure of each state
 - $\epsilon\text{-closure}(q_0) = \{q_0, q_1, q_2\}$
 - $\epsilon\text{-closure}(q_1) = \{q_1, q_2\}$
 - $\epsilon\text{-closure}(q_2) = \{q_2\}$

Removing Epsilon Transition using the concept of Epsilon Closure

- Now we will obtain δ_1 transitions for each state on each input symbol
 - $\delta_1(q_0, 0) = \epsilon\text{-closure}(\delta(\delta^*(q_0, \epsilon), 0))$
 - $= \epsilon\text{-closure}(\delta(\epsilon\text{-closure}(q_0), 0))$
 - $= \epsilon\text{-closure}(\delta(q_0, q_1, q_2), 0)$
 - $= \epsilon\text{-closure}(\delta(q_0, 0) \cup \delta(q_1, 0) \cup \delta(q_2, 0))$
 - $= \epsilon\text{-closure}(q_0 \cup \Phi \cup \Phi)$
 - $= \epsilon\text{-closure}(q_0) = \{q_0, q_1, q_2\}$
 - $\delta'(q_0, 1) = \epsilon\text{-closure}(\delta(\delta^*(q_0, \epsilon), 1))$
 - $= \epsilon\text{-closure}(\delta(q_0, q_1, q_2), 1)$
 - $= \epsilon\text{-closure}(\delta(q_0, 1) \cup \delta(q_1, 1) \cup \delta(q_2, 1))$
 - $= \epsilon\text{-closure}(\Phi \cup q_1 \cup \Phi)$
 - $= \epsilon\text{-closure}(q_1)$
 - $= \{q_1, q_2\}$

Removing Epsilon Transition using the concept of Epsilon Closure

- $\delta_1(q_0, 2) = \epsilon\text{-closure}(\delta(\delta^*(q_0, \epsilon), 2))$
 - $= \epsilon\text{-closure}(\delta(q_0, q_1, q_2), 2)$
 - $= \epsilon\text{-closure}(\delta(q_0, 2) \cup \delta(q_1, 2) \cup \delta(q_2, 2))$
 - $= \epsilon\text{-closure}(\Phi \cup \Phi \cup q_2)$
 - $= \epsilon\text{-closure}(q_2)$
 - $= \{q_2\}$
- $\delta_1(q_1, 0) = \epsilon\text{-closure}(\delta(\delta^*(q_1, \epsilon), 0))$
 - $= \epsilon\text{-closure}(\delta(q_1, q_2), 0)$
 - $= \epsilon\text{-closure}(\delta(q_1, 0) \cup \delta(q_2, 0))$
 - $= \epsilon\text{-closure}(\Phi \cup \Phi)$
 - $= \epsilon\text{-closure}(\Phi)$
 - $= \Phi$

Removing Epsilon Transition using the concept of Epsilon Closure

- $\delta_1(q_1, 1) = \epsilon\text{-closure}(\delta(\delta^+(q_1, \epsilon), 1))$
 - $= \epsilon\text{-closure}(\delta(q_1, q_2), 1)$
 - $= \epsilon\text{-closure}(\delta(q_1, 1) \cup \delta(q_2, 1))$
 - $= \epsilon\text{-closure}(q_1 \cup \Phi)$
 - $= \epsilon\text{-closure}(q_1)$
 - $= \{q_1, q_2\}$
- $\delta_1(q_1, 2) = \epsilon\text{-closure}(\delta(\delta^+(q_1, \epsilon), 2))$
 - $= \epsilon\text{-closure}(\delta(q_1, q_2), 2)$
 - $= \epsilon\text{-closure}(\delta(q_1, 2) \cup \delta(q_2, 2))$
 - $= \epsilon\text{-closure}(\Phi \cup q_2)$
 - $= \epsilon\text{-closure}(q_2)$
 - $= \{q_2\}$

Removing Epsilon Transition using the concept of Epsilon Closure

- $\delta_1(q_2, 0) = \epsilon\text{-closure}(\delta(\delta^*(q_2, \epsilon), 0))$
 - $= \epsilon\text{-closure}(\delta(q_2), 0)$
 - $= \epsilon\text{-closure}(\delta(q_2, 0))$
 - $= \epsilon\text{-closure}(\Phi)$
 - $= \Phi$
- $\delta_1(q_2, 1) = \epsilon\text{-closure}(\delta(\delta^*(q_2, \epsilon), 1))$
 - $= \epsilon\text{-closure}(\delta(q_2), 1)$
 - $= \epsilon\text{-closure}(\delta(q_2, 1))$
 - $= \epsilon\text{-closure}(\Phi)$
 - $= \Phi$
- $\delta_1(q_2, 2) = \epsilon\text{-closure}(\delta(\delta^*(q_2, \epsilon),))$
 - $= \epsilon\text{-closure}(\delta(q_2), 2))$
 - $= \epsilon\text{-closure}(\delta(q_2, 2))$
 - $= \epsilon\text{-closure}(q_2)$
 - $= \{q_2\}$

Removing Epsilon Transition using the concept of Epsilon Closure

- summarize all the computed δ_1 transitions as given below –
 - $\delta_1(q_0, 0) = \{q_0, q_1, q_2\}$
 - $\delta_1(q_0, 1) = \{q_1, q_2\}$
 - $\delta_1(q_0, 2) = \{q_2\}$

 - $\delta_1(q_1, 0) = \{ \Phi \}$
 - $\delta_1(q_1, 1) = \{q_1, q_2\}$
 - $\delta_1(q_1, 2) = \{q_2\}$

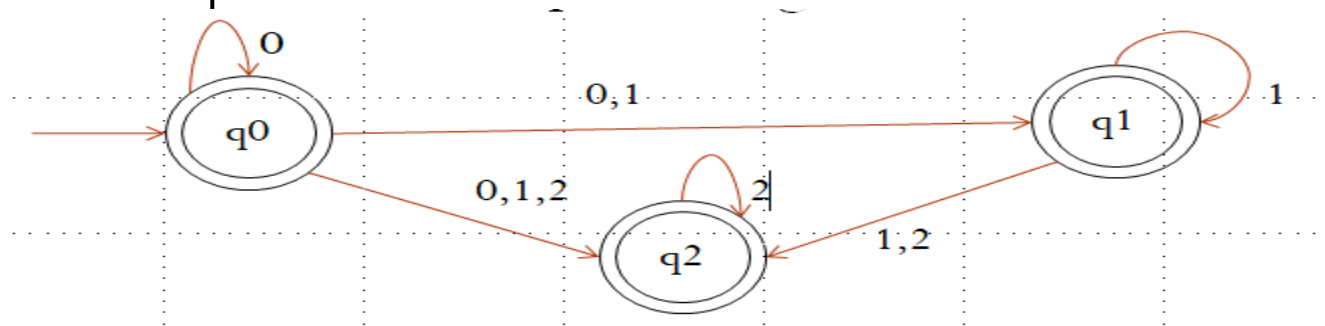
 - $\delta_1(q_2, 0) = \{ \Phi \}$
 - $\delta_1(q_2, 1) = \{ \Phi \}$
 - $\delta_1(q_2, 2) = \{q_2\}$

Removing Epsilon Transition using the concept of Epsilon Closure

- The **transition table** is given below –

States/Inputs	0	1	2
q0	{q0,q1,q2}	{q1,q2}	{q2}
q1	Φ	{q1,q2}	{q2}
q2	Φ	Φ	{q2}

- The NFA without epsilon is given below – Here, q0, q1, q2 are final states because ϵ -closure(q0), ϵ -closure(q1) and ϵ -closure(q2) contain a final state q2.



Equivalence of NFA and ϵ – NFA

- every language that can be described by some NFA can also be described by some ϵ -NFA.

Equivalence of DFA and ϵ – NFA

- every language that can be described by some DFA can also be described by some ϵ -NFA.

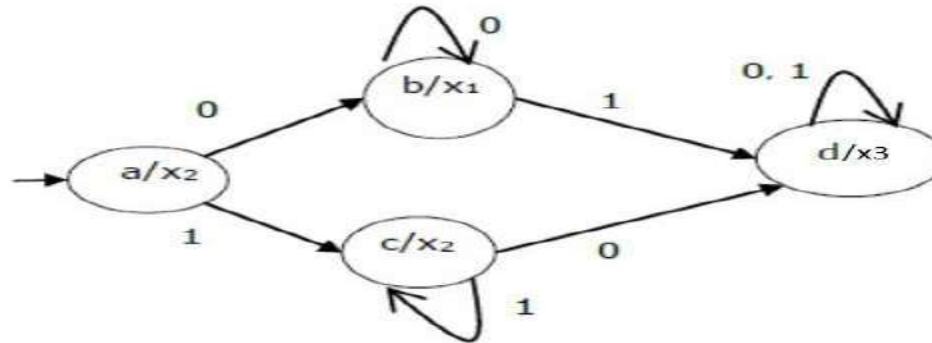
Finite State Machines with output

- Finite automata may have outputs corresponding to each transition.
- There are two types of finite state machines that generate output —
 - Moore machine
 - Mealy Machines

Moore Machine

- Moore machine is an FSM whose outputs depend on only the present state.
- A Moore machine can be described by a 6 tuple $(Q, \Sigma, O, \delta, X, q_0)$ where –
 - Q is a finite set of states.
 - Σ is a finite set of symbols called the input alphabet.
 - O is a finite set of symbols called the output alphabet.
 - δ is the input transition function where $\delta: Q \times \Sigma \rightarrow Q$
 - X is the output transition function where $X: Q \rightarrow O$
 - q_0 is the initial state from where any input is processed ($q_0 \in Q$).

Moore Machine

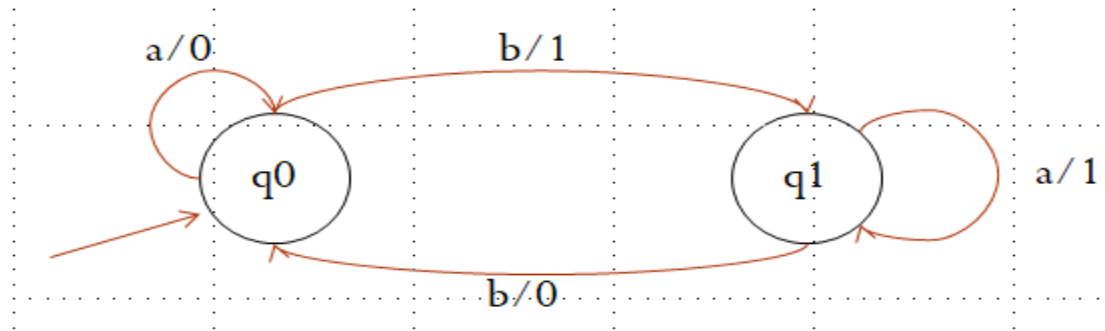


Present State	Next State		Output
	Input = 0	Input = 1	
→ a	b	c	x2
b	b	d	x1
c	d	c	x2
d	d	d	x3

Mealy Machine

- A Mealy Machine is an FSM whose output depends on the present state as well as the present input.
- It can be described by a 6 tuple $(Q, \Sigma, O, \delta, X, q_0)$ where –
 - Q is a finite set of states.
 - Σ is a finite set of symbols called the input alphabet.
 - O is a finite set of symbols called the output alphabet.
 - δ is the input transition function where $\delta: Q \times \Sigma \rightarrow Q$
 - X is the output transition function where $X: Q \times \Sigma \rightarrow O$
 - q_0 is the initial state from where any input is processed ($q_0 \in Q$).

Mealy Machine



Present State	Next State			
	Input = a		Input = b	
	State	Output	State	Output
→ q0	q0	0	q1	1
q1	q1	1	q0	0