

# Optimization Methods - Assignment 2

## CS1.404 (Spring 2024)

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### 1 Derive the Jacobians and Hessian for the new functions.

#### 1. Matyas function

$$f(x) = 0.26(x_1^2 + x_2^2) - 0.48x_1 \times x_2$$

##### • Jacobian

$$\begin{aligned}\frac{df}{dx_1} &= 0.26(2x_1) - 0.48x_2 \\ \frac{df}{dx_1} &= 0.52x_1 - 0.48x_2\end{aligned}\tag{1}$$

$$\begin{aligned}\frac{df}{dx_2} &= 0.26(2x_2) - 0.48x_1 \\ \frac{df}{dx_2} &= 0.52x_2 - 0.48x_1\end{aligned}\tag{2}$$

Therefore, the Jacobian is,

$$\begin{bmatrix} \frac{df}{dx_1} \\ \frac{df}{dx_2} \end{bmatrix} = \begin{bmatrix} 0.52x_1 - 0.48x_2 \\ 0.52x_2 - 0.48x_1 \end{bmatrix}$$

##### • Hessian

$$\begin{aligned}\frac{d^2f}{dx_1^2} &= 0.52 \\ \frac{d^2f}{dx_2^2} &= 0.52 \\ \frac{d^2f}{dx_1 dx_2} &= -0.48\end{aligned}$$

Therefore, the Hessian is,

$$\begin{bmatrix} \frac{d^2f}{dx_1^2} & \frac{d^2f}{dx_1 dx_2} \\ \frac{d^2f}{dx_2 dx_1} & \frac{d^2f}{dx_2^2} \end{bmatrix} = \begin{bmatrix} 0.52 & -0.48 \\ -0.48 & 0.52 \end{bmatrix}$$

## 2. Rotated Hyper-Ellipsoid Function

$$f(x) = \sum_{i=1}^d \sum_{j=1}^i x_j^2$$

For simplicity, here I'm taking d as 2, then f(x) can be re-written as

$$f(x) = \sum_{i=1}^2 \sum_{j=1}^i x_j^2$$

$$f(x) = (x_1^2) + (x_1^2 + x_2^2)$$

$$f(x) = 2x_1^2 + x_2^2$$

- **Jacobian**

$$\frac{df}{dx_1} = 4x_1 \tag{3}$$

$$\frac{df}{dx_2} = 2x_2 \tag{4}$$

Therefore, the Jacobian is,

$$\begin{bmatrix} \frac{df}{dx_1} \\ \frac{df}{dx_2} \end{bmatrix}$$

$$\begin{bmatrix} 4x_1 \\ 2x_2 \end{bmatrix}$$

- **Hessian**

$$\frac{d^2 f}{dx_1^2} = 4$$

$$\frac{d^2 f}{dx_1 dx_2} = 0$$

$$\frac{d^2 f}{dx_2^2} = 2$$

Therefore, the Hessian is,

$$\begin{bmatrix} \frac{d^2 f}{dx_1^2} & \frac{d^2 f}{dx_1 dx_2} \\ \frac{d^2 f}{dx_2 dx_1} & \frac{d^2 f}{dx_2^2} \end{bmatrix}$$

$$\begin{bmatrix} 4 & 0 \\ 0 & 2 \end{bmatrix}$$

## 2 Using the Jacobians and Hessians, calculate the minimas for the new functions.

### 1. Matyas function

$$f(x) = 0.26(x_1^2 + x_2^2) - 0.48x_1 \times x_2$$

The Jacobian is,

$$\begin{bmatrix} 0.52x_1 - 0.48x_2 \\ 0.52x_2 - 0.48x_1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Solving for  $x_1$  and  $x_2$  we get:

$$0.52x_1 - 0.48x_2 = 0$$

$$0.52x_2 - 0.48x_1 = 0$$

$$x_1 = 0 \text{ and } x_2 = 0$$

The Hessian is,

$$\begin{bmatrix} 0.52 & -0.48 \\ -0.48 & 0.52 \end{bmatrix}$$

Since the Hessian is positive definite because we can clearly see, all the leading principal minors are positive. Therefore  $[0, 0]$  is the minima for the function.

## 2. Rotated Hyper-Ellipsoid Function

$$f(x) = \sum_{i=1}^2 \sum_{j=1}^i x_j^2$$

The Jacobian is,

$$\begin{bmatrix} 4x_1 \\ 2x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

Solving for  $x_1$  and  $x_2$  we get:

$$4x_1 = 0$$

$$2x_2 = 0$$

$$x_1 = 0 \text{ and } x_2 = 0$$

The Hessian is,

$$\begin{bmatrix} 4 & 0 \\ 0 & 2 \end{bmatrix}$$

Since the Hessian is positive definite because we can clearly see, all the leading principal minors are positive. Therefore  $[0, 0]$  is the minima for the function.

## 3 State which algorithms failed to converge and under which circumstances.

The reason for not converging successfully is an inadequate number of iterations, Becoming trapped at local minima, overflow, division by zero, etc...

Rosenbrock function with point  $[2.0, 2, 2, -2]$  as the starting point is not converging Fletcher-Reeves because of a slightly smaller number of iterations. The same case holds with points  $[3.0, 3, 3, 3]$  with approach SR1,  $[2., -2., -2., 2.]$  with approach SR1,  $[2., -2., -2., 2.]$  with approach DFP, and  $[-2., 2., 2., 2.]$  with method SR1.

## 4 Plot $f(x)$ vs iterations and $f'(x)$ vs iterations.

## 5 Make a contour plot with arrows indicating the direction of updates for all 2-D functions.

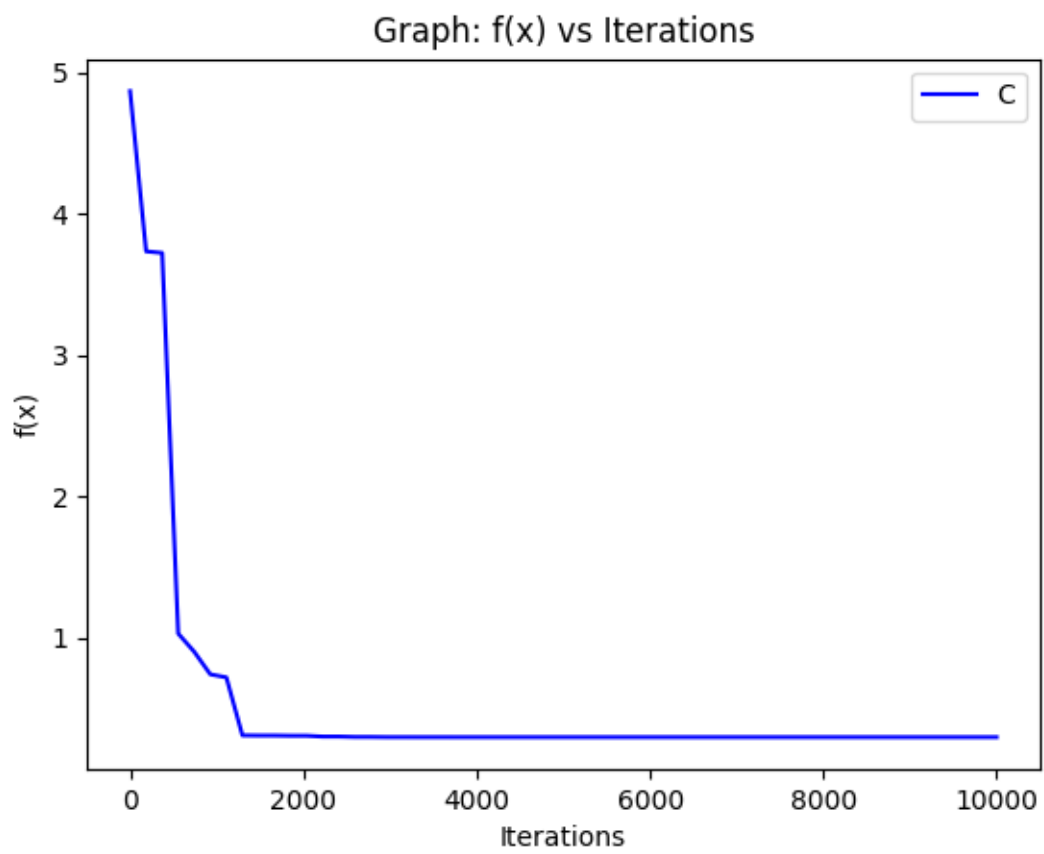


Figure 1: three\_hump\_camel\_function\_[2. 1.]\_PolakRibiere\_vals

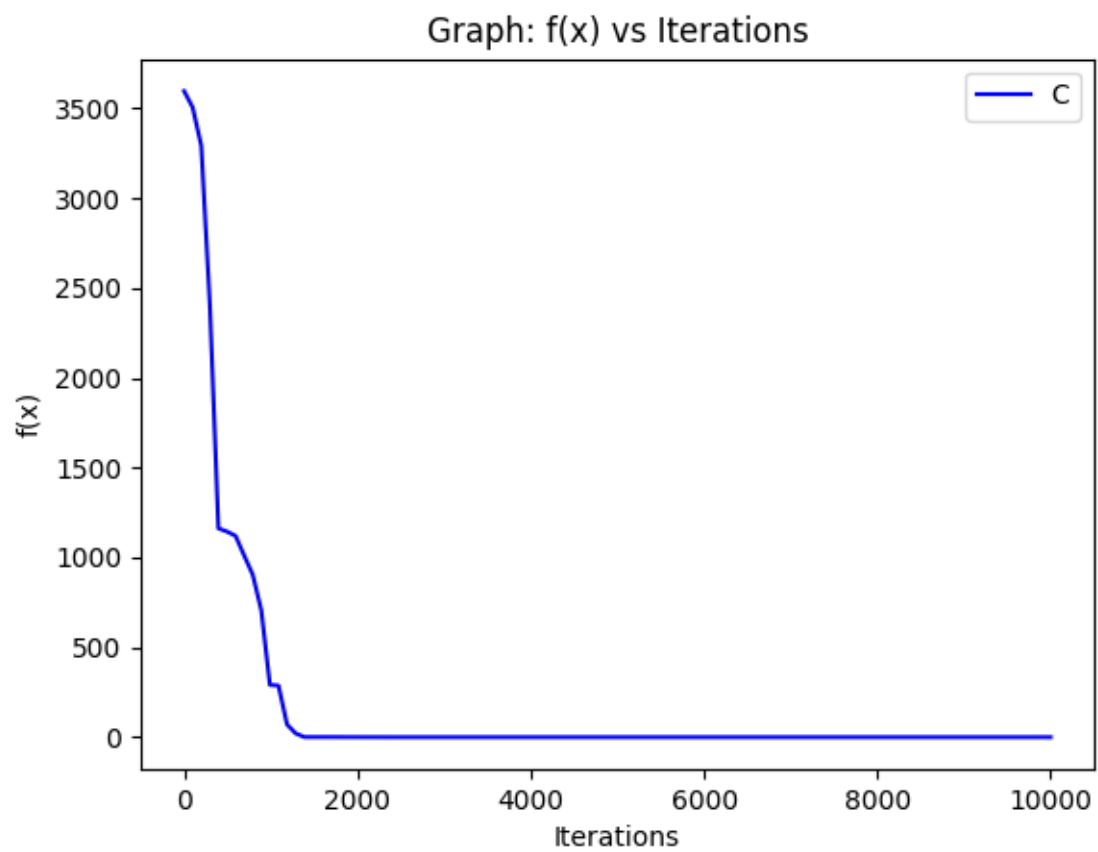


Figure 2: hyperEllipsoid\_function\_[ 10. -10. 15. 15. -20. 11. 312.]\_PolakRibiere\_vals

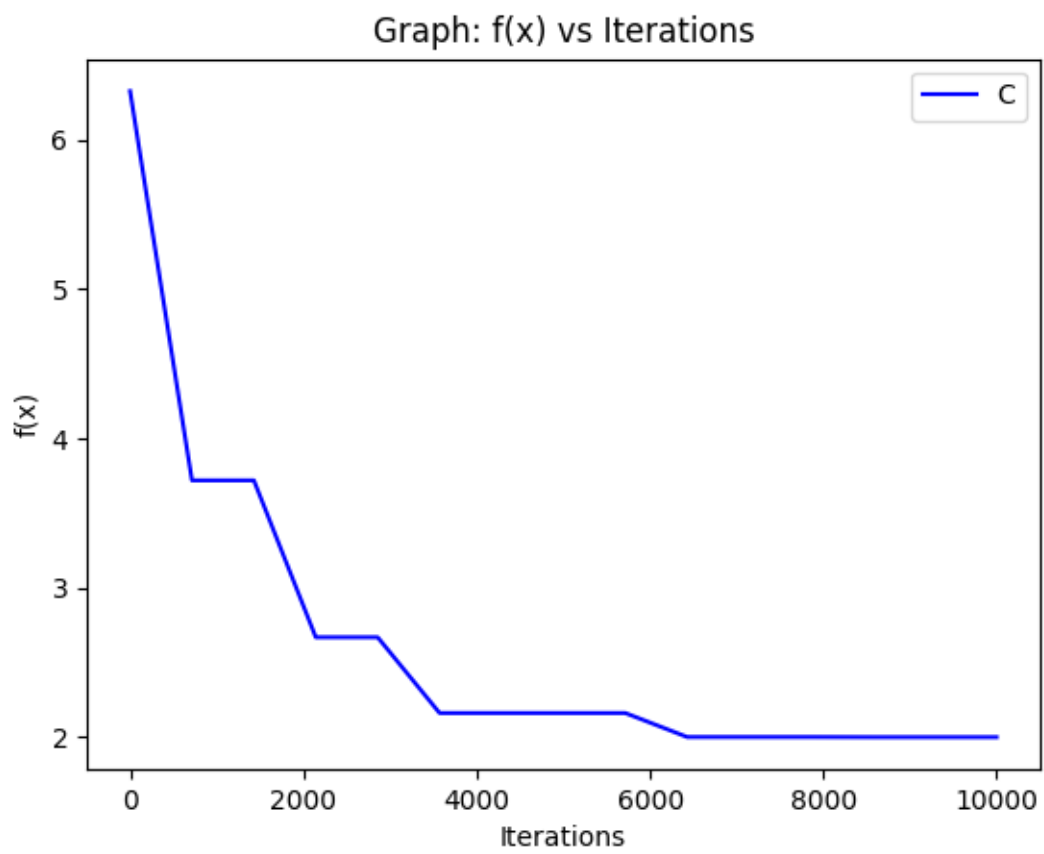


Figure 3: func\_1-[3. 3.]\_HestenesStiefel\_vals

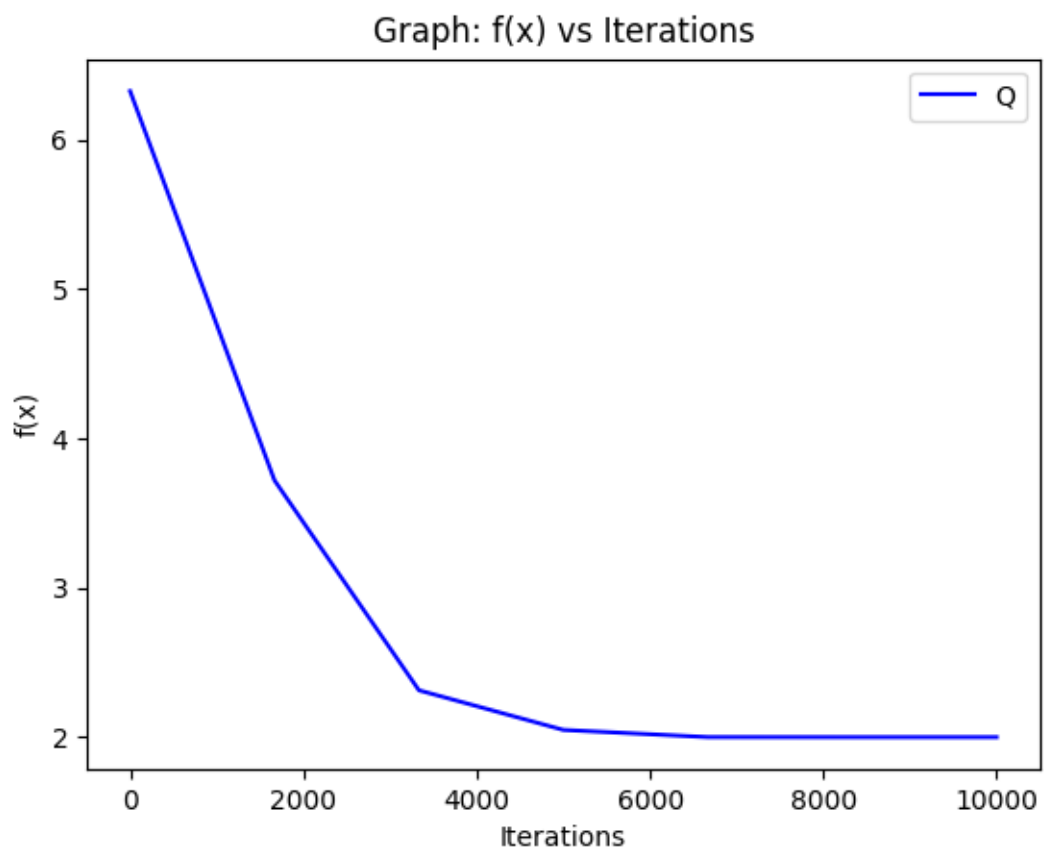


Figure 4: func.1.[3. 3.]\_DFP\_vals

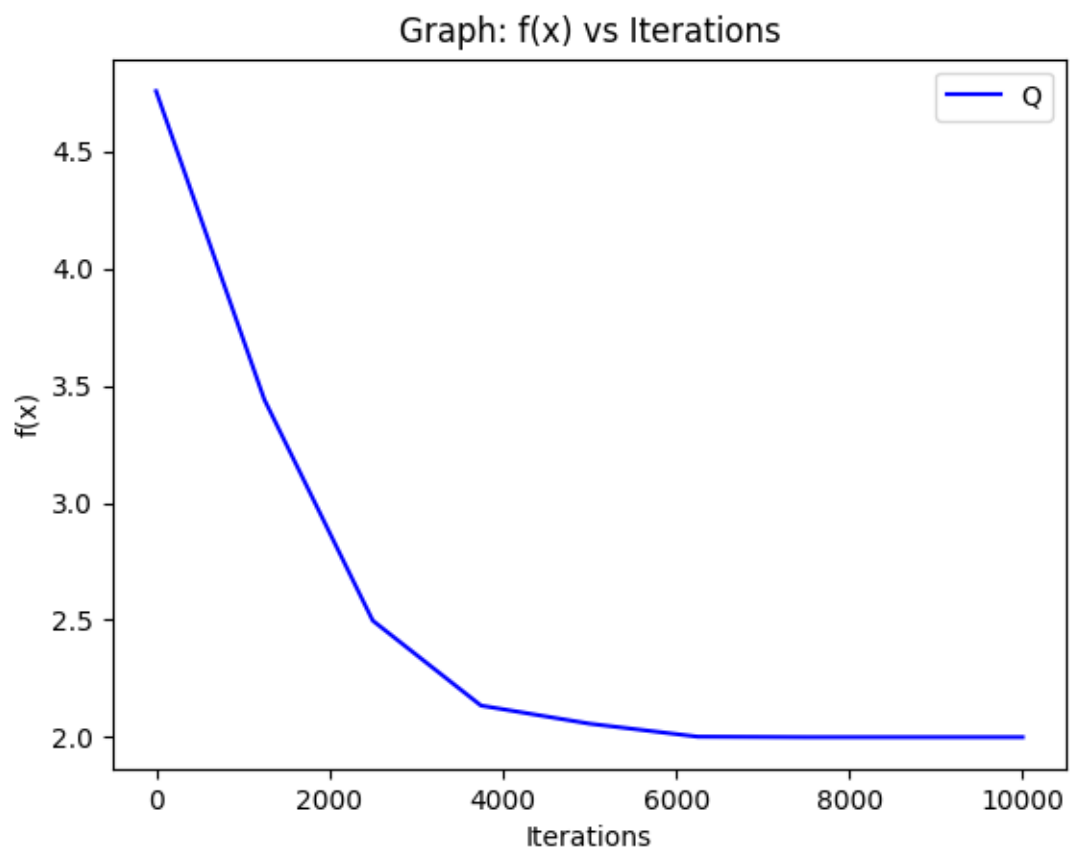


Figure 5: func\_1\_[-3.5 0.5]\_SR1\_vals



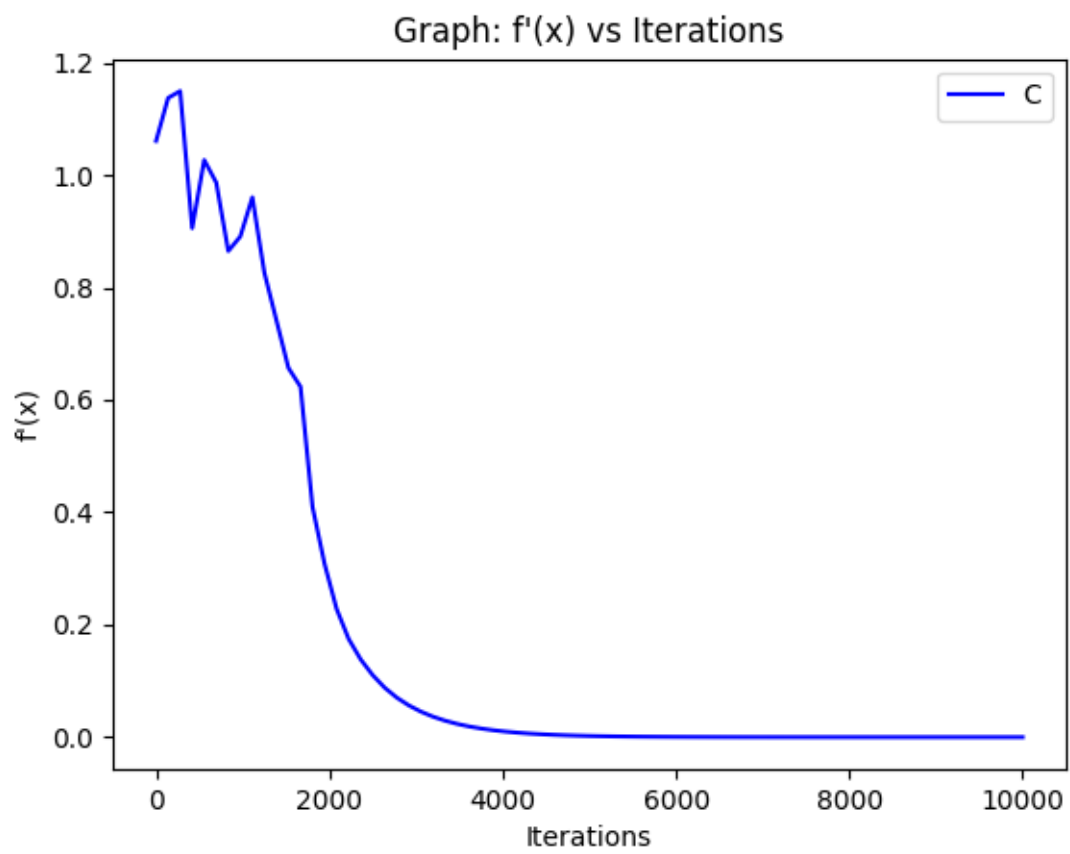


Figure 6: func\_1\_derivative\_[-3.5 0.5]\_FletcherReeves\_grad

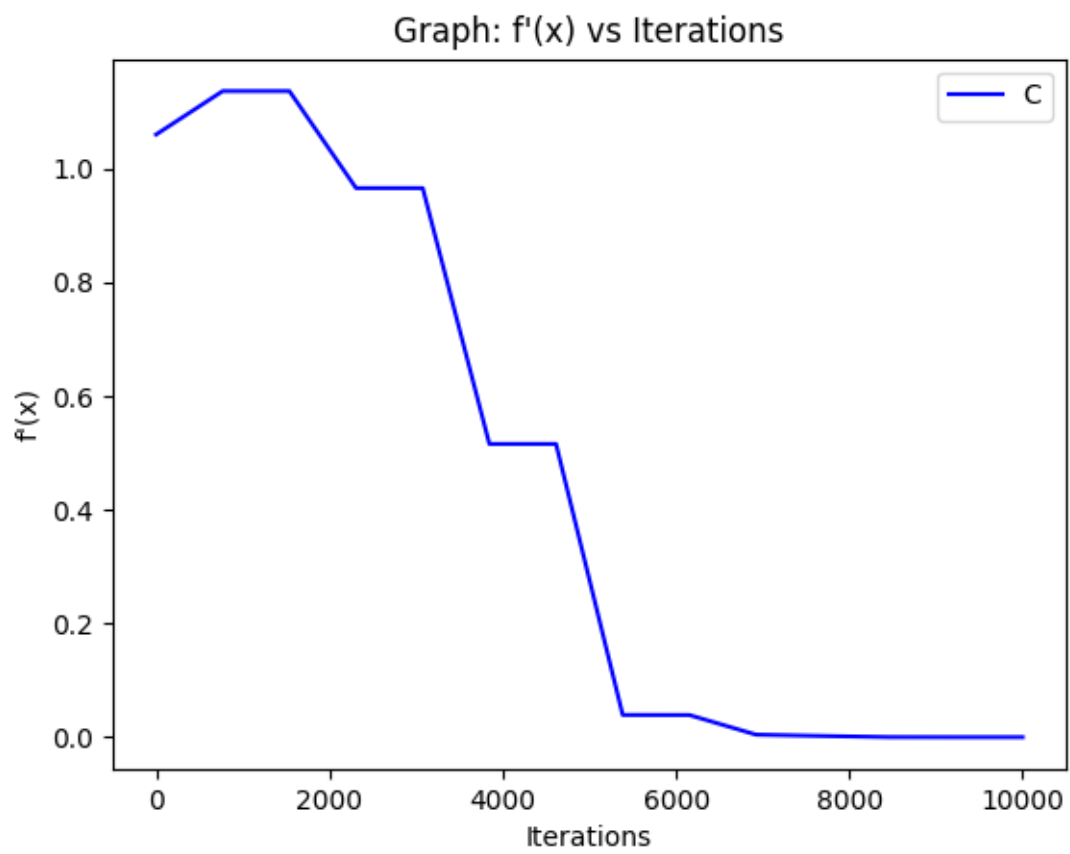


Figure 7: func\_1\_derivative\_[-3.5 0.5]\_PolakRibiere\_grad

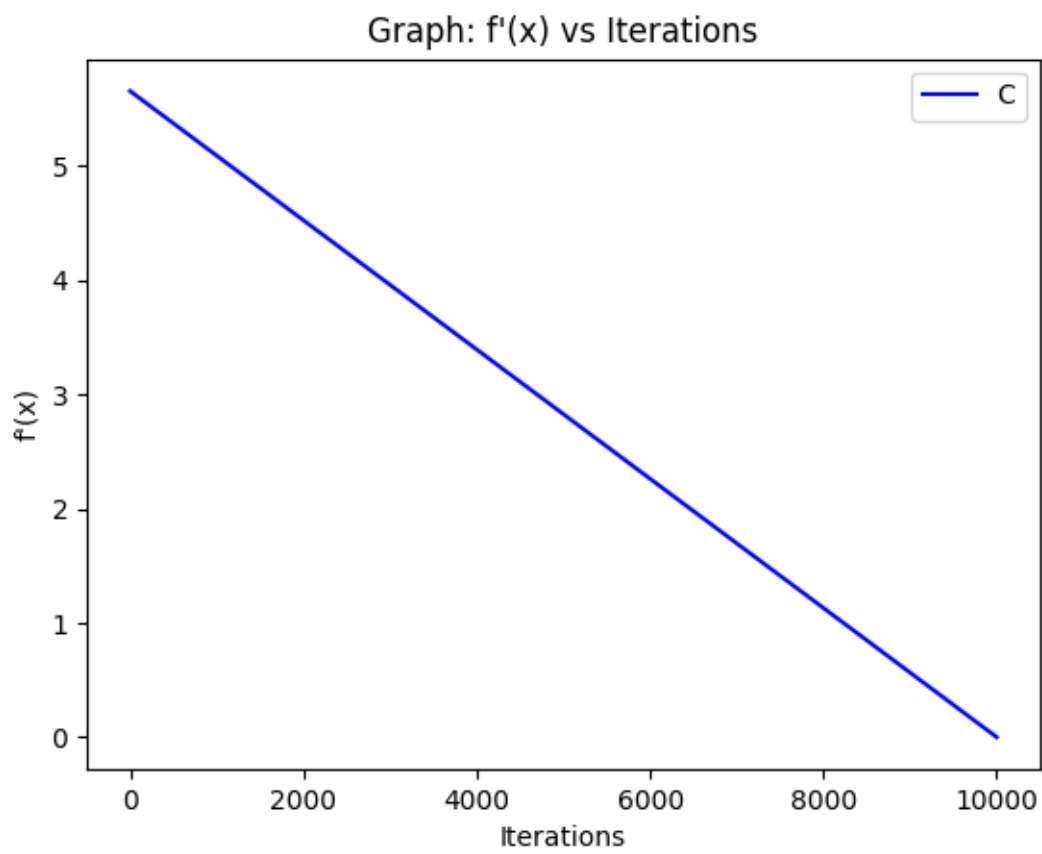


Figure 8: trid\_function\_derivative\_[-2. -2.]\_HestenesStiefel\_grad

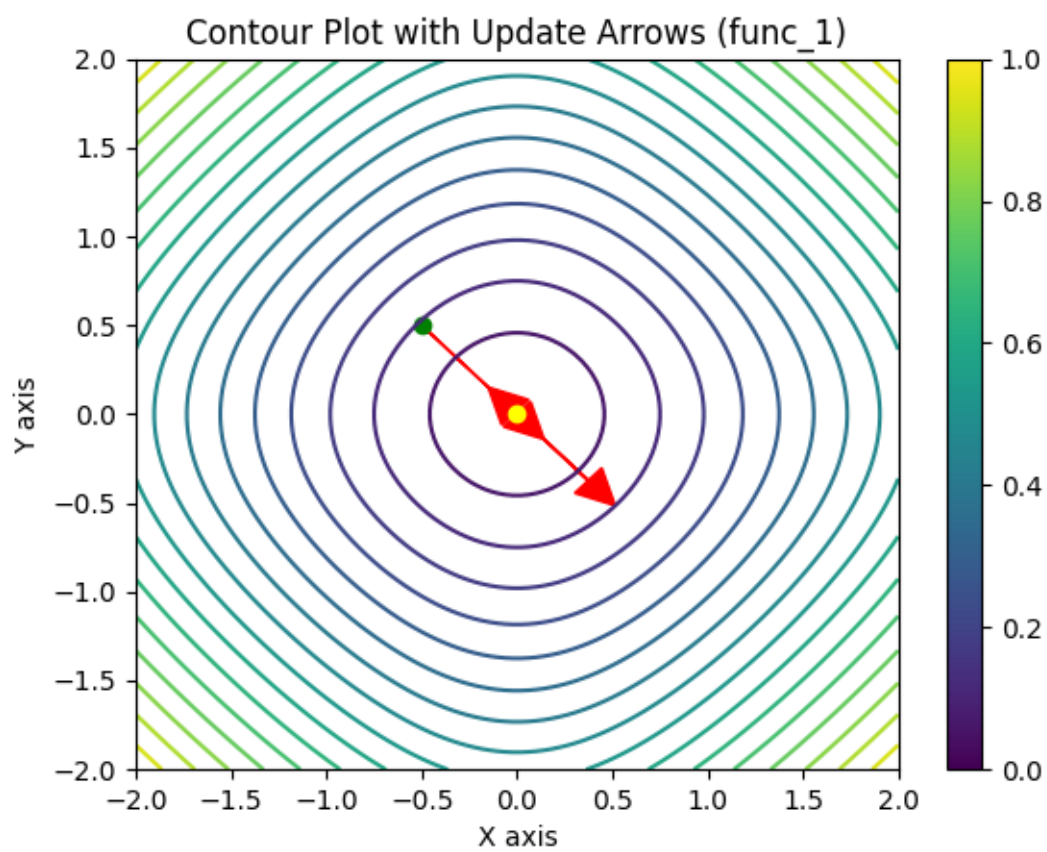


Figure 9: func\_1-[-0.5 0.5]-DFP\_cont

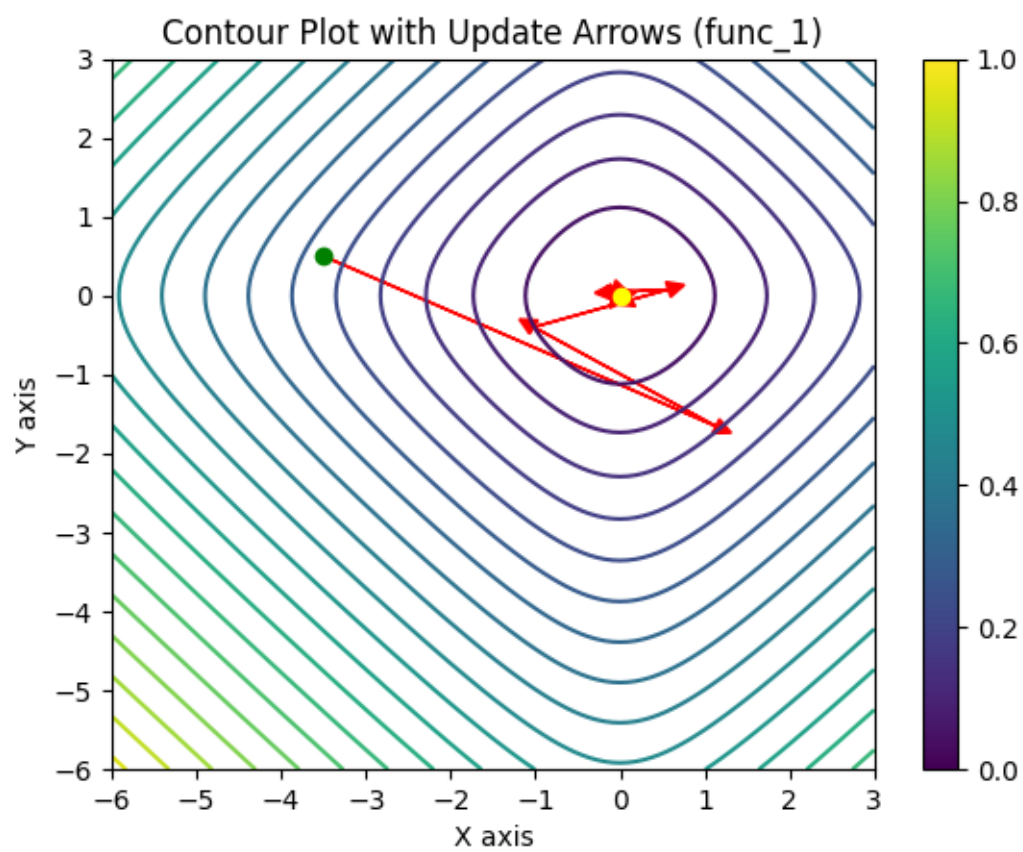


Figure 10: func\_1-[-3.5 0.5]-BFGS-cont

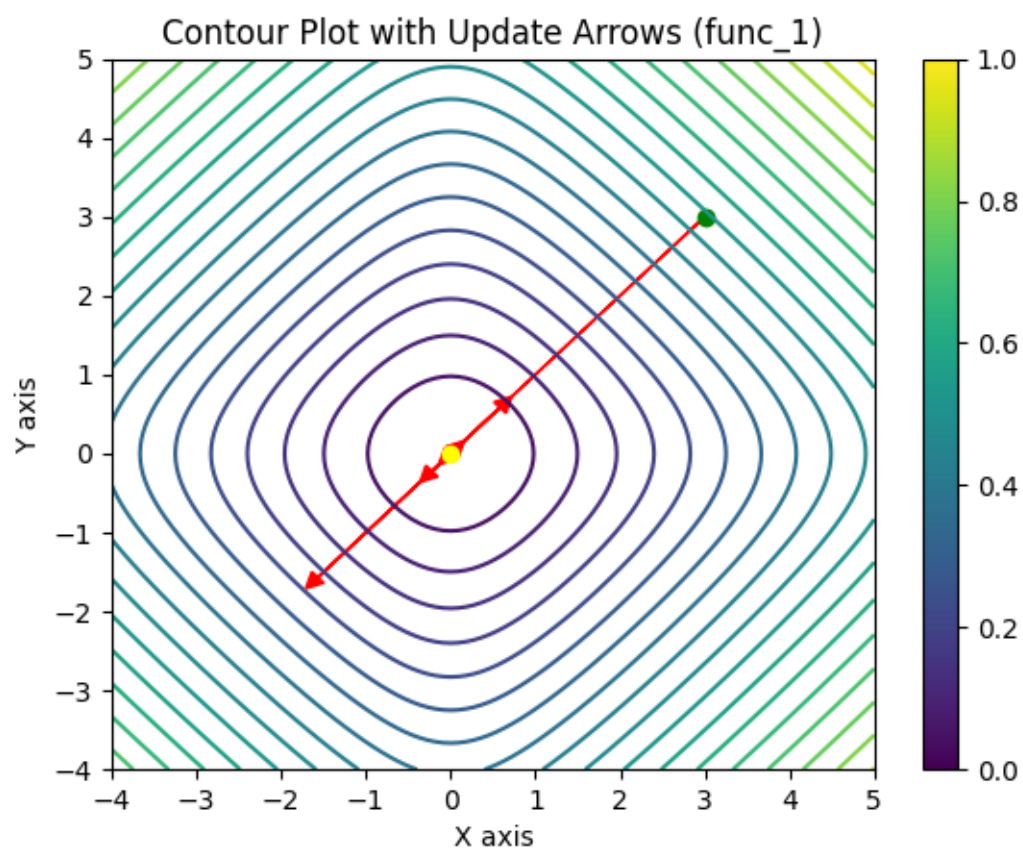


Figure 11: `func_1.[3. 3.]_BFGS_cont`

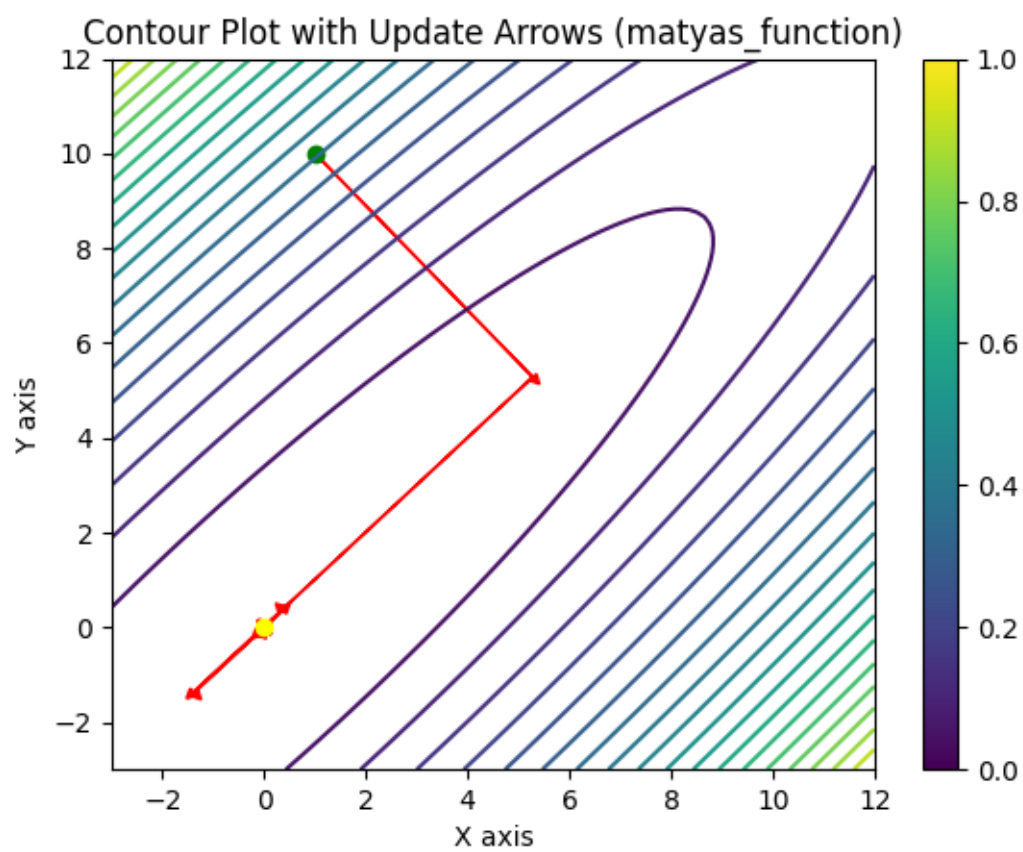


Figure 12: matyas\_function-[ 1. 10.]-HestenesStiefel.cont

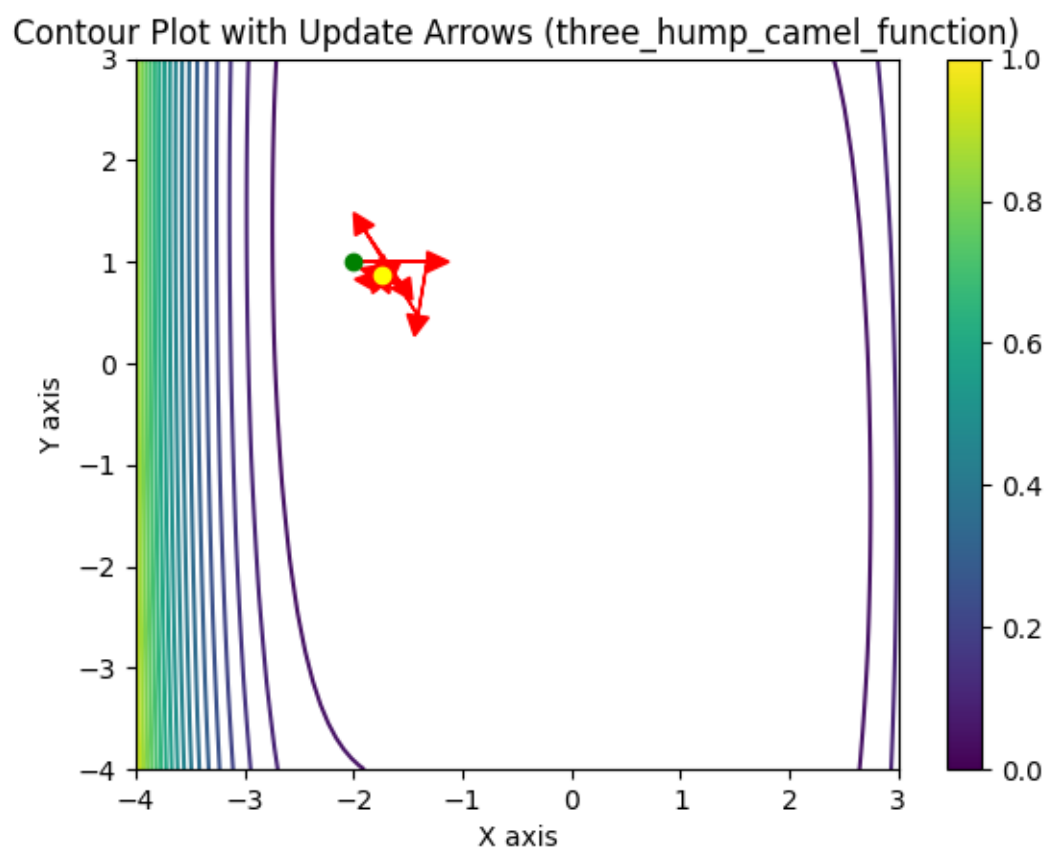


Figure 13: three\_hump\_camel\_function-[-2. 1.]\_DFP\_cont