

Data Systems at Scale: Scaling Up by Scaling Down and Out

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Bioinformatics on twitter

Mick W@tson
@BioMickWatson

Bioinformatics over the years:
1990s: doing a BLAST search
2000s: analysing 30 microarrays
2010s: analysing 6Tb of NGS
2020s: creating a cloud the size of Netflix to reanalyse the whole of SRA for one figure

12:57 AM · 2/12/21 · Twitter Web App

117 Retweets 9 Quote Tweets 697 Likes

Michael Schatz @mike_schatz · 2h

Replying to @BioMickWatson

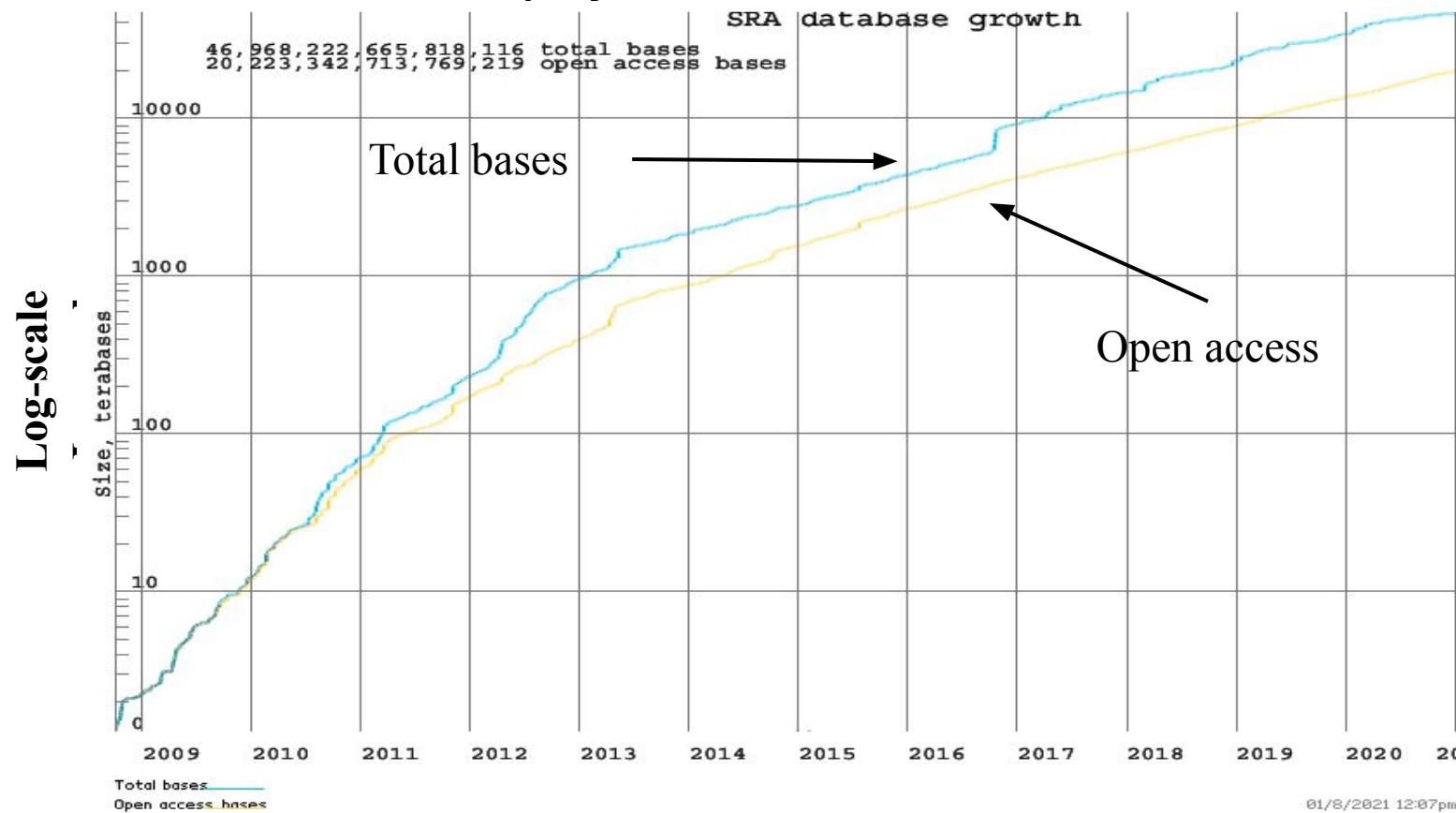
This is basically my life right now

Professor Bioinformatics and Computational Biology
The University of Edinburgh

Associate Professor
Computational Biology
Johns Hopkins University

Sequence Read Archive (SRA) growth

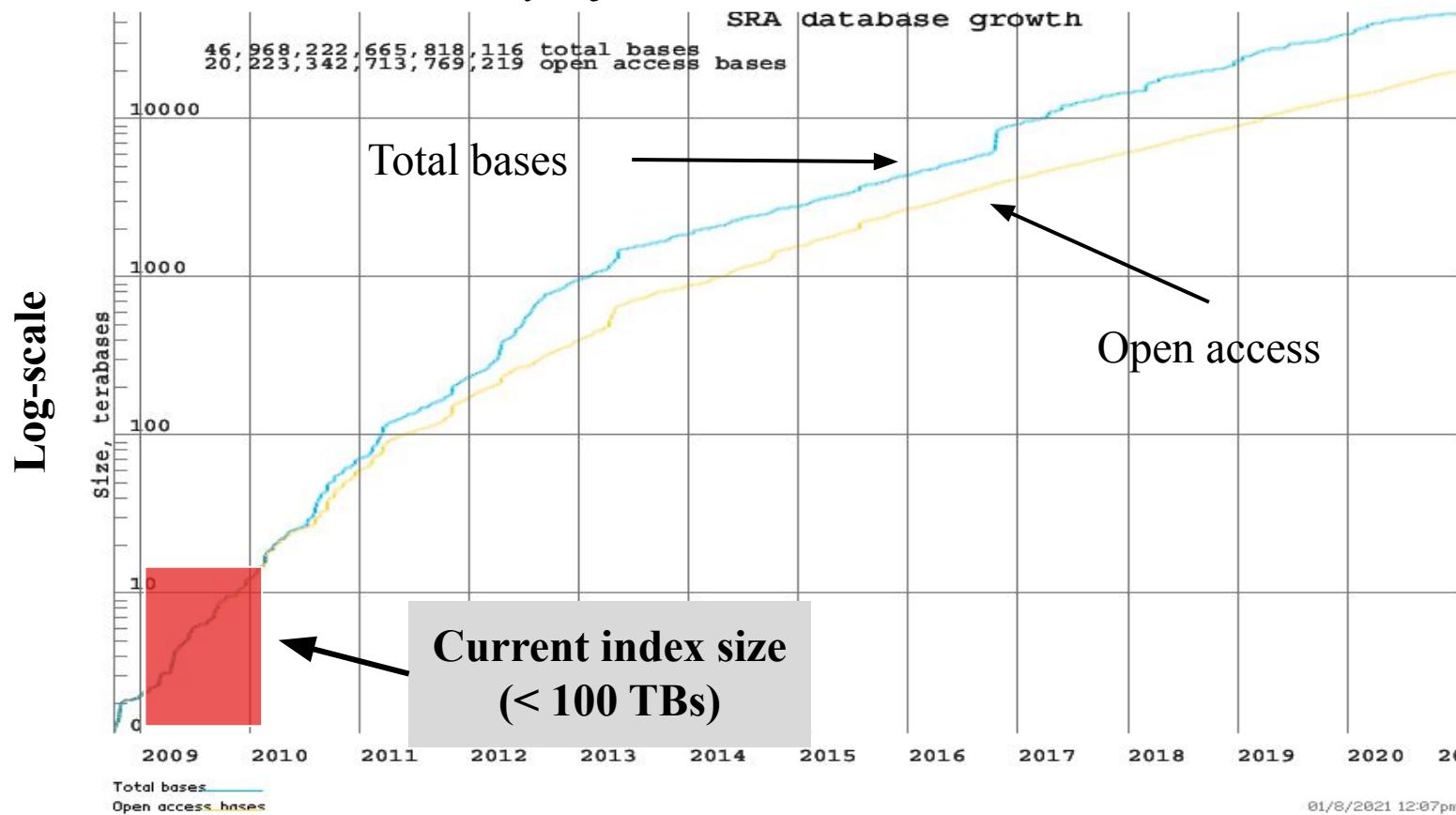
SRA contains a lot of *diversity information*



Q: What if I find e.g., a new disease-related gene, and want to see if it appeared in other experiments?

Scalability is the bottleneck for data science

SRA contains a lot of *diversity information*



This renders what is otherwise an immensely valuable public resource *largely inert*

Scalability is a ubiquitous challenge

Cyber monitoring

Internet of Things

Financial tech

Social networks

AstroPhysics

Chemistry

Environmental science

- People generate 2.5 quintillion bytes of data each day. ([IBM](#), 2016)
- More than 150 zettabytes (150 trillion gigabytes) of data will need analysis by 2025. ([Forbes](#), 2019)
- 90 percent of the world's data was created between 2015 and 2016 alone. ([IBM](#), 2016)

<https://learn.g2.com/big-data-statistics>

24. 88% of data is ignored by companies.

<https://leftronic.com/big-data-statistics/>

(Forrester Research)

A widely-quoted figure from a 2012 paper from Forrester Research says that, on average, companies analyze only 12% of the available data. Reasons for this include a lack of analytics tools, repressive data silos, and the difficulty in knowing which information is valuable and which is worth leaving.

My goal as a researcher

My goal as a researcher is to build *scalable data systems* to *accelerate* and *scale* next generation data analysis

Three approaches to handle massive data

Three approaches to handle massive data

Shrink it

Goal: make data smaller to fit in RAM

Techniques:

- Compact & succinct data structures
- Filters, e.g., Bloom, quotient, etc.

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Organize it

Goal: organize data in a disk-friendly way

Techniques:

- B-tree
- B^ε -tree
- LSM-tree

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Distribute it

Goal: partition and distribute data on multiple nodes

Techniques:

- Distributed hash table
- Distributed key-value store

Research output

Shrink

Organize

Distribute



**Data structures
& Algorithms**

Systems

Applications

Computational
biology

Research output

Shrink

Organize

Distribute



**Data structures
& Algorithms**

Quotient Filter
SIGMOD '17,
SIGMOD '21

Buffered CMS
ESA '18,
Scalable MG
arXiv '19

**Order Min
Hash**
ISMB '19

Systems

Applications

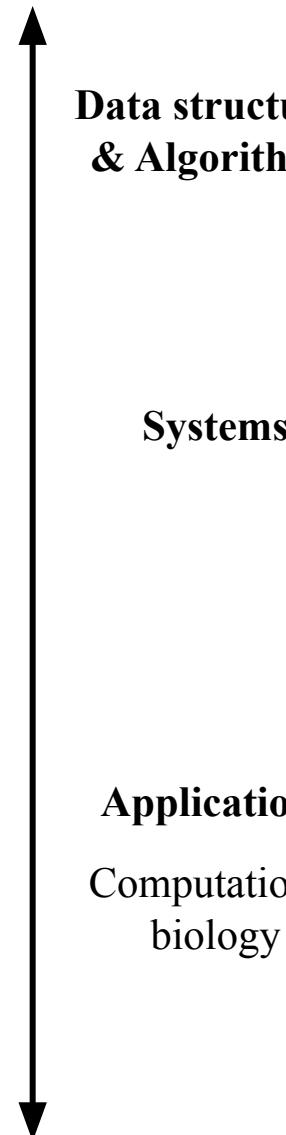
Computational
biology

Research output

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Quotient Filter
SIGMOD '17,
SIGMOD '21

Buffered CMS
ESA '18,
Scalable MG
arXiv '19

Order Min Hash
ISMB '19

BetrFS file system
FAST '15, TOS 15,
FAST '16, TOS 16,
SPAA '19, TOPC '21

LERTs
SIGMOD '20

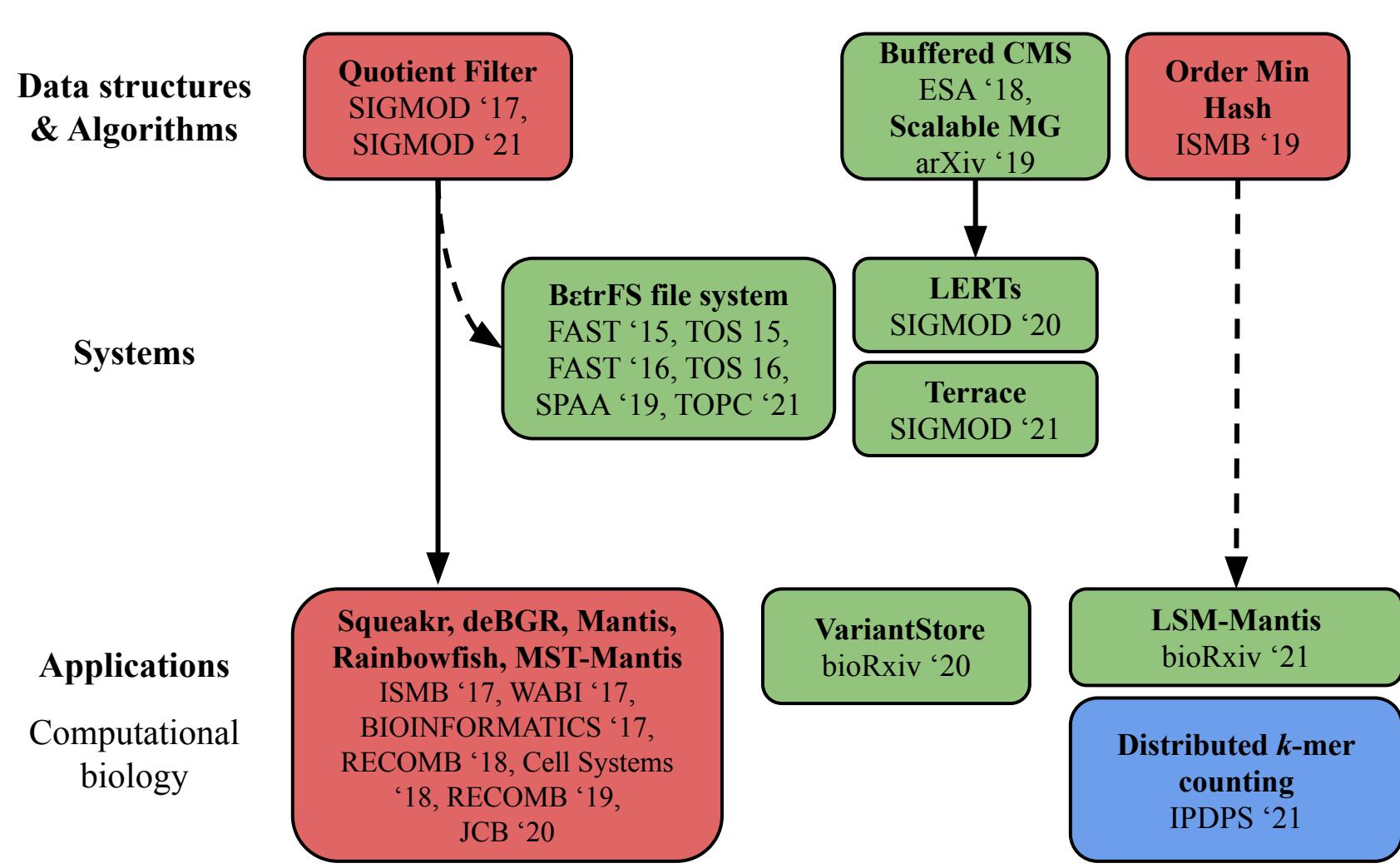
Terrace
SIGMOD '21

Research output

Shrink

Organize

Distribute

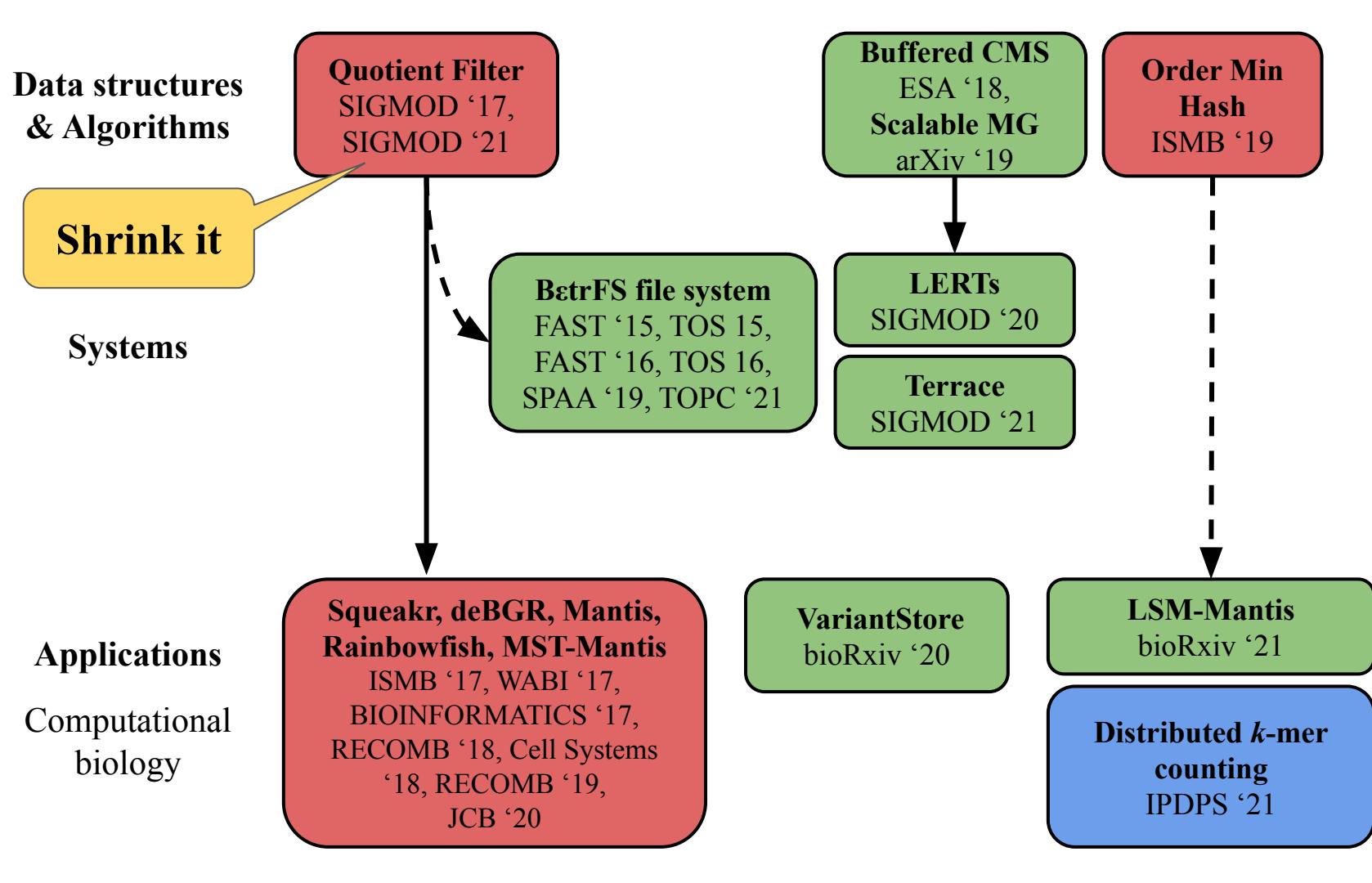


In this talk:

Shrink

Organize

Distribute

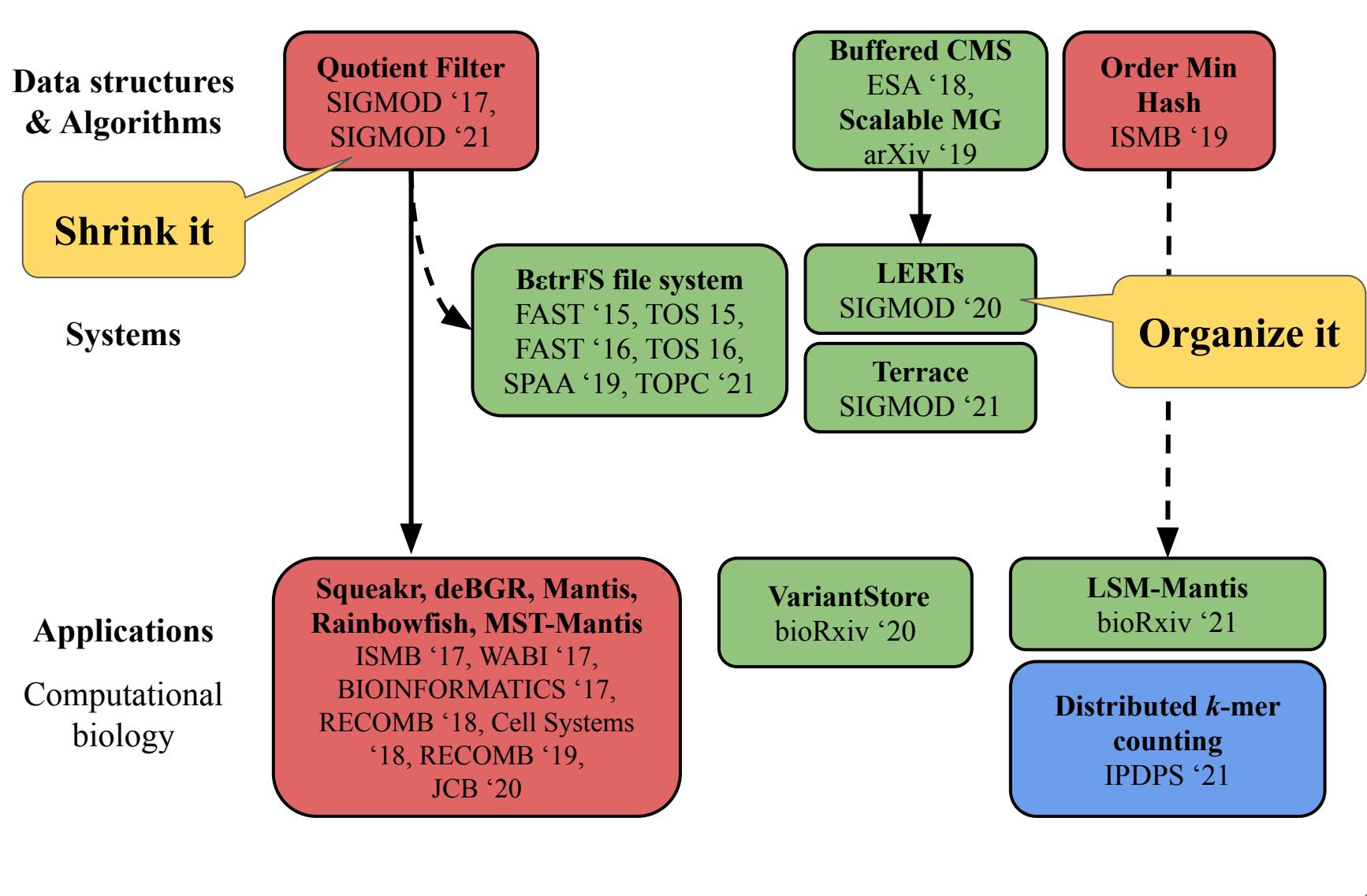


In this talk:

Shrink

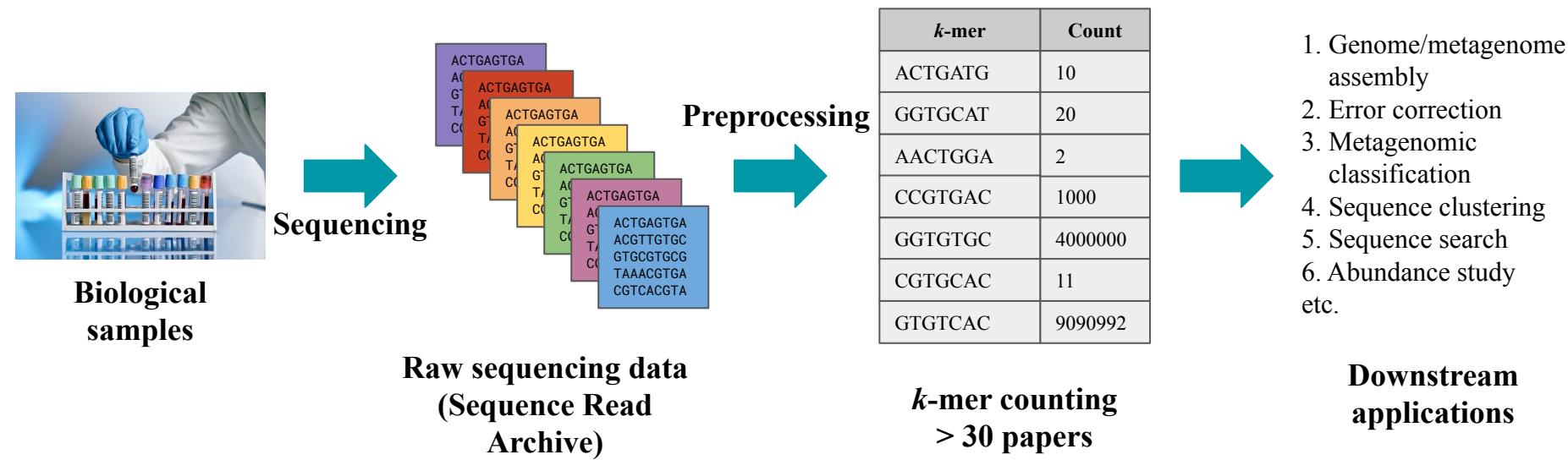
Organize

Distribute



Computational biology applications using quotient filters

Application 1: k -mer counting



- The **size** of the raw sequencing data makes the problem challenging
- k -mer counts follow ***highly skewed distributions*** making the problem computationally intensive

Application 1: Squeakr [Pandey et al. Bioinformatics '17]

Index space

Dataset	KMC2 [Deorowicz, et al '14]	Jellyfish2 (Bloom filter) [Marçais & Kingsford '11]	Squeakr (quotient filter)	Squeakr-exact (quotient filter)
<i>F. vesca</i>	8.3	8.3	4.8	9.3
<i>G. gallus</i>	32.8	31.7	13.0	28.8
<i>M. balbisiana</i>	48.3	16.3	11.1	14.2
<i>H. sapiens 1</i>	71.4	61.8	22.1	51.5
<i>H. sapiens 2</i>	107.4	61.8	30.8	60.1

Using *space-efficient* data structures, we can save space and build
simpler and *efficient* systems

Application 2: sample discovery problem

Solomon & Kingsford Nat Biotech '16

...ACACGT...

Check if this new transcript has been seen before?

ACTGAGTGA
ACGTTGTGC
GTGCGTGGC
TAAACGTGA
CGTCACGTA

ACTGAGTGA
ACGTTGTGC
GTGCGTGGC
TAAACGTGA
CGTCACGTA

⋮

ACTGAGTGA
ACGTTGTGC
GTGCGTGGC
TAAACGTGA
CGTCACGTA

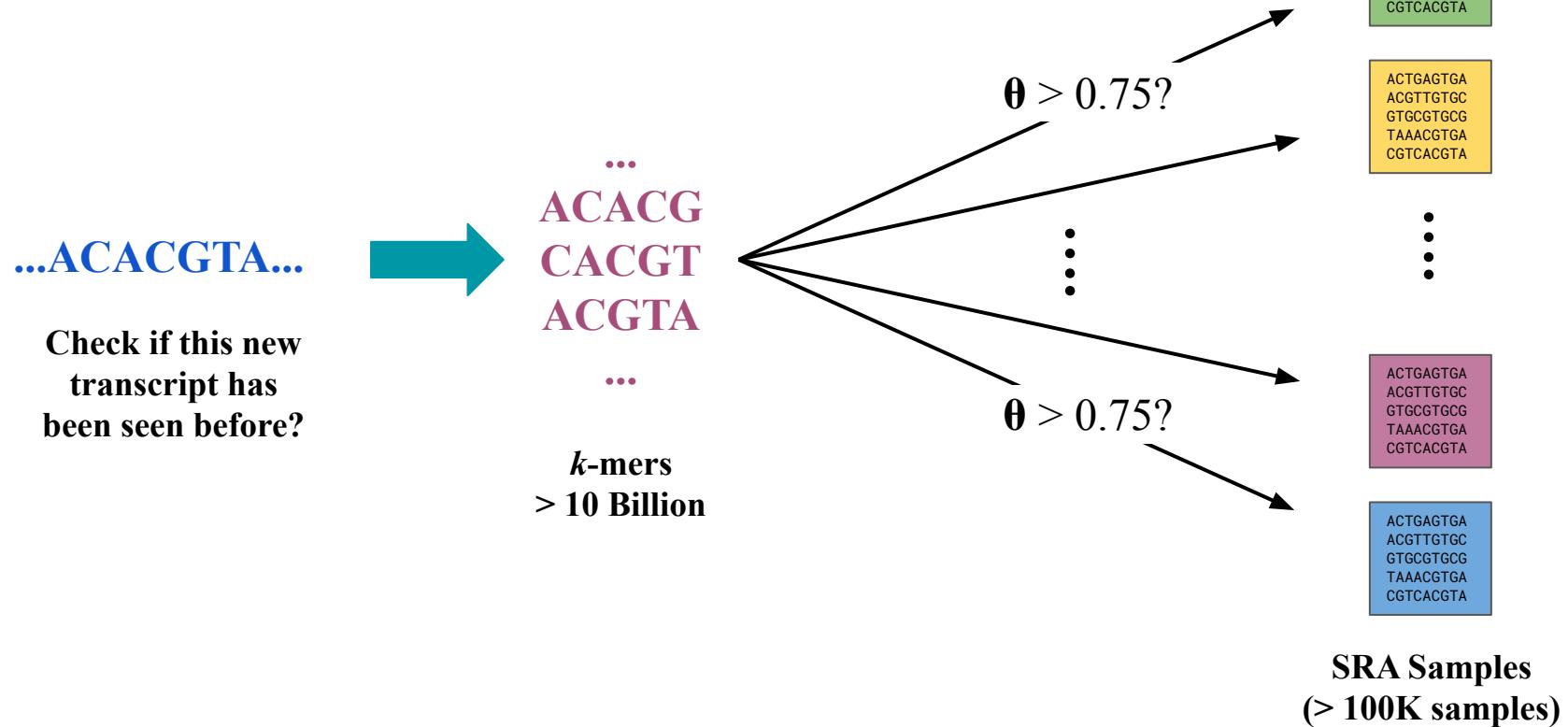
ACTGAGTGA
ACGTTGTGC
GTGCGTGGC
TAAACGTGA
CGTCACGTA

SRA Samples
(> 100K samples)

Return all samples that contain at least some user-defined fraction θ of the k -mers present in the query string.

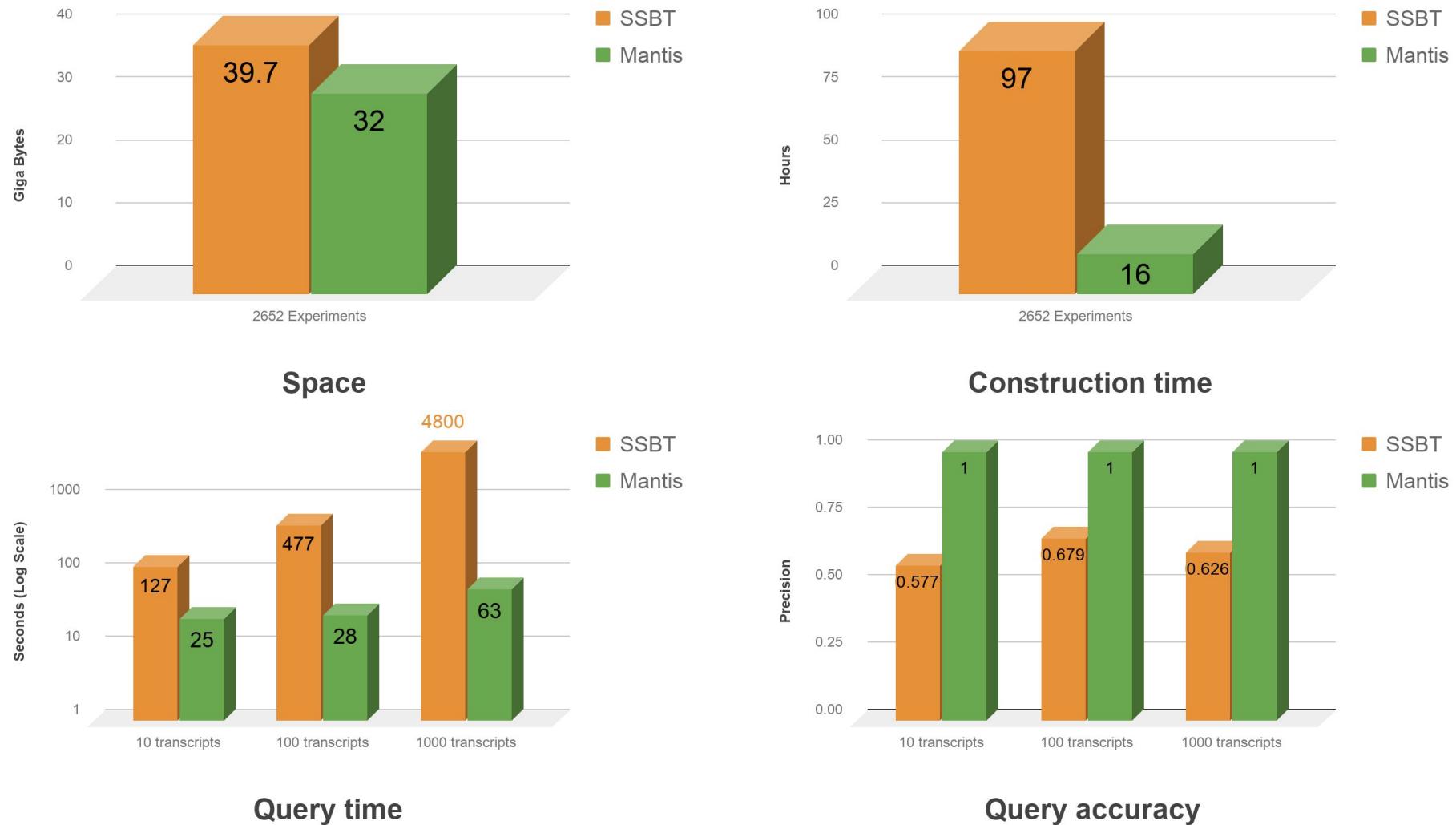
Application 2: sample discovery problem

Solomon & Kingsford Nat Biotech '16



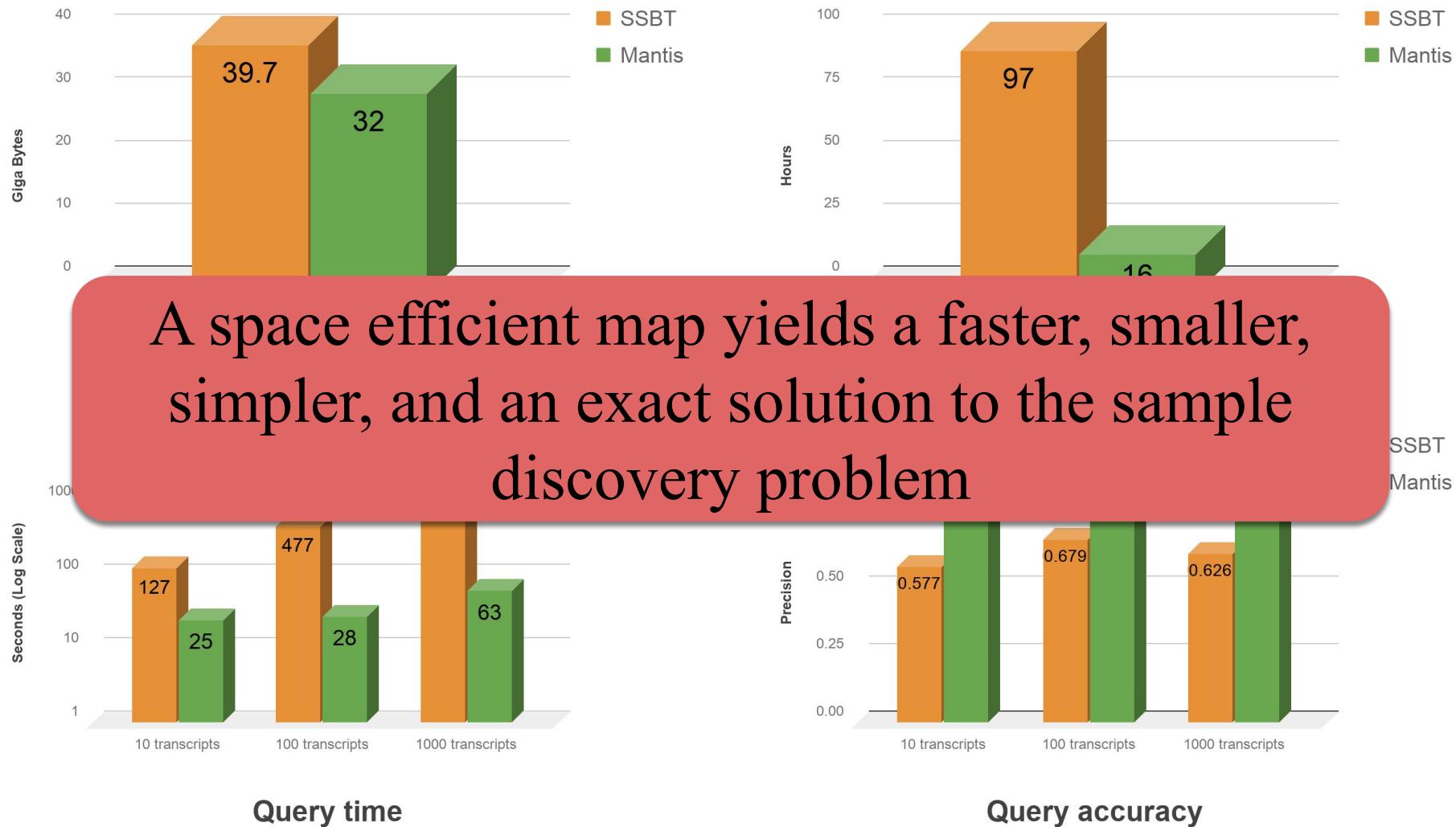
Return all samples that contain at least some user-defined fraction θ of the k -mers present in the query string

Application 2: Mantis [Pandey et al. RECOMB '18, Cell Systems '18]



SSBT (Bloom filter) [Solomon & Kingsford '17]
Mantis (quotient filter) [Pandey et al. '18]

Application 2: Mantis [Pandey et al. RECOMB '18, Cell Systems '18]



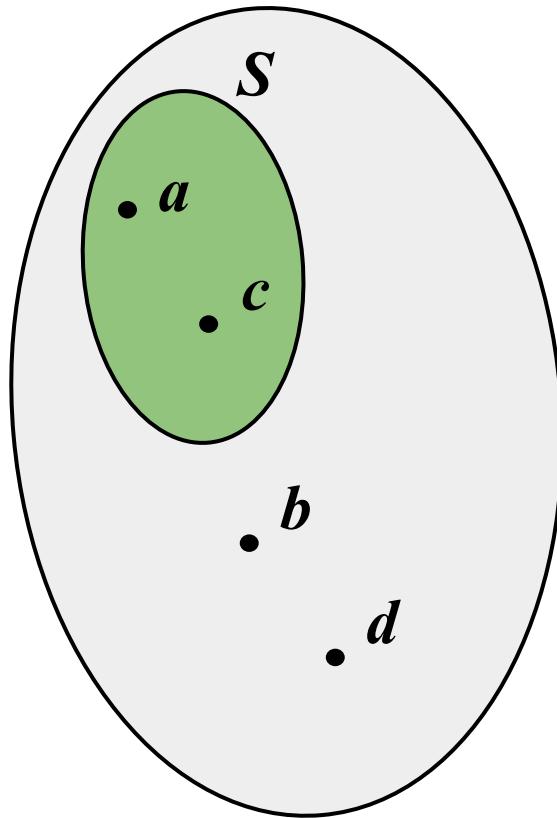
A space efficient map yields a faster, smaller, simpler, and an exact solution to the sample discovery problem

SSBT
Mantis

SSBT (Bloom filter) [Solomon & Kingsford '17]
Mantis (quotient filter) [Pandey et al. '18]

Dictionary data structure

A dictionary maintains a set S from universe U .



membership(a): ✓

membership(b): ✗

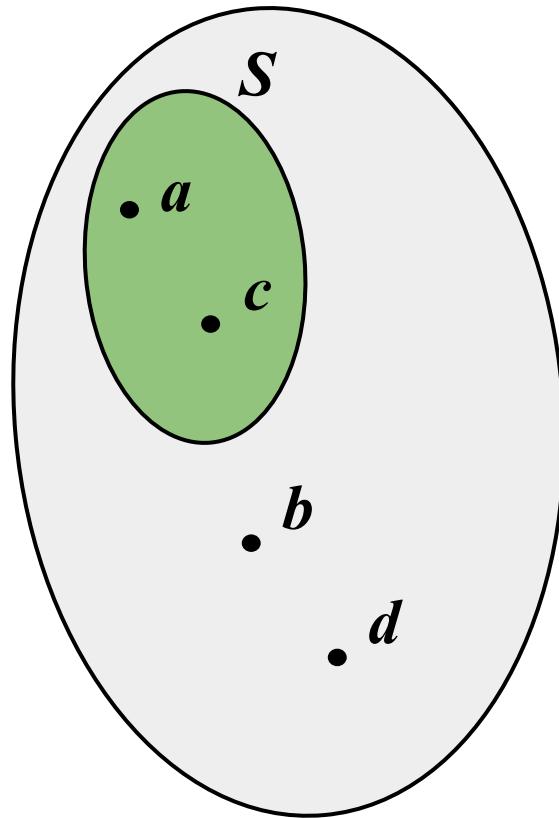
membership(c): ✓

membership(d): ✗

A dictionary supports membership queries on S .

Filter data structure

A filter is an *approximate* dictionary.



membership(a): ✓

membership(b): ✗

membership(c): ✓

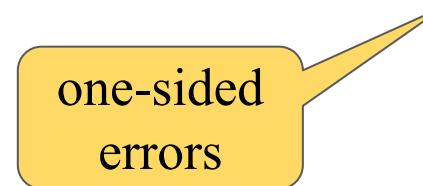
membership(d): ✓ ✖ **false positive**

A filter supports approximate membership queries on S .

A filter guarantees a false-positive rate ε

if $q \in S$, return  with probability 1 **true positive**

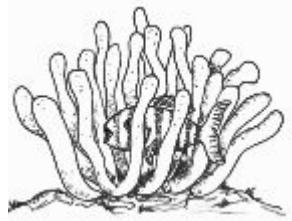
if $q \notin S$, return   with probability $\square 1 - \varepsilon$ **true negative**
 with probability $\leq \varepsilon$ **false positive**



False-positive rate enables filters to be compact

$$\text{space} \geq n \log(1/\epsilon)$$

$$\text{space} = \Omega(n \log |U|)$$



Filter

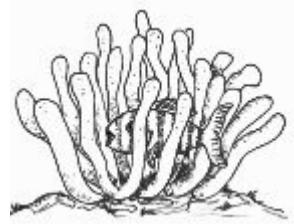


Dictionary

False-positive rate enables filters to be compact

space $\geq n \log(1/\epsilon)$

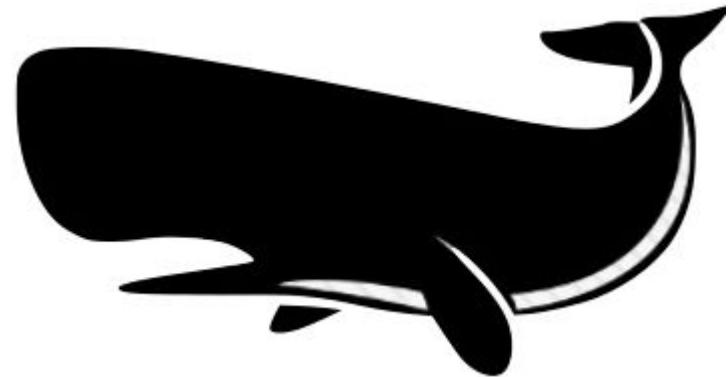
Small



Filter

space = $\Omega(n \log |U|)$

Large



Dictionary

For most practical purposes:
 $\epsilon = 2\%$, a Bloom filter requires ≈ 8 bits/item

Classic filter: The Bloom filter [Bloom '70]

Bloom filters are ubiquitous (> 4300 citations)

Streaming applications



Networking



Databases



Computational biology



Storage systems



Bloom filters have suboptimal performance

	Bloom filter	Optimal
Space (bits)	$\approx 1.44 n \log(1/\epsilon)$	$\approx n \log(1/\epsilon) + \Omega(n)$
CPU cost	$\Omega(1/\epsilon)$	$O(1)$
Data locality	$\Omega(1/\epsilon)$ probes	$O(1)$ probes

Applications often work around Bloom filter limitations

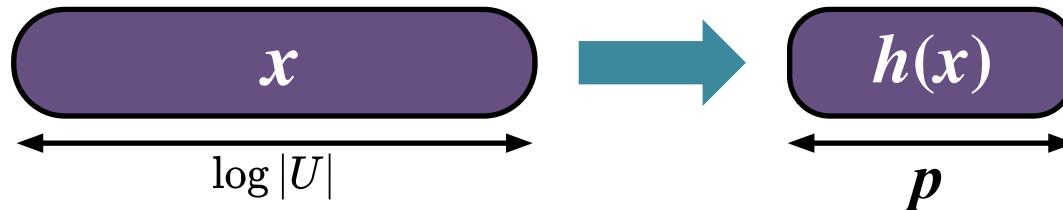
Limitations	Workarounds
No deletes	Rebuild
No resizes	Guess N , and rebuild if wrong
No filter merging or enumeration	???
No values associated with keys	Combine with another data structure

Bloom filter limitations increase system complexity, waste space, and slow down application performance

Quotienting is an alternative to Bloom filters

[Knuth. Searching and Sorting Vol. 3, '97]

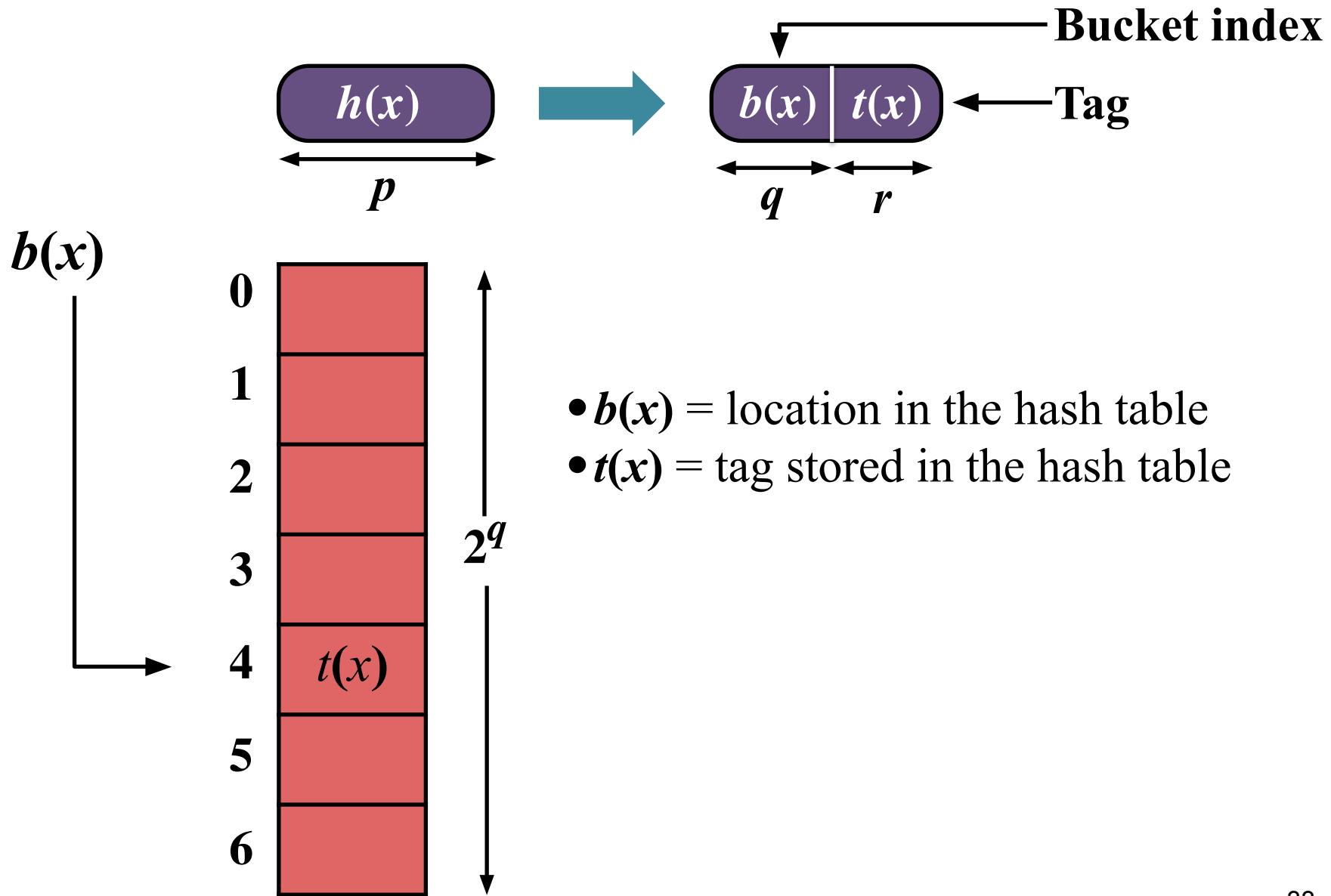
- **Store fingerprints compactly in a hash table.**
 - Take a fingerprint $h(x)$ for each element x .



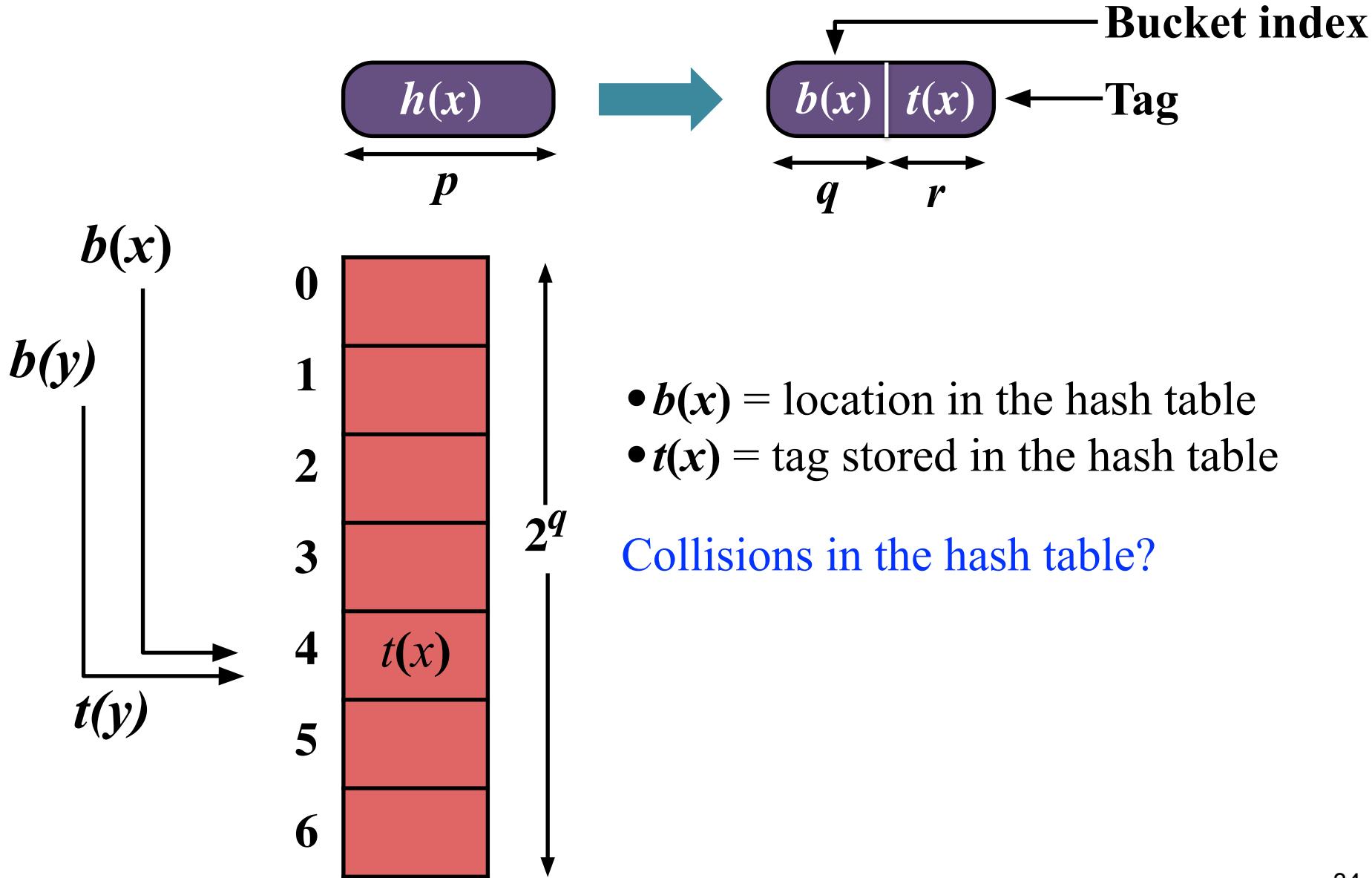
- **Only source of false positives:**
 - Two distinct elements x and y , where $h(x) = h(y)$
 - If x is stored and y isn't, $\text{query}(y)$ gives a false positive

$$\Pr[x \text{ and } y \text{ collide}] = \frac{1}{2^p}$$

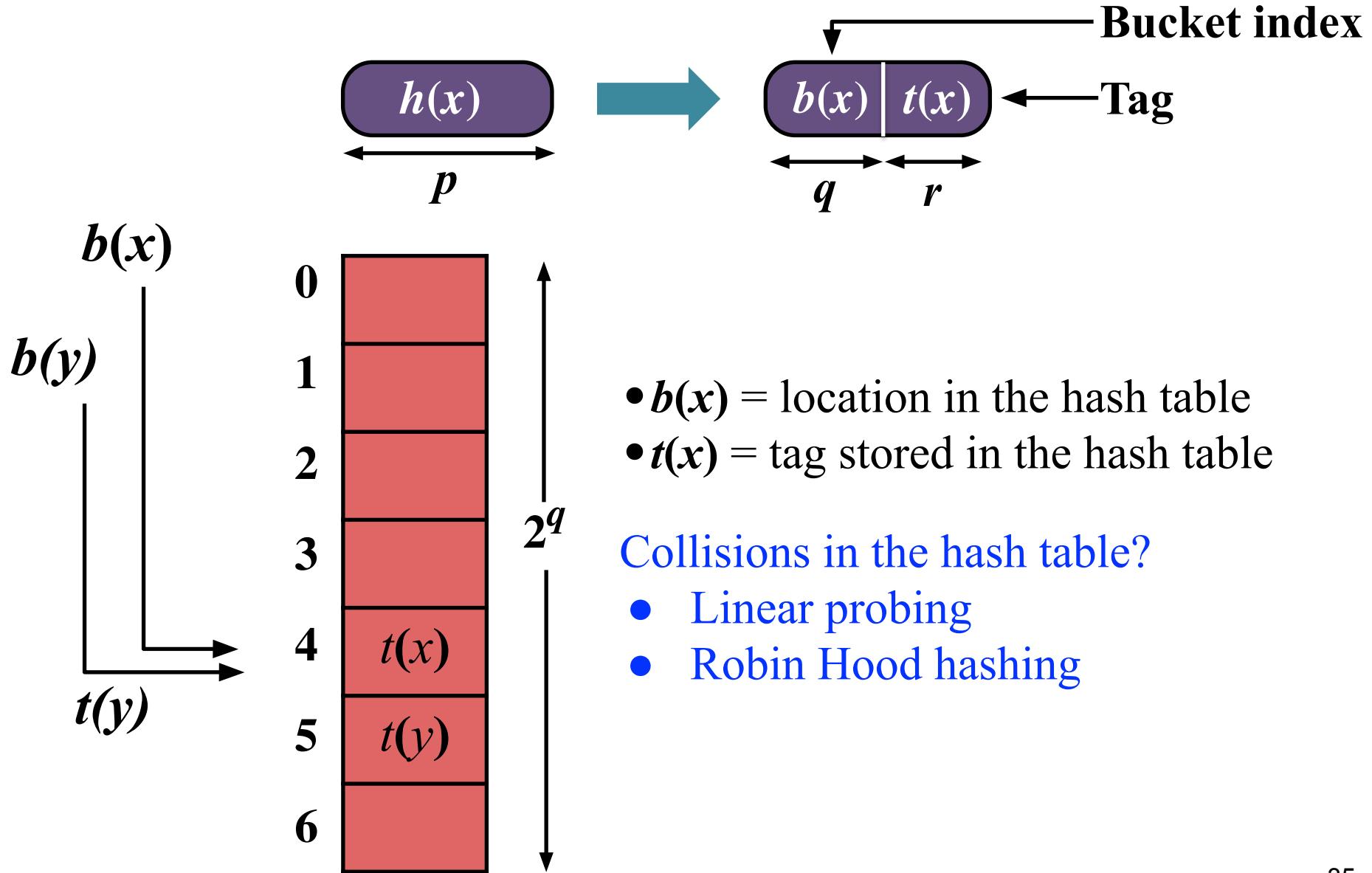
Storing fingerprints compactly



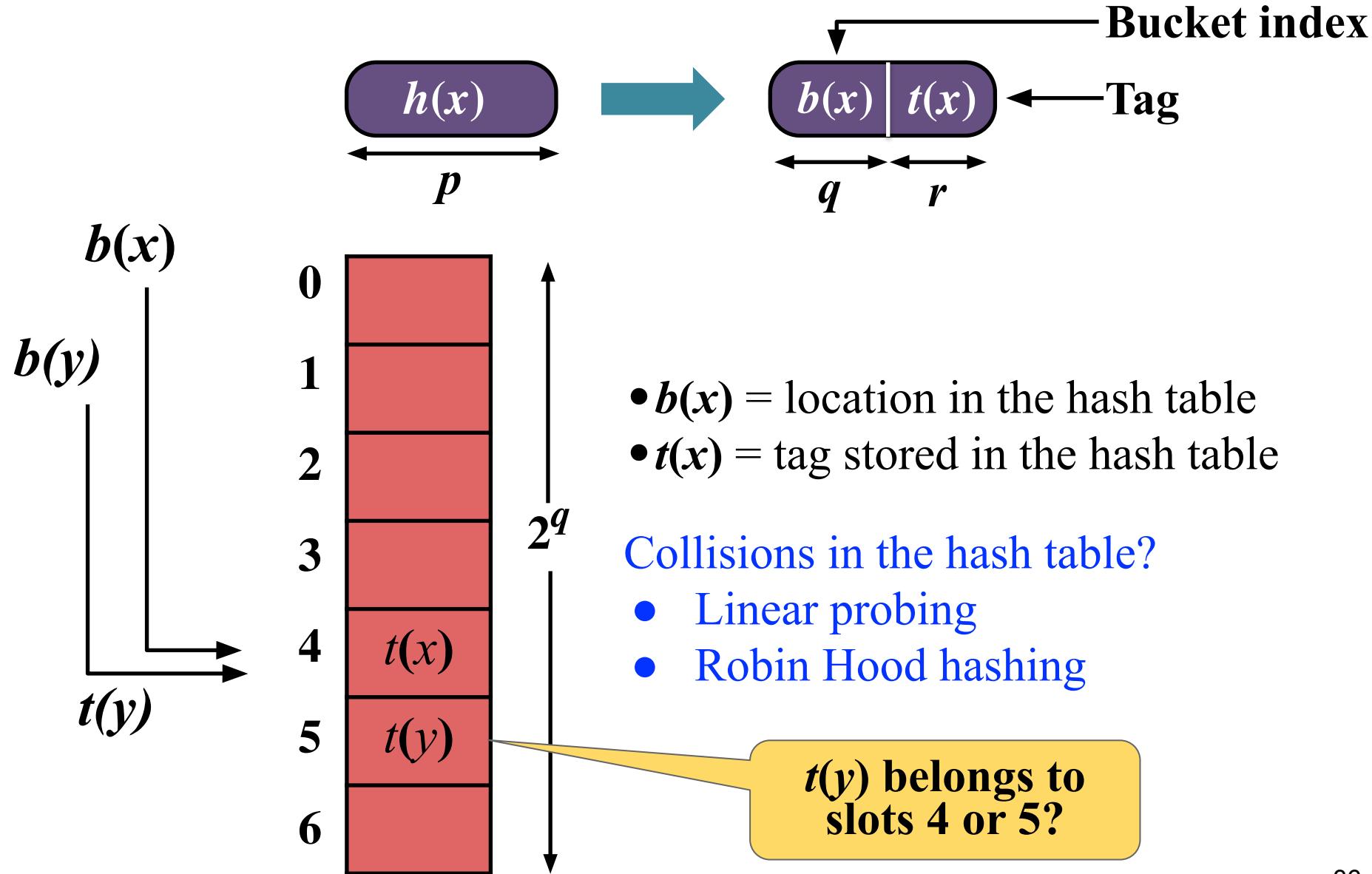
Storing fingerprints compactly



Storing fingerprints compactly



Storing fingerprints compactly



Resolving collisions in the QF [Panay et al. SIGMOD '17]

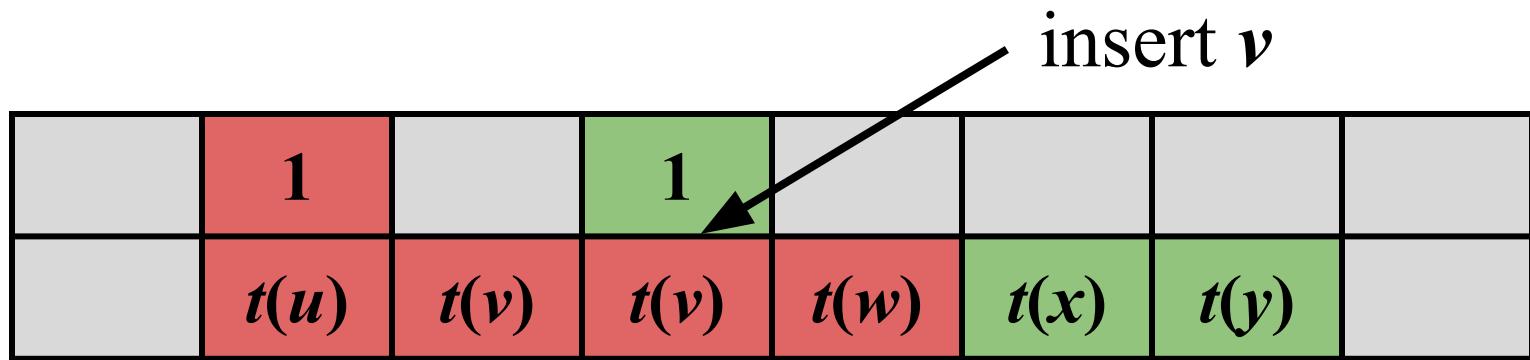
- QF uses two metadata bits to resolve collisions and identify home bucket

	1		1				
	$t(u)$	$t(v)$	$t(w)$	$t(x)$	$t(y)$		

- The metadata bits group tags by their home bucket

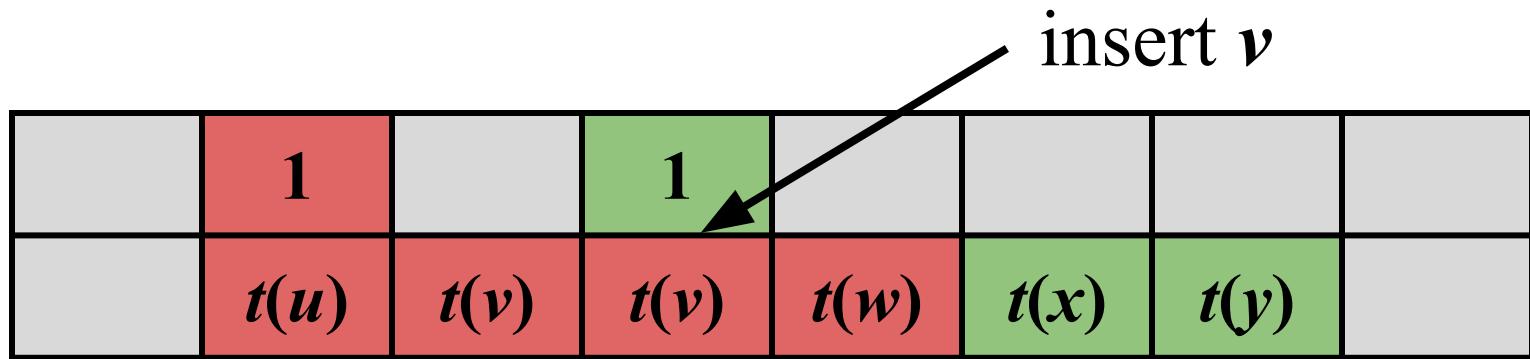
Resolving collisions in the QF [Panay et al. SIGMOD '17]

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- QF uses two metadata bits to resolve collisions and identify home bucket



- The metadata bits group tags by their home bucket

The metadata bits enable us to identify the slots holding the contents of each bucket.

Quotienting enables many features in the QF

- Good cache locality
- Efficient scaling out-of-RAM
- Deletions
- Enumerability/Mergeability
- Resizing
- Maintains count estimates or associate values
- Uses variable-sized encoding for counts [Counting quotient filter]
 - **Asymptotically optimal space: $O(\sum |C(x)|)$**



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- Good cache locality
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- Maintains count estimates or associate values
- Uses variable-sized encoding for counts [Counting quotient filter]
 - **Asymptotically optimal space: $O(\sum |C(x)|)$**

Mantis uses the QF
to map small keys to
values

Squeakr uses the QF
to count items



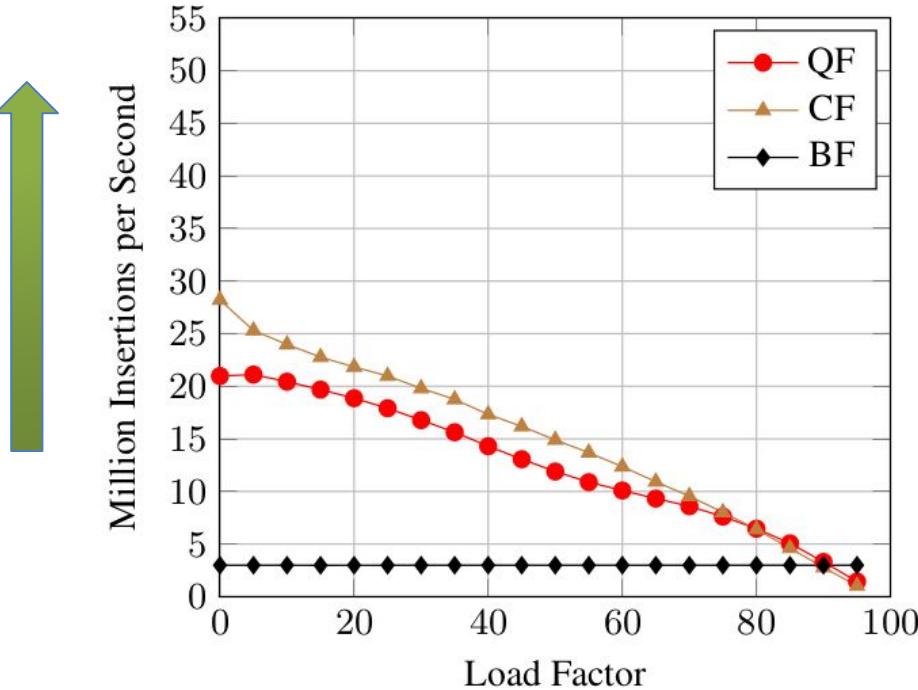
Quotient filters use less space than Bloom filters for all practical configurations

	Quotient filter	Bloom filter	Optimal
Space (bits)	$\approx n \log(1/\epsilon) + 2.125n$	$\approx 1.44 n \log(1/\epsilon)$	$\approx n \log(1/\epsilon) + \Omega(n)$
CPU cost	$O(1)$ expected	$\Omega(1/\epsilon)$	$O(1)$
Data locality	1 probe + scan	$\Omega(1/\epsilon)$ probes	$O(1)$ probes

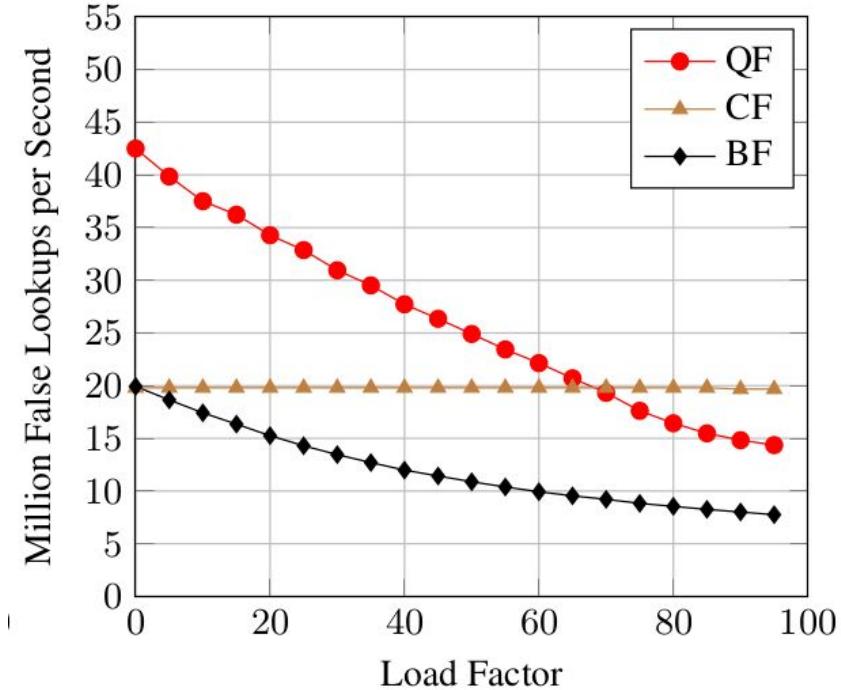
The quotient filter has theoretical advantages over the Bloom filter

Quotient filters perform better (or similar) to other non-counting filters

Inserts

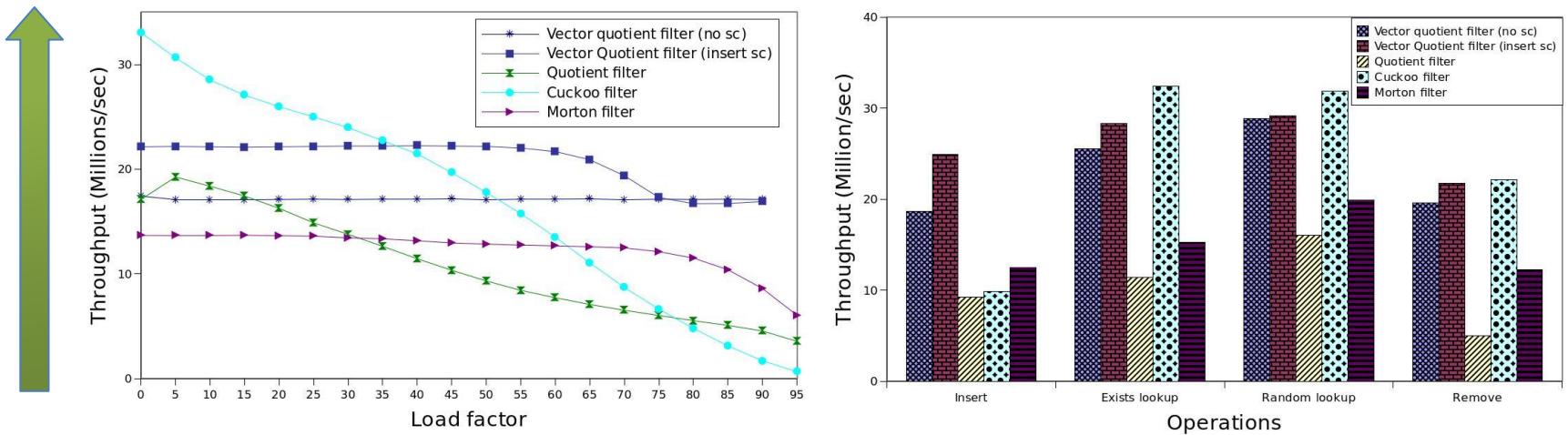


Lookups



- Insert performance is similar to the state-of-the-art non-counting filters
- Query performance is significantly fast at low load-factors and slightly slower at higher load-factors

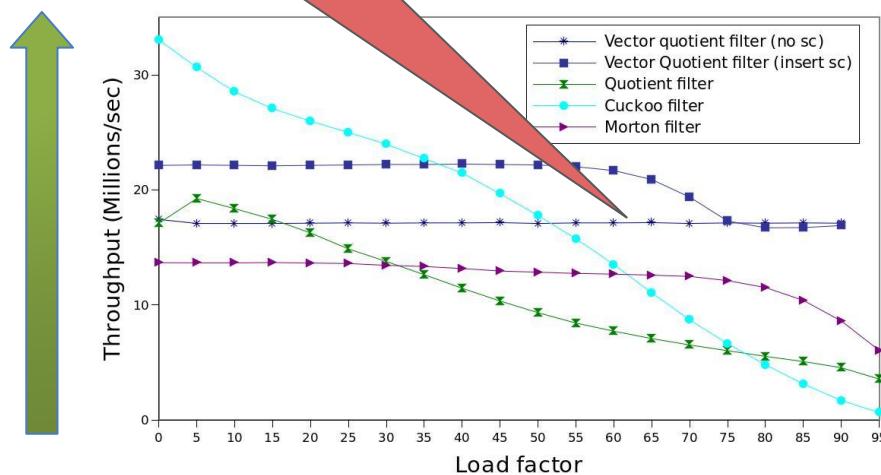
Vector quotient filter (VQF)^[Pandey et al. SIGMOD '21]



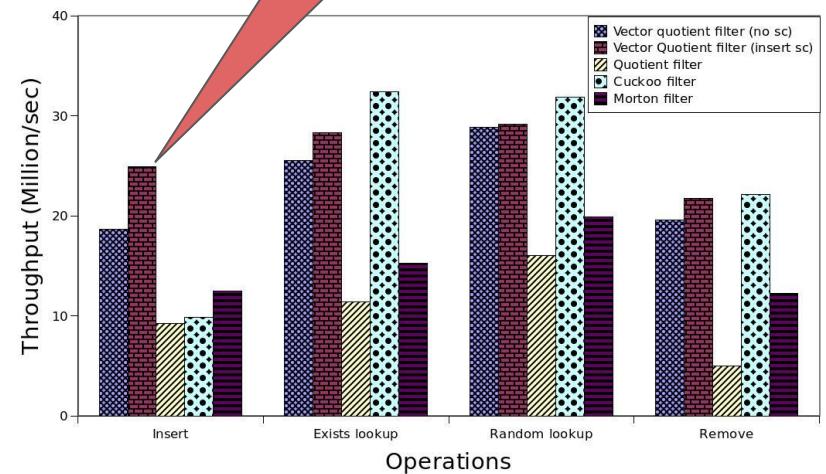
Combining hashing techniques (**Robin Hood + 2-choice hashing**)
Using ultra-wide vector operations (**AVX512-BW**)

Vector quotient filter (VQF)^[Pandey et al. SIGMOD '21]

Constant high performance from empty to full



Faster overall



Combining hashing techniques (**Robin Hood + 2-choice hashing**)
Using ultra-wide vector operations (**AVX512-BW**)

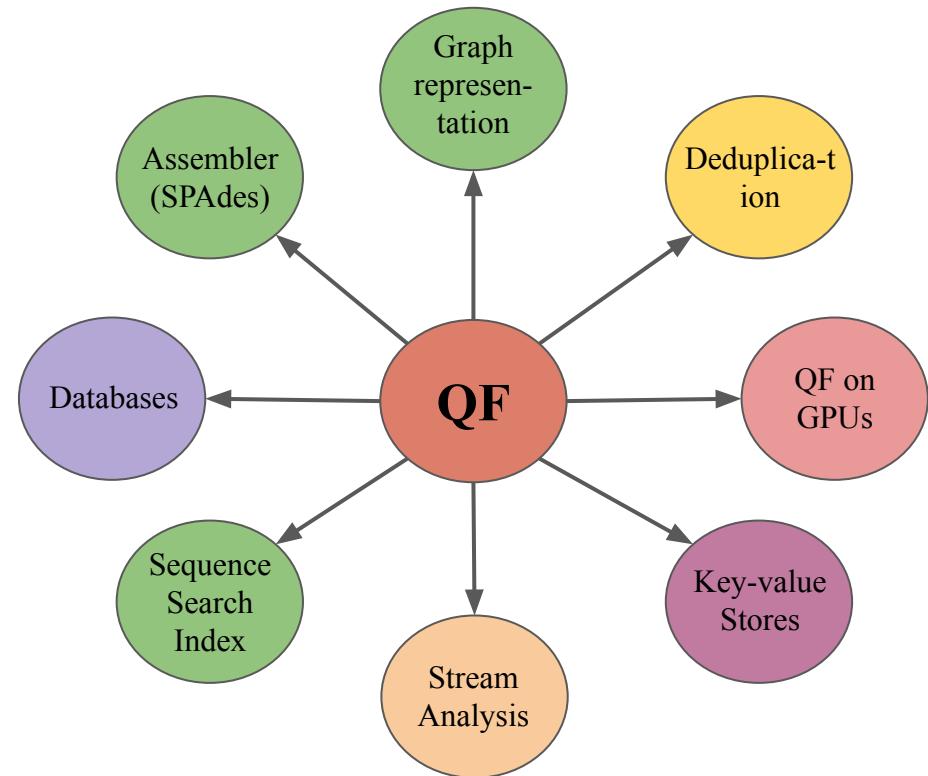
Quotient filter's impact in computer science

Computational biology

1. Squeakr
2. deBGR
3. Mantis
4. VariantStore

Databases/Systems

1. Anomaly detection
2. BetrFS file system



Theoretically well-founded data structures can have a **big impact** on multiple subfields across **academia and industry**

Quotient filter's impact in computer science

Computational biology

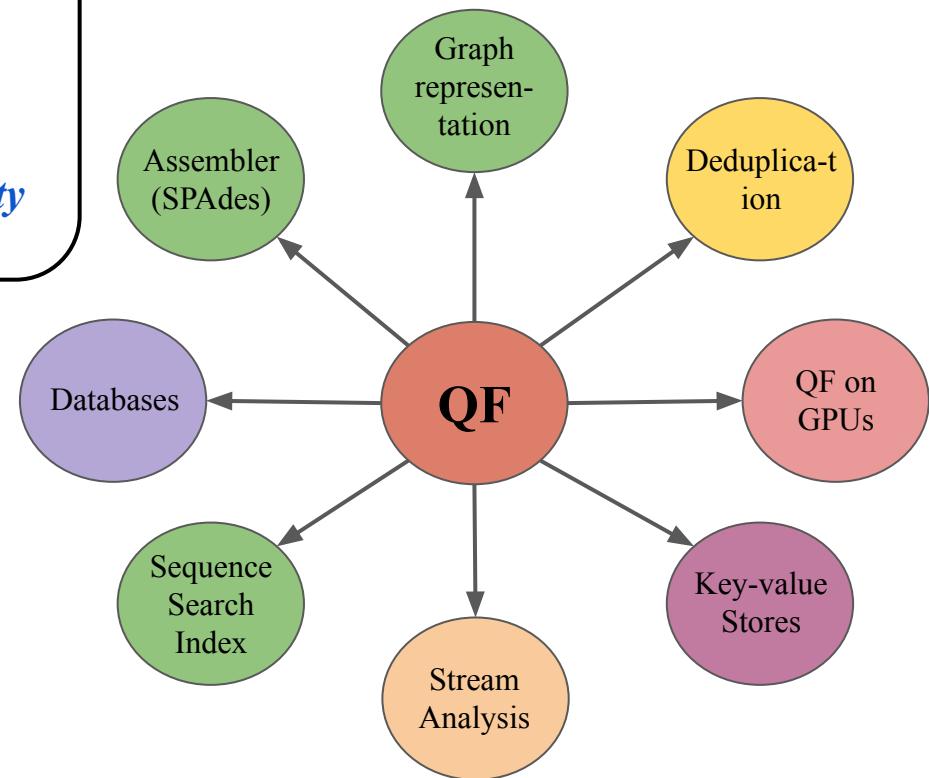
1. Squeakr
2. deBGR
3. Mantis
4. VariantStore
5. SPAdes assembler
6. Khmer software
7. MQF

Industry

1. VMware
2. Nutanix
3. Apocrypha
4. Hyrise
5. *A data security startup*

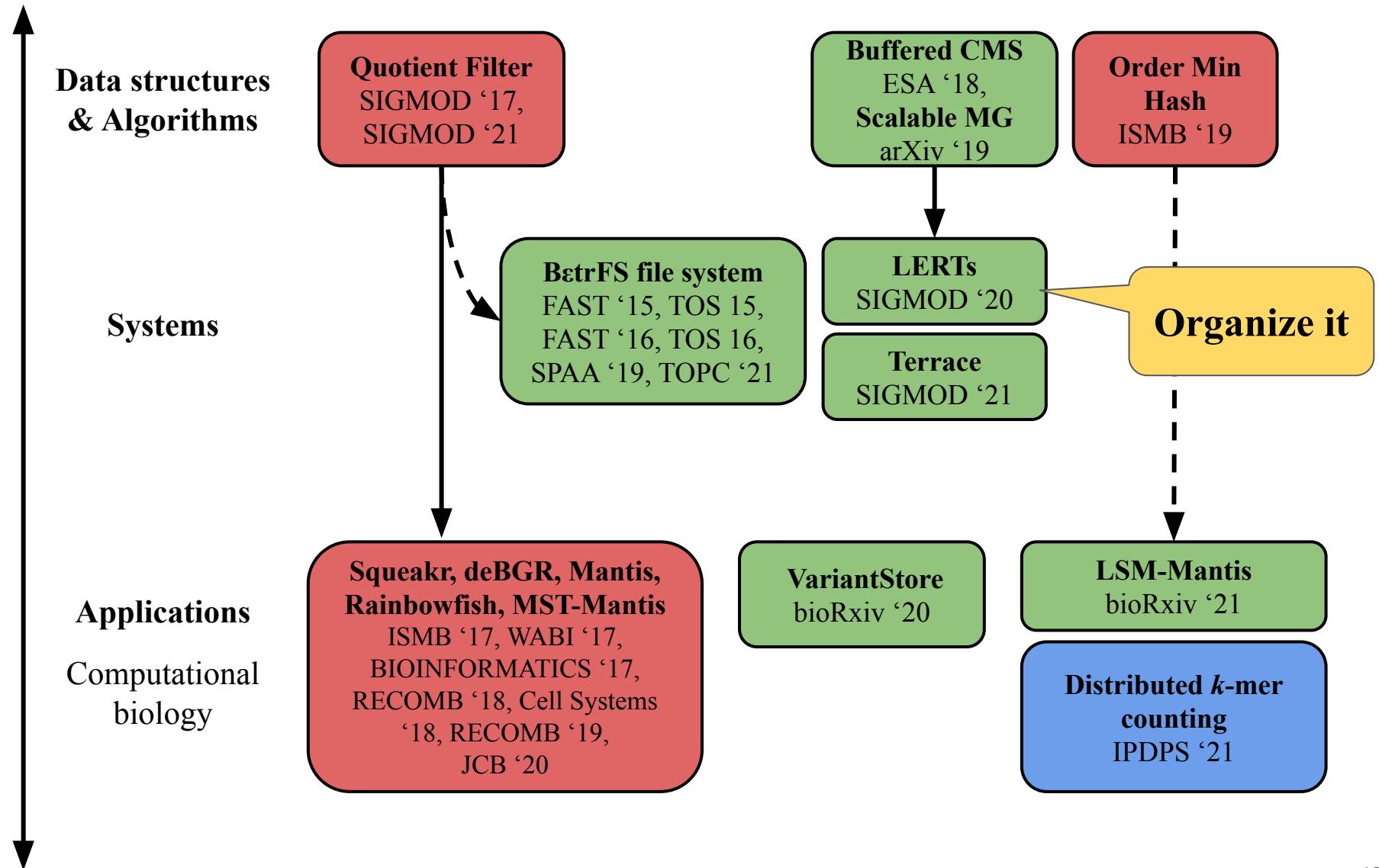
Databases/Systems

1. Anomaly detection
2. BetrFS file system
3. Counting on GPUs
4. Concurrent filters

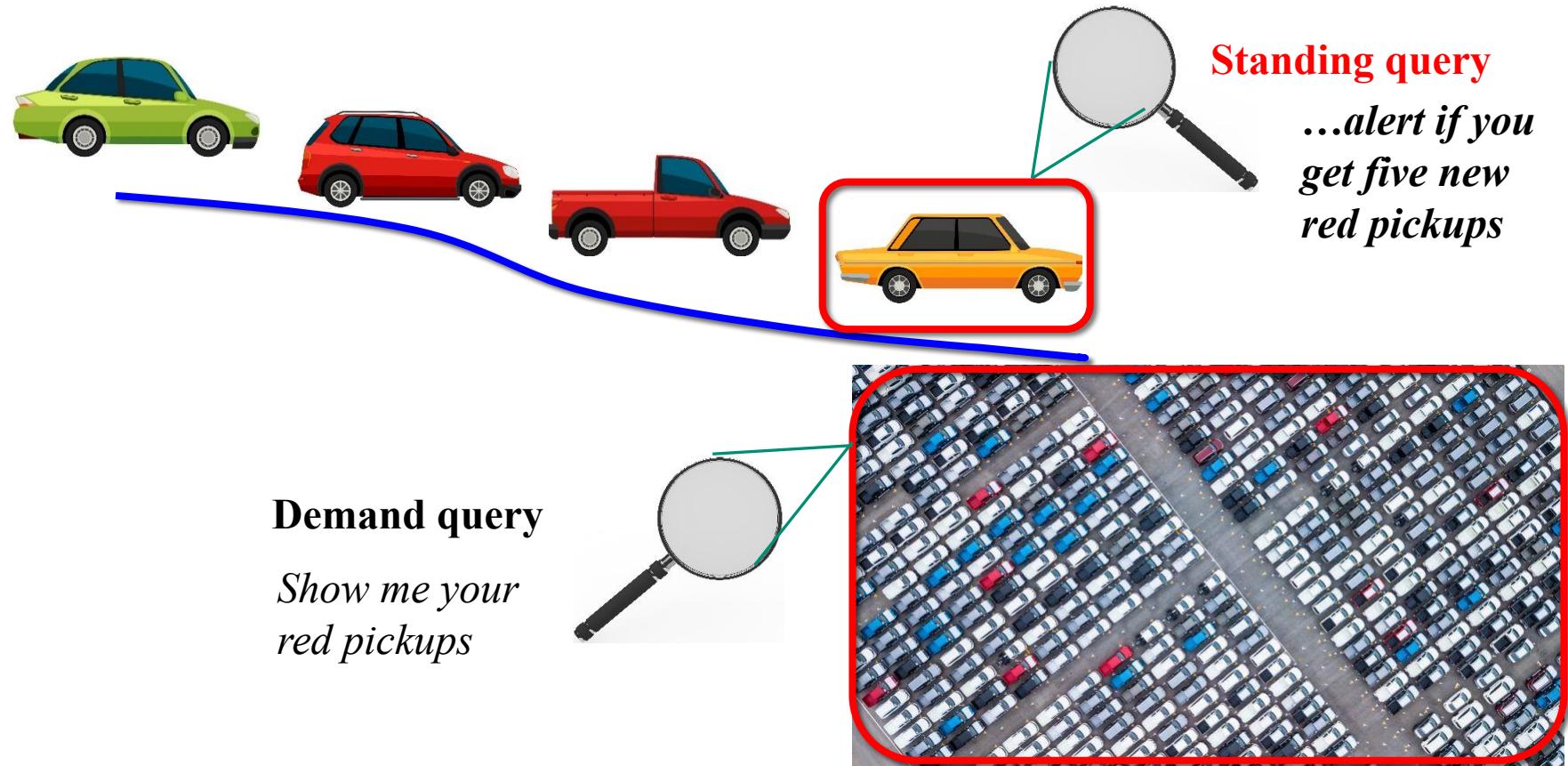


Theoretically well-founded data structures can have a **big impact** on multiple subfields across **academia and industry**

Learned “Shrink it”. Now “Organize it”



Timely event detection problem



In **timely event-detection problem (TED)**, we want to answer standing queries

Features we need in the solution

- Stream is large (e.g., terabytes) and high-speed (millions/sec)

High throughput ingestion



Features we need in the solution

- Stream is large (e.g., terabytes) and high-speed (millions/sec)

High throughput ingestion



- Events are high-consequence real-life events

No false-negatives; few false-positives

Sampling

A red circle with a diagonal slash through it, indicating that sampling is not desired or is prohibited.

Timely reporting (real-time)



Features we need in the solution

- Stream is large (e.g., terabytes) and high-speed (millions/sec)

High throughput ingestion



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Timely reporting (real-time)

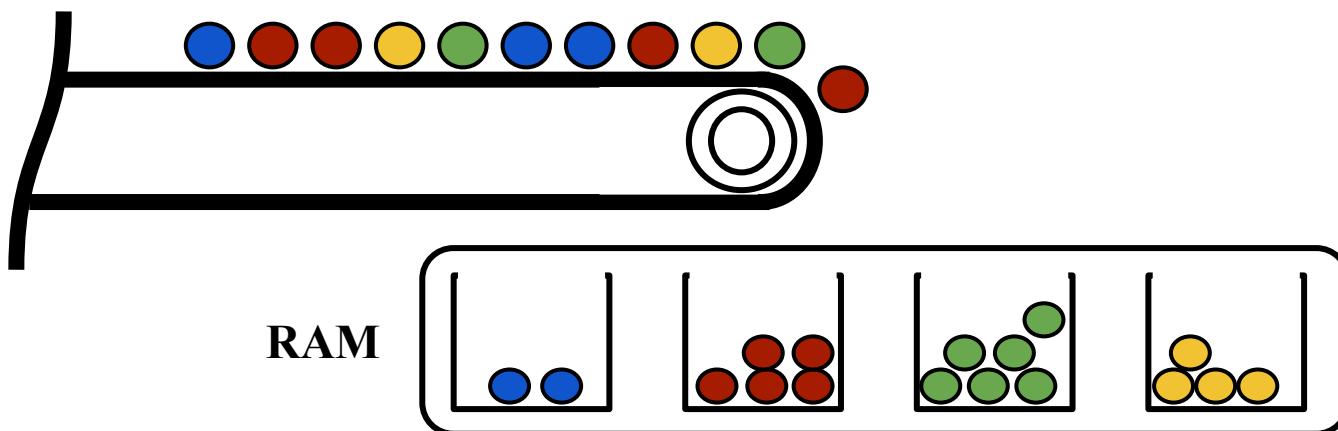
- Malicious traffic forms a small portion of the stream

Very small reporting thresholds



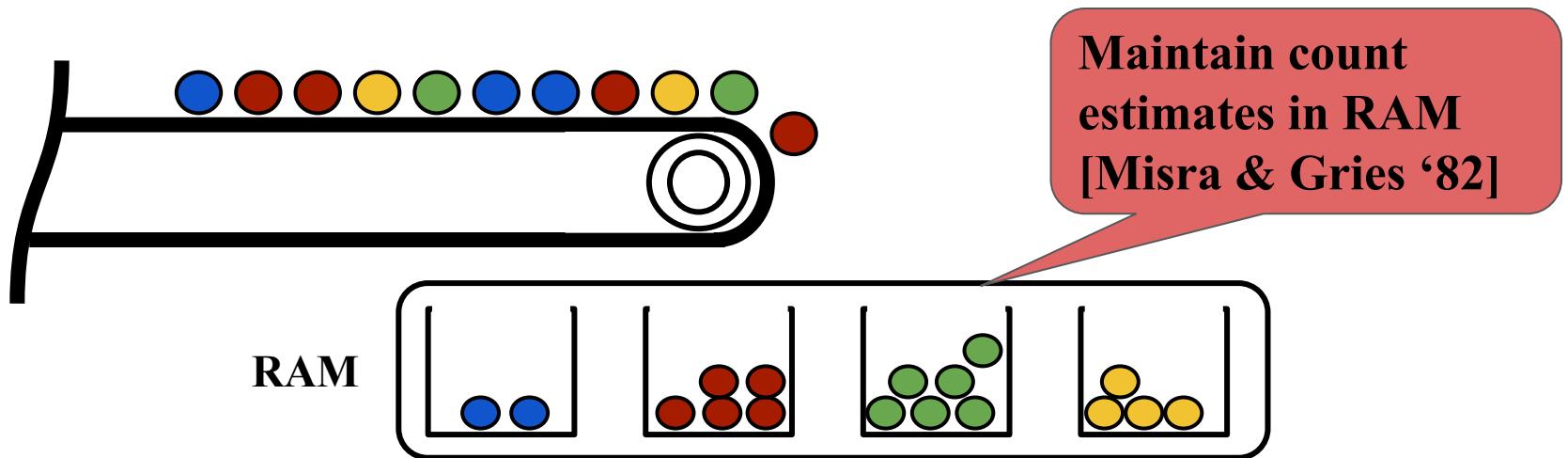
One-pass streaming has errors

- **Heavy hitter problem:** report items whose frequency $\geq \varphi N$
- Exact one-pass solution requires $\Omega(N)$ space



One-pass streaming has errors

- **Approximate solution:** report all items with count $\geq \varphi N$, none with $< (\varphi - \varepsilon)N$ [Alon et al. 96, Berinde et al. 10, Bhattacharyya et al. 16, Bose et al. 03, Braverman et al. 16, Charikar et al. 02, Cormode et al. 05, Demaine et al. 02, Dimitropoulos et al. 08, Larsen et al. 16, Manku et al. 02.]
- Approximate solutions require $\Omega(1/\varepsilon)$ space

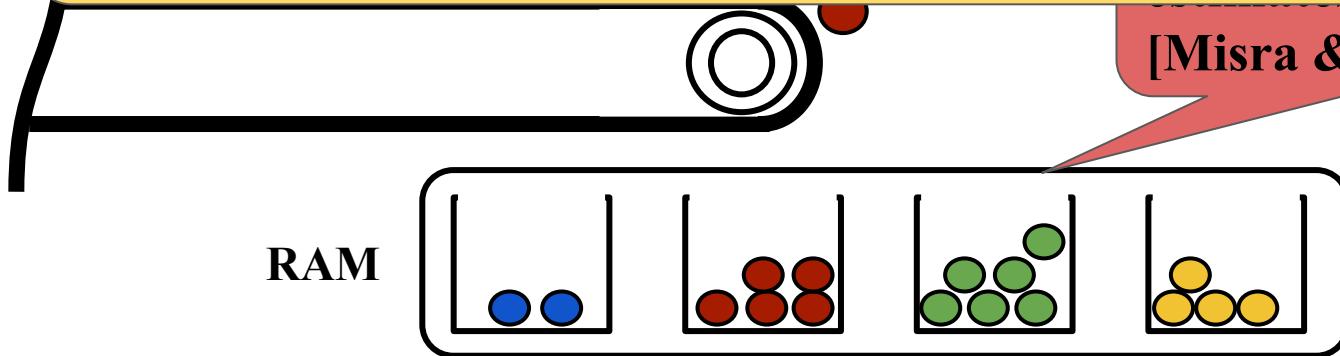


Real time with false-positives!

One-pass streaming has errors

- **Approximate solution:** report all items with count $\geq \varphi N$, none with $< (\varphi - \epsilon)N$ [Alon et al. 96, Berinde et al. 10, Bhattacharyya et al. 16, Bose et al. 03, Braverman et al. 16, Charikar et al. 02, Cormode et al. 05, Demaine et al. 02, Dimitropoulos et al. 08, Larsen et al. 16, Manku et al. 02.]
- Approximate solutions require $\Omega(1/\epsilon)$ space

For some apps, φN is a small constant,
So $\Omega(1/\epsilon)$ is very very large!!
Can't solve in RAM for very small φ



Real time with false-positives!

One-pass solution has:

- Stream is large (e.g., terabytes) and high-speed (millions/sec)

High throughput ingestion



- Events are high-consequence real-life events

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Timely reporting (real-time)



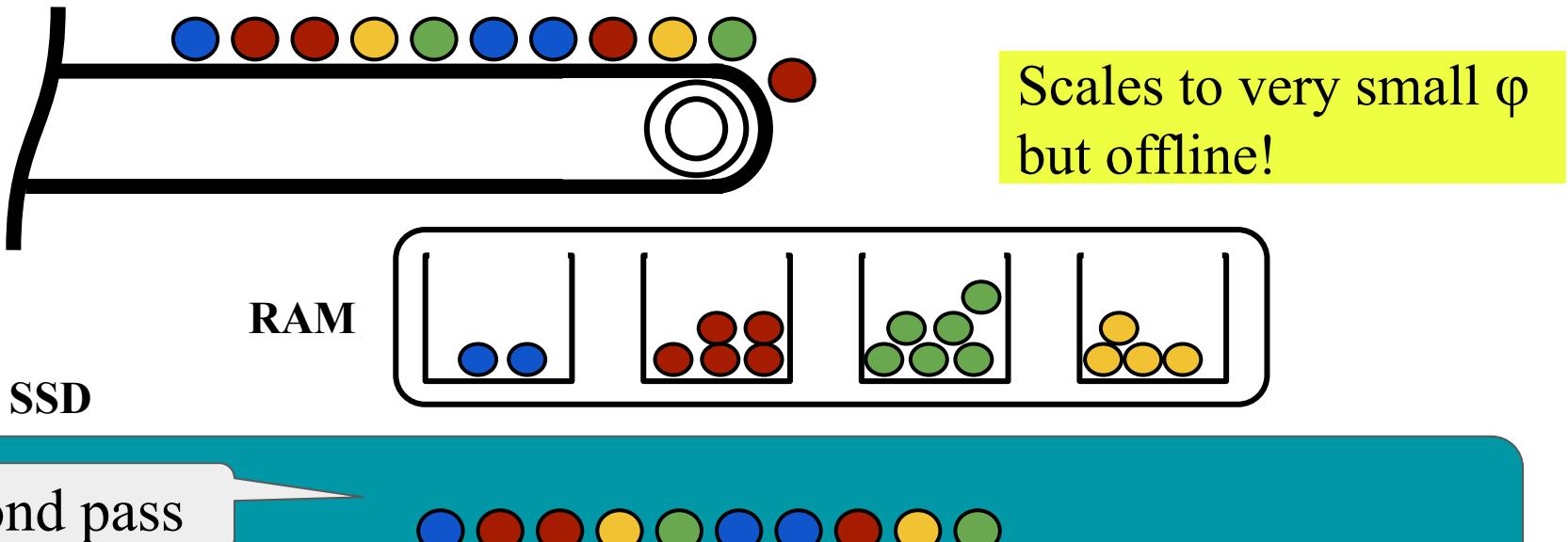
- Malicious traffic forms a small portion of the stream

Very small reporting thresholds



Two-pass streaming isn't real-time

- A second pass over the stream can get rid of errors
- Store the stream on SSD and access it later



Two-pass solution has:

- Stream is large (e.g., terabytes) and high-speed (millions/sec)

High throughput ingestion



- Events are high-consequence real-life events

No false-negatives; few false-positives



Timely reporting (real-time)



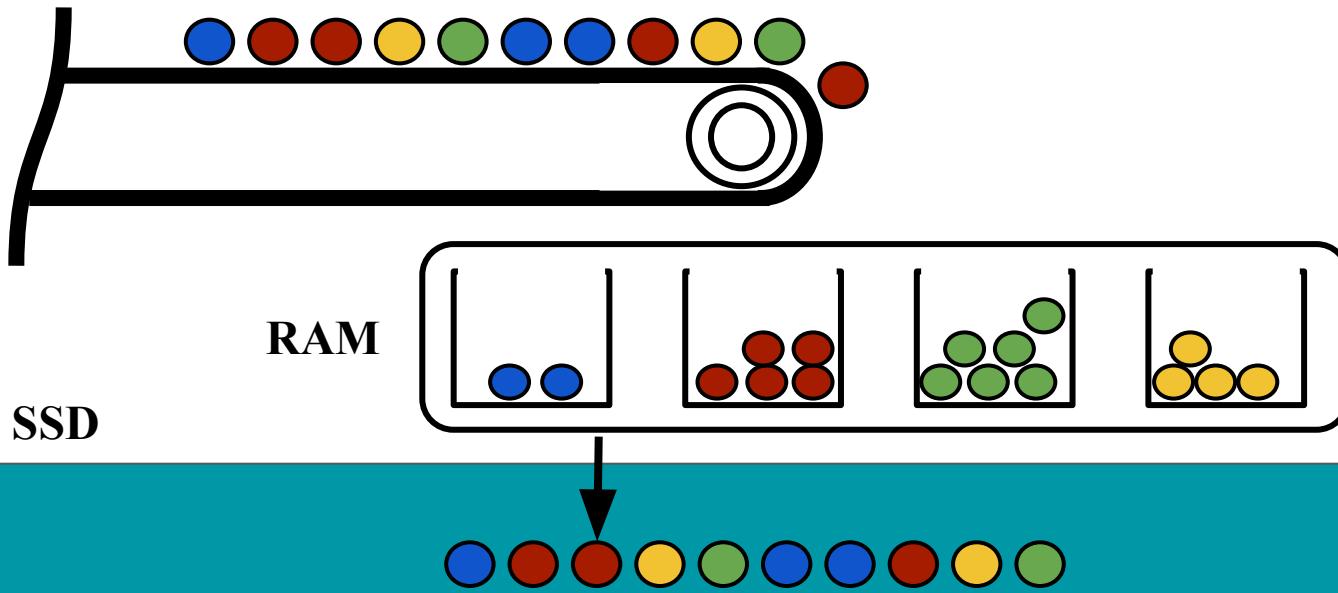
- Malicious traffic forms a small portion of the stream

Very small reporting thresholds



If data is stored: why not access it?

Why wait for second pass?





Idea: combine streaming and external memory (EM) [Pandey et al. SIGMOD '20]



Use an efficient external-memory counting data structure to scale Misra-Gries algorithm to SSDs

Operations in external memory dictionaries

Bender et al. '12

Insert	Query
$O\left(\frac{1}{B} \log \frac{N}{M}\right)$	$O\left(\log \frac{N}{M}\right)$

Performance bounds are parameterized by block transfer size B ,
memory size M , data size N .

Operations in external memory dictionaries

Bender et al. '12

Insert	Query
$O\left(\frac{1}{B} \log \frac{N}{M}\right)$	$O\left(\log \frac{N}{M}\right)$

< 1 I/O per
observation



Performance guarantees are parameterized by block transfer size B ,
memory size M , data size N .

Operations in external memory dictionaries

Bender et al. '12

Insert	Query
$O\left(\frac{1}{B} \log \frac{N}{M}\right)$	$O\left(\log \frac{N}{M}\right)$

< 1 I/O per observation



> 1 I/O per observation



Performance guarantees are parameterized by block size B , memory size M , data size N .

EM dictionary doesn't have real-time reporting

Bender et al. '12

**But every insert is also a query in
real-time reporting!**

Insert	Query
$O\left(\frac{1}{B} \log \frac{N}{M}\right)$	$O\left(\log \frac{N}{M}\right)$

< 1 I/O per
observation



> 1 I/O per
observation



Performance curves are parameterized by batch size B ,
memory size M , data size N .

EM dictionary doesn't have real-time reporting

Bender et al. '12

**But every insert is also a query in
real-time reporting!**

insert	Query
$O\left(\frac{1}{B} \log \frac{N}{M}\right)$	$O\left(\log \frac{N}{M}\right)$

**Traditional EM dictionary doesn't solve
the problem!**

observation

observation

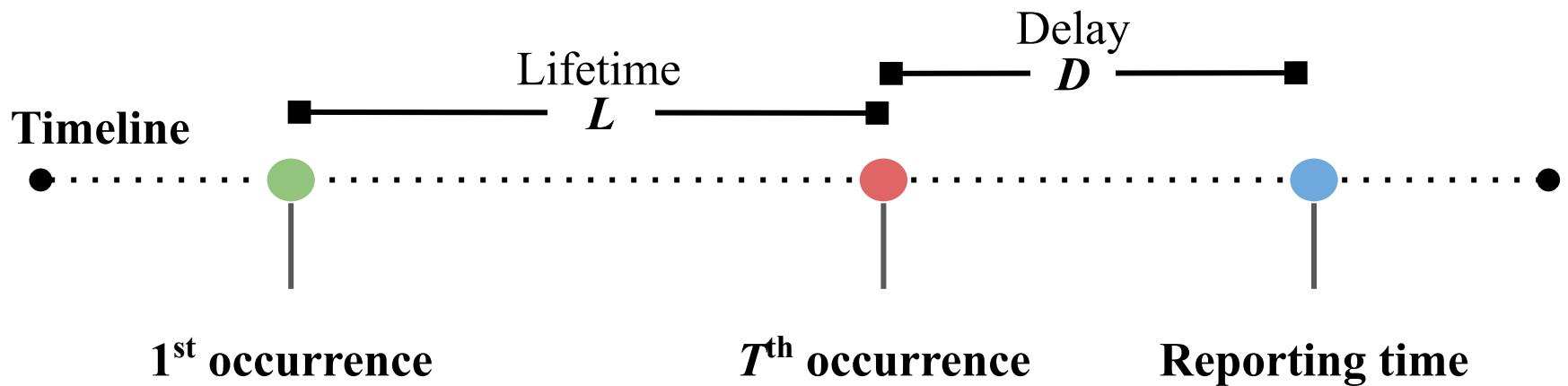
Performance guarantees are parameterized by batch size B ,
memory size M , data size N .



Idea: reporting with bounded delay

We define the time stretch of a report to be

$$\text{Time stretch} = 1 + \alpha = 1 + \frac{\text{Delay}}{\text{Lifetime}}$$





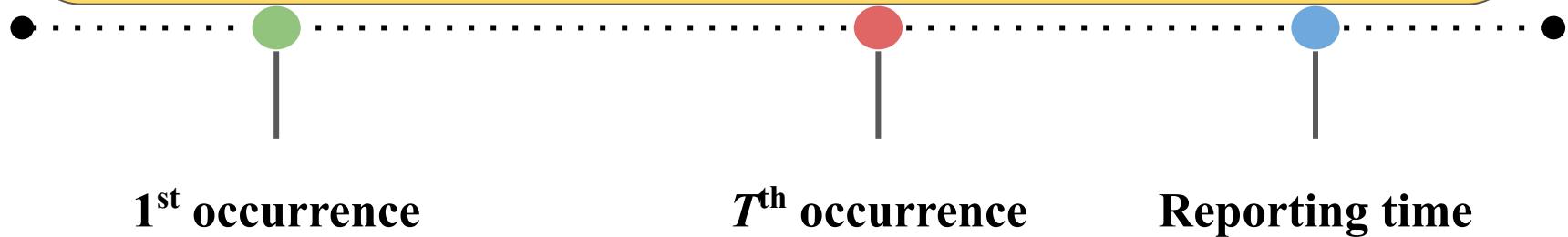
Idea: reporting with bounded delay

We define the time stretch of a report to be

$$\text{Time stretch} = 1 + \alpha = 1 + \frac{\text{Delay}}{\text{}}$$

Main idea: the longer the lifetime of an item, the more leeway we have in reporting it

Tip:



Leveled External-Memory Reporting Table (LERT) [Pandey et al. SIGMOD '20]

- Given a stream of size N and $\varphi N > \Omega(N/M)$ the amortized cost of solving real-time event detection is

$$O\left(\left(\frac{1}{B} + \frac{1}{(\phi-1/M)N}\right) \log \frac{N}{M}\right)$$

- For a **constant α** , can support arbitrarily small thresholds φ with amortized cost

$$O\left(\frac{1}{B} \log \frac{N}{M}\right)$$

Takeaway: Online reporting comes at the cost of throughput but almost online reporting is essentially free!

Leveled External-Memory Reporting Table (LERT) [Pandey et al. SIGMOD '20]

- Given a stream of size N and $\varphi N > \Omega(N/M)$ the amortized cost of solving real-time event detection is

$$\tilde{O}((\ell_1 + 1) \cdot \log \frac{N}{M})$$

Can achieve timely reporting at effectively the optimal insert cost; no query cost

with amortized cost

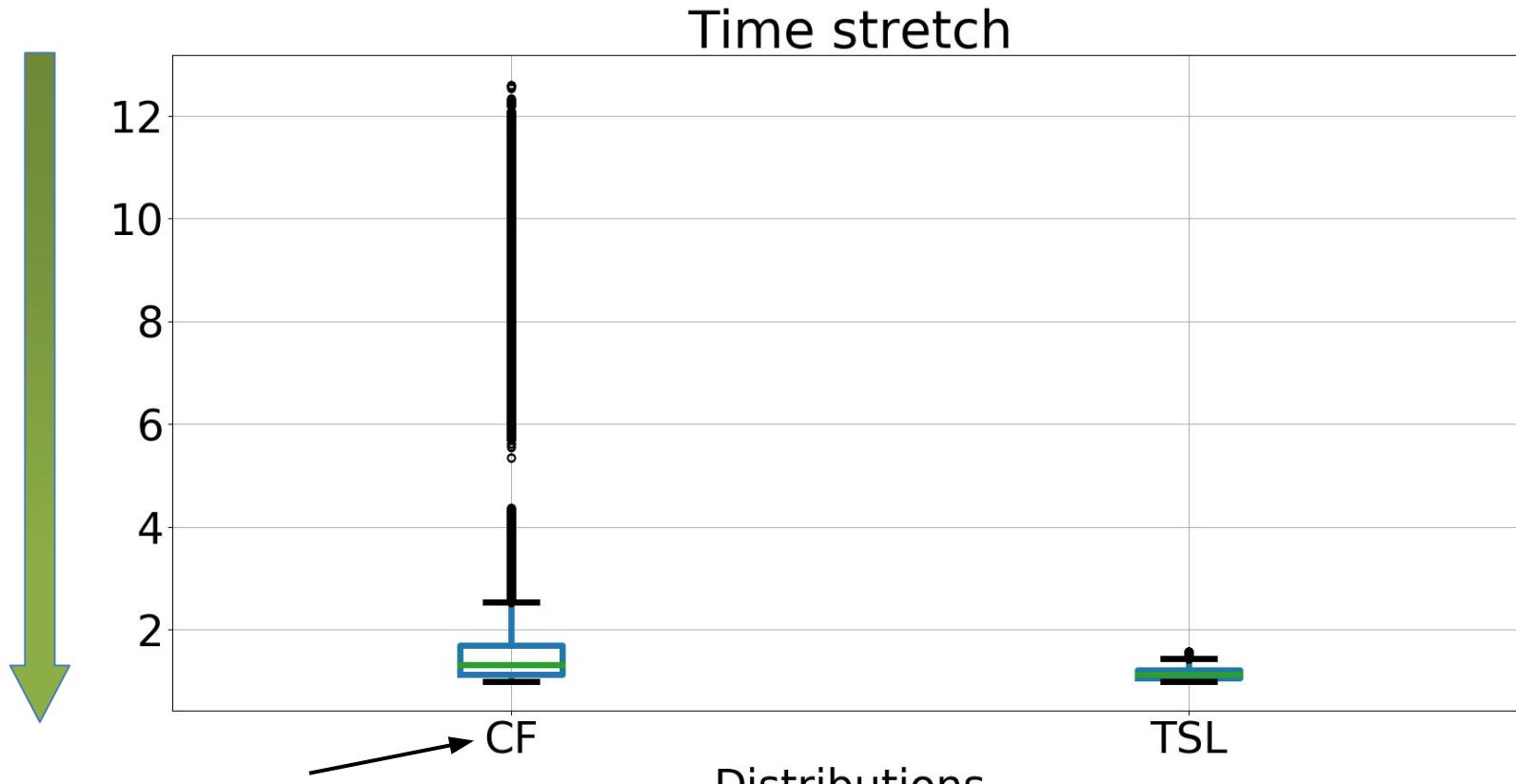
$$O\left(\frac{1}{B} \log \frac{N}{M}\right)$$

Takeaway: Online reporting comes at the cost of throughput but almost online reporting is essentially free!

Evaluation

- Empirical timeliness
- High-throughput ingestion

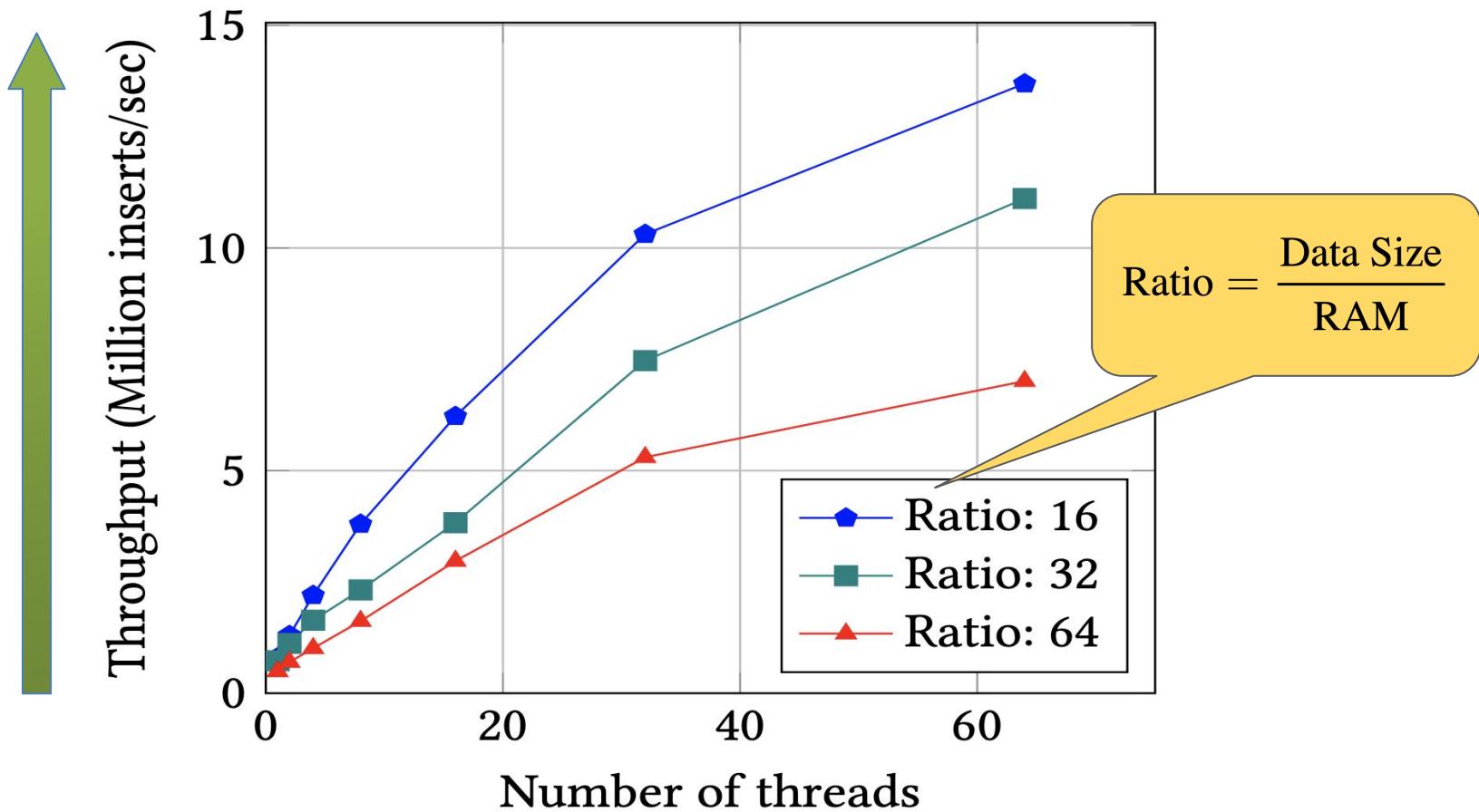
Evaluation: empirical time stretch



Cascade filter [Bender et al. '12]
State-of-the-art external memory counting
table

Average time stretch is 43% smaller than theoretical upper bound.

Evaluation: scalability



The insertion throughput increases as we add more threads.
We can achieve > 13M insertions/sec.

LERT: supports scalable and real-time reporting

- Stream is large (e.g., terabytes) and high-speed (millions/sec)

High throughput ingestion



- Events are high-consequence real-life events

No false-negatives; few false-positives



Timely reporting (real-time)



- Malicious traffic forms a small portion of the stream

Very small reporting thresholds



Ongoing/future work

Shrink

Organize

Distribute



**Data structures
& Algorithms**

High performance filters/hash tables

Optimize large-scale indexes using ML

CQF on GPUs

Systems

Scalable streaming graph processing system

Distributed hash table (based on quotient filters)

Event detection for infinite streams

Applications
Computational biology

Population-scale index for multi-coordinate variation data

Graph neural networks for metagenomics

Distributed Mantis: publicly hosted for scientific use

Ongoing/future work

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Distributed Mantis: publicly hosted for scientific use

Future work: next gen data structure library

Goal: Overcome *decades-old* data structure *trade-offs* using new algorithmic paradigms and modern hardware

Existing hash table techniques

Separate chaining

- Chaining with linked-list
- Chaining with binary tree

Open addressing

- Linear probing
- Coalesced chaining
- Cuckoo hashing
- Hopscotch hashing
- Robin Hood hashing
- 2-choice hashing
- d-left hashing

- Cuckoo hashing suffers from *random hopping*
- Linear probing/Robin Hood hashing suffer from *long chains*
- 2-choice/d-left hashing suffer from *multiple probes*

Iceberg hash table

Collaborators: Joe Durie, Alex Conway, Rob Johnson, Michael Bender, Martin Farach-Colton



Balanced for most items

Very low variance

- Step 1: set *primary bin* by single hashing
 - If the bin has $< \tau$ *type 1* items, insert the new item in the bin as *type 1*
- Step 2: If there are $< \square$ *type 2* items, insert the new item using d-left as *type 2*
- Step 3: select the *primary bin* and inserted as *type 3*

$$\tau = h + (3h \log h)^{2/3} \quad \delta = cn \quad h = \frac{\#items}{\#bins}$$

Iceberg hash table

Collaborators: Joe Durie, Alex Conway, Rob Johnson, Michael Bender, Martin Farach-Colton

Single hashing

d-left hashing



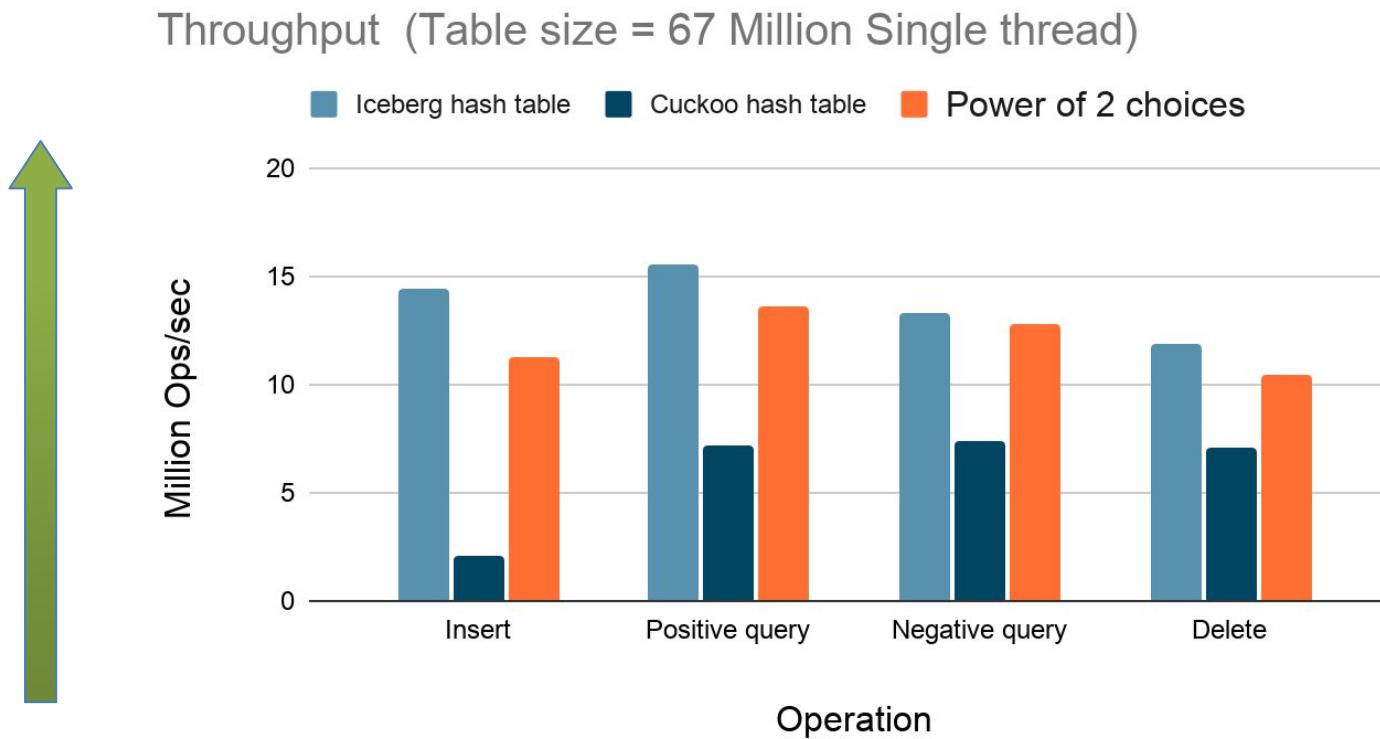
Limits variance across bins without random hopping and multiple probes

- If the bin has $< \tau$ *type 1* items, insert the new item in the bin as *type 1*
- Step 2: If there are $< \square$ *type 2* items, insert the new item using d-left as *type 2*
- Step 3: select the *primary bin* and inserted as *type 3*

$$\tau = h + (3h \log h)^{2/3} \quad \delta = cn \quad h = \frac{\#items}{\#bins}$$

Iceberg hash table performance

Collaborators: Joe Durie, Alex Conway, Rob Johnson, Michael Bender, Martin Farach-Colton

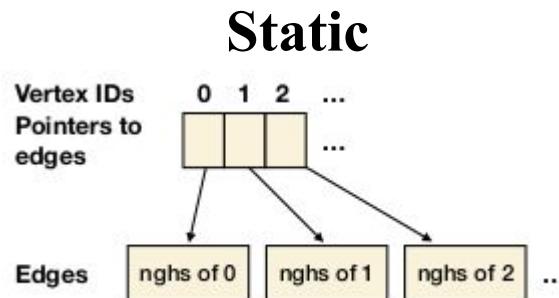


- **6.8X faster for insertions**
- **~2X faster for queries**
- **1.6X faster for deletes**

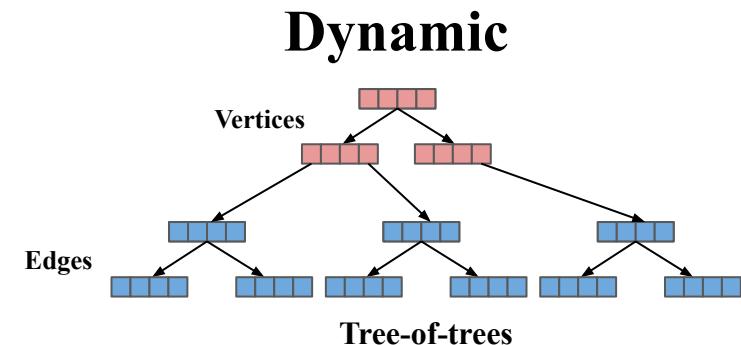
Future work: system for streaming graphs

Goal: build *highly scalable* streaming graph representation system

“One-size-fits-all” approach is suboptimal



LIGRA [Shun & Blelloch '13]



ASPEN [Dhulipala et al.
'19]

	LIGRA	ASPEN
add_edge	$O((E + V))/B$	$O(\log V + c^2 \log(\deg(u))/B)$
get_neighbors	$O(\deg(u)/B)$	$O(\log V + \deg(u)/B + \deg(u)/c)$

Neighbor access requires at least ***two cache misses***
For dynamic, all operations have a ***log factor***

“One-size-fits-all” approach is suboptimal



Static → Fast computations; no updates

Dynamic → Slower computations; updates

	LIGRA	ASPEN
add_edge	$O((E + V))/B)$	$O(\log V + c^2 \log(\deg(u))/B)$
get_neighbors	$O(\deg(u)/B)$	$O(\log V + \deg(u)/B + \deg(u)/c)$

Neighbor access requires at least *two cache misses*

For dynamic, all operations have a *log factor*

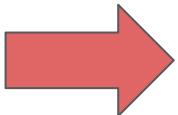
Real world graphs are often skewed

High variance in the
degree distribution

Hierarchical structure + dynamic partitioning

Collaborators: Helen Xu, Brian Wheatman, Aydin Buluc, Kathy Yelick

High variance in the degree distribution

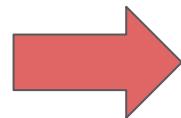


- In-place structure for vertices with low degree
- Shared sparse-array (PMA) for vertices with medium degree
- Independent B-tree for vertices with high degree

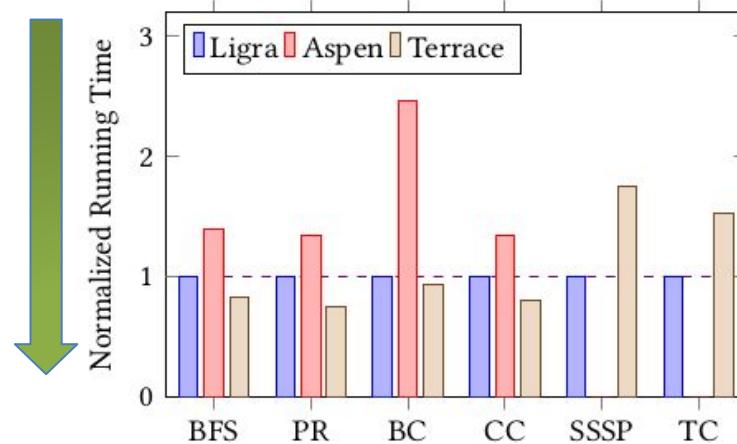
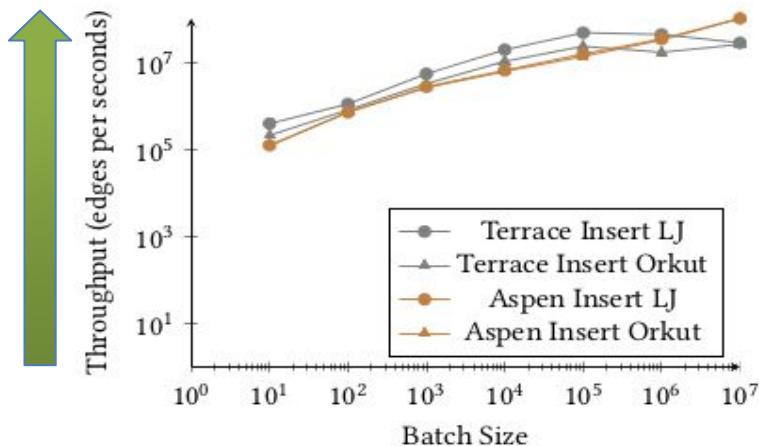
Hierarchical structure + dynamic partitioning

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High variance in the degree distribution



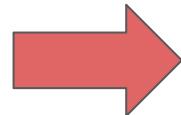
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Hierarchical structure + dynamic partitioning

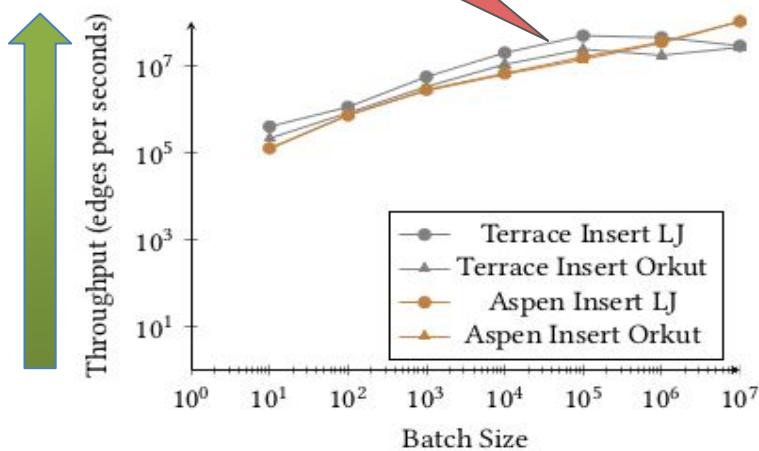
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High variance in the degree distribution

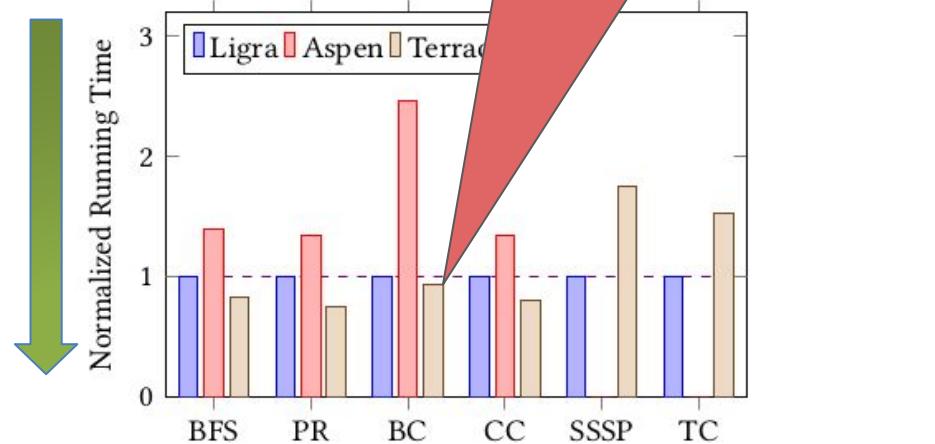


- In-place structure for vertices with low degree
- Shared sparse-array (PMA) for vertices with medium degree
- Independent B-tree for vertices with high degree

Terrace:
fast updates



Terrace:
faster computations



Future work: ML/DL for scalable indexing

Goal: optimize large-scale indexing
solutions using machine learning

Sample discovery problem

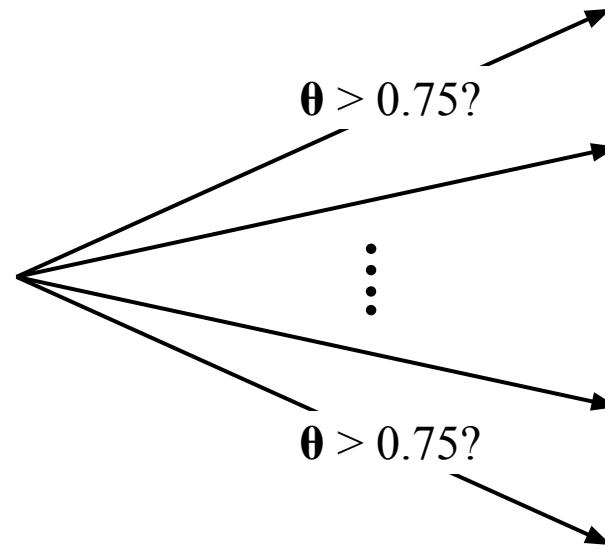
Solomon & Kingsford Nat Biotech '16

...ACACGTA...



Check if this new transcript has been seen before?

...
ACACG
CACGT
ACGTA
...
 **k -mers
> 10 Billion**



**SRA Samples
(> 100K samples)**

Return all samples that contain at least some user-defined fraction θ of the k -mers present in the query string

Mantis index for sample discovery problem

...ACACGT... 
Check if this new transcript has been seen before?

Input Samples			
SRR 001	SRR 002	SRR 003	SRR 004
	ACTG	ACTG	
ACTT			
		CTTG	CTTG
	TTTC	TTTC	
	GCGT	GCGT	GCGT
	AGCC	AGCC	

QF

k-mer	Color ID
ACTG	0
ACTT	10
CTTG	1
TTTC	0
GCGT	11
AGCC	0

Color Class Table

	S1	S2	S3	S4
0	0	1	1	0
1	0	0	1	1
10	1	0	0	0
11	0	1	1	1

Mantis index

ACTGAGTGA
ACGTTGTGC
GTGCGTGGC
TAAACGTGA
CGTCACGTGA

ACTGAGTGA
ACGTTGTGC
GTGCGTGGC
TAAACGTGA
CGTCACGTGA

⋮
⋮

ACTGAGTGA
ACGTTGTGC
GTGCGTGGC
TAAACGTGA
CGTCACGTGA

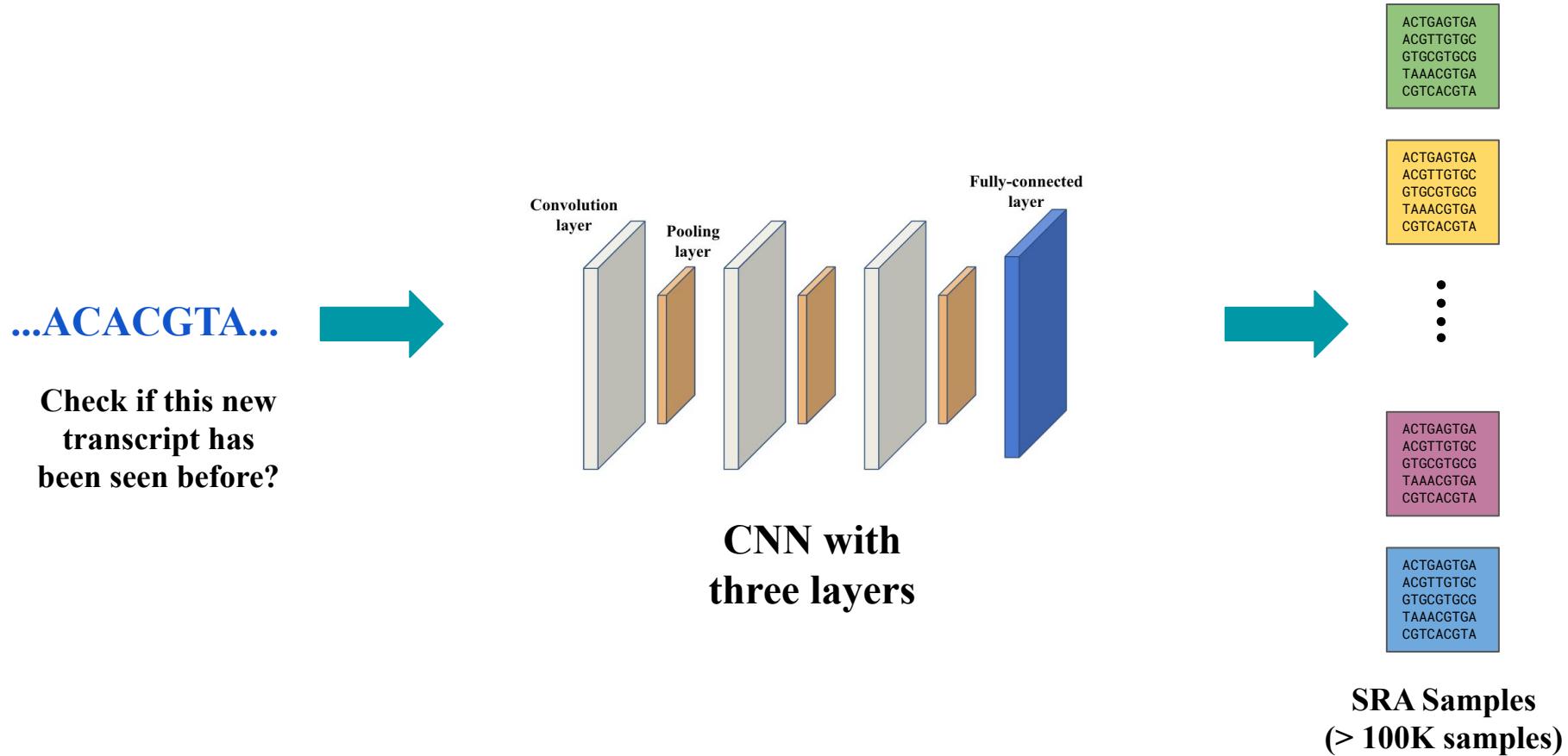
ACTGAGTGA
ACGTTGTGC
GTGCGTGGC
TAAACGTGA
CGTCACGTGA

SRA Samples
(> 100K samples)

Mantis index is based on a map from k -mers to a list of samples where the k -mer appears.

ML for sample discovery problem

Collaborators: Nick Bhattacharya, Aydin Buluc, Kathy Yelick



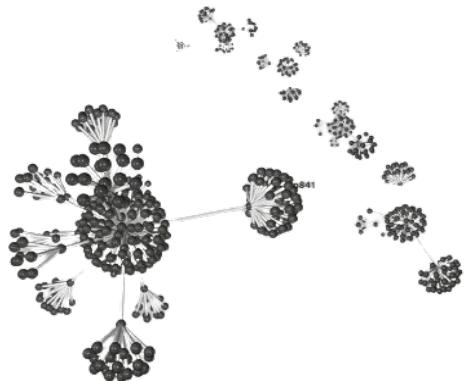
The loss function is optimized for the edit distance between sequences

We are planning to use (Order Min Hash ISMB '19) a LSH for edit distance

Metagenomic reads classification

Collaborators: Giulia Guidi, Alok Tripathi, Aydin Buluc, Kathy Yelick

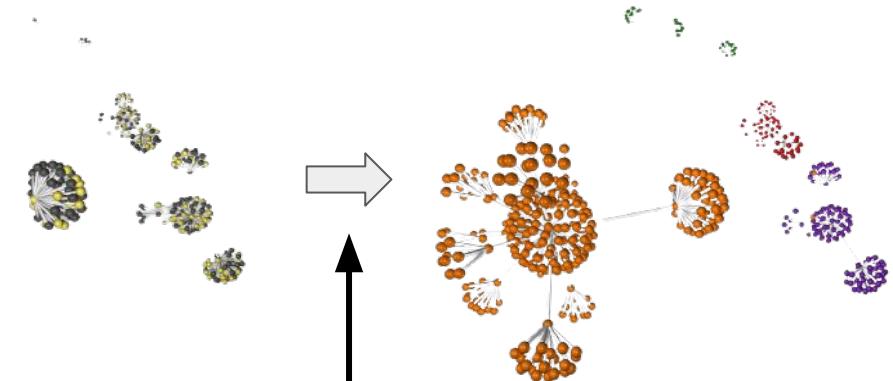
Overlap graph with no labels



Overlap graph with training labels



Overlap graph with learned labels



- Assign ground truth labels to training nodes
- Assign tetra-nucleotide frequency as node vectors

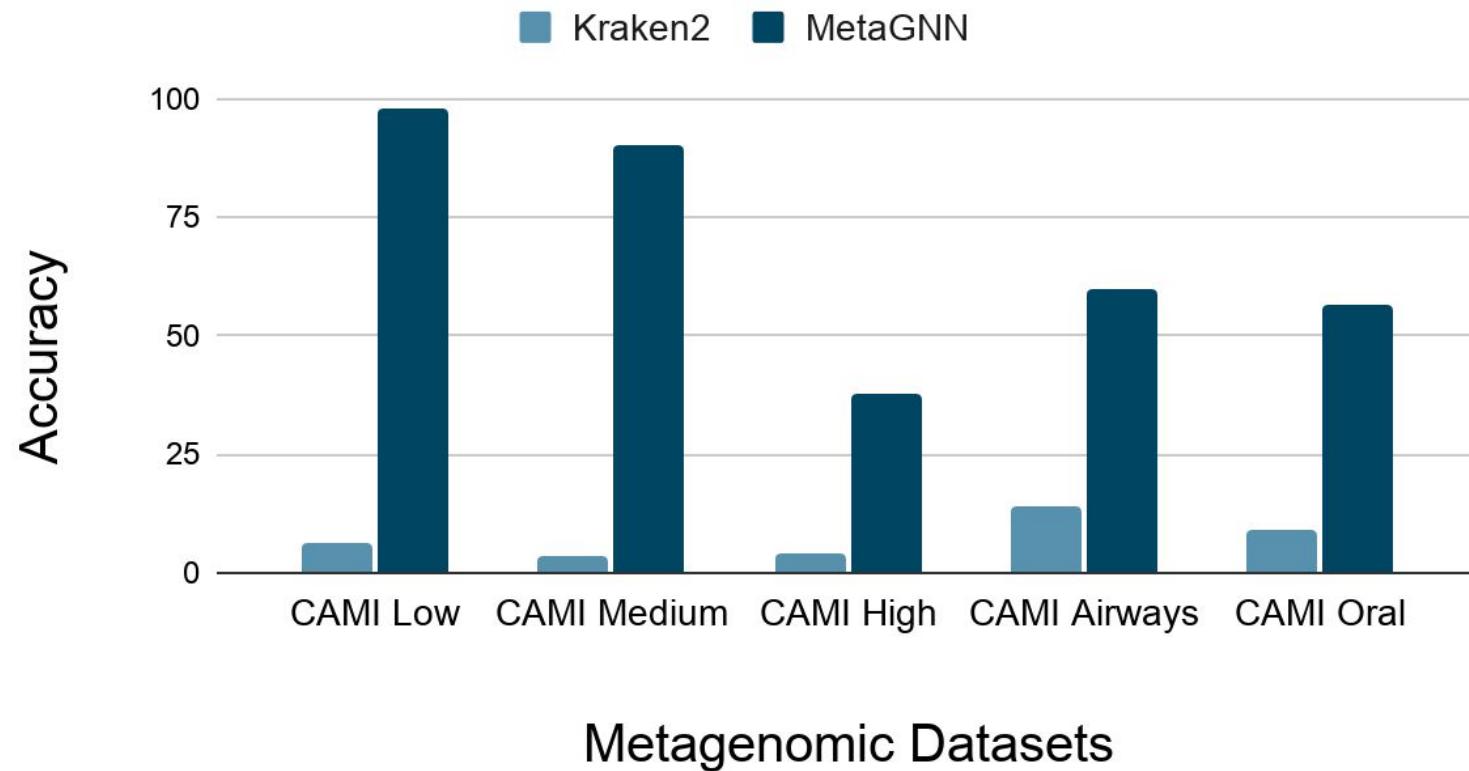
Semi-supervised learning using
Graph Convolutional Network
(GCN)

- Generate overlap graph: **reads** → **nodes** & **overlap** → **edges**
- Node features → Tetra nucleotide freq of reads
- Reference-based mapping as ground truth labels

Overlap graph + graph neural network (GNN)

Collaborators: Giulia Guidi, Alok Tripathi, Aydin Buluc, Kathy Yelick

Kraken2 and MetaGNN (F1 Score)



Can achieve higher accuracy using graph-based learning

Conclusion

- Scalability of data management systems will be the biggest challenge in future
- Changing hardware give rise to new algorithmic paradigms

Data Science at Scale

ML

Genomics

Cyber Sec.

NLP

Data Systems

Data structures & Algorithms

Scale down

Scale to disk

Scale out

Modern hardware

Vector inst.

GPU

NVM

SSD

We need to *redesign* existing data structures to take full advantage of modern hardware and *rebuild* data systems to efficiently support *future* data science.

Backup slides

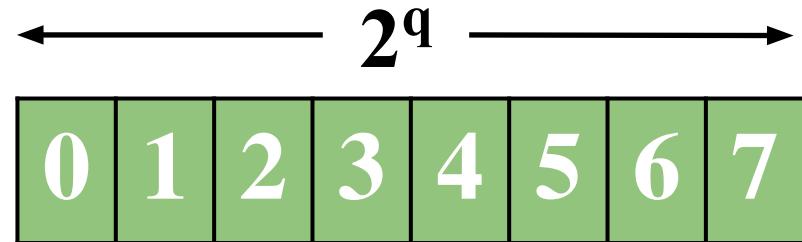
Quotient filter design

Implementation:

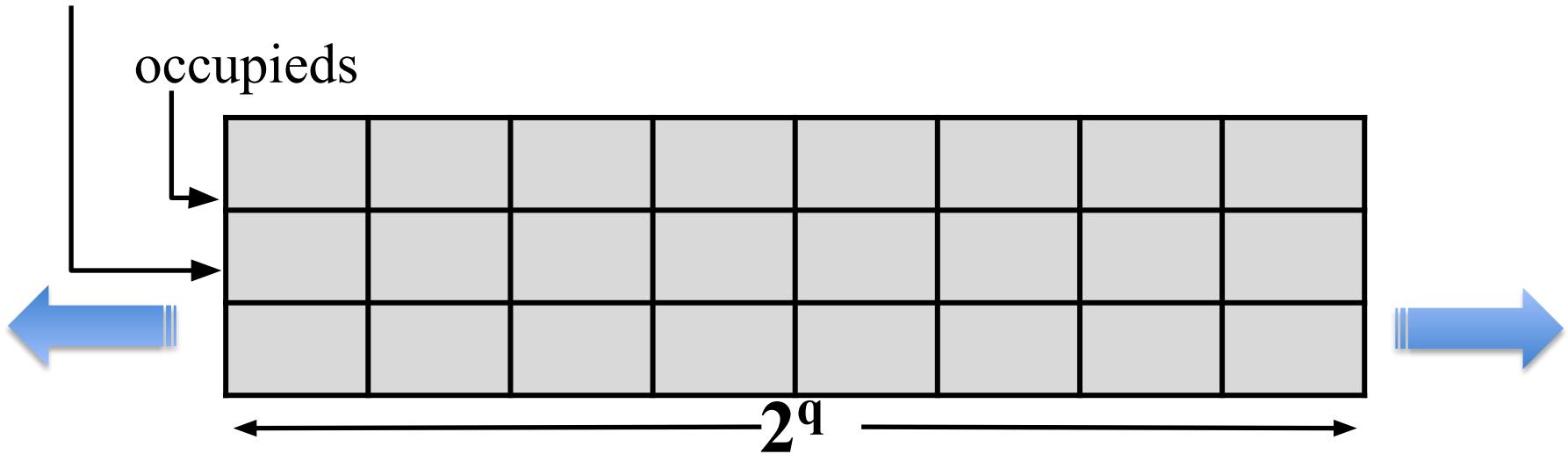
2 Meta-bits per slot.

$$h(x) \rightarrow h_0(x) \parallel h_1(x)$$

Abstract Representation



runends



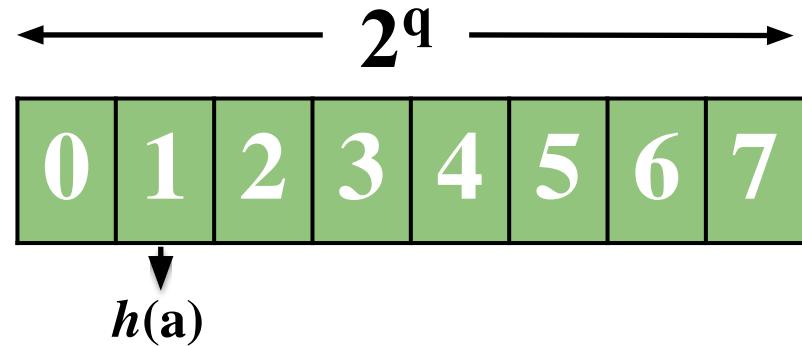
Quotient filter design

Implementation:

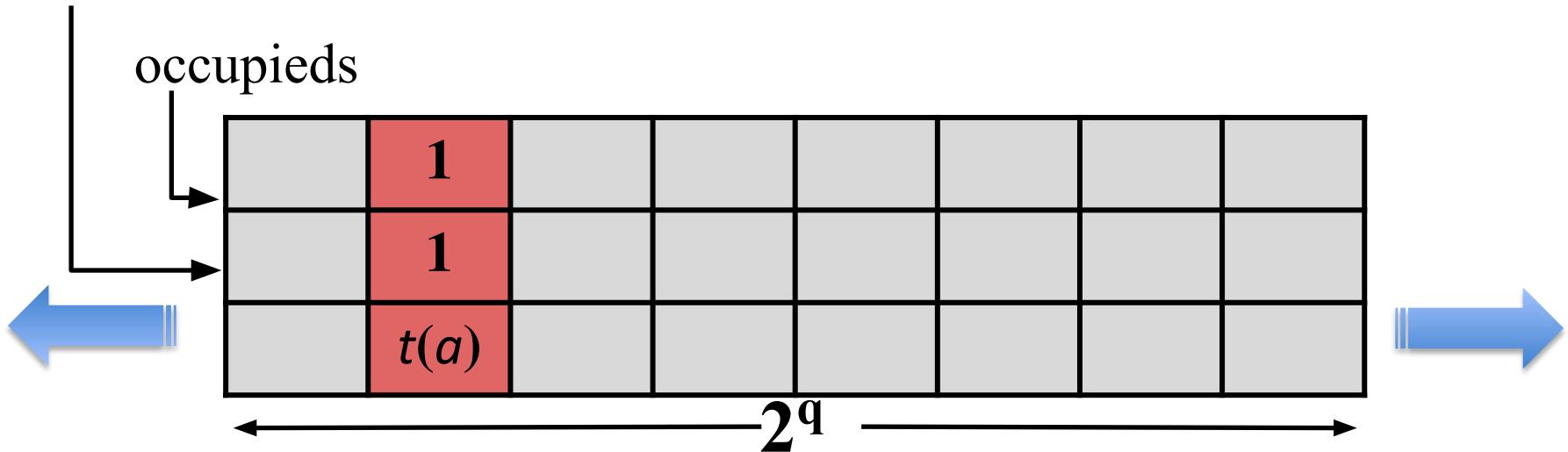
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$$h(x) \rightarrow h_0(x) \parallel h_1(x)$$

Abstract Representation



runends



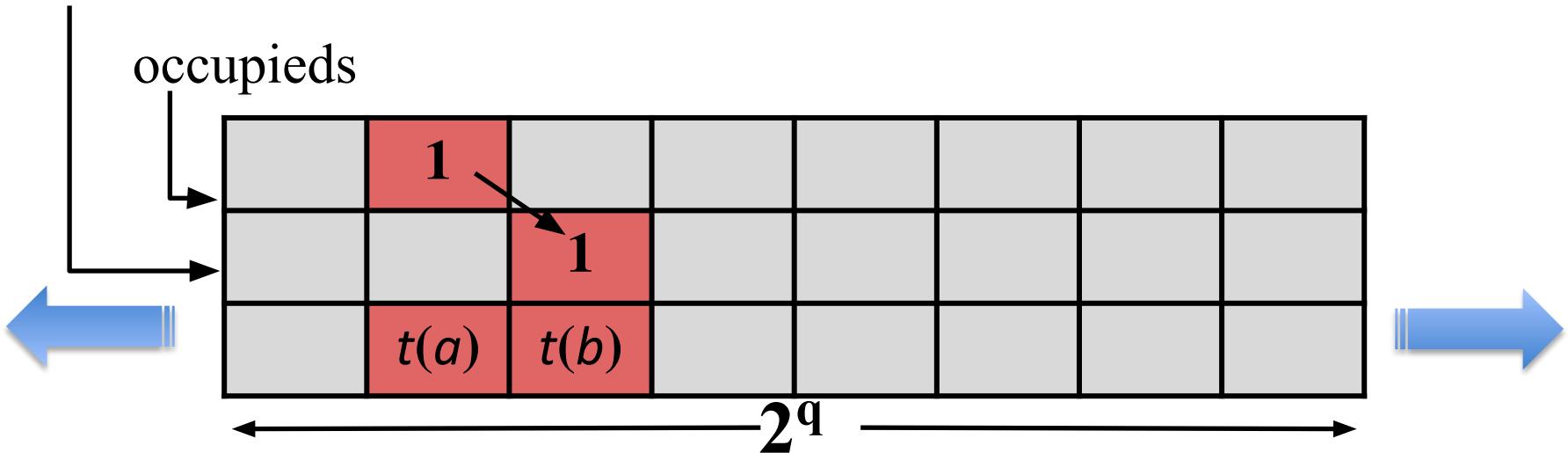
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2 Meta-bits per slot.

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runends



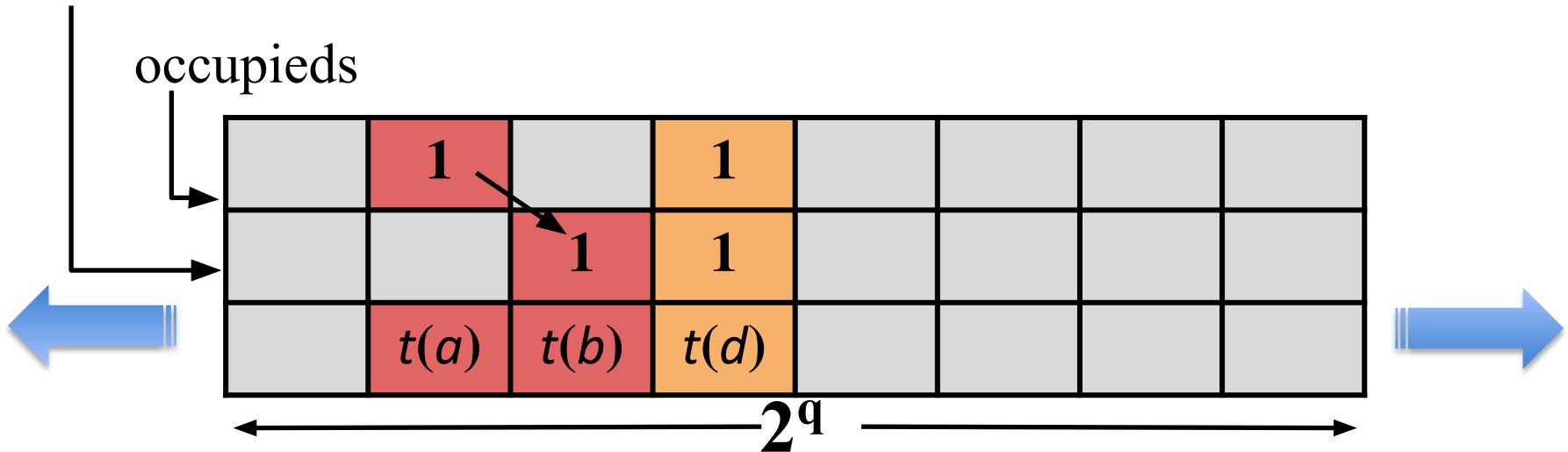
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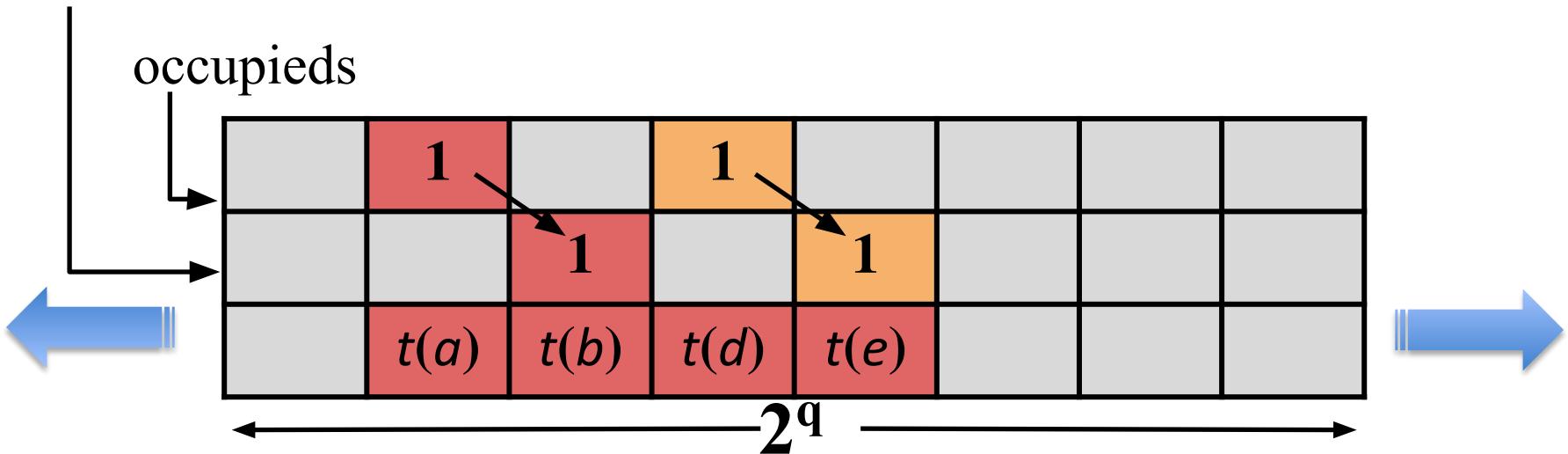
Quotient filter design

Implementation:

2 Meta-bits per slot.

$$h(x) \rightarrow h_0(x) \parallel h_1(x)$$

runends



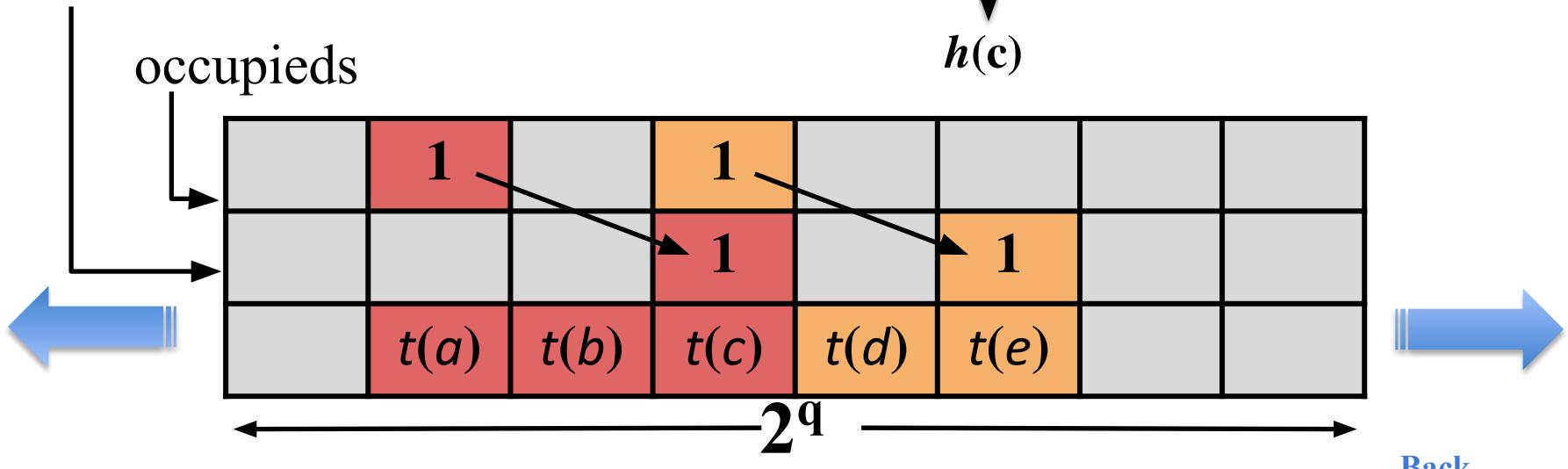
Quotient filter design

Implementation:

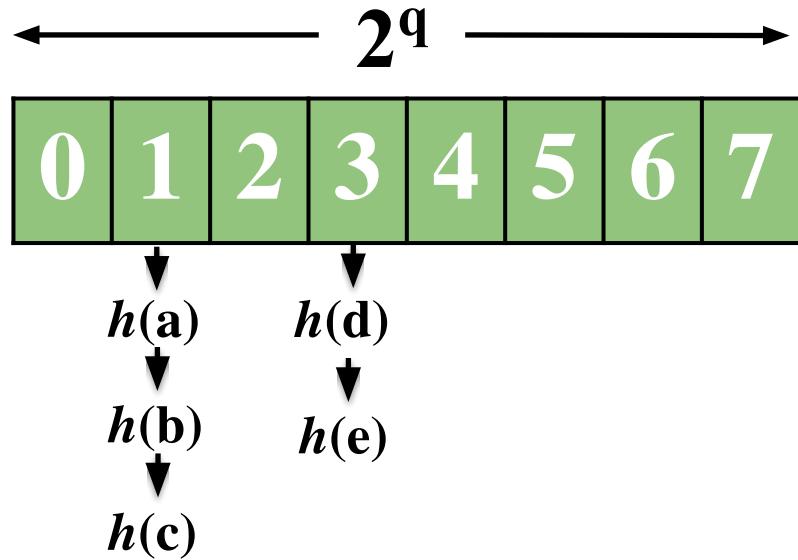
2 Meta-bits per slot.

$$h(x) \rightarrow h_0(x) \parallel h_1(x)$$

runends



Abstract Representation



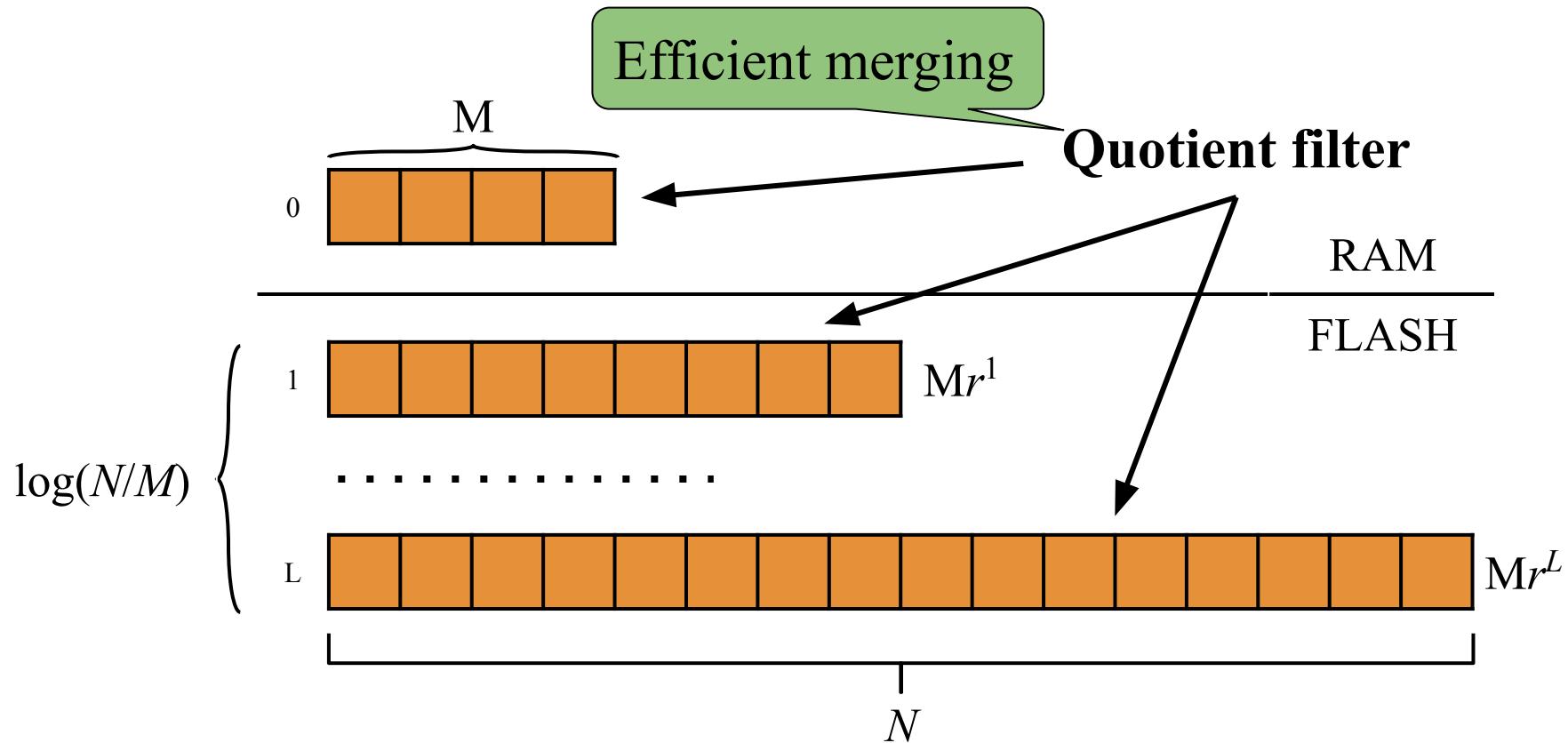
$h(a)$ $h(d)$
 $h(b)$ $h(e)$
 $h(c)$

2^q

Back

Cascade filter: write-optimized quotient filter

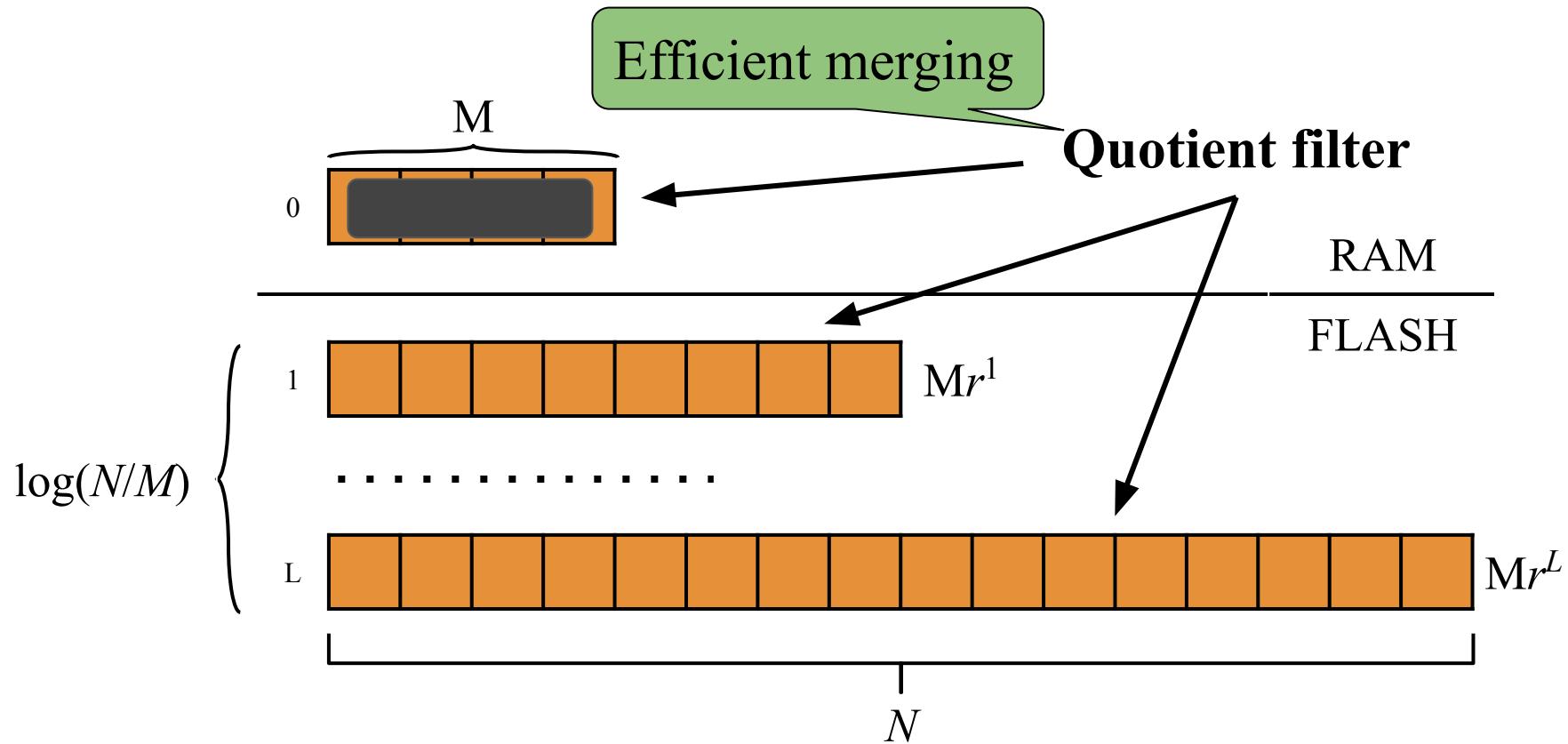
[Bender et al. '12, Pandey et al. '17]



- The Cascade filter efficiently scales out-of-RAM
- It accelerates insertions at some cost to queries

Cascade filter: flushing

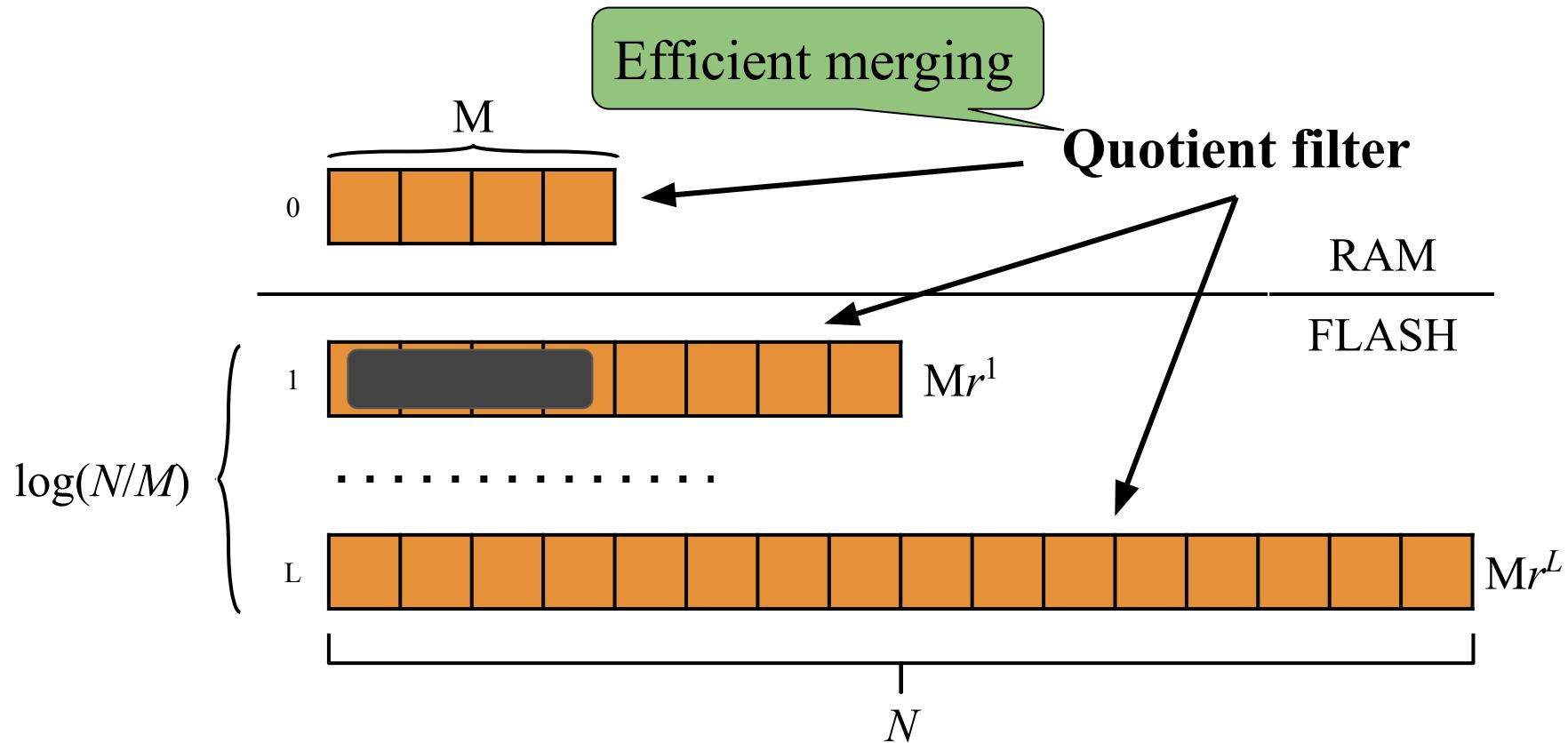
[Bender et al. '12, Pandey et al. '17]



Items are initially inserted in the RAM level

Cascade filter: flushing

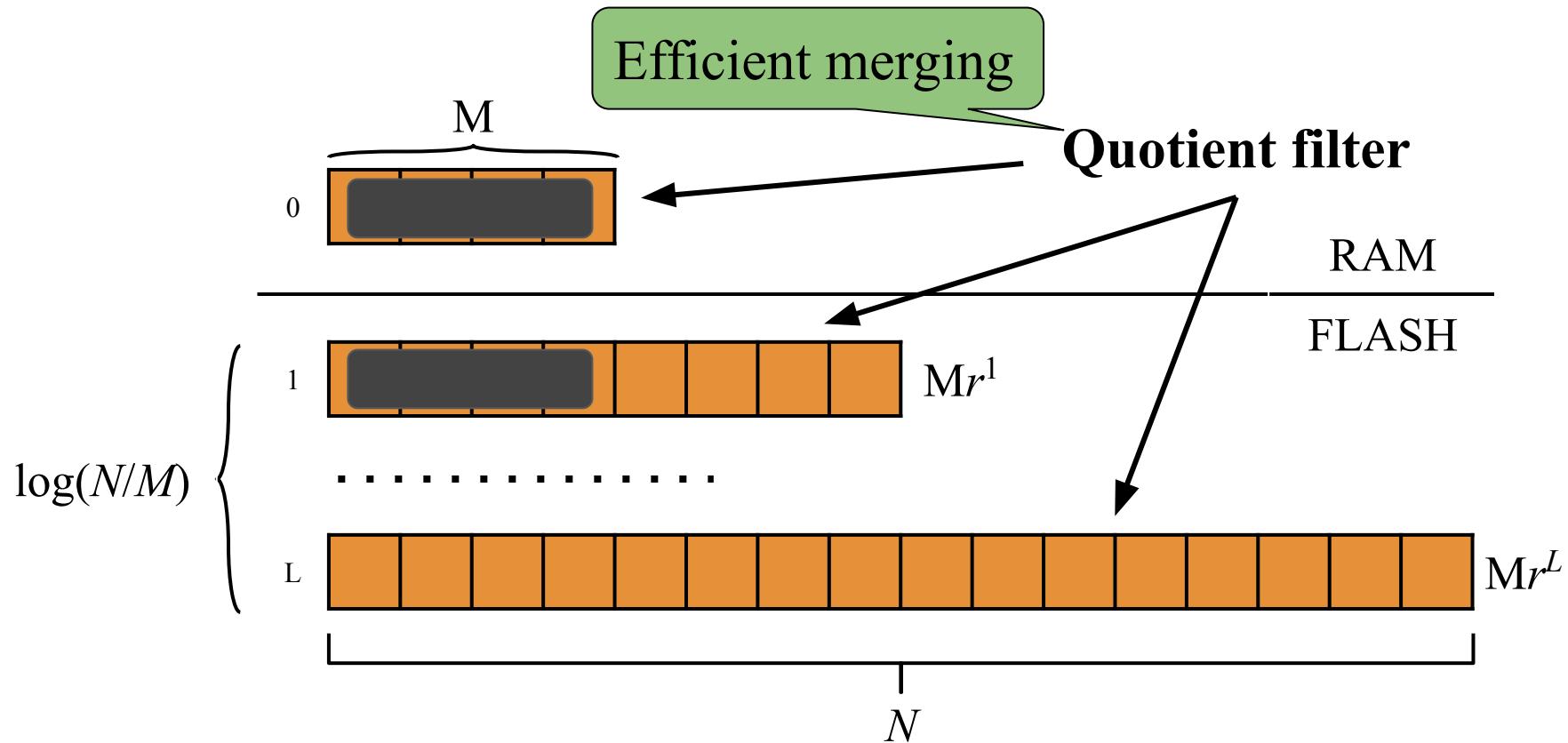
[Bender et al. '12, Pandey et al. '17]



When RAM is full, items are flushed to the smallest level on disk i with space to insert items in level 0 to $i-1$

Cascade filter: flushing

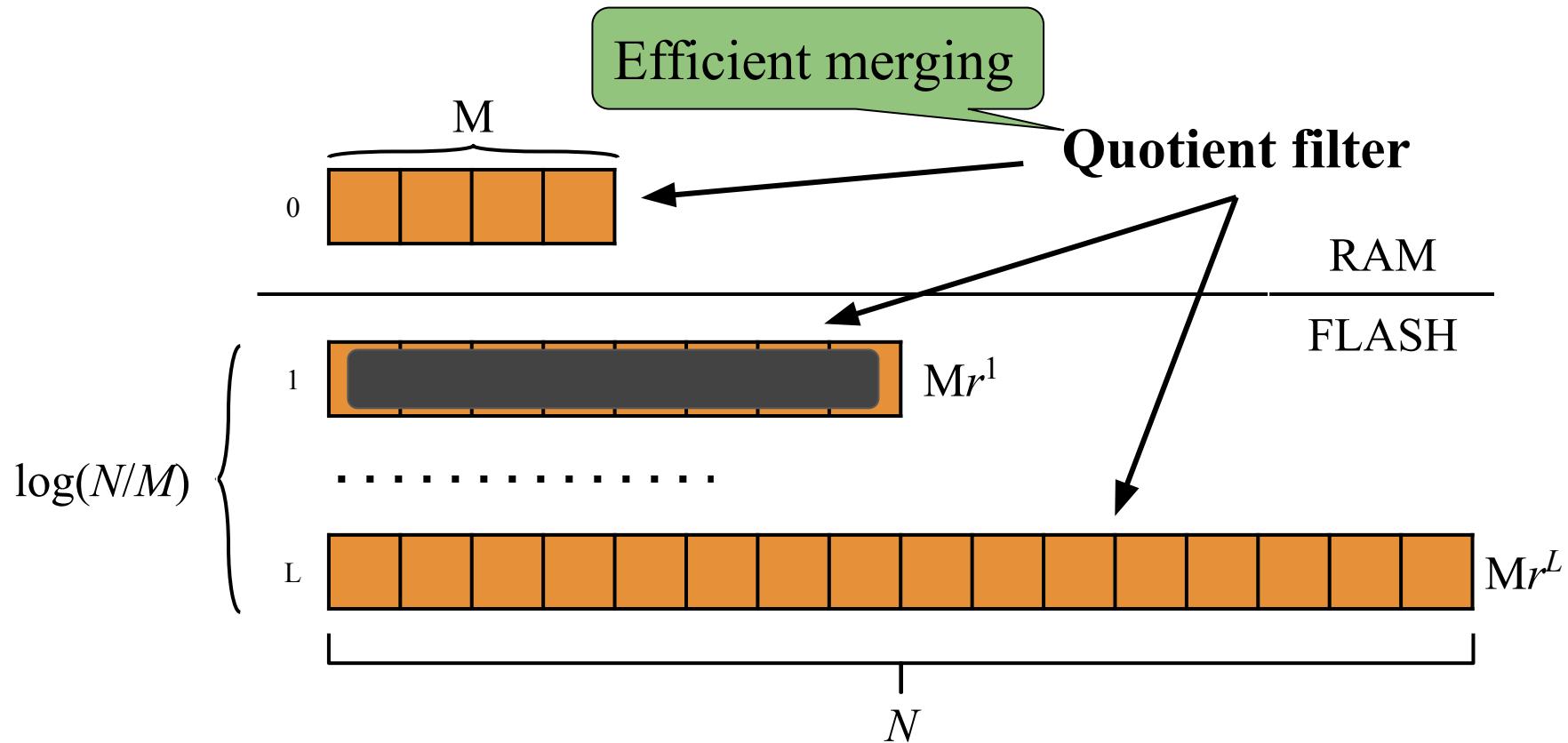
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Cascade filter: flushing

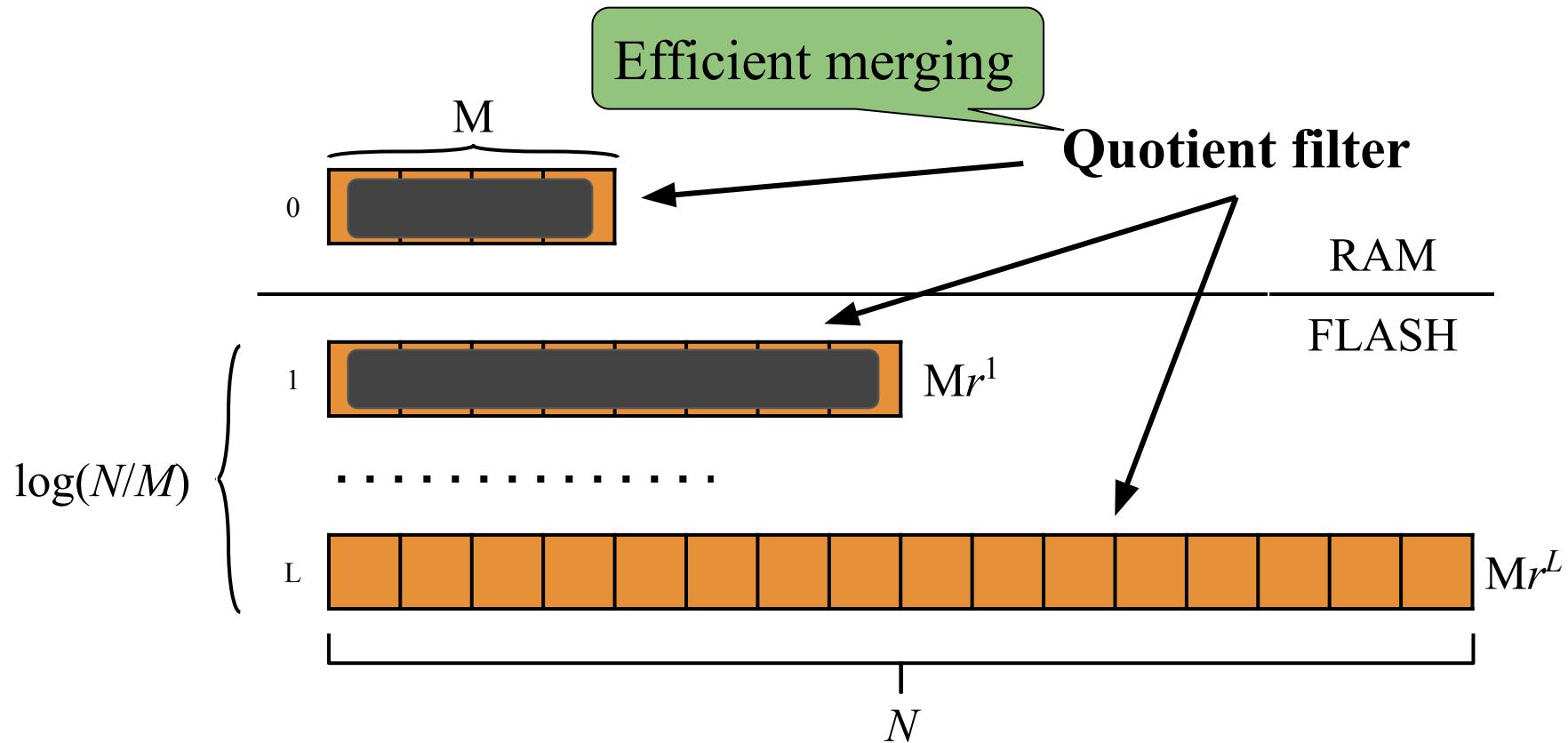
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Cascade filter: flushing

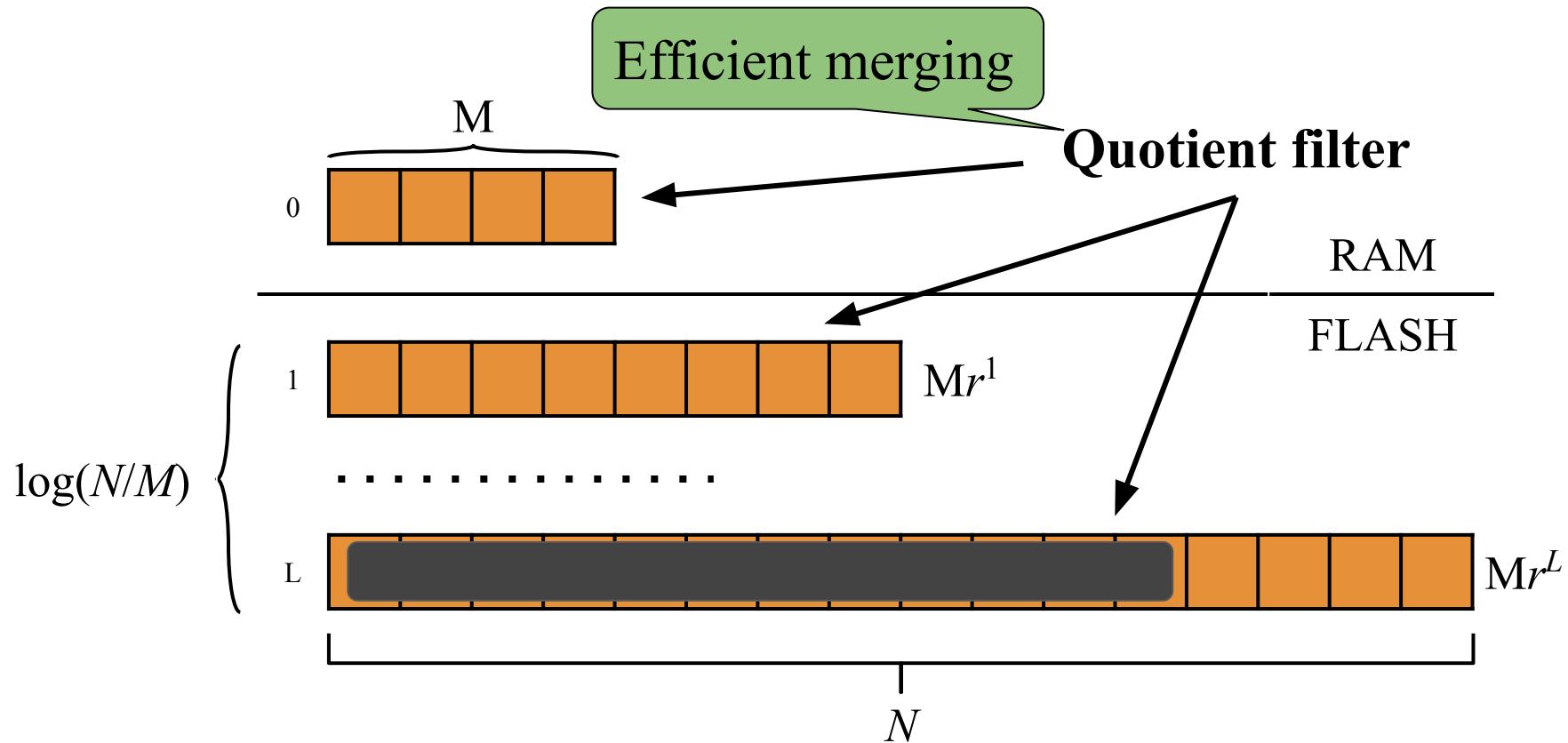
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When RAM is full, items are flushed to the smallest level on disk i with space to insert items in level 0 to $i-1$

Cascade filter: flushing

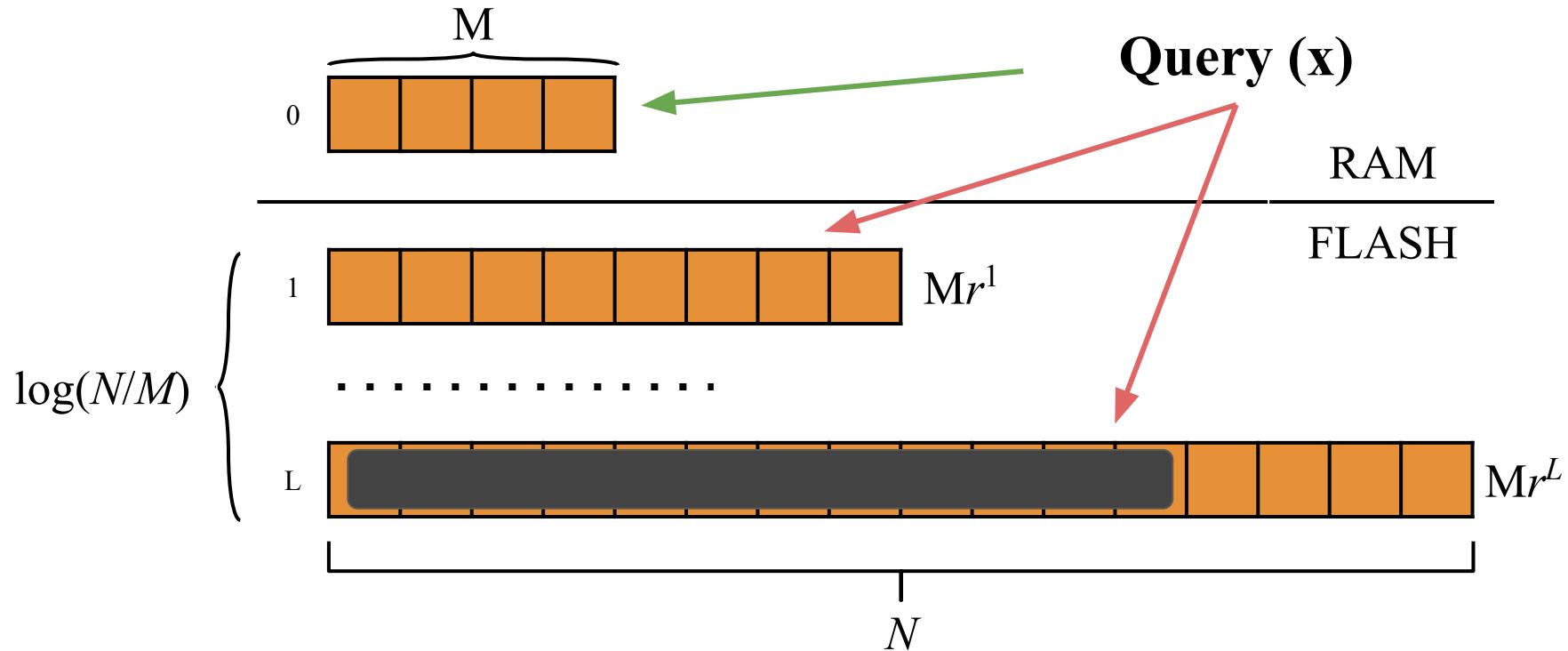
[Bender et al. '12, Pandey et al. '17]



When RAM is full, items are flushed to the smallest level on disk i with space to insert items in level 0 to $i-1$

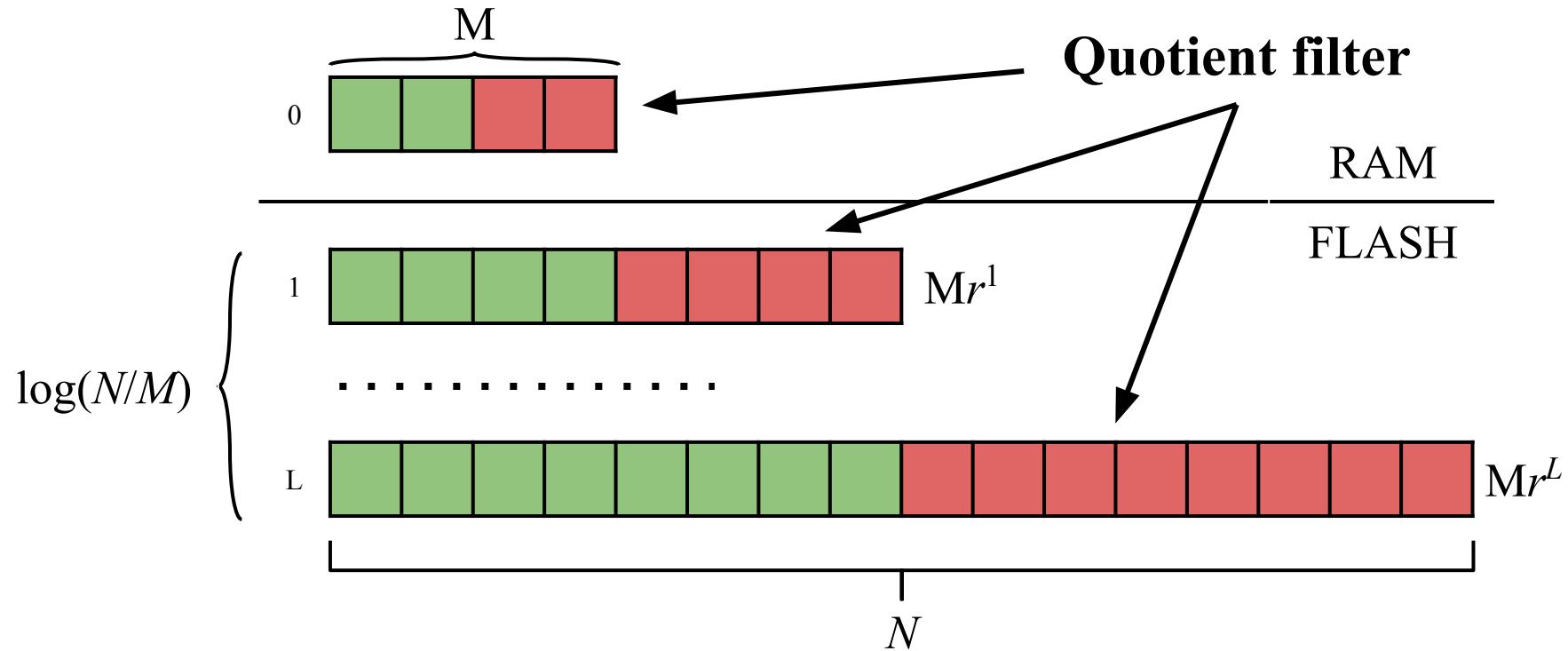
Cascade filter: query

[Bender et al. '12, Pandey et al. '17]



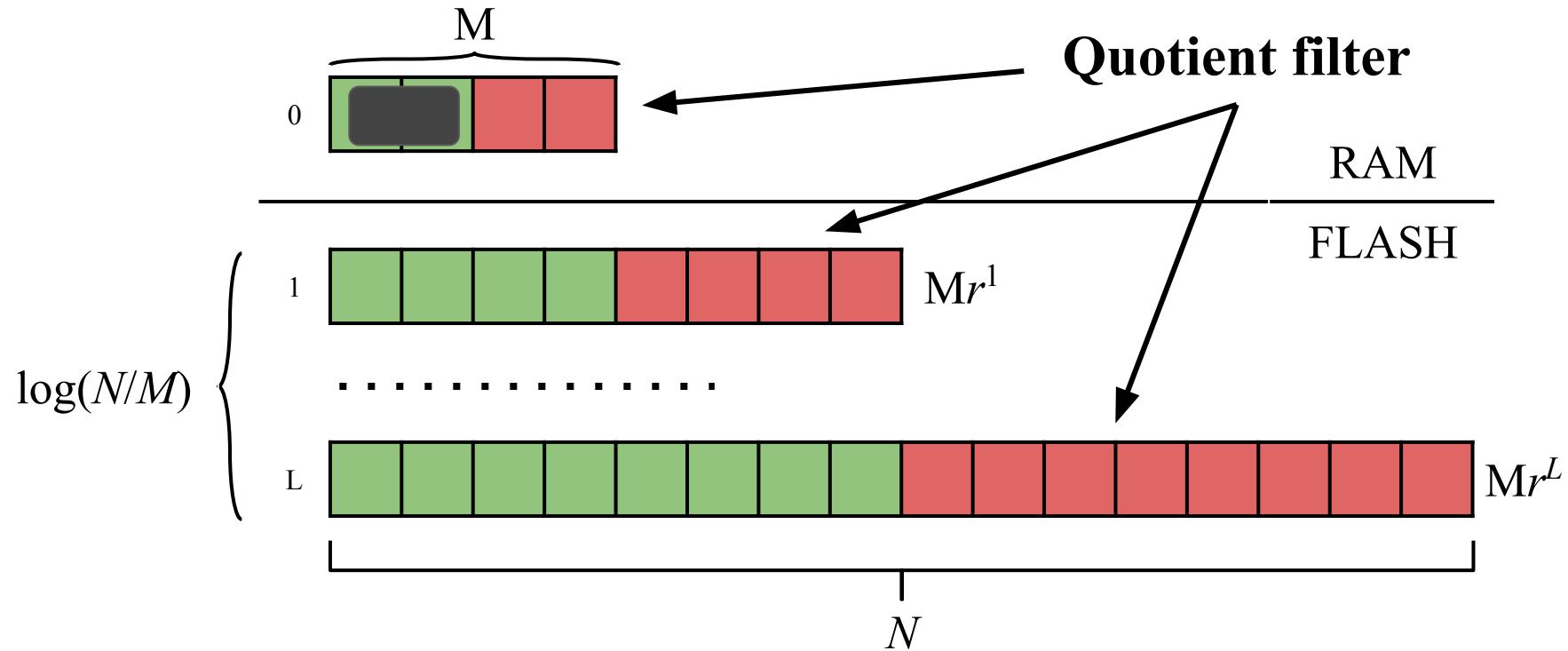
A query operation requires a lookup in each non-empty level

Time-stretch LERT



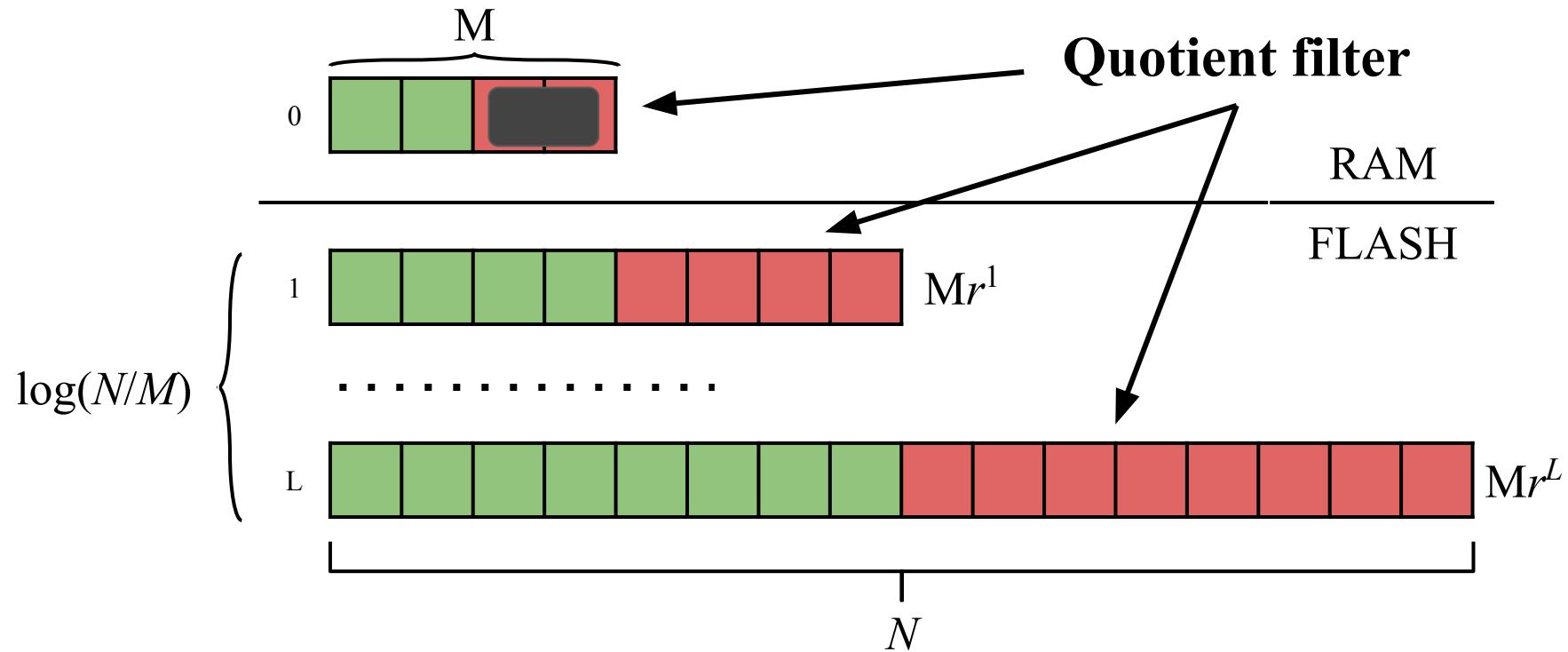
Divide each level into $1 + 1/\alpha$, equal-sized bins.

Time-stretch LERT



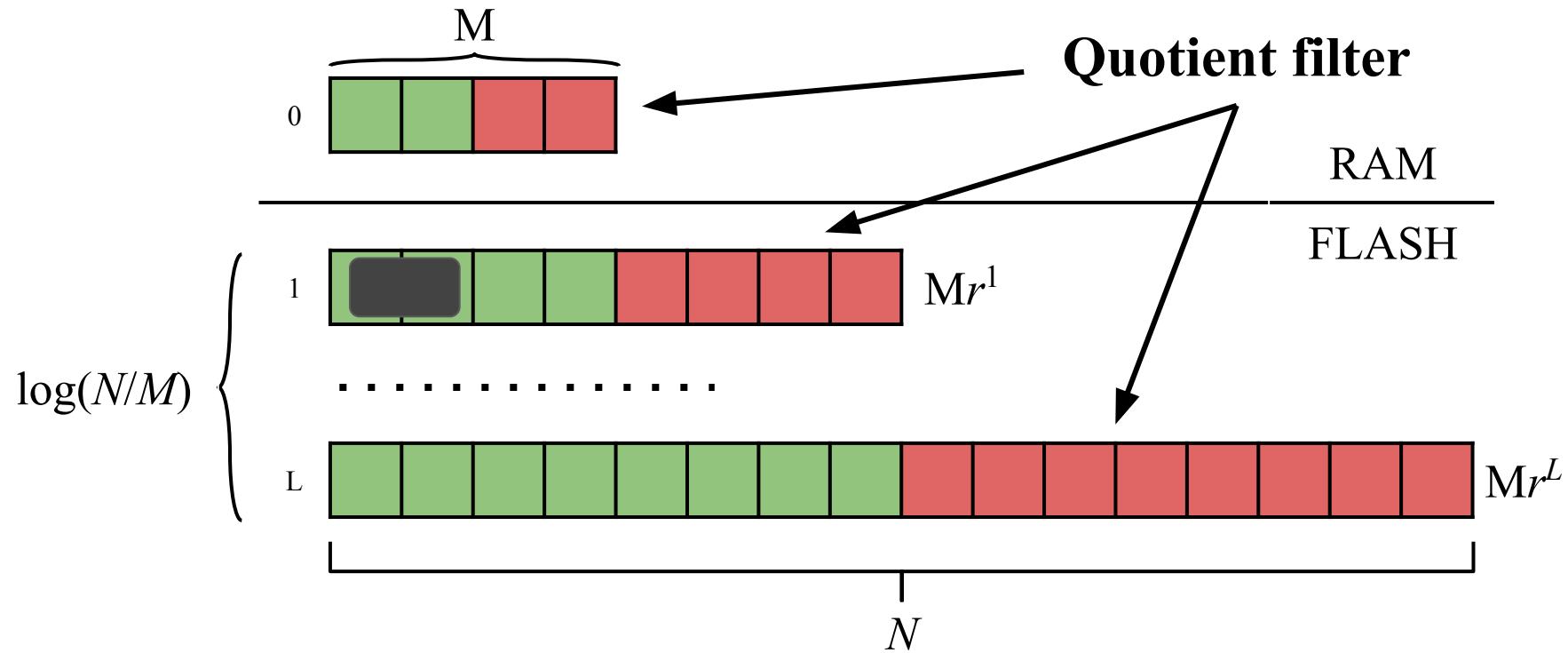
When a bin is full, items move to the adjacent bin

Time-stretch LERT



When a bin is full, items move to the adjacent bin

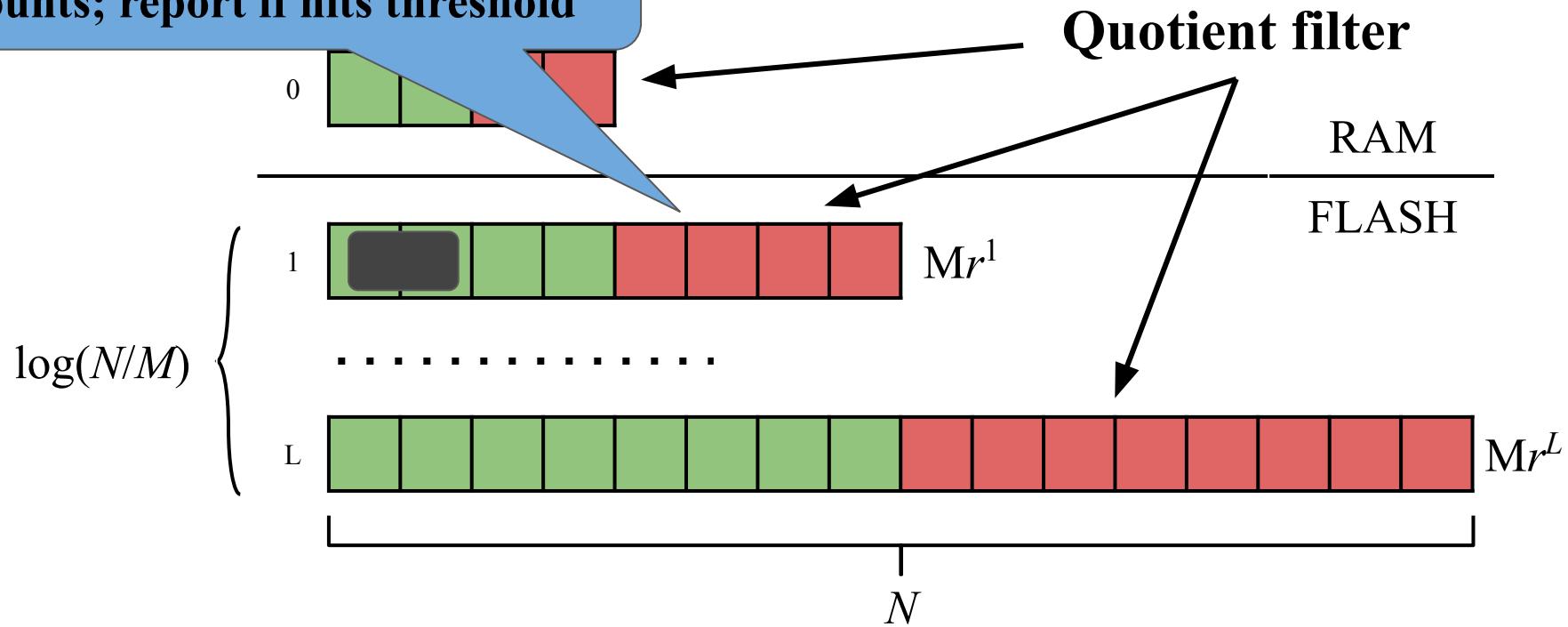
Time-stretch LERT



Last bin flushed to first bin of the next level

Time-stretch LERT

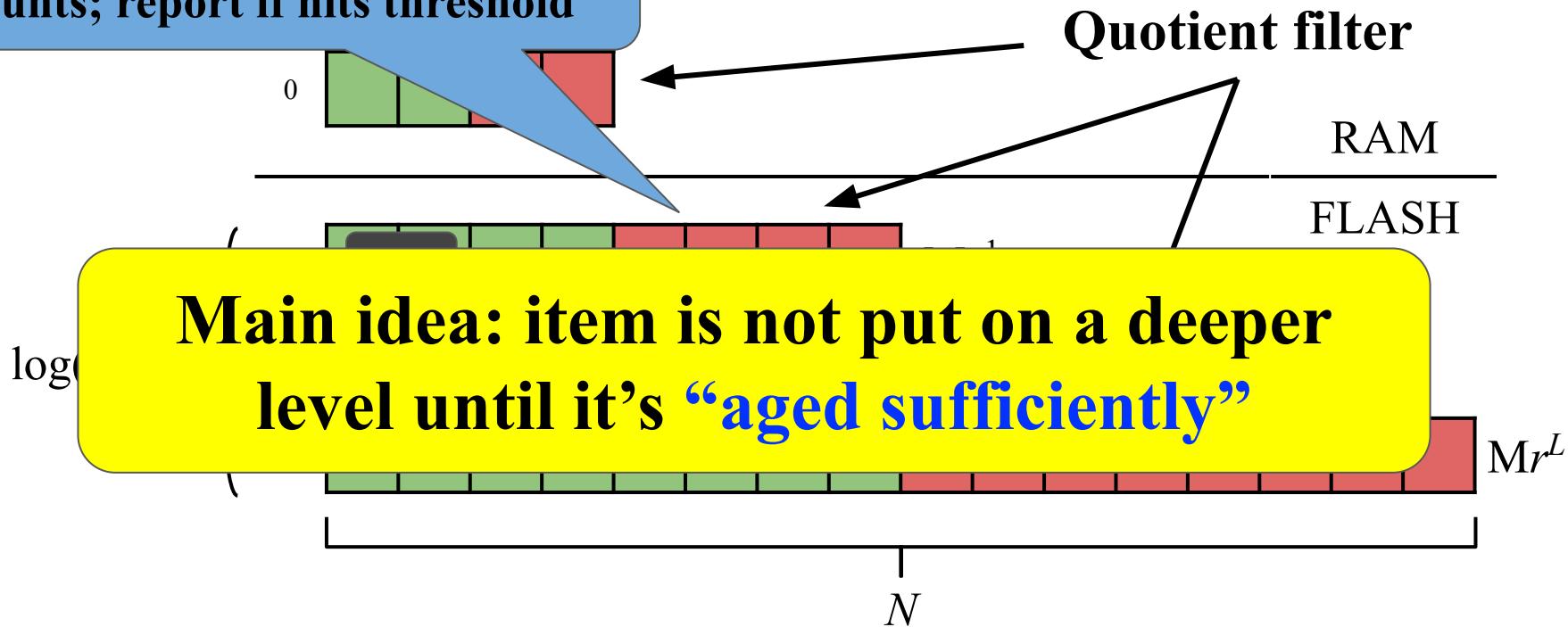
While flushing consolidate counts; report if hits threshold



Last bin flushed to first bin of the next level

Time-stretch LERT

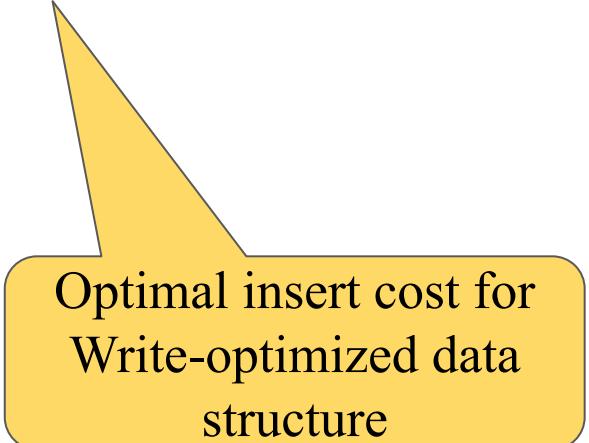
While flushing consolidate counts; report if hits threshold



Last bin flushed to first bin of the next level

Time-stretch LERT I/O complexity

$$O\left(\left(\frac{\alpha+1}{\alpha}\right) \frac{1}{B} \log \frac{N}{M}\right)$$



Optimal insert cost for
Write-optimized data
structure

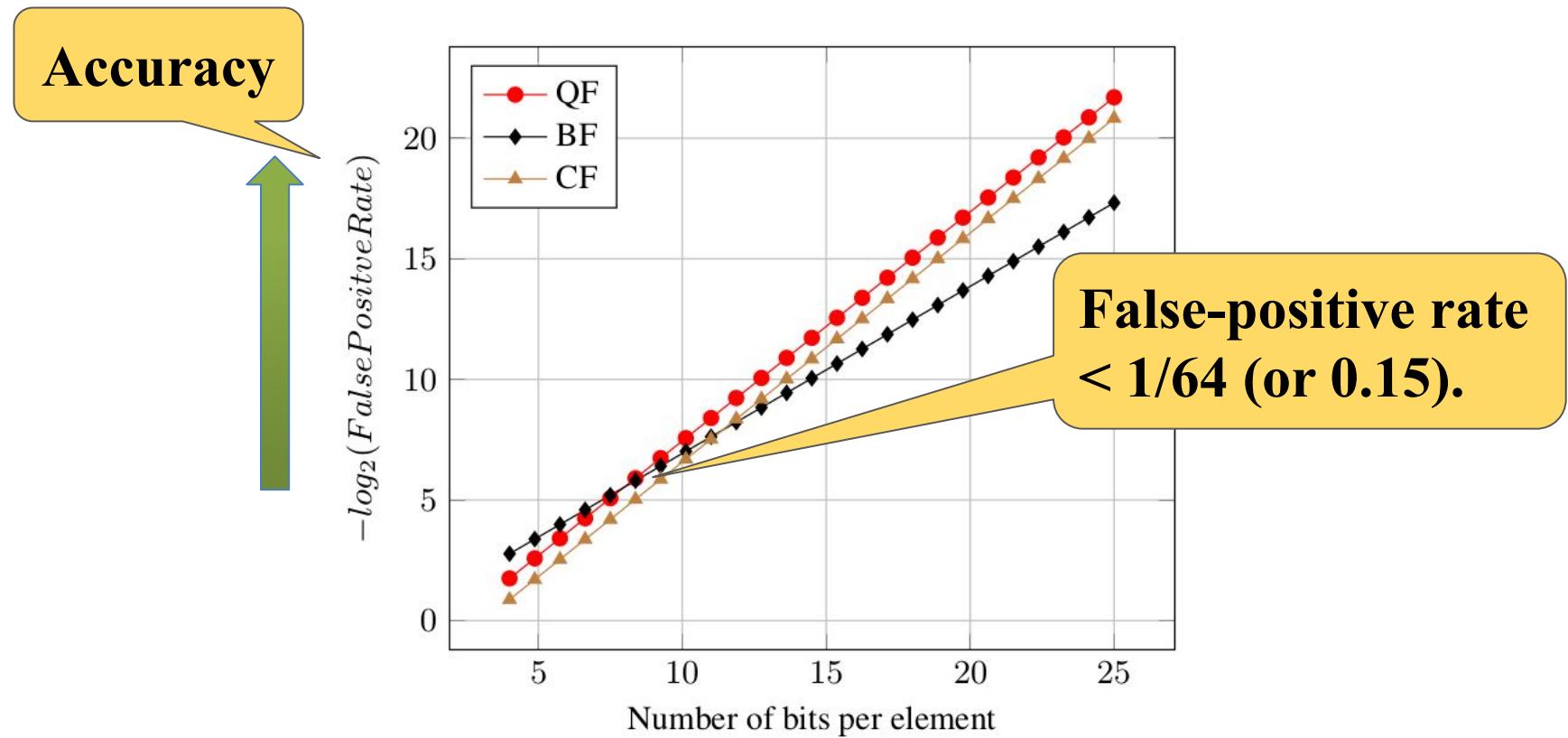
Time-stretch LERT I/O complexity

$$O\left(\left(\frac{\alpha+1}{\alpha}\right) \frac{1}{B} \log \frac{N}{M}\right)$$

Extra cost because we only move one bin during a flush. Constant loss for constant α

Optimal insert cost for Write-optimized data structure

Quotient filters use less space than Bloom filters for all practical configurations



Bloom filter: $\sim 1.44 \log(1/\varepsilon)$ bits/element.

Quotient filter: $\sim 2.125 + \log(1/\varepsilon)$ bits/element.

Cyber monitoring → real-time data analysis

Defense systems for cyber security
monitor **high-speed** streams for
malicious traffic over **large periods**
of time

Malicious traffic forms a **small portion** of the stream

Automated systems take defensive actions for **every reported event**



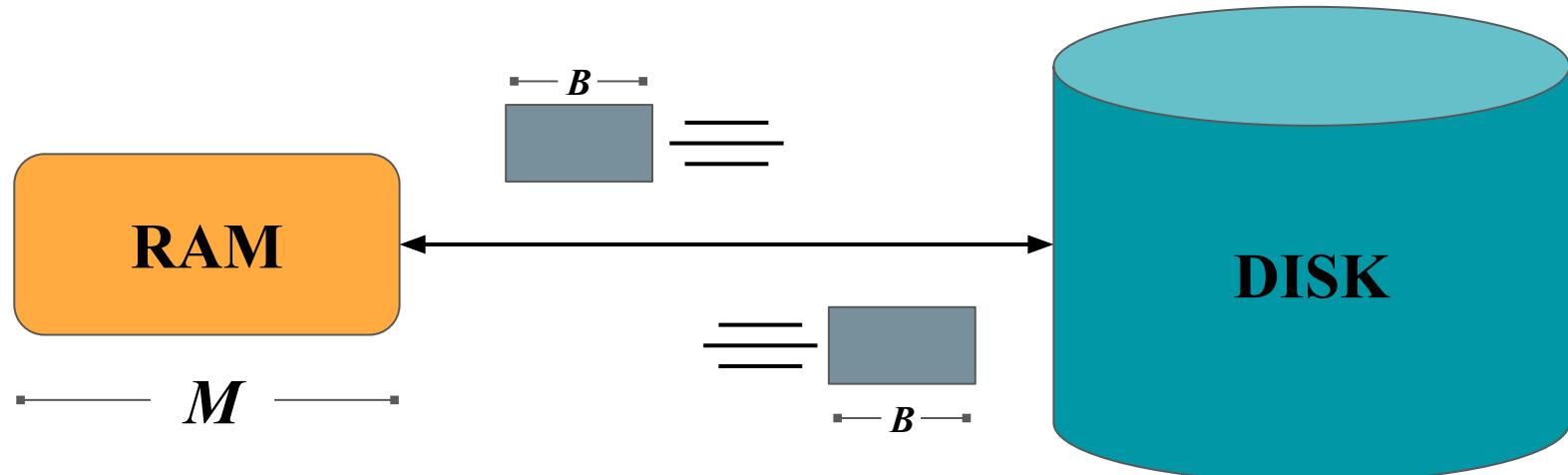
External memory model [Aggarwal+Vitter '08]

- **How computations work:**

- Data is transferred in blocks between RAM and disk.
- The number of block transfers dominate the running time.

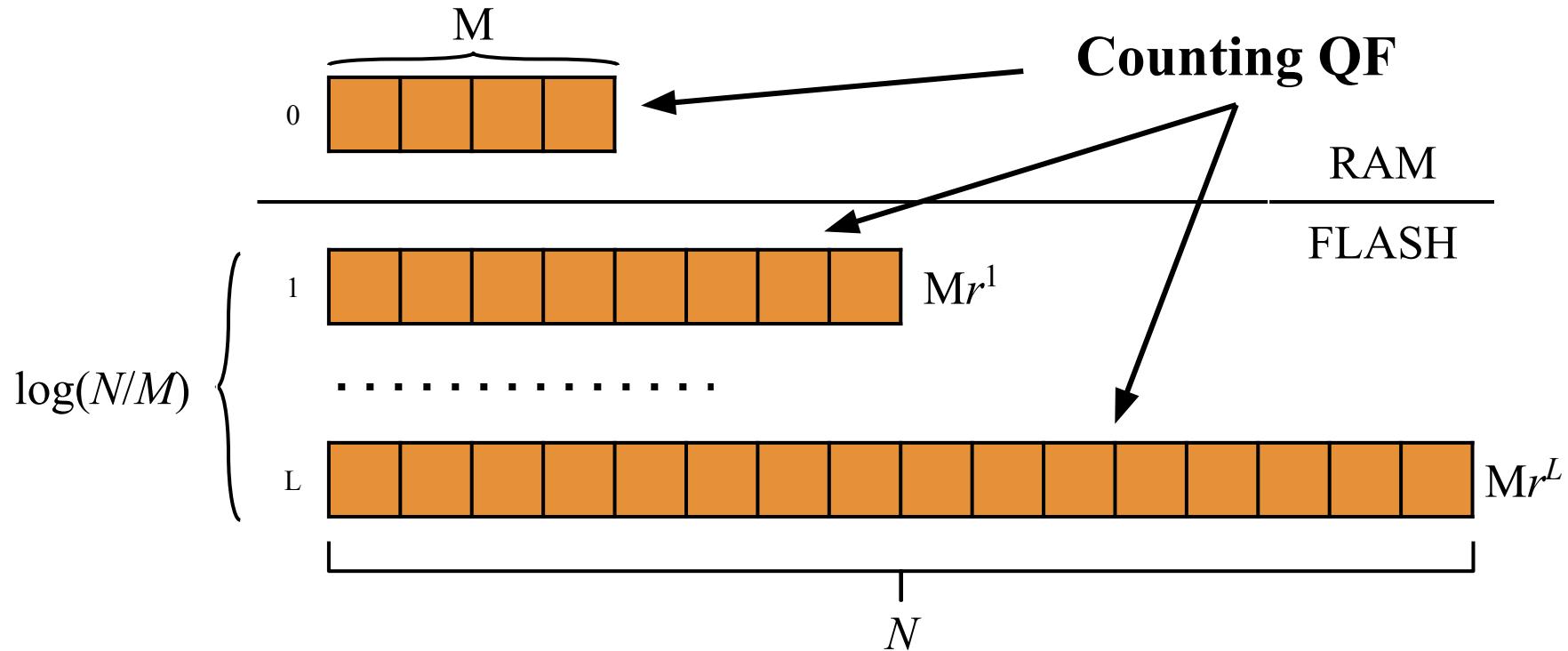
- **Goal: Minimize number of block transfers**

- Performance bounds are parameterized by block size B , memory size M , data size N .



Cascade filter: write-optimized quotient filter

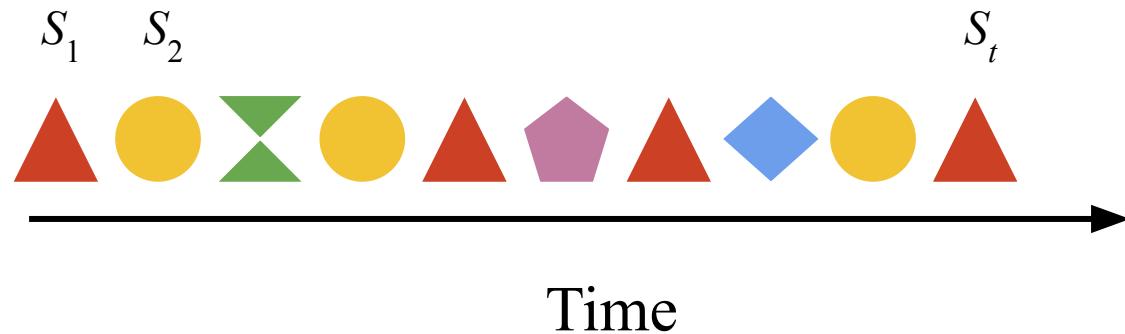
[Bender et al. '12, Pandey et al. '17]



- The Cascade filter efficiently scales out-of-RAM
- It accelerates insertions at some cost to queries

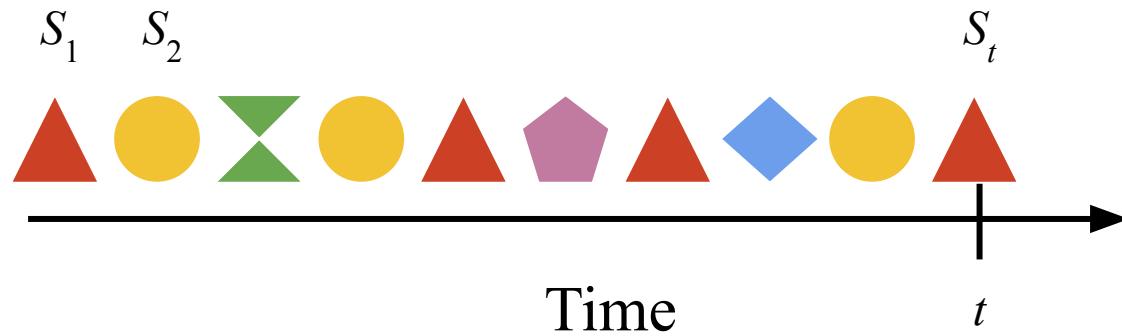
Timely event detection problem

- Stream of elements arrive over time



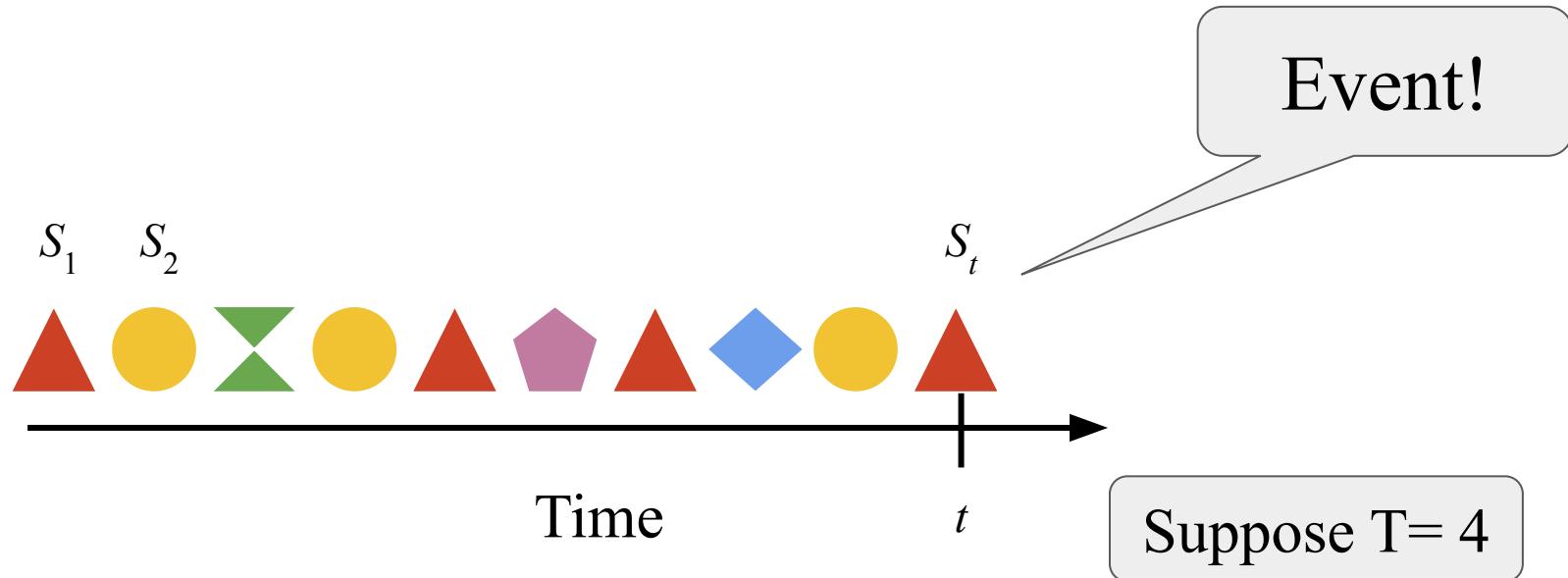
Timely event detection problem

- Stream of elements arrive over time
- An **event** occurs at time t if S_t occurs exactly T times in (s_1, s_2, \dots, s_t)



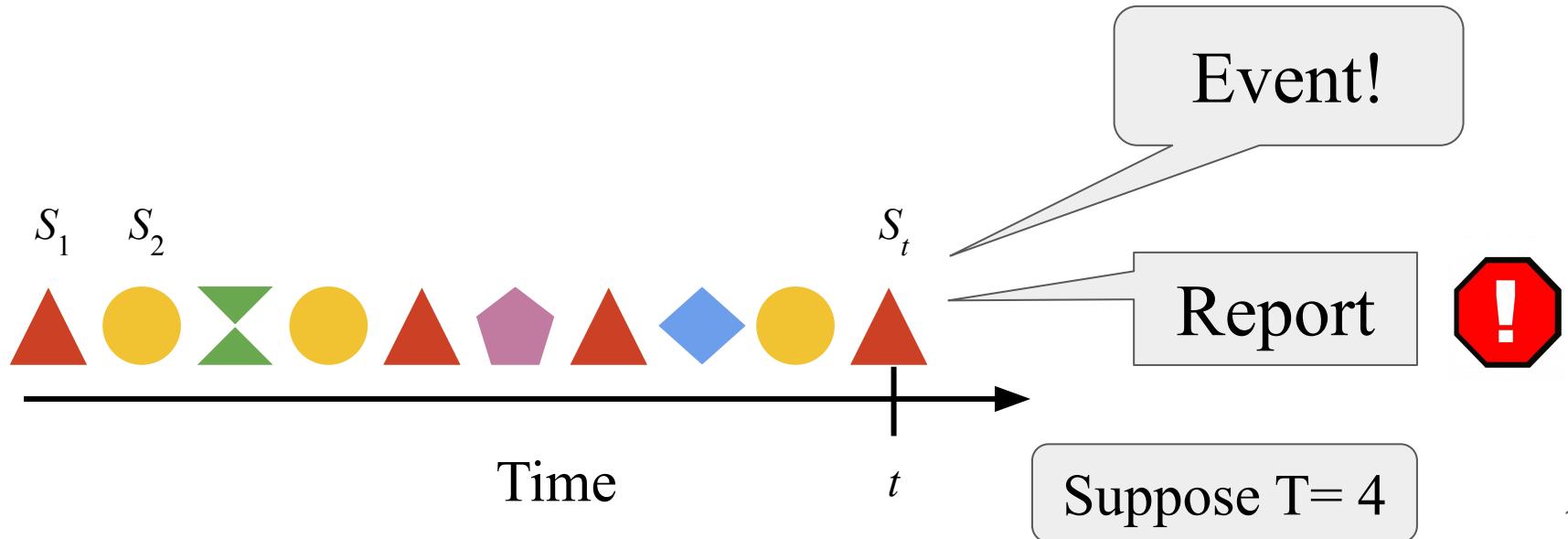
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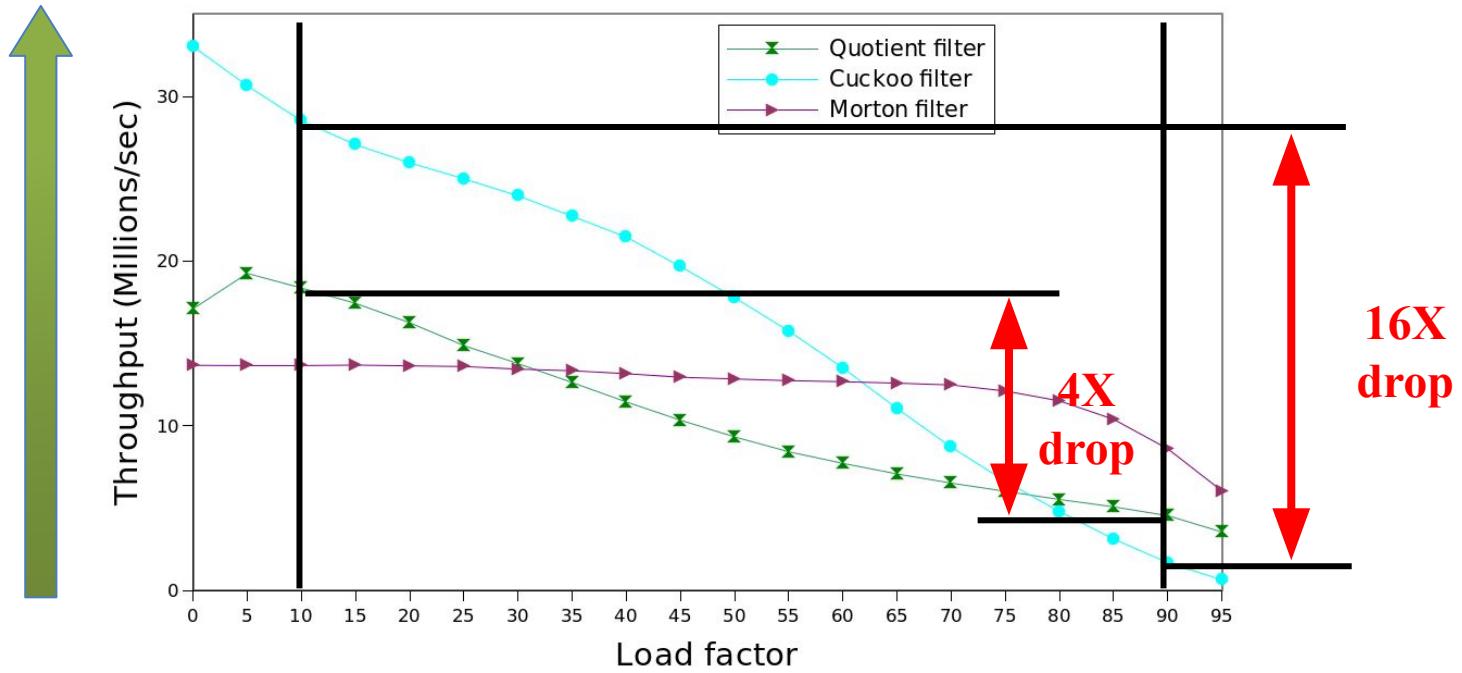


Timely event detection problem

- Stream of elements arrive over time
- An **event** occurs at time t if S_t occurs exactly T times in (s_1, s_2, \dots, s_t)
- In **timely event-detection problem (TED)**, we want to report all events shortly after they occur.



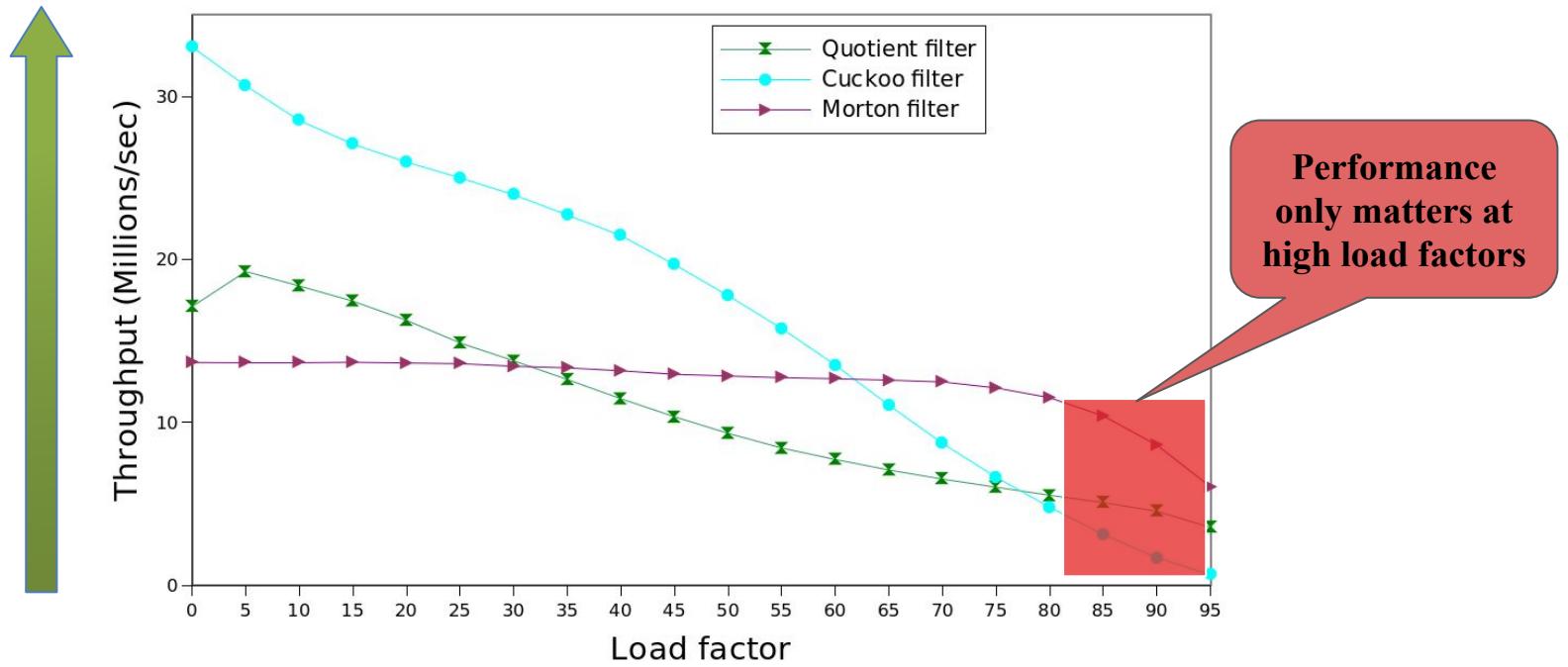
Trade-off: Insertion throughput degrades with load factor



Performance suffers due to high-overhead of *collision resolution*

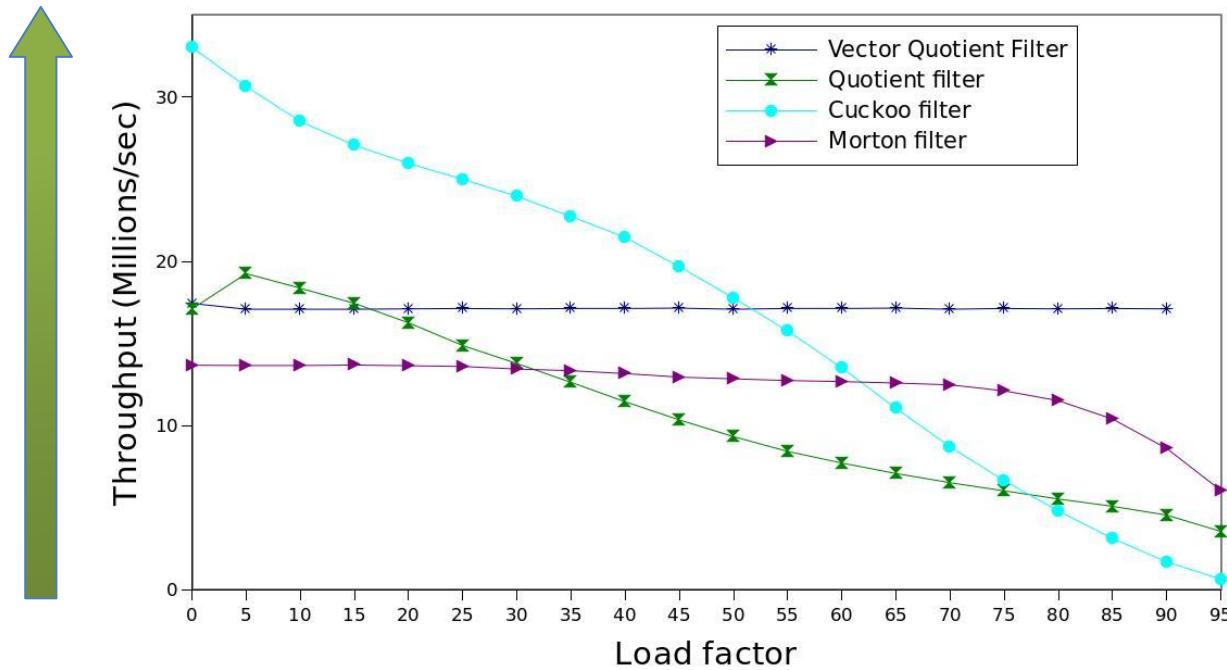
Trade-off: Insertion throughput degrades with load factor

Insertion throughput vs load factor of state-of-the-art filters



Many update-intensive applications (e.g., network caches, data analytics, etc.) maintain filters at high load factors

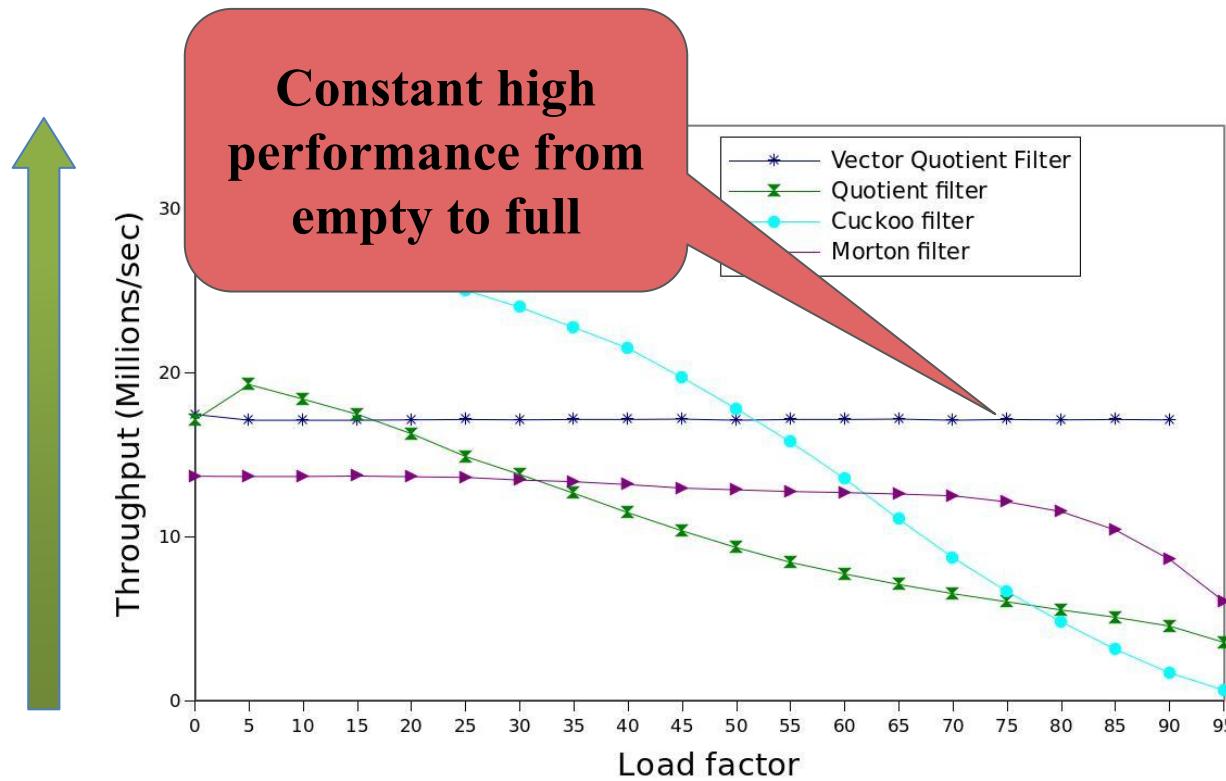
Combining techniques + new hardware



Combining hashing techniques (**Robin Hood + 2-choice hashing**)
Using ultra-wide vector operations (**AVX512-BW**)

Combining techniques + new hardware

Pandey et al. SIGMOD '21

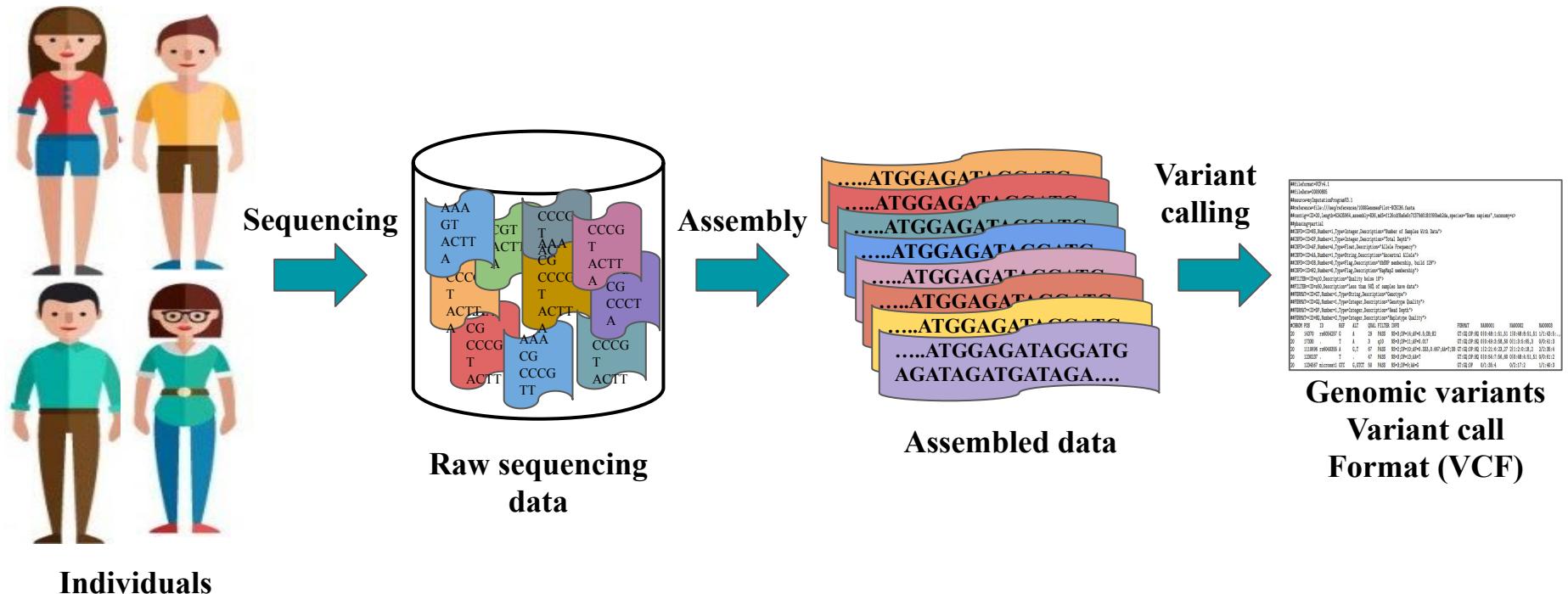


Combining hashing techniques (**Robin Hood + 2-choice hashing**)
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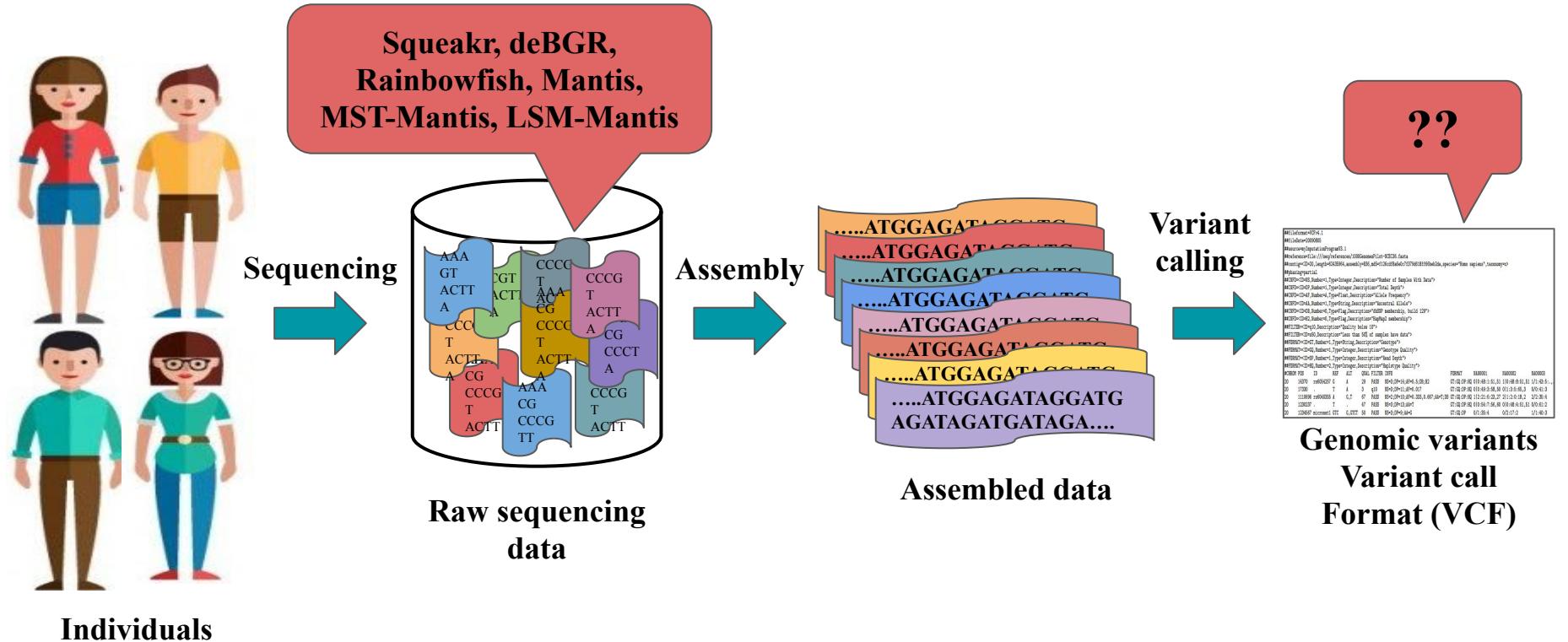
Future work: population-scale variant index

Goal: Build a *population-scale* index on variation data to enable downstream apps to gain *quick insights into variants*

Country-scale sequencing efforts produce huge amounts of sequencing data



Country-scale sequencing efforts produce huge amounts of sequencing data



- 1000 Genomes project [<https://www.internationalgenome.org/>]
 - The Cancer Genome Atlas (TCGA) [<https://portal.gdc.cancer.gov/>]
 - Genotype-Tissue Expression (GTEx) [<https://gtexportal.org/home/>]

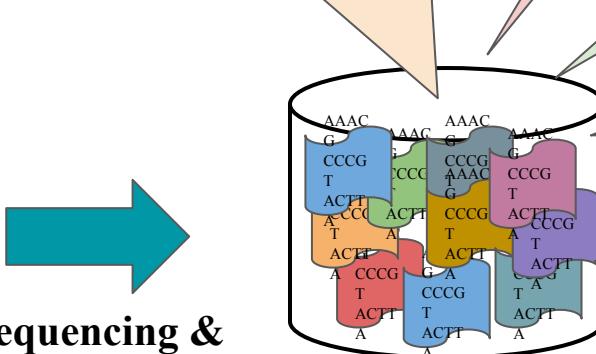
Variation data analysis can improve downstream applications

- Population-level disease analysis
- Genome-wide association studies
- Personalized medicine
- Cancer remission-rate prediction
- Colocalization analysis
- PCR primer design
- Genome assembly



Individuals

Sequencing &
assembly



Population Genomes

Count the number of variants in a gene

List all people, with $> N$ variants in a gene

Return all positions with variants in a gene

For person P , return the closest variant from position X

List all people, with sequence S in a gene

Indexing in multiple coordinates is challenging

Reference-only indexes map positions only in the reference coordinate system

$$f(p_i, p_j) \rightarrow (v_i \dots v_n), \text{ where } p_i \leq p_j$$

Pan-genome analysis involves queries based on sample coordinate systems

$$\left\{ \begin{array}{l} f_1(p_i, p_j) \rightarrow (v_i \dots v_n), \text{ where } p_i \leq p_j \\ \vdots \\ f_s(p_i, p_j) \rightarrow (v_i \dots v_n), \text{ where } p_i \leq p_j \end{array} \right.$$

Num Samples

Maintaining thousands of mappings *increases* computational **complexity** and **memory footprint**

Limits scalability to population-scale data

Indexing in multiple coordinates is challenging

Reference-only indexes map positions only in the reference coordinate system

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Pan-genome analysis involves queries based on sample coordinate systems

Nu
Sam

Existing systems don't support multiple coordinate systems. The ones that do, don't *scale* beyond a few thousand samples.

$$\cup f_s(p_i, p_j) \rightarrow (v_i \dots v_n), \text{ where } p_i \leq p_j$$

Maintaining thousands of mappings *increases* computational *complexity* and *memory footprint*

Limits scalability to population-scale data

An inverted index on the pan-genome graph

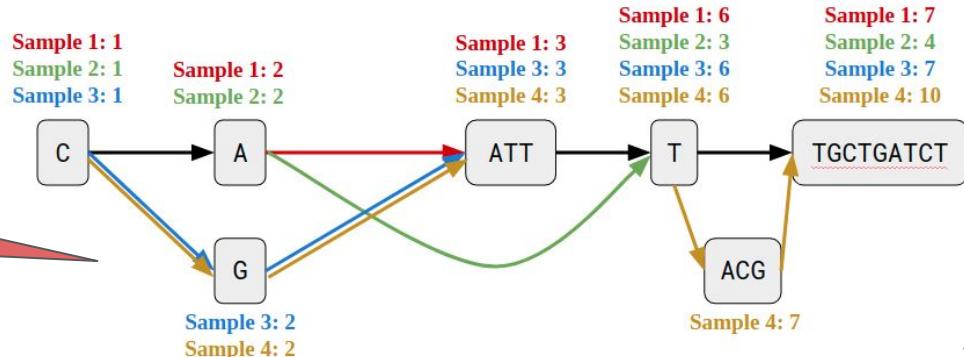
Collaborators: Yinjie Gao, Carl Kingsford

- Partition the variation graph based on coordinate ranges
- Store partitions on disk

} Queries often require loading 1-2 partitions

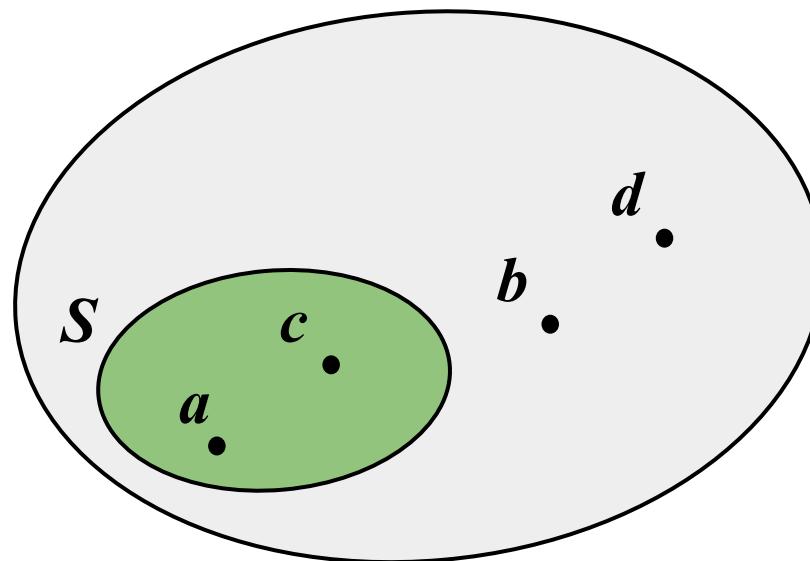
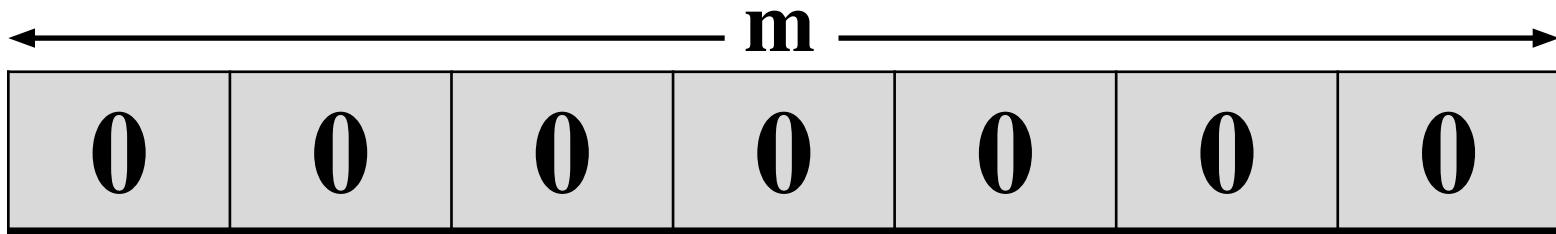
- Succinct index for reference coordinate system
- Local-graph exploration to map position from reference to sample coordinate

Variation graph



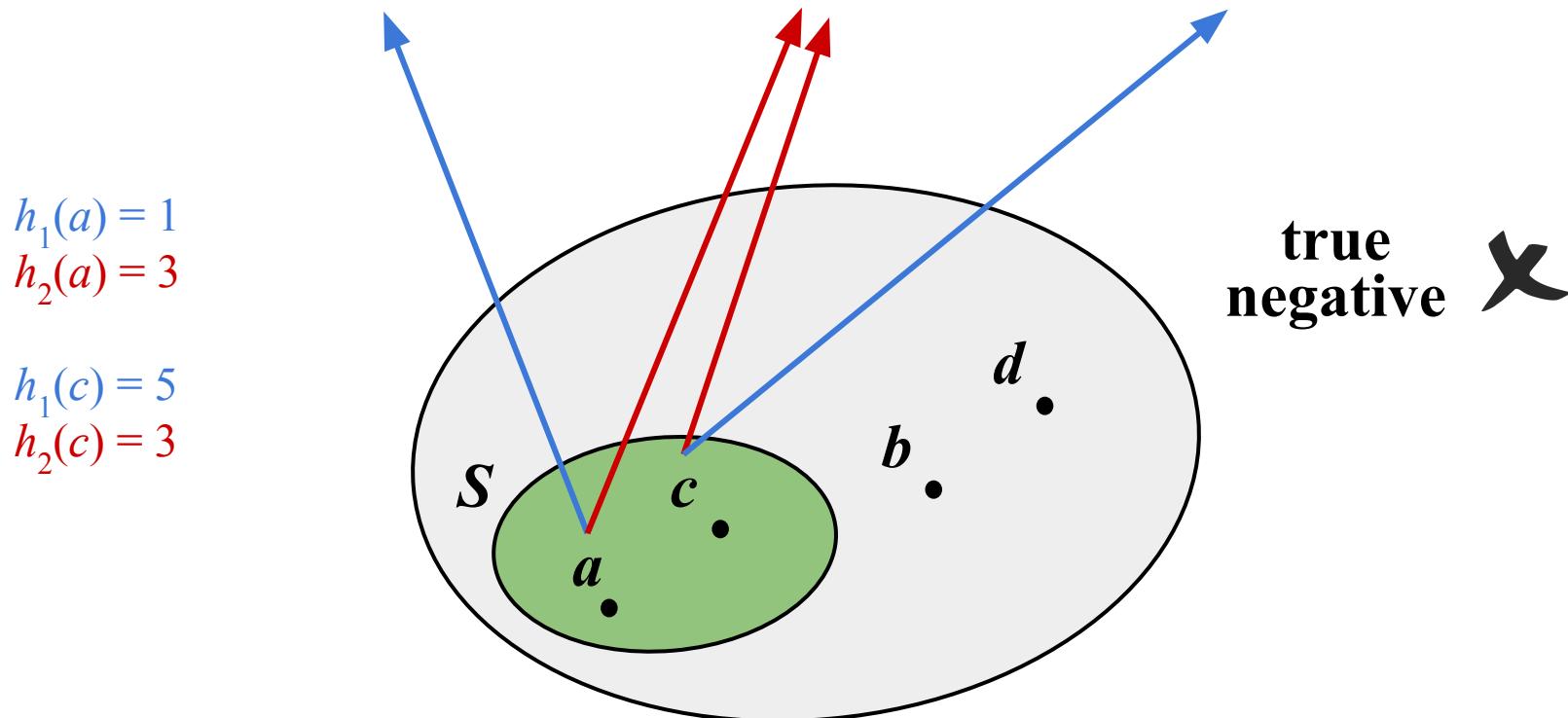
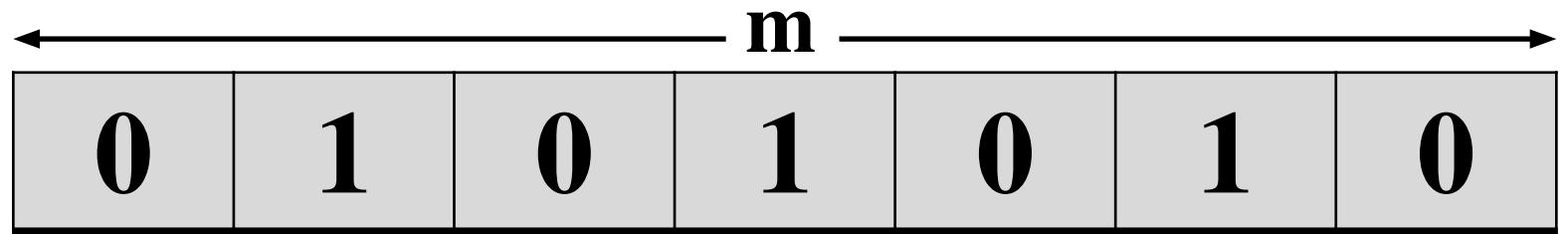
Classic filter: The Bloom filter [Bloom '70]

Bloom filter: a bit array + k hash functions



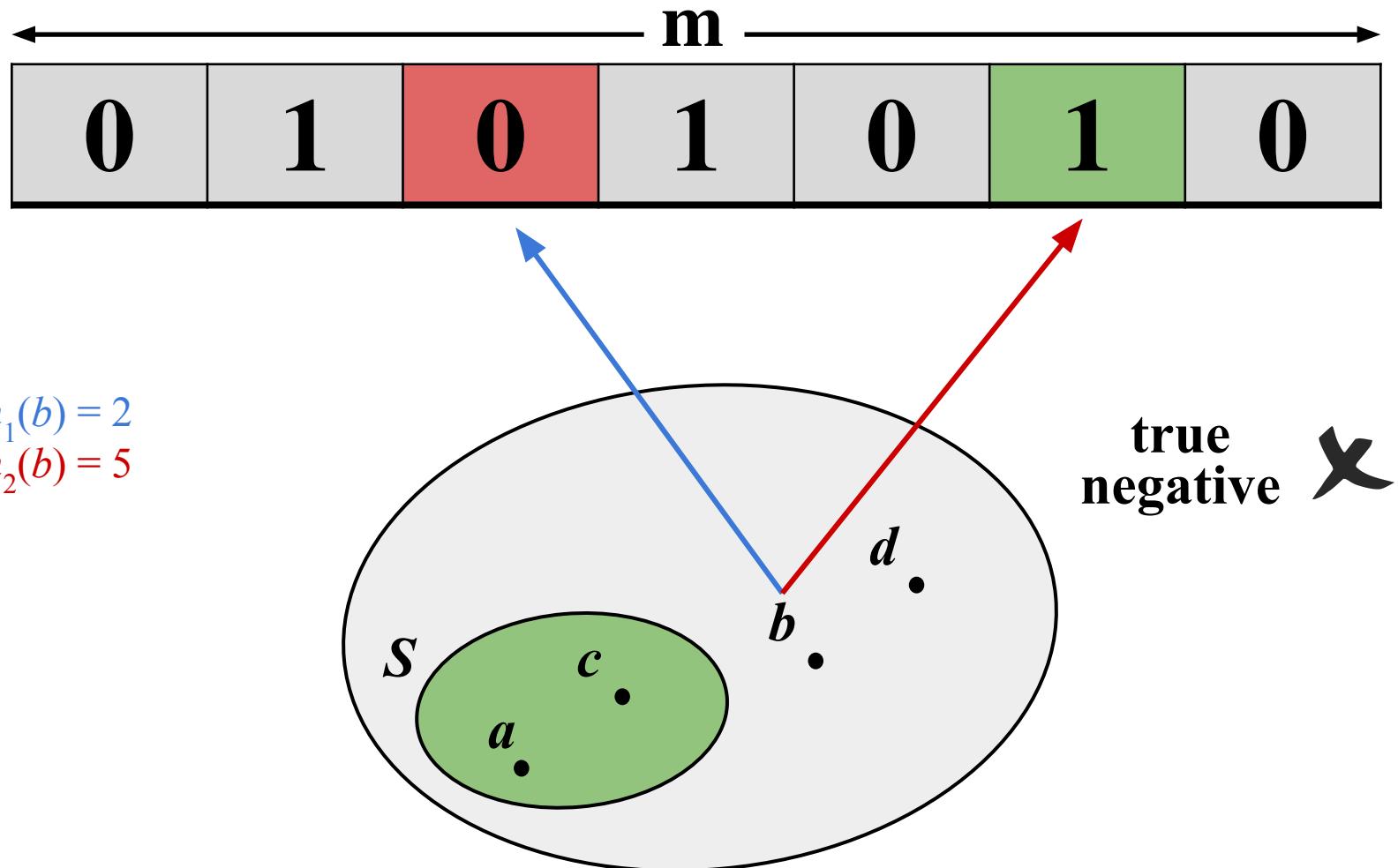
Classic filter: The Bloom filter [Bloom '70]

Bloom filter: a bit array + k hash functions (here $k = 2$)



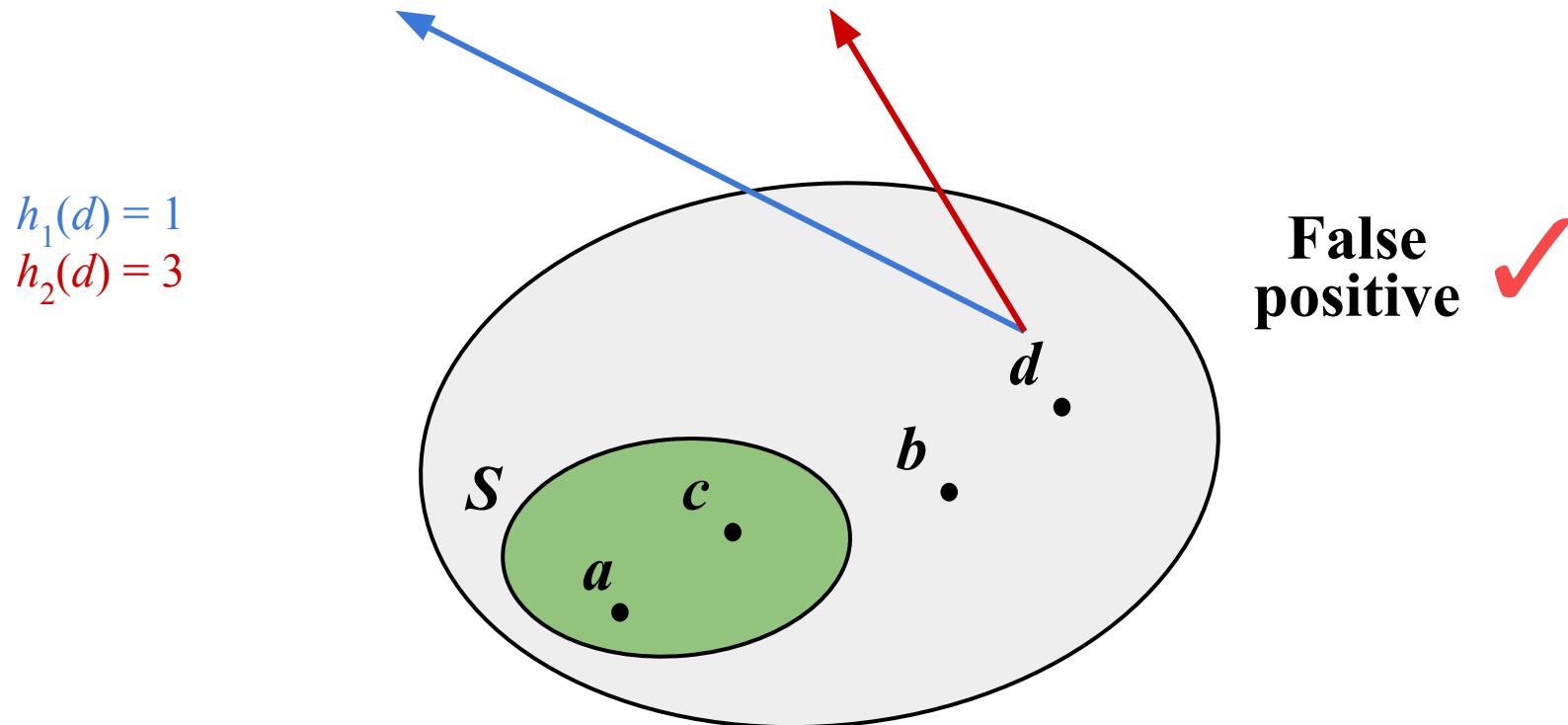
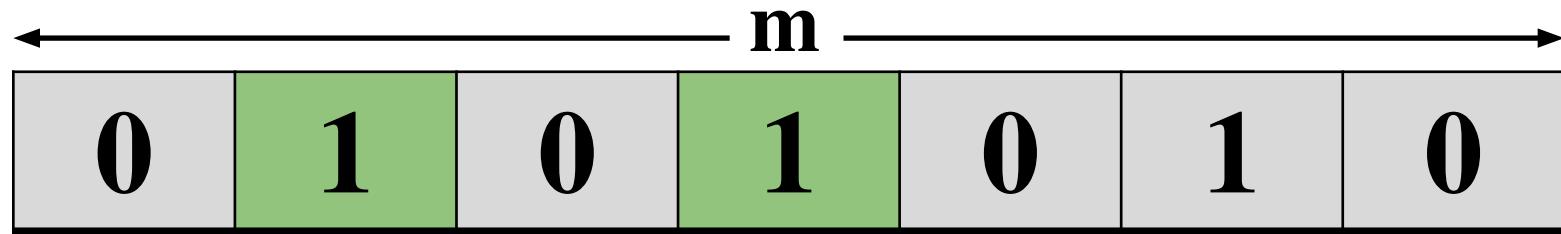
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Classic filters: The Bloom filter [Bloom '70]

Bloom filter: a bit array + k hash functions (here $k=2$)



Bloom filters are ubiquitous (> 4300 citations)

Streaming applications



Networking



Databases



Computational biology

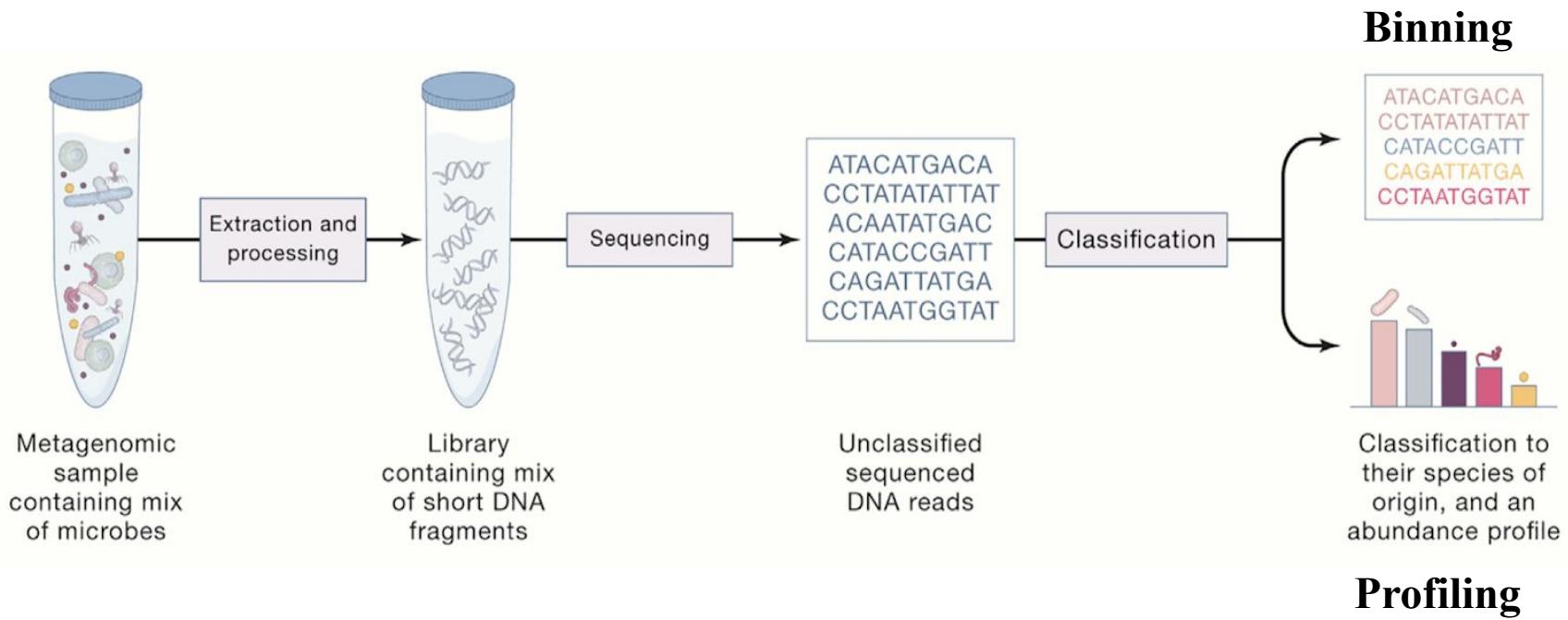


Storage systems



Metagenomic classification pipeline

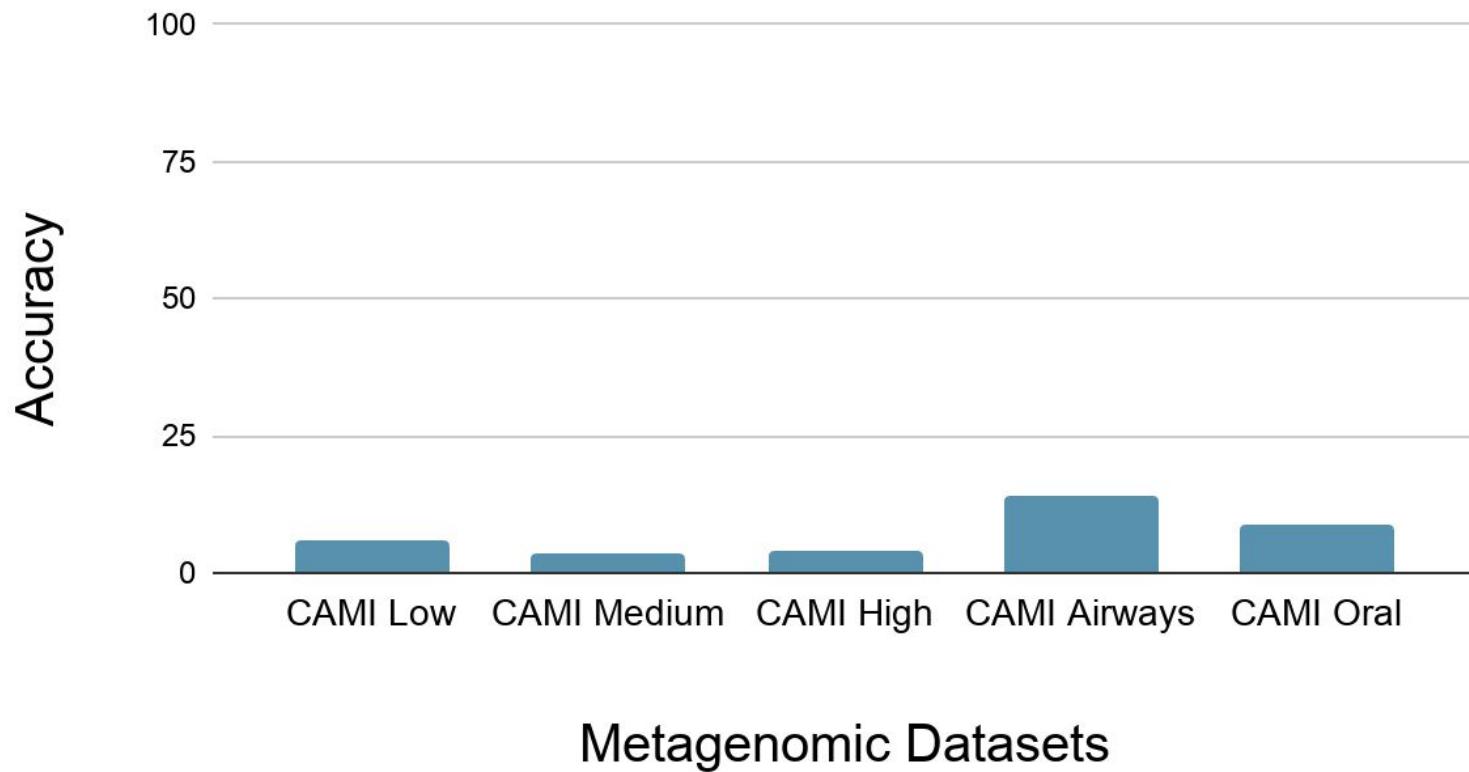
[Ye et al. 2019]



Classification is the *critical first step* in many metagenomic analysis pipeline

Existing indexing techniques offer low accuracy

Kraken2 (F1 Score)



Indexing-based classification is done based ***only on the contents
on the input sequences***