

Dimensionality Reduction

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PCA Exercise 1

Question 1: Review the steps to perform PCA mathematically.

Focus: PCA for compression.

PCA Step-by-step I

Organize the Dataset: Write the data as a matrix \mathbf{X} of $D \times N$: N instances of D dimensional data.

Calculate the Empirical Mean:

$$\bar{\mathbf{x}} = \frac{1}{N} \sum_{n=1}^N \mathbf{x}_n$$

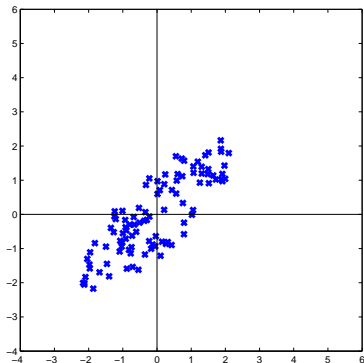
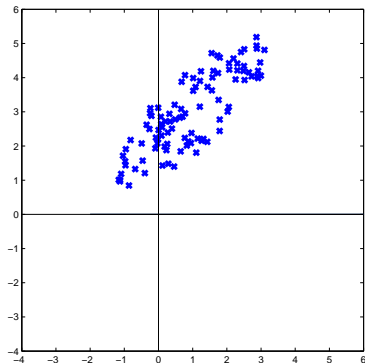
Center the data: Center the data by subtracting the mean from each data sample:

$$\bar{\mathbf{X}} = \mathbf{X} - \mathbf{M}$$

where $\mathbf{M} = \underbrace{[\bar{\mathbf{x}}, \dots, \bar{\mathbf{x}}]}_{N \text{ times}}$

PCA Step-by-step 1a

Centering



PCA Step-by-step II

Compute the covariance matrix

$$\Sigma = \frac{1}{N} \sum_{n=1}^N (\mathbf{x}_n - \bar{\mathbf{x}})(\mathbf{x}_n - \bar{\mathbf{x}})^\top = \frac{1}{N} \underbrace{\bar{\mathbf{X}}\bar{\mathbf{X}}^\top}_{\text{Scatter Matrix } \mathbf{S}}.$$

Question: What is the difference between the covariance matrix of the original dataset \mathbf{X} and that of the zero-mean data $\bar{\mathbf{X}}$?

PCA Step-by-step II

Eigenvalue decomposition: Compute the eigenvalue decomposition of the covariance matrix. Since Σ is symmetric,

$$\Sigma = \mathbf{U}\mathbf{\Lambda}\mathbf{U}^\top,$$

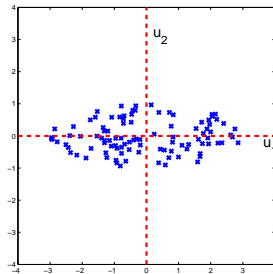
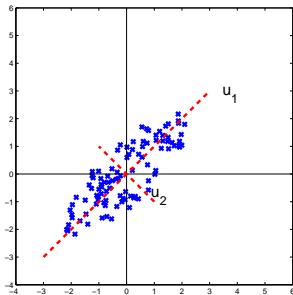
where $\mathbf{\Lambda} = \text{diag}[\lambda_1, \dots, \lambda_D]$, such that $\lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_D$.

Eigenvector matrix $\mathbf{U} = [u_1, \dots, u_D]$, where $u_i \in \mathbb{R}^D$ are unit (i.e. $\|u_i\|_2 = 1$) and orthonormal column eigenvectors.

Question: How does the eigendecomposition of the scatter matrix \mathbf{S} differ from that of Σ ?

PCA Step-by-step IIa

Eigenvalue decomposition and rotation



PCA Step-by-step III

Model selection: Pick a $K \leq D$ and keep the projections associated with the top K eigenvalues. (Capture maximal variance of the data.)

Transform the data onto the new basis of K dimensions:

Projection matrix: $\mathbf{U}_K = [u_1, \dots, u_K] \in \mathbb{R}^{D \times K}$

$$\bar{\mathbf{Z}} = \mathbf{U}_K^\top \bar{\mathbf{X}}$$

$\bar{\mathbf{Z}} \in \mathbb{R}^{K \times N}$: We obtain a dimension reduction of the data.

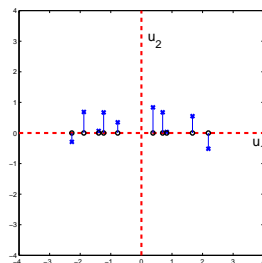
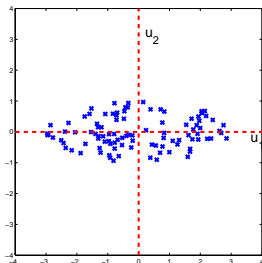
Reconstruction: Go back to original basis:

$$\tilde{\tilde{\mathbf{X}}} = \mathbf{U}_K \bar{\mathbf{Z}}$$

and correct for shift $\tilde{\mathbf{X}} = \tilde{\tilde{\mathbf{X}}} + \mathbf{M}$.

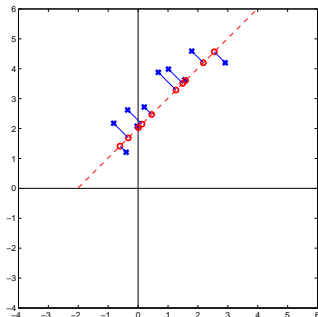
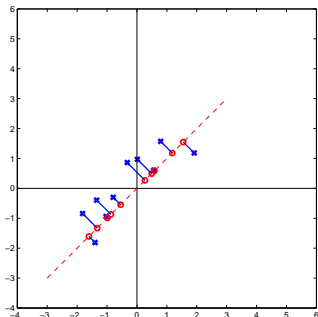
PCA Step-by-step IIIa

Scalar projection onto eigenvector subspaces



PCA Step-by-step IIIb

Inverse rotation and shift



PCA Reconstruction Error

$$\text{err} = \frac{1}{N} \sum_{i=1}^N \|\tilde{x}_i - \bar{x}_i\|_2^2 = \frac{1}{N} \|\tilde{\mathbf{X}} - \bar{\mathbf{X}}\|_F^2$$

where $\|A\|_F = \sqrt{\sum_i \sum_j a_{ij}^2} = \sqrt{\text{trace}(AA^\top)}$ is the Frobenius norm of matrix A .

Goal:

Prove that

$$\text{err} = \sum_{i=K+1}^D \lambda_i$$

PCA Reconstruction Error - Proof

$$\text{err} = \frac{1}{N} \|\tilde{\mathbf{X}} - \bar{\mathbf{X}}\|_F^2$$

PCA Reconstruction Error - Proof

$$\text{err} = \frac{1}{N} \|\tilde{\mathbf{X}} - \bar{\mathbf{X}}\|_F^2 = \frac{1}{N} \|(\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \bar{\mathbf{X}}\|_F^2$$

PCA Reconstruction Error - Proof

$$\begin{aligned}\text{err} &= \frac{1}{N} \|\tilde{\mathbf{X}} - \bar{\mathbf{X}}\|_F^2 = \frac{1}{N} \|(\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \bar{\mathbf{X}}\|_F^2 \\ &= \frac{1}{N} \text{trace}((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \bar{\mathbf{X}} \bar{\mathbf{X}}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)^\top)\end{aligned}$$

PCA Reconstruction Error - Proof

$$\begin{aligned}\text{err} &= \frac{1}{N} \|\tilde{\mathbf{X}} - \bar{\mathbf{X}}\|_F^2 = \frac{1}{N} \|(\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \bar{\mathbf{X}}\|_F^2 \\ &= \frac{1}{N} \text{trace}((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \bar{\mathbf{X}} \bar{\mathbf{X}}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)^\top) \\ &= \text{trace} \left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \boldsymbol{\Sigma} \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \right)\end{aligned}$$

PCA Reconstruction Error - Proof

$$\begin{aligned}\text{err} &= \frac{1}{N} \|\tilde{\mathbf{X}} - \bar{\mathbf{X}}\|_F^2 = \frac{1}{N} \|(\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \bar{\mathbf{X}}\|_F^2 \\&= \frac{1}{N} \text{trace}((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \bar{\mathbf{X}} \bar{\mathbf{X}}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)^\top) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \boldsymbol{\Sigma} \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)\right) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \mathbf{U} \boldsymbol{\Lambda} \mathbf{U}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)\right)\end{aligned}$$

PCA Reconstruction Error - Proof

$$\begin{aligned}\text{err} &= \frac{1}{N} \|\tilde{\mathbf{X}} - \bar{\mathbf{X}}\|_F^2 = \frac{1}{N} \|(\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \bar{\mathbf{X}}\|_F^2 \\&= \frac{1}{N} \text{trace}((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \bar{\mathbf{X}} \bar{\mathbf{X}}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)^\top) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \boldsymbol{\Sigma} \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)\right) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \mathbf{U} \boldsymbol{\Lambda} \mathbf{U}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)\right) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top \mathbf{U} - \mathbf{U}) \cdot \boldsymbol{\Lambda} \cdot (\mathbf{U}^\top \mathbf{U}_K \mathbf{U}_K^\top - \mathbf{U}^\top)\right)\end{aligned}$$

PCA Reconstruction Error - Proof

$$\begin{aligned}\text{err} &= \frac{1}{N} \|\tilde{\mathbf{X}} - \bar{\mathbf{X}}\|_F^2 = \frac{1}{N} \|(\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \bar{\mathbf{X}}\|_F^2 \\&= \frac{1}{N} \text{trace}((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \bar{\mathbf{X}} \bar{\mathbf{X}}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)^\top) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \boldsymbol{\Sigma} \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)\right) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \mathbf{U} \boldsymbol{\Lambda} \mathbf{U}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)\right) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top \mathbf{U} - \mathbf{U}) \cdot \boldsymbol{\Lambda} \cdot (\mathbf{U}^\top \mathbf{U}_K \mathbf{U}_K^\top - \mathbf{U}^\top)\right) \\&= \text{trace}\left(([\mathbf{U}_K; \mathbf{0}] - \mathbf{U}) \boldsymbol{\Lambda} ([\mathbf{U}_K; \mathbf{0}] - \mathbf{U})^\top\right)\end{aligned}$$

PCA Reconstruction Error - Proof

$$\begin{aligned}\text{err} &= \frac{1}{N} \|\tilde{\mathbf{X}} - \bar{\mathbf{X}}\|_F^2 = \frac{1}{N} \|(\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \bar{\mathbf{X}}\|_F^2 \\&= \frac{1}{N} \text{trace}((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \bar{\mathbf{X}} \bar{\mathbf{X}}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)^\top) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \boldsymbol{\Sigma} \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)\right) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \mathbf{U} \boldsymbol{\Lambda} \mathbf{U}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)\right) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top \mathbf{U} - \mathbf{U}) \cdot \boldsymbol{\Lambda} \cdot (\mathbf{U}^\top \mathbf{U}_K \mathbf{U}_K^\top - \mathbf{U}^\top)\right) \\&= \text{trace}\left(([\mathbf{U}_K; \mathbf{0}] - \mathbf{U}) \boldsymbol{\Lambda} ([\mathbf{U}_K; \mathbf{0}] - \mathbf{U})^\top\right) \\&= \text{trace}\left(\sum_{i=K+1}^D \lambda_i u_i u_i^\top\right)\end{aligned}$$

PCA Reconstruction Error - Proof

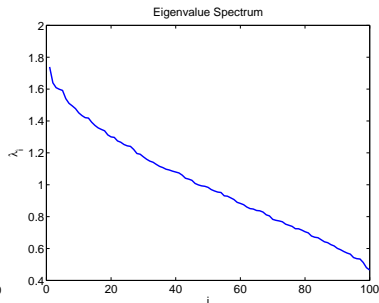
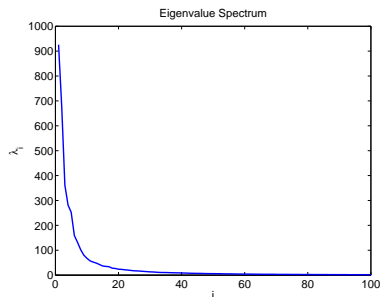
$$\begin{aligned}\text{err} &= \frac{1}{N} \|\tilde{\mathbf{X}} - \bar{\mathbf{X}}\|_F^2 = \frac{1}{N} \|(\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \bar{\mathbf{X}}\|_F^2 \\&= \frac{1}{N} \text{trace}((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \bar{\mathbf{X}} \bar{\mathbf{X}}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)^\top) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \Sigma \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)\right) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \mathbf{U} \Lambda \mathbf{U}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)\right) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top \mathbf{U} - \mathbf{U}) \cdot \Lambda \cdot (\mathbf{U}^\top \mathbf{U}_K \mathbf{U}_K^\top - \mathbf{U}^\top)\right) \\&= \text{trace}\left([\mathbf{U}_K; \mathbf{0}] - \mathbf{U}) \Lambda ([\mathbf{U}_K; \mathbf{0}] - \mathbf{U})^\top\right) \\&= \text{trace}\left(\sum_{i=K+1}^D \lambda_i u_i u_i^\top\right) = \sum_{i=K+1}^D \lambda_i \cdot \text{trace}\left(u_i u_i^\top\right)\end{aligned}$$

PCA Reconstruction Error - Proof

$$\begin{aligned}\text{err} &= \frac{1}{N} \|\tilde{\mathbf{X}} - \bar{\mathbf{X}}\|_F^2 = \frac{1}{N} \|(\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \bar{\mathbf{X}}\|_F^2 \\&= \frac{1}{N} \text{trace}((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \bar{\mathbf{X}} \bar{\mathbf{X}}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)^\top) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \boldsymbol{\Sigma} \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)\right) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d) \cdot \mathbf{U} \boldsymbol{\Lambda} \mathbf{U}^\top \cdot (\mathbf{U}_K \mathbf{U}_K^\top - \mathbf{I}_d)\right) \\&= \text{trace}\left((\mathbf{U}_K \mathbf{U}_K^\top \mathbf{U} - \mathbf{U}) \cdot \boldsymbol{\Lambda} \cdot (\mathbf{U}^\top \mathbf{U}_K \mathbf{U}_K^\top - \mathbf{U}^\top)\right) \\&= \text{trace}\left(([\mathbf{U}_K; \mathbf{0}] - \mathbf{U}) \boldsymbol{\Lambda} ([\mathbf{U}_K; \mathbf{0}] - \mathbf{U})^\top\right) \\&= \text{trace}\left(\sum_{i=K+1}^D \lambda_i u_i u_i^\top\right) = \sum_{i=K+1}^D \lambda_i \cdot \text{trace}\left(u_i u_i^\top\right) \\&\stackrel{\text{unit norm}}{=} \sum_{i=K+1}^D \lambda_i\end{aligned}$$

Reading the Eigenspectrum

Interpret eigenvalues as the **variance** in the dimension specified by the corresponding eigenvector.



For each eigenvalue spectrum, how many dimensions (K) should we keep?