

Assignment 1

1. Problem

I. Jacobi iterative method

i. Code

```
#include<stdio.h>

#include<stdlib.h>

#include<math.h>

# define m 31

# define n 21

int main()

{

    double dx = 6.0/(m-1),dy = 4.0/(n-1),psi_old[n][m],psi_new[n][m],as,aw,ap,ae,an, Error;

    int iteration = 0,i,j;

    Error=1;

    ap=2.0*((1.0/pow(dx,2.0))+(1.0/pow(dy,2.0)));

    as=(1.0/pow(dy,2.0));

    aw=(1.0/pow(dx,2.0));

    ae=(1.0/pow(dx,2.0));

    an=(1.0/pow(dy,2.0));

    //boudary conditions

    for(i=0; i<n ; i++)

    {

        for(j=0 ; j<m ; j++)

        {

            if(i==0)

            {

                //bottom boundary

                if(j<=5){

                    psi_new[i][j]=0;
```

```

    }
    if(j >= 6){
        psi_new[i][j]=100.0;
    }
}
//top boundary
else if(i == n-1 )
{
    psi_new[i][j]=0.0;
}
//left boundary
else if(j == 0){
    psi_new[i][j]=0.0;
}
else{
    psi_new[i][j]=0.0;
}
}

}

//jacobi iterative method
FILE *file1;
file1= fopen("error.txt","w");
fprintf(file1,"Iter\t Error\n");
while(Error>1e-6)
{
    for( i=0; i<n ; i++)
    {

```

```

for( j=0 ; j<m ; j++)
{
    psi_old[i][j]=psi_new[i][j];
}
}

for( i=1; i<n-1 ; i++)
{
    for(j=1 ; j<m-1 ; j++)
    {
        psi_new[i][j]=(1/ap)*((ae*psi_old[i][j+1])+(aw*psi_old[i][j-1])+(an*psi_old[i+1][j])+(as*psi_old[i-1][j]));
    }
}

for(i=0; i<n ; i++)
{
    psi_new[i][m-1]=psi_new[i][m-2];
}

Error=0;
for(int i=1; i<n-1 ; i++)
{
    for(j=1 ; j<m-1 ; j++)
    {
        Error = Error + pow((psi_new[i][j]-psi_old[i][j]),2);
    }
}

Error=sqrt(Error/((m-2)*(n-2)));
iteration=iteration+1;

```

```

printf("Iteration= %d\t", iteration);
printf("Error= %.9f\n", Error);
fprintf(file1, "%d \t %.9f \n", iteration, Error);
}

FILE *file2;
file2=fopen("Stream1a.plt","w");
fprintf(file2,"VARIABLES= \"X\", \"Y\", \"PHI\" \n");
fprintf(file2, "ZONE t=\"BLOCK1\", J=31,I=21,F= POINT \n\n");

for( i=0; i<n ; i++)
{
    for(j=0 ; j<m ; j++)
    {
        fprintf(file2, "%lf \t %lf \t %lf \n",j*dy,i*dx,psi_new[i][j]);
        printf("%f\t",psi_new[i][j]);
    }
}

return 0;

}

```

II. Point Gauss-Seidel iterative method

ii. Code

```

#include<stdio.h>
#include<stdlib.h>
#include<math.h>
# define m 31

```

```
# define n 21
```

```
int main()
```

```
{
```

```
    double dx = 6.0/(m-1),dy = 4.0/(n-1),psi_old[n][m],psi_new[n][m],as,aw,ap,ae,an,  
    Error,tem[n][m];
```

```
    int iteration = 0,i,j;
```

```
    Error=1;
```

```
    ap=2.0*((1.0/pow(dx,2.0))+(1.0/pow(dy,2.0)));
```

```
    as=(1.0/pow(dy,2.0));
```

```
    aw=(1.0/pow(dx,2.0));
```

```
    ae=(1.0/pow(dx,2.0));
```

```
    an=(1.0/pow(dy,2.0));
```

```
    for(int i=0; i<n ; i++)
```

```
    {
```

```
        for(int j=0 ; j<m ; j++)
```

```
        {
```

```
            if(i==0)
```

```
            {
```

```
                if(j<=4){
```

```
                    psi_new[i][j]=0;
```

```
                }
```

```
            else if(j >= 5){
```

```
                psi_new[i][j]=100.0;
```

```
            }
```

```
        }
```

```
    else if(i == n-1 ){
```

```
        psi_new[i][j]=0.0;
```

```
    }
```

```

else if(j == 0){
    psi_new[i][j]=0.0;
}
else{
    psi_new[i][j]=0.0 ;
}
}

//point gauss-seidal method
FILE *file1;
file1= fopen("error.txt","w");
fprintf(file1,"Iter\t Error\n");
while(Error>1e-6)
{
    Error=0;
    for( i=0; i<n ; i++)
    {
        for( j=0 ; j<m ; j++)
        {
            tem[i][j]=psi_new[i][j];
        }
    }

    for( i=1; i<n-1 ; i++)
    {
        for(j=1 ; j<m-1 ; j++)
        {
            psi_new[i][j]=(1/ap)*((ae*psi_new[i][j+1])+(aw*psi_new[i][j-1])+(an*psi_new[i+1][j])+(as*psi_new[i-1][j]));

```

```

        Error = Error + pow((psi_new[i][j]-tem[i][j]),2);

    }
}
for(i=0; i<n ; i++)
{
    psi_new[i][m-1]=psi_new[i][m-2];
}

    Error =sqrt(Error/(m*n));
    printf("iteration %d\t",iteration);
    printf("error %.10lf\n",Error);
    fprintf(file1, "%d\t%.10f\n",iteration,Error);
    iteration++;
}
FILE *file2;
file2=fopen("Stream1b.plt","w");
fprintf(file2,"VARIABLES= \"x\\\", \"y\\\", \"PHI\\\"\\n");
fprintf(file2, "ZONE t= \"BLOCK1\\\", J=31,I=21,F= POINT \\n\\n");

for(int i=0; i<n ; i++)
{
    for(int j=0 ; j<m ; j++)
    {
        fprintf(file2, "%lf\t%lf\t%lf\n",j*dy,i*dx,psi_new[i][j]);
        printf("%f\t",psi_new[i][j]);
    }
}

```

```
return 0;
}
```

iii. Line Gauss-Seidel iterative method (TriDiagonal Matrix Algorithm)

A. Code

```
#include<stdio.h>
#include<stdlib.h>
#include<math.h>
# define m 31
# define n 21
int main(){
    double psi_new[n][m],B,tem[n][m],ai,bi,ci,d[m-2],P[m-2],Q[m-2],dy=4.0/(n-1), dx=6.0/(m-1), error;
    int i,j,iteration=0;
    B = (dx/dy);
    ai=-2*(1+pow(B,2));
    bi=1;
    ci=1;
    for(i=0; i<n ; i++)
    {
        for(j=0 ; j<m; j++)
        {
            if(i==0)
            {
                //bottom boundary
                if(j<=5){
                    psi_new[i][j]=0;
                }
                if(j >= 6){
```



```

        psi_new[i][j]=100.0;
    }
}
//top boundary
else if(i == n-1 )
{
    psi_new[i][j]=0.0;
}
//left boundary
else if(j == 0){
    psi_new[i][j]=0.0;
}
else{
    psi_new[i][j]=0.0;
}
}

}

FILE *file1;
file1=fopen("error.txt","w");
error=1;
while(error > 1e-6)
{
    error = 0.0;
    for(j=1; j<m-1;j ++ )
    {
        d[0]=-(pow(B,2))*(psi_new[0][j+1]+psi_new[0][j-1]);
        P[0]=-bi/ai;
    }
}

```

```

Q[0]=d[0]/ai;

for(i=1; i<n-1; i++){
    d[i]=-(pow(B,2))*(psi_new[i][j+1]+psi_new[i][j-1]);;

    P[i]=-(bi/(ai+ci*P[i-1]));
    Q[i]=(d[i]-ci*Q[i-1])/(ai+ci*P[i-1]);
}

for(i=n-2; i>0; i--){
    tem[i][j]=psi_new[i][j];
    psi_new[i][j]=P[i]*psi_new[i+1][j]+Q[i];
    error+=pow((psi_new[i][j]- tem[i][j]),2.0);
}

}

for (i=0; i<n; i++){
    psi_new[i][m-1]=psi_new[i][m-2];
}

error=sqrt(error/((m-2)*(n-2)));
iteration = iteration+1;
printf("iteration %d\t",iteration);
printf("error %.9f\n",error);
fprintf(file1,"%d\t%.9lf\n",iteration,error);
}

FILE *file2;

```

```

file2=fopen("tdmam1.plt","w");
fprintf(file2,"VARIABLES= \"x\\\", \"y\\\", \"PHI\\\"\\n");
fprintf(file2, "ZONE t=\"BLOCK1\\\", J=31,I=21,F= POINT \\n\\n");

for(int i=0; i<n; i++)
{
    for(int j=0 ; j<m; j++)
    {
        fprintf(file2, "%lf\\t%lf\\t%lf\\n",j*dy,i*dx,psi_new[i][j]);
        printf("%f\\t",psi_new[i][j]);
    }
}

return 0;

}

```

iv. Alternating Direction Implicit method (ADI)

A. Code

```

#include<stdio.h>
#include<stdlib.h>
#include<math.h>
# define m 31
# define n 21
int main()
{
    double tem[m][n], psi_new[m][n],P[m-2],Q[m-2],d[m-2],d1[n-2],P1[n-2],Q1[n-
2],dx=6.0/(m-1),dy=4.0/(n-1),as,aw,ap,ae,an,aj,bj,cj,ai,bi,ci ,error;
    int i,j, iteration = 0;
    as=(1.0/pow(dy,2.0));
    aw=(1.0/pow(dx,2.0));

```

```

ap=2.0*((1.0/pow(dx,2.0))+(1.0/pow(dy,2.0)));
ae=(1.0/pow(dx,2.0));
an=(1.0/pow(dy,2.0));
ai=ap;
bi=-ae;
ci=-aw;
aj=ap;
bj=-an;
cj=-as;

```

```

for(i=0; i<m ; i++)
{
    for(j=0 ; j<n; j++)
    {
        if(j==0)
        {
            //bottom boundary
            if(i<=5){
                psi_new[i][j]=0;
            }
            if(i>= 6){
                psi_new[i][j]=100.0;
            }
        }
        //top boundary
        else if( j == n-1 )
        {
            psi_new[i][j]=0.0;
        }
        //left boundary
        else if( i == 0){
            psi_new[i][j]=0.0;
        }
        else{
            psi_new[i][j]=0.0;
        }
    }
}

```

```

FILE *file1;

```

```

file1=fopen("error.txt","w");
error=1;
while(error > 1e-6)
{

    for(i=0; i<m; i++)
    {
        for(j=0; j<n; j++)
        {
            tem[i][j]= psi_new[i][j];
        }
    }
    for(j=1; j<n-1; j++)
    {
        d[0]=an*(psi_new[0][j+1]+psi_new[0][j-1]);
        P[0]=-bi/ai;
        Q[0]=d[0]/ai;

        for(i=1; i<m-1; i++)
        {
            d[i]=an*(psi_new[i][j+1]+psi_new[i][j-1]);
            P[i]=-(bi/(ai+ci*P[i-1]));
            Q[i]=(d[i]-ci*Q[i-1])/(ai+ci*P[i-1]);
        }
        for(i=m-2; i>0; i--)
        {

            psi_new[i][j]=P[i]*psi_new[i+1][j]+Q[i];

        }
    }
    for(i=1; i<m-1; i++)
    {
        d1[0]=ae*(psi_new[i+1][0]+psi_new[i-1][0]);
        P1[0]=-(bj/aj);
        Q1[0]=(d1[0])/aj;

        for(j=1; j<n-1; j++)
        {

```

```

        d1[j]=ae*(psi_new[i+1][j]+psi_new[i-1][j]);
        P1[j]=-(bj/(aj+cj*P1[j-1]));
        Q1[j]=(d1[j]-cj*Q1[j-1])/(aj+cj*P1[j-1]);
    }
    for(j=n-2; j>0; j--){

        psi_new[i][j]=P1[j]*psi_new[i][j+1]+Q1[j];
    }
}

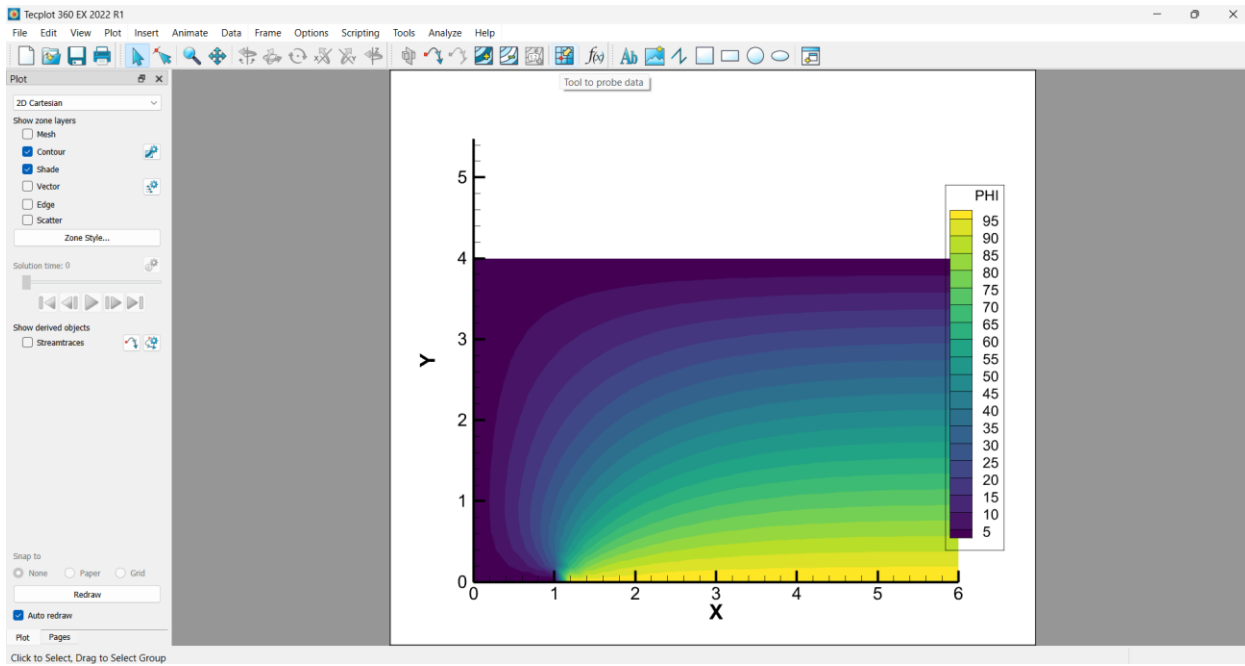
for (j=0; j<n; j++)
{
    psi_new[m-1][j]=psi_new[m-2][j] ;
}
error=0.0;
    for(i=0; i<m; i++)
    {
        for(j=0; j<n; j++){
            error+=pow((psi_new[i][j]-tem[i][j]),2);
        }
    }
    iteration=iteration+1 ;
    error=sqrt(error/((m-2)*(n-2)));
    printf("iteration %d\t",iteration);
    printf("error %.9f\n",error);
    fprintf(file1,"%d\t%.9f\n",iteration,error);
}
FILE *file2;
file2=fopen("adi_1.plt","w");
fprintf(file2,"VARIABLES= \"x\", \"y\", \"PHI\" \n");
fprintf(file2, "ZONE t=\"BLOCK1\", J=31,I=21,F= POINT \n\n");
for(i = 0; i < m; i++) {
    for(j = 0; j < n; j++)
    {
        fprintf(file2,"%f\t%f\t%f\n",dx*i,dy*j,psi_new[i][j]);
        printf("%f\t",psi_new[i][j]);

    }
}
return 0;

```

}

v. The output



The conclusion

Method in term speed

Adi method> Tdma>Point gauss seidel> jacobi

2. Problem 2

i. Jacobi iterative method

Code

```
#include<stdio.h>

#include<stdlib.h>

#include<math.h>

# define m 41

int main()

{
    double dx = 1.0/(m-1),dy = 1.0/(m-1),psi_old[m][m],psi_new[m][m],as,aw,ap,ae,an, Error;
    int iteration = 0,i,j;
    Error=1;
    ap=2.0*((1.0/pow(dx,2.0))+(1.0/pow(dy,2.0)));
    as=(1.0/pow(dy,2.0));
    aw=(1.0/pow(dx,2.0));
    ae=(1.0/pow(dx,2.0));
    an=(1.0/pow(dy,2.0));
    //boudary conditions

    for ( i = 0; i < m; i++)
    {
        for ( j = 0; j <m; j++)
        {

            psi_new[0][j]=1.0;
            psi_new[m-1][j]=1.0;
            psi_new[i][0]=1.0;
            if (j==m-1)
            {
```



```

        psi_new[i][j]=0.0;
    }
    else
    {
        psi_new[i][j]=0.0;
    }

}

}

FILE *file1;
file1= fopen("error.txt","w");
fprintf(file1,"Iter\t Error\n");
while (Error>1e-6)
{
    for ( i = 0; i <m; i++)
    {
        for ( j = 0; j <m; j++)
        {
            psi_old[i][j]=psi_new[i][j];
        }

    }

    for ( i = 1; i <m-1; i++)
    {
        for ( j = 0; j <m-1; j++)
        {
            psi_new[i][j]=(1/ap)*((ae*psi_old[i][j+1])+(aw*psi_old[i][j-1])+(an*psi_old[i+1][j])+(as*psi_old[i-1][j]));

```

```

    }

}

Error=0.0;
for ( i = 0; i < m; i++)
{
    for ( j =0; j< m; j++)
    {
        Error = Error + pow((psi_new[i][j]-psi_old[i][j]),2);
    }

}

Error=sqrt(Error/((m-2)*(m-2)));
iteration=iteration+1;
printf("Iteration= %d\t", iteration);
printf("Error= %.9f\n", Error);
fprintf(file1, "%d \t %.9f \n", iteration, Error);

}

FILE *file2;
file2=fopen("Stream1Ta.plt","w");
fprintf(file2,"VARIABLES= \"X\", \"Y\", \"T\" \n");
fprintf(file2, "ZONE t=\"BLOCK1\", J=41,I=41,F= POINT \n\n");

```

```

for( i=0; i<m ; i++)
{
    for(j=0 ; j<m ; j++)
    {
        fprintf(file2, "%lf \t %lf \t %lf \n",j*dy,i*dx,psi_new[i][j]);
        printf("%f\t",psi_new[i][j]);
    }
}

return 0;
}

```

ii. Point Gauss-Seidel iterative method

Code

```

#include<stdio.h>
#include<stdlib.h>
#include<math.h>
# define m 41
int main()
{
    double dx = 1.0/(m-1),dy = 1.0/(m-1),tem[m][m],psi_new[m][m],as,aw,ap,ae,an, Error;
    int iteration = 0,i,j;
    Error=1;
    ap=2.0*((1.0/pow(dx,2.0))+(1.0/pow(dy,2.0)));
    as=(1.0/pow(dy,2.0));
    aw=(1.0/pow(dx,2.0));
    ae=(1.0/pow(dx,2.0));
    an=(1.0/pow(dy,2.0));
    //boudary conditions

    for ( i = 0; i < m; i++)

```

```

{
    for ( j = 0; j <m; j++)
    {

        psi_new[0][j]=1.0;
        psi_new[m-1][j]=1.0;
        psi_new[i][0]=1.0;
        if (j==m-1)
        {
            psi_new[i][j]=0.0;
        }
        else
        {
            psi_new[i][j]=0.0;
        }

    }

}

FILE *file1;
file1= fopen("error.txt","w");
fprintf(file1,"Iter\t Error\n");
while (Error>1e-6)
{
    Error=0.0;
    for ( i = 0; i <m; i++)
    {
        for ( j = 0; j <m; j++)
        {
            tem[i][j]=psi_new[i][j];
        }

    }
    for ( i = 1; i <m-1; i++)
    {
        for ( j = 0; j <m-1; j++)
        {
            psi_new[i][j]=(1/ap)*((ae*psi_new[i][j+1])+(aw*psi_new[i][j-1])+(an*psi_new[i+1][j])+(as*psi_new[i-1][j]));
            Error = Error + pow((psi_new[i][j]-tem[i][j]),2);

```

```

    }

    }
    Error=sqrt(Error/((m-2)*(m-2)));
    iteration=iteration+1;
    printf("Iteration= %d\t", iteration);
    printf("Error= %.9f\n", Error);
    fprintf(file1, "%d \t %.9f \n", iteration, Error);

}

FILE *file2;
file2=fopen("Stream1Tb.plt","w");
fprintf(file2,"VARIABLES= \"X\", \"Y\", \"T\" \n");
fprintf(file2, "ZONE t=\"BLOCK1\", J=41,I=41,F= POINT \n\n");

for( i=0; i<m ; i++)
{
    for(j=0 ; j<m ; j++)
    {
        fprintf(file2, "%lf \t %lf \t %lf \n",j*dy,i*dx,psi_new[i][j]);
        printf("%f\t",psi_new[i][j]);
    }
}

return 0;
}

```

iii. Line Gauss-Seidel iterative method (TriDiagonal Matrix Algorithm)

Code

```

#include<stdio.h>
#include<stdlib.h>
#include<math.h>
# define m 41
int main()
{

```

```

double dx = 1.0/(m-1),dy = 1.0/(m-
1),tem[m][m],psi_new[m][m],Error,B,ai,bi,ci,d[m],P[m],Q[m];
int iteration = 0,i,j;
Error=1.0;
B=(dx/dy);
ai=-2*(1+pow(B,2));
bi=1.0;
ci=1.0;

//boudary conditions

for ( i = 0; i < m; i++)
{
    for ( j = 0; j <m; j++)
    {

        psi_new[0][j]=1.0;
        psi_new[m-1][j]=1.0;
        psi_new[i][0]=1.0;
        if (j==m-1)
        {
            psi_new[i][j]=0.0;
        }
        else
        {
            psi_new[i][j]=0.0;
        }

    }

}

}
FILE *file1;
file1= fopen("error.txt","w");
fprintf(file1,"Iteration\t Error\n");
while (Error>1e-6)
{
    Error=0.0;
    for ( j = 1; j< m; j++)
    {
        d[0]=-pow(B,2)*(psi_new[0][j+1]+psi_new[0][j-1]);

```

```

P[0]=-bi/ai;
Q[0]=d[0]/ai;

for (i = 1; i < m; i++)
{

    d[i]=-pow(B,2)*(psi_new[i][j+1]+psi_new[i][j-1]);
    P[i]=-(bi/(ai+ci*P[i-1]));
    Q[i]=(d[i]-ci*Q[i-1])/(ai+ci*P[i-1]);

}

for ( i = m-2; i > 0; i--)
{
    tem[i][j]=psi_new[i][j];
    psi_new[i][j]=P[i]*psi_new[i+1][j]+Q[i];
    Error = Error + pow((psi_new[i][j]-tem[i][j]),2.0);
}
}
Error=sqrt(Error/((m-2)*(m-2)));
iteration=iteration+1;
printf("Iteration= %d\t", iteration);
printf("Error= %.9f\n", Error);
fprintf(file1, "%d \t %.9f \n", iteration, Error);

}

FILE *file2;
file2=fopen("Stream1Tcccv.plt","w");
fprintf(file2,"VARIABLES= \"X\", \"Y\", \"T\" \n");
fprintf(file2, "ZONE t=\"BLOCK1\", J=41,I=41,F= POINT \n\n");

for( i=0; i<m ; i++)
{
    for(j=0 ; j<m ; j++)
    {
        fprintf(file2, "%lf \t %lf \t %lf \n",j*dy,i*dx,psi_new[i][j]);
        printf("%f\t",psi_new[i][j]);
    }
}

```

```

    }

    return 0;

}

```

iv. Alternating Direction Implicit method (ADI)

Code

```

#include<stdio.h>
#include<stdlib.h>
#include<math.h>
# define m 41
int main()
{

    double dx = 1.0/(m-1),dy = 1.0/(m-
1),tem[m][m],psi_new[m][m],Error,B,ai,bi,ci,d[m],P[m],Q[m],d1[m],P1[m],Q1[m];
    int iteration = 0,i,j;
    Error=1.0;
    B=(dx/dy);
    ai=-2*(1+pow(B,2));
    bi=1.0;
    ci=1.0;
    //boudary conditions
    for ( i = 0; i < m; i++)
    {
        for ( j = 0; j <m; j++)
        {

            psi_new[0][j]=1.0;
            psi_new[m-1][j]=1.0;
            psi_new[i][0]=1.0;
            if (j==m-1)
            {
                psi_new[i][j]=0.0;
            }
            else
            {
                psi_new[i][j]=0.0;
            }

```



```

    }
}
FILE *file1;
file1= fopen("error.txt","w");
fprintf(file1,"Iteration\t Error\n");
    while (Error>1e-6)
{
    for ( i = 0; i < m; i++)
    {
        for (j = 0; j <m; j++)
        {
            tem[i][j]=psi_new[i][j];
        }
    }

    for ( j = 0.5; j< m-1; j++)
    {
        d[0]=-pow(B,2)*(psi_new[0][j+1]+psi_new[0][j-1]);
        P[0]=-bi/ai;
        Q[0]=d[0]/ai;

        for (i = 0.5; i < m-1; i++)
        {

            d[i]=-pow(B,2)*(psi_new[i][j+1]+psi_new[i][j-1]);
            P[i]=-(bi/(ai+ci*P[i-1]));
            Q[i]=(d[i]-ci*Q[i-1])/(ai+ci*P[i-1]);

        }
        for ( i = m-2; i > 0; i--)
        {

            psi_new[i][j]=P[i]*psi_new[i+1][j]+Q[i];

        }
    }
    for ( i = 1; i < m-1; i++)

```

```

{
    d1[0]=-pow(B,2)*(psi_new[i+1][0]+psi_new[i-1][0]);
    P1[0]=-bi/ai;
    Q1[0]=d1[0]/ai;

    for ( j = 1; j < m-1; j++)
    {
        d1[j]=-pow(B,2)*(psi_new[i][j+1]+psi_new[i][j-1]);
        P1[j]=-(bi/(ai+ci*P1[j-1]));
        Q1[j]=(d1[j]-ci*Q1[j-1])/(ai+ci*P1[j-1]);

    }
    for ( j = m-2; j >0; j--)
    {
        psi_new[i][j]=P1[j]*psi_new[i+1][j]+Q1[j];
    }

}
Error=0.0;
for ( i = 0; i <m; i++)
{
    for ( j = 0; j < m; j++)
    {
        Error = Error + pow((psi_new[i][j]-tem[i][j]),2.0);
    }

}
Error=sqrt(Error/((m-2)*(m-2)));
iteration=iteration+1;
printf("Iteration= %d\t", iteration);
printf("Error= %.9f\n", Error);
fprintf(file1, "%d \t %.9f \n", iteration, Error);

}
FILE *file2;
file2=fopen("Stream1Tddd.plt","w");
fprintf(file2,"VARIABLES= \"X\", \"Y\", \"T\" \n");
fprintf(file2, "ZONE t=\"BLOCK1\", J=41,I=41,F= POINT \n\n");

```

```

for( i=0; i<m ; i++)
{
    for(j=0 ; j<m ; j++)
    {
        fprintf(file2, "%lf \t %lf \t %lf \n",j*dy,i*dx,psi_new[i][j]);
        printf("%f\t",psi_new[i][j]);
    }
}
return 0;
}

```

v. The output

