

## Lecture 6

$$\left. \begin{aligned} \frac{dv}{dt} &= g - \frac{c_d}{m} v^2 \\ v(0) &= 0 \end{aligned} \right\}, \quad 0 < t \leq t_f$$

(\*)  $\frac{dv(t)}{dt} \approx \frac{v(t+h) - v(t)}{h}$  provided  $h$  is small

$$\rightarrow t_0 = 0, \quad t_1 = \Delta t, \quad t_2 = 2\Delta t, \dots, \quad t_f = n \Delta t$$

$\Delta t$ : time step

$$v_i = v(t_i)$$

from (\*)  $\left. \frac{dv}{dt}(t_i) \approx \frac{v(t_i + \Delta t) - v(t_i)}{\Delta t} \right\} - \text{xx}$

from equation of  $v$ :

$$\frac{dv}{dt}(t_1) = g - c_d v(t_1)^2$$

$$\frac{dv}{dt}(t_2) = g - c_d v(t_2)^2$$

⋮

$$\frac{dv}{dt}(t_{n-1}) = g - c_d v(t_{n-1})^2$$

general i,  $i = 1, 2, \dots, n-1$   $v_i := v(t_i)$

$$\frac{dv}{dt}(t_i) \approx \frac{\tilde{v}(t_i + \Delta t) - v(t_i)}{\Delta t} = g - \frac{c_d}{m} v(t_i)^2$$

$$\Rightarrow \frac{v_{i+1} - v_i}{\Delta t} = g - \frac{c_d}{m} v_i^2$$

$$\Rightarrow v_{i+1} = v_i + \Delta t \left( g - \frac{c_d}{m} v_i^2 \right)$$

✓  $v_0$

$$\checkmark v_1 = v_0 + \Delta t \left( g - \frac{c_d}{m} v_0^2 \right)$$

$$\checkmark v_2 = v_1 + \Delta t \left( g - \frac{c_d}{m} v_1^2 \right)$$

⋮

$$\checkmark v_n = v_{n-1} + \Delta t \left( g - \frac{c_d}{m} v_{n-1}^2 \right)$$

$v(t_0) = v_0$

for  $i = 2 : n$

$v(i) = v(i-1)$

$+ \Delta t \left( g - \frac{c_d}{m} v_{i-1}^2 \right)$

end

## Errors in Numerical simulation

- X (i) finite capacity of computers in representing numbers
- ✓ (ii) discretization error, truncation error, numerical errors
- ✓, X (iii) modeling error

E.P. Bon  $\Rightarrow$  "All models are wrong, but some are useful"

- X (iv) uncertainty / observation error / experimental error in data
- ✓ (v) wrong numerical implementation

Precision :  $a_i$ ,  $i = 1, \dots, n$

$$|a_2 - a_1| \geq |a_3 - a_2| \geq \dots \geq |a_n - a_{n-1}|$$

Accuracy : if suppose, I know true value  $a$ ,

then

$$a - a_i$$

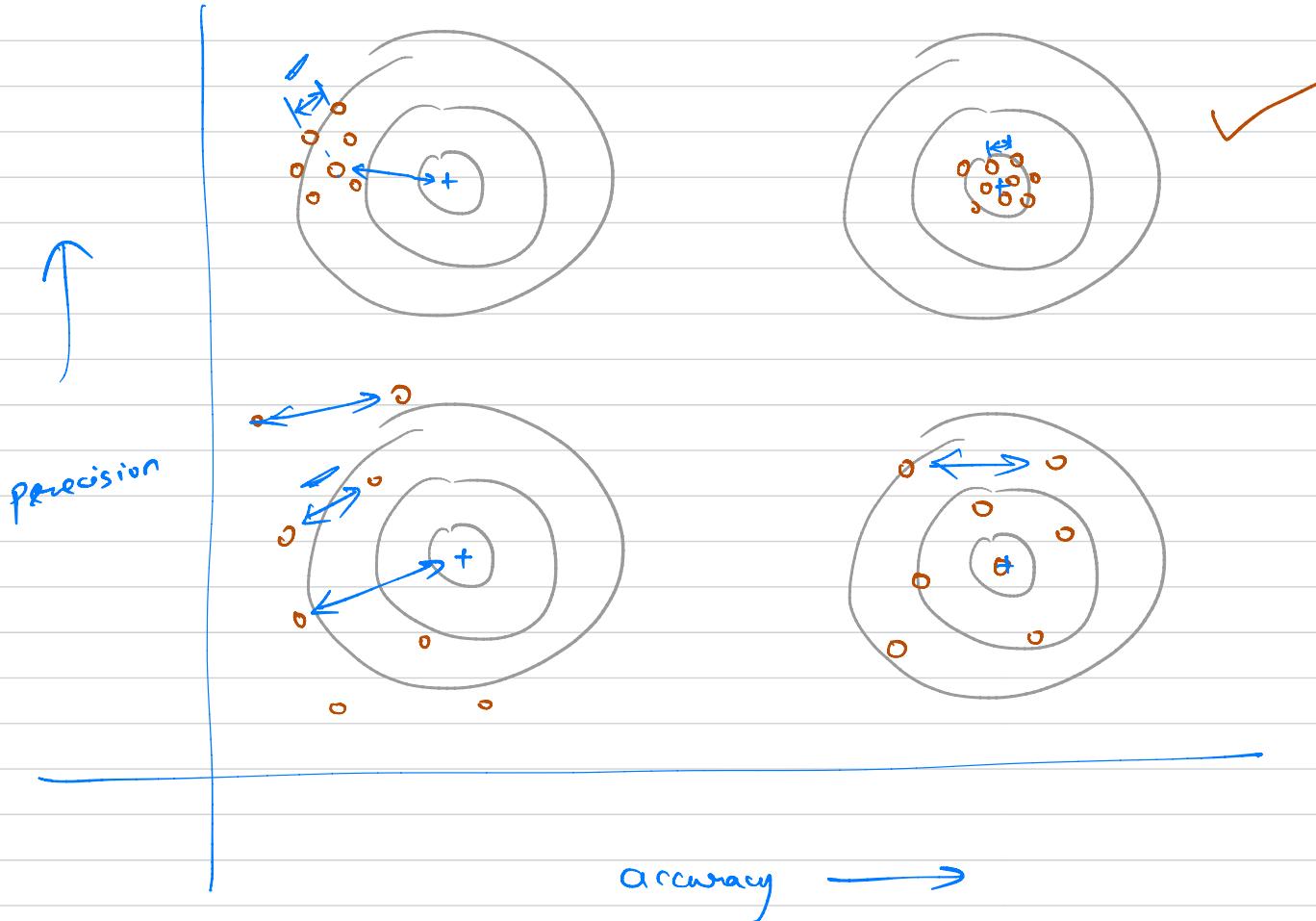
$$|a - a_1| > |a - a_2| > \dots > |a - a_n|$$

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### Definition of error :

True errors : Applicable only if you know the true value

$$E_t = (\text{True value} - \text{Approximate value})$$

$$V_{\text{true}} = 10 \text{ m/s}$$

$$V_{\text{app}} = 9 \text{ m/s}$$

$$E_t = 1 \text{ m/s}$$

$$V_{\text{true}} = 1000 \text{ m/s}$$

$$V_{\text{app}} = 999 \text{ m/s}$$

$$E_t = 1 \text{ m/s}$$

$$e_t = \frac{t_t}{\text{True value}} \times 100 \text{ \%}$$

$$e_t = 10\%$$

$$e_t = 0.01 \%$$

Present approximate value

$$E_a = \frac{\text{Previous approximate value}}{\text{Present approx. val.}} \times 100\%$$

$$N(t_F; \Delta t) \quad N(t_F; \Delta t_{1/2}) \quad N(t_F; \Delta t_{1/4}) \dots N(t_F; \Delta t_{2^n})$$

$$\frac{N(t_F; \Delta t_{1/2}) - N(t_F; \Delta t)}{N(t_F; \Delta t_{1/2})} > \frac{N(t_F; \Delta t_{1/4}) - N(t_F; \Delta t_{1/2})}{N(t_F; \Delta t_{1/4})} > \dots > \frac{N(t_F; \Delta t_{2^n}) - N(t_F; \Delta t_{2^{n-1}})}{N(t_F; \Delta t_{2^n})}$$

$x \in [x_1, x_2]$

$f(y), f'(y), f''(y), \dots$

$$f(x) = f(y) + f'(y)(y-x) + \frac{1}{2!} f''(y)(y-x)^2$$

$$+ \frac{1}{3!} f'''(z)(y-x)^3$$

$$f'(y) = \frac{df}{dy}, \quad \dot{f}(y) = \frac{df}{dy}, \quad f''(y) = \frac{d}{dy} f'(y) \\ = \frac{d^2 f}{dy^2}(y)$$

$$f(x) = f(y) + \frac{f'(y)}{1!} (y-x) + \frac{f''(y)}{2!} (y-x)^2 \\ + \dots + \frac{f^{(n)}(y)}{n!} (y-x)^n + \dots$$