Congratulations! You passed!

TO PASS 80% or higher

Keep Learning

grade 100%

Neural Network Basics

LATEST SUBMISSION GRADE

100%

1. What does a neuron compute?

1 / 1 point

- A neuron computes a linear function (z = Wx + b) followed by an activation function
- A neuron computes a function g that scales the input x linearly (Wx + b)
- \bigcirc A neuron computes an activation function followed by a linear function (z = Wx + b)
- $\bigcirc \ \ \text{A neuron computes the mean of all features before applying the output to an activation function}$



Correct, we generally say that the output of a neuron is a = g(Wx + b) where g is the activation function (sigmoid, tanh, ReLU, ...).

2. Which of these is the "Logistic Loss"?

1/1 point

- $\bigcirc \mathcal{L}^{(i)}(\mathring{y}^{(i)}, y^{(i)}) = \mid y^{(i)} \mathring{y}^{(i)} \mid$
- $\bigcirc \mathcal{L}^{(i)}(\hat{y}^{(i)}, y^{(i)}) = |y^{(i)} \hat{y}^{(i)}|^2$
- $\bigcirc \mathcal{L}^{(i)}(\mathring{y}^{(i)}, y^{(i)}) = -(y^{(i)}\log(\mathring{y}^{(i)}) + (1-y^{(i)})\log(1-\mathring{y}^{(i)}))$
- $\bigcirc \ \mathcal{L}^{(i)}(\mathring{\boldsymbol{y}}^{(i)}, \boldsymbol{y}^{(i)}) = max(0, \boldsymbol{y}^{(i)} \mathring{\boldsymbol{y}}^{(i)})$

✓ Correct

Correct, this is the logistic loss you've seen in lecture!

3. Suppose img is a (32,32,3) array, representing a 32x32 image with 3 color channels red, green and blue. How do you reshape this into a column vector?

1 / 1 point

- x = img.reshape((3,32*32))
- x = img.reshape((1,32*32,*3))
- x = img.reshape((32*32*3,1))
- x = img.reshape((32*32,3))

Correct

4. Consider the two following random arrays "a" and "b":

1/1 point

What will be the shape of "c"?

- c.shape = (2, 3)
- c.shape = (2, 1)
- c.shape = (3, 2)
- The computation cannot happen because the sizes don't match. It's going to be "Error"!

Correct

Yes! This is broadcasting. b (column vector) is copied 3 times so that it can be summed to each column of a.

5. Consider the two following random arrays "a" and "b":

1 / 1 point

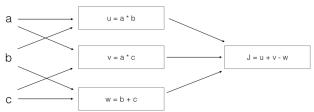
1 a = np.random.randn(4, 3) # a.shape = (4, 3) 2 b = np.random.randn(3, 2) # b.shape = (3, 2) 3 c = a*b

What will be the shape of "c"? c.shape = (3, 3) c.shape = (4, 3) $\textcircled{\scriptsize \textbf{0}} \ \ \, \textbf{The computation cannot happen because the sizes don't match. It's going to be "Error"!} \\$ c.shape = (4,2) ✓ Correct Indeed! In numpy the " \star " operator indicates element-wise multiplication. It is different from "np.dot()". If you would try "c = np.dot(a,b)" you would get c.shape = (4, 2). Suppose you have n_x input features per example. Recall that $X = [x^{(1)}x^{(2)}...x^{(m)}]$. What is the dimension 1 / 1 point \bigcap (m, n_x) $\bigcirc \ (m,1)$ $\bigcirc \ (1,m)$ \bigcirc (n_x, m) ✓ Correct 7. Recall that "np.dot(a,b)" performs a matrix multiplication on a and b, whereas "a*b" performs an element-1 / 1 point wise multiplication. Consider the two following random arrays "a" and "b": 1 a = np.random.randn(12288, 150) # a.shape = (12288, 150) 2 b = np.random.randn(150, 45) # b.shape = (150, 45) 3 c = np.dot(a,b) What is the shape of c? c.shape = (12288, 45) c.shape = (150,150) c.shape = (12288, 150) The computation cannot happen because the sizes don't match. It's going to be "Error"! ✓ Correct Correct, remember that a np.dot(a, b) has shape (number of rows of a, number of columns of b). The sizes match because: "number of columns of a = 150 = number of rows of b" 8. Consider the following code snippet: 1/1 point 1 # a.shape = (3,4) 2 # b.shape = (4,1) 3 4 for i in range(3): 5 for j in range(4): 6 c[i][j] = a[i][j] + b[j] 6 How do you vectorize this? C = a.T + b.T c = a + b.T \bigcirc c = a + b C = a.T + b ✓ Correct 9. Consider the following code: 1/1 point 1 a = np.random.randn(3, 3) 2 b = np.random.randn(3, 1) 3 c = a*b

What will be c? (If you're not sure, feel free to run this in python to find out).

■ This will invoke proadcasting, so b is copied three times to become (3,3), and * is an element-wise product so c.shape will be (3, 3) ○ This will invoke broadcasting, so b is copied three times to become (3, 3), and * invokes a matrix multiplication operation of two 3x3 matrices so c.shape will be (3, 3) This will multiply a 3x3 matrix a with a 3x1 vector, thus resulting in a 3x1 vector. That is, c.shape = (3,1). O It will lead to an error since you cannot use "*" to operate on these two matrices. You need to instead use np.dot(a,b) ✓ Correct 10. Consider the following computation graph.

1/1 point



What is the output J?

- $\int J = (c 1)*(b + a)$
- J = (a 1) * (b + c)
- J = a*b + b*c + a*c
- $\int J = (b 1) * (c + a)$

Yes. J = u + v - w = a*b + a*c - (b + c) = a*(b + c) - (b + c) = (a - 1)*(b + c).