

Project Phase II

Final Review

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SAINTGITS

COLLEGE OF ENGINEERING

(AUTONOMOUS)

Project Area: Robotics

Project Topic : Design and Fabrication of Robot for Assistance in Rescue Operations during Flood

Supervisor

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Presented by

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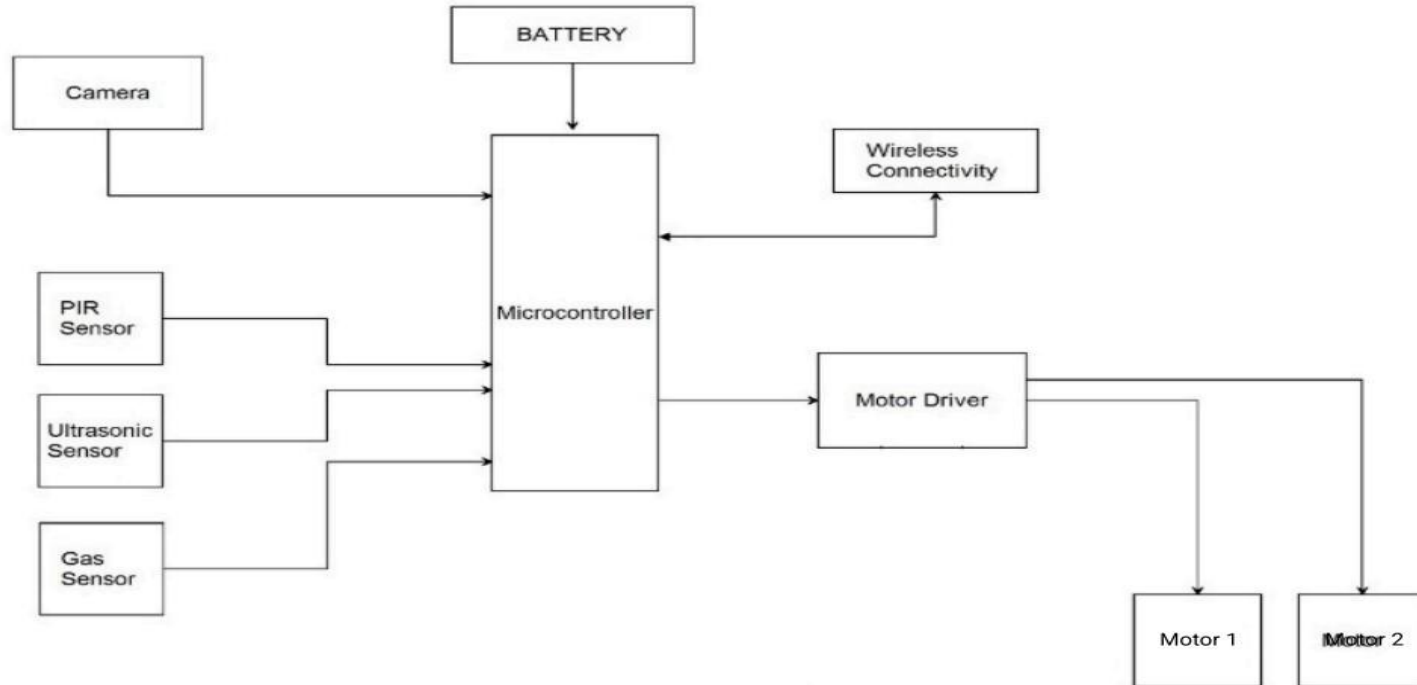
INTRODUCTION

- Floods are natural disasters that can result in extreme level of consequences.
- During such emergencies, rescue operations plays a crucial role in saving lives.
- Delay in rescue operations causing threat to the lives.
- For avoiding this situation to an extent, the robot helps to find the person by real time data.
- Using PIR Sensor we can detect humans trapped or confined in flooded area.
- To detect amorphous gases

OBJECTIVE

- The main goal is to develop a bluetooth based robot that assists in rescue operations during flood.
- To provide live feed visuals of the path it travels.
- To assist in search and rescue activities.
- To detect amorphous gases.
- To carry necessary medicines in a small box and to deliver it to people stuck in flooded areas.

BLOCK DIAGRAM



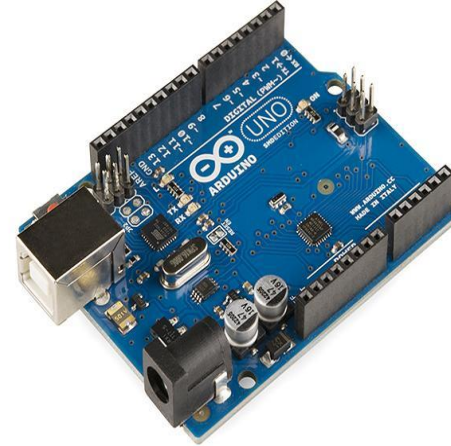
- When the rescue robot detects any movement came in front of the path, the PIR sensor detects the movement and sends signal to the control unit.
- The control unit sends signal to the Bluetooth module and to the mobile application.
- Amorphous gas detection is possible by gas sensor(MQ135) in the robot and can be analysed.
- Distance can be measured using ultrasonic sensor in the robot and can be viewed.
- Live video recording is possible using an IP webview application using a smartphone.
- An emergency medicine and food box is placed in the robot which can be opened using the application.

COMPONENTS USED

- Arduino Uno
- Motor driver
- DC motor
- Bluetooth module
- Ultrasonic sensor
- PIR sensor
- Gas sensor
- Limit Switch
- Servo motor
- Aluminium sheets
- PVC pipe and end caps
- 12V battery
- Battery wire connector

Arduino Uno

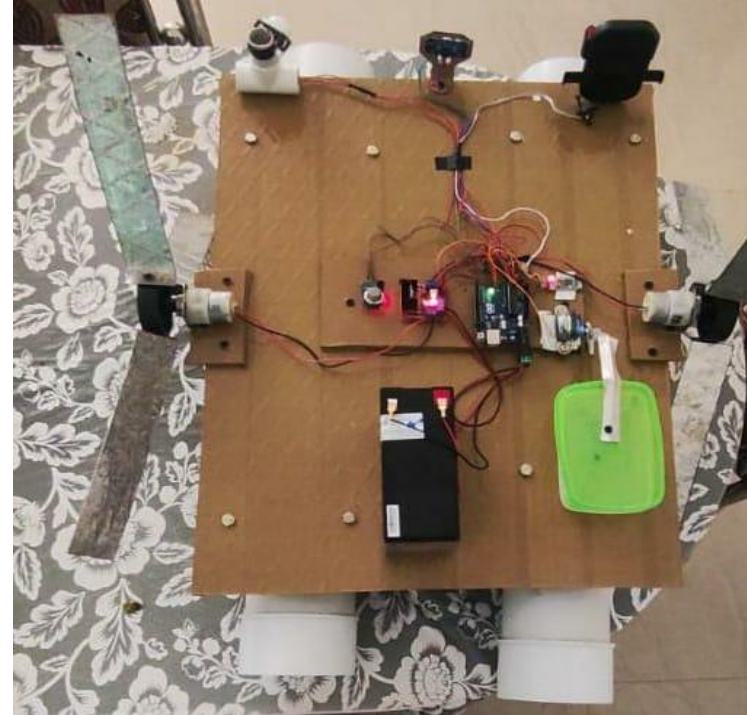
- ❖ Arduino Uno is an open-source microcontroller board
- ❖ Based on the ATmega328P microcontroller.
- ❖ Widely used in various projects ranging from robotics to home automation.
- ❖ The board has :
 - 14 digital input/output pins
 - 6 analog input pins
 - a 16 MHz quartz crystal oscillator
 - a USB connection
 - a power jack
 - an ICSP header
 - a reset button.



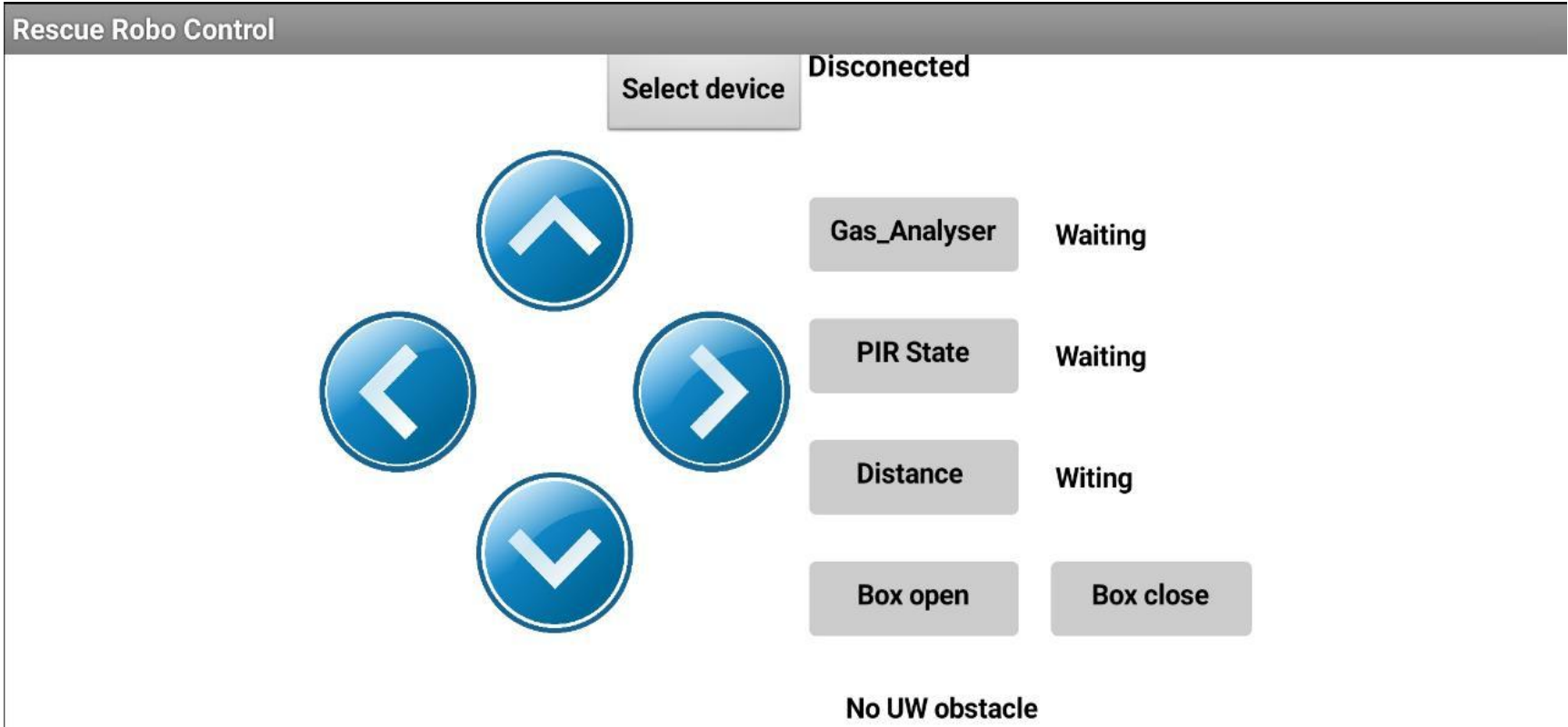
TOOLS REQUIRED

- ❖ Software
 - Arduino IDE
 - IP webview
 - Mobile Application
- ❖ Hardware
 - PVC pipes
 - BLDC motors
 - Propellers
 - Aluminium Sheet
 - Battery
 - Sensors

RESULTS



App Interface



PROJECT TIMELINE

	Week 1	Week 3	Week 5	Week 7	Week 9	Week 10	Week 11	Week 12
Study of Components								
Structure Design								
Assembly of Components								
Implementation								
Prototype Testing								
Report Writing								
Publication								

TASK ALLOCATION

- Aleena - Literature Survey, Study of components, Testing , Report writing, Publication
- Alkesh - Literature survey, study of components, Design, Testing, Assembly
- Brahamajith - Literature Survey, Study of components, Testing, Assembly
- Nayan - Literature survey, study of components, Design, Testing, Assembly

FUTURE SCOPE

- Intelligent Navigation and Mapping
- Remote monitoring and Control
- Autonomous Rescue Actions
- Integration with IoT and Cloud Services
- Swarm Robotics

CONCLUSION

- The main aim of this project was to construct a rescue robot which provides the service of rescue operations during flood season.
- We have designed and developed a model robot which can sense people, distance, obstacle and various other functions.
- This is a low cost service robot which can be designed and used for rescue operations.
- A promising solution to enhance rescue operations during flood situations.
- The flood rescue robot offers an efficient and reliable solution for locating individuals in flood affected areas.

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Thank You