

Computer Algorithm Lab

Q] Write a suitable example, analyze the difference between point-to-point communication and collective communication

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2020BTEIT00034

CA LAB ESE

Platform: *Linux*

Language: *Python*

Execution: *python 2020BTEIT00034.py len_of_array*

If argument len_of_array is not provided then it will set the length to 100000

Code:

```
'''
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Name: Daulatrao Patil
'''

import random, time, sys
import multiprocessing
from multiprocessing import Process, Pipe
```

```

def main():

    """
    This is the main method, where we:
    -generate a random list.
    -time a sequential quicksort on the list.
    -time a parallel quicksort on the list.
    """

    N = 100000

    if len(sys.argv) > 1: #the user input a list size.
        N = int(sys.argv[1])

    n = multiprocessing.cpu_count()

    # print(multiprocessing.cpu_count())

    #We want to sort the same list, so make a backup.
    backup_list = [random.random() for x in range(N)]

    #Sequential quicksort a copy of the list.
    main_list = list(backup_list)           #copy the list
    start_time = time.time()                #start time
    main_list = quicksort(main_list)        #quicksort the list
    elapsed_time = time.time() - start_time #calculate time

```

```

if not isSorted(main_list):

    print('😞 quicksort did not sort the list. oops. 😞\n')

    return

print('💎 Sequential quicksort: %f sec\n' % elapsed_time)

#So that cpu usage shows a lull.

time.sleep(1)

print('\tPreparing the processors... 👍')

time.sleep(1)

print('\tIntializing the Pipes... 👍\n')

time.sleep(1)

#Parallel quicksort.

main_list = list(backup_list)

if n > multiprocessing.cpu_count():

    print("\t🔥 System Overloading 🔥\n\t🚫 Processors not available!!!  

🚫\n\t👋 Aborting the mission 👋")

    return

start_time = time.time()

```

```

    #Instantiate a Pipe so that we can receive the process's response.

    pconn, cconn = Pipe()

    #Instantiate a process that executes quicksortParallel on the entire
list.

    p = Process(target=quicksortParallel, args=(main_list, cconn, n))

    p.start()

    main_list = pconn.recv()

    #Blocks until there is something (the sorted list) to receive.

    p.join()

    elapsed_time = time.time() - start_time

    if not isSorted(main_list):

        print('😞 quicksortParallel did not sort the list. oops. 😞\n')

    print('💠 Parallel quicksort: %f sec' % elapsed_time)

def quicksort(list_array):

    """

    Quicksort implementation, return a new sorted version of the input
list.

    """

```

```

    if len(list_array) <= 1:

        return list_array

    pivot = list_array.pop(random.randint(0, len(list_array)-1))

    return quicksort([x for x in list_array if x < pivot]) + [pivot] +
quicksort([x for x in list_array if x >= pivot])

def quicksortParallel(list_array, conn, procNum):

    """

    Partition the list, then quicksort the left and right sides in
parallel.

    """

    if procNum <= 1 or len(list_array) <= 1:

        #In the case of len(list) <= 1, quicksort will immediately return
anyway.

        conn.send(quicksort(list_array))

        conn.close()

        return

    pivot = list_array.pop(random.randint(0, len(list_array)-1))

    leftSide = [x for x in list_array if x < pivot]

    rightSide = [x for x in list_array if x >= pivot]

```

```

    #Creat a Pipe to communicate with the left subprocess

    pconnLeft, cconnLeft = Pipe()

    #Create a leftProc that executes quicksortParallel on the left
half-list.

    leftProc = Process(target=quicksortParallel, args=(leftSide, cconnLeft,
procNum - 1))

    #Again, for the right.

    pconnRight, cconnRight = Pipe()

    rightProc = Process(target=quicksortParallel, args=(rightSide,
cconnRight, procNum - 1))

    #Start the two subprocesses.

    leftProc.start()

    rightProc.start()

    #Our answer is the concatenation of the subprocesses answers, with the
pivot in between.

    conn.send(pconnLeft.recv() + [pivot] + pconnRight.recv())

    conn.close()

    #Join our subprocesses.

    leftProc.join()

    rightProc.join()

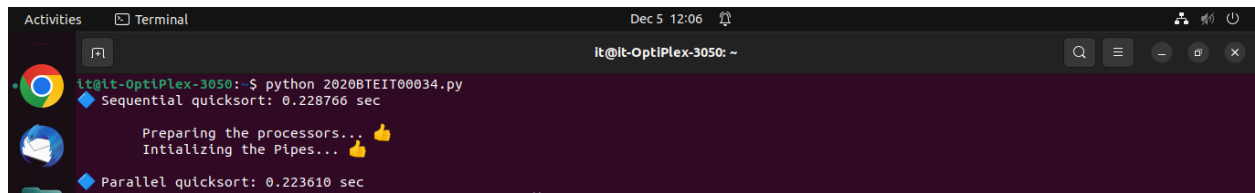
```

```
def isSorted(list):  
    """  
    Checking if the list is sorted or not.  
    """  
    for i in range(1, len(list)):  
        if list[i] < list[i-1]:  
            return False  
    return True  
  
#Call the main method if run from the command line.  
if __name__ == '__main__':  
    main()
```

Output

Output of the code for different numbers of processors.

P = 2



```

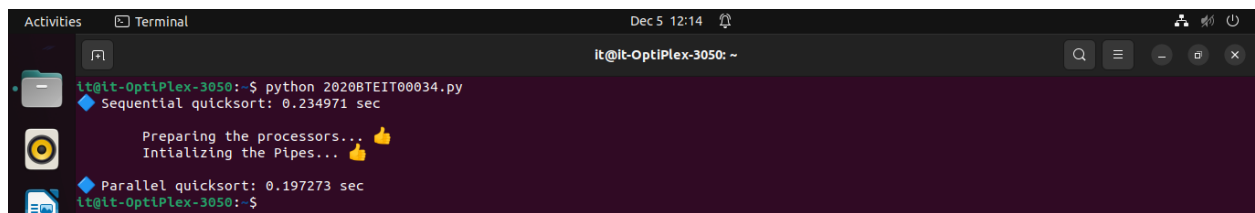
it@it-OptiPlex-3050: ~
$ python 2020BTEIT00034.py
Sequential quicksort: 0.228766 sec

Preparing the processors...
Initializing the Pipes...

Parallel quicksort: 0.223610 sec

```

P = 3



```

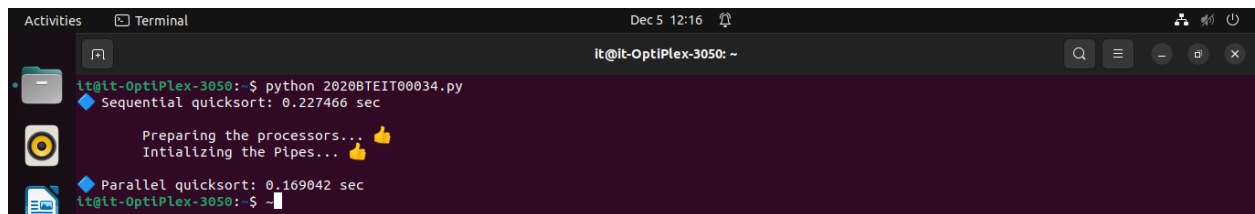
it@it-OptiPlex-3050: ~
$ python 2020BTEIT00034.py
Sequential quicksort: 0.234971 sec

Preparing the processors...
Initializing the Pipes...

Parallel quicksort: 0.197273 sec
it@it-OptiPlex-3050: ~
$

```

P = 4 (Max)



```

it@it-OptiPlex-3050: ~
$ python 2020BTEIT00034.py
Sequential quicksort: 0.227466 sec

Preparing the processors...
Initializing the Pipes...

Parallel quicksort: 0.169042 sec
it@it-OptiPlex-3050: ~
$

```

Comparison

Output No	QuickSort	Parallel Quicksort
1 -> P = 2	T = 0.228766	T = 0.223610
2 -> P = 3	T = 0.234971	T = 0.197273
3 -> P = 4 (max)	T = 0.227466	T = 0.169042

Conclusion

1. Point-to-Point Communication and Collective Communication is demonstrated using example of Sequential Quicksort v/s Parallel Quicksort
2. As we increase the number of processors the time eventually decreases for parallel processing of quicksort.
3. Implementation is done in python.