Hybrid Quad copter

Implementation

A race against time

1st week (5th April to 11th April)

Detailed study on project

2nd week (12th to 19th April)

1st review of our study.

Narrowing down on materials.

Applying 6 hats to get to know what we need

3rd week (20th to 26th April)

Getting our materials in place.

Creating a blueprint of our work.

Creating the wheels

4th week (27th April to 3rd May)

Quadcopter build.

Review 2

5th week (4th to 9th May)

Hybrid quad copter version 1.0.

First test flight.

3rd review

Analysis 1

6th week (10th and 11th May)

Version 1.1.

Second test flight.

Finishing touches.

12th May

Project exhibition.

Components required and their prize estimate:

| SI | Component Name | Specification | Amount |
|----|-----------------------------------|-----------------------|---------|
| 1 | Wireless Surveillance Camera with | RKI-1371 | Rs.1950 |
| | Receiver | | |
| 2 | Motor x4 | hexTronik DT750 | 788 * 4 |
| | | Brushless Outrunner | |
| | | 750kv | |
| 3 | Electronic Speed Control (ESC) x4 | RCTimer 30A SimonK | 750 * 4 |
| | | ESC | |
| 4 | Flight Control Board | HobbyKing KK2.0 | 3000 |
| | | Multirotor LCD Flight | |
| | | Control Board w/ | |
| | | Updated Firmware | |
| 5 | Radio transmitter and receiver | Turnigy 9X 9Ch | 5820 |
| | | Transmitter w/ | |
| | | Module & 8ch | |
| | | Receiver (Mode 2) | |
| | | (v2 Firmware) | |
| 6 | Propeller x4 (2 clockwise and 2 | | 480 |
| | counter-clockwise) | | |
| 7 | Battery & Charger | Turnigy Nano-Tech | 2100 |
| | | 3000mAh 25-50C 3S | |
| | | LiPo | |
| 8 | Miscellaneous cost | Wire, bolts, glue etc | 300 |

Objectives:

- To design and build a manoeuvrable and agile quad copter.
- To design a completely longitudinally stable copter for better imaging purposes.
- To combine the quad copter and hovercraft design and build a hybrid model that can fly as well as glide on the surface of water and ground for better imaging of specimen.
- To understand the concept of Ground Effect Vehicles.
- To carry and drop light weight objects.
- We may test this Quad copter to carry sensors as in Remote Sensing satellites and study various parameters regarding it.

Learnings:

- In depth knowledge about aerodynamics
- Clarity in the basics concepts of physics -pressure and thrust
- To know more about dynamic of quad copter
- To know the basics electrical involved

These are the various learning from our project.