

Project Name: MOTION SENSING HEXAPOD

Timeline:

Week 1:

- Study about the servos and microprocessor required
- Completion of basic solid work model
- Collect all required material

Week 2:

- Design PCB (to learn more about circuits)
- One prototype leg

Week 3:

- Modification of leg (if required)
- Give PCB for printing

Week 4:

- Complete basic hexapod
- Begin work toward motion sensing

Week 5:

- Continue the work of motion sensing

Week 6:

- Finishing touches
- Improvement of design (if required)

Requirements:

- servos, PCBs, ICs, Batteries, Acrylic board, nuts and bolts, IC holders, sensors, microprocessor, bread boards, heat sinks, capacitors, resistors, wires, etc...

Approximate expense: 6000-7000/- Rs

Things might to learn:

- Mechanism of motion sensing
- PCB designing
- Learning skill of solid works