

Module - 1 (Complex Numbers)

* $z = x + iy = re^{i\theta}$ ($r = \sqrt{x^2 + y^2}$, $\theta = \tan^{-1}(\frac{y}{x})$).

$\Rightarrow x = r \cos \theta$, $y = ir \sin \theta$.

⊕ De Moivre's Theorem.

$\rightarrow (\cos \theta + i \sin \theta)^n = \cos n\theta + i \sin n\theta$.

⊕ Binomial theorem

$\rightarrow (\cos \theta + i \sin \theta)^n = {}^nC_0 \cos^n \theta + {}^nC_1 \cos^{n-1} \theta (i \sin \theta) + {}^nC_2 \cos^{n-2} \theta \sin^2 \theta i^2 + \dots$
 $= \cos^n \theta + i \sin \theta \dots + {}^nC_n (i \sin \theta)^n$.

⊕ $x^n + \frac{1}{x^n} = 2 \cos n\theta$; $x^n - \frac{1}{x^n} = 2i \sin n\theta$.

Use for combining homogeneous terms. to convert θ to $n\theta$ / $n\theta$ to θ .

$(x + \frac{1}{x})^n = (2 \cos \theta)^n$; $(x - \frac{1}{x})^n = (2i \sin \theta)^n$.

⊕ Roots

1) $x^3 = 1$, \Rightarrow Cube roots of unity $\Rightarrow 1 (e^{i2k\pi})$, $\omega (e^{i\frac{2k\pi}{3}})$, $\omega^2 (e^{i\frac{4k\pi}{3}})$

$\Rightarrow n^{\text{th}}$ roots of unity $\Rightarrow e^{i2k\pi/n}$, put $n=0, 1, 2, \dots, n$ for roots.

* Circular functions (Period $\rightarrow 2\pi$)

$\cos \theta = \frac{e^{i\theta} + e^{-i\theta}}{2}$; $\sin \theta = \frac{e^{i\theta} - e^{-i\theta}}{2i}$; $\tan \theta = \frac{e^{i\theta} - e^{-i\theta}}{e^{i\theta} + e^{-i\theta}}$

⊕ Hyperbolic functions (Period $\rightarrow 2\pi i$)

$\rightarrow \sin ix = i \sinh x$; $\sinh ix = i \sin x$

$\cos ix = \cosh x$; $\cosh ix = \cos x$

$\tan ix = i \tanh x$; $\tanh ix = i \tan x$

$\rightarrow \sinh x = \frac{e^x - e^{-x}}{2}$, $\cosh x = \frac{e^x + e^{-x}}{2}$, $\tanh x = \frac{e^x - e^{-x}}{e^x + e^{-x}}$

$\rightarrow e^x = \cosh x + \sinh x$; $e^{-x} = \cosh x - \sinh x$

$\rightarrow \sinh(-x) = -\sinh x$, $\cosh(-x) = \cosh x$; $\tanh(-x) = -\tanh x$

$\rightarrow \cosh^2 x - \sinh^2 x = 1$;

$\operatorname{sech}^2 x + \tanh^2 x = 1$;

$\coth^2 x - \operatorname{cosech}^2 x = 1$.

$\rightarrow \sinh x = 2 \sinh \frac{x}{2} \cosh \frac{x}{2}$

$\cosh x = \cosh^2 \frac{x}{2} + \sinh^2 \frac{x}{2} = 2 \cosh^2 \frac{x}{2} - 1 = 2 \sinh^2 \frac{x}{2} + 1$

$\tanh x = \frac{2 \tanh \frac{x}{2}}{1 + \tanh^2 \frac{x}{2}}$

$\rightarrow \sinh 2x = 2 \sinh x \cosh x$

$\cosh 2x = 2 \cosh^2 x - 1$

$\tanh 2x = \frac{2 \tanh x}{1 + \tanh^2 x}$

x	$-\infty$	0	∞
$\sinh x$	$-\infty$	0	∞
$\cosh x$	∞	1	∞
$\tanh x$	-1	0	1

$\rightarrow \sinh x \xrightarrow{D} \cosh x$

$\cosh x \xrightarrow{D} \sinh x$

$\tanh x \xrightarrow{D} \operatorname{sech}^2 x$

$\rightarrow \cosh x + \sinh x = e^x$

⊕ Inverse hyperbolic function.

i) $\sinh^{-1} x = \log(x + \sqrt{x^2 + 1}) \rightarrow \int \frac{dx}{\sqrt{x^2 + a^2}} = \sinh^{-1}\left(\frac{x}{a}\right).$

ii) $\cosh^{-1} x = \log(x + \sqrt{x^2 - 1}) \rightarrow \int \frac{dx}{\sqrt{x^2 - a^2}} = \cosh^{-1}\left(\frac{x}{a}\right).$

iii) $\tanh^{-1} x = \frac{1}{2} \log\left(\frac{1+x}{1-x}\right) \rightarrow \int \frac{dx}{a^2 - x^2} = \frac{1}{a} \tanh^{-1}\left(\frac{x}{a}\right).$

⊕ $\int \frac{dx}{\sqrt{x^2 + a^2}} = \sinh^{-1}\left(\frac{x}{a}\right) ; \int \frac{dx}{\sqrt{x^2 - a^2}} = \cosh^{-1}\left(\frac{x}{a}\right) ; \int \frac{dx}{a^2 - x^2} = \frac{1}{a} \tanh^{-1}\left(\frac{x}{a}\right).$

⊕ Separation of Real & Imaginary.

1) $\sin(x+iy) = \sin x \cosh y + i \cos x \sinh y.$

2) $\cos(x+iy) = \cos x \cosh y - i \sin x \sinh y.$

3) $\tan(x+iy) = \frac{\sin 2x}{\cos 2x + \cosh 2y} + \frac{i \sinh 2y}{\cos 2x + \cosh 2y}.$

4) $\sinh(x+iy) = \sinh x \cos y + i \cosh x \sin y.$

5) $\cosh(x+iy) = \cosh x \cos y + i \sinh x \sin y.$

6) $\tanh(x+iy) = \frac{\sinh 2x}{\cosh 2x + \cos 2y} + \frac{i \sin 2y}{\cosh 2x + \cos 2y}.$

$\rightarrow \tan(\alpha + i\beta) = x + iy ; \tan(\alpha - i\beta) = x - iy$

$\Rightarrow \tan 2\alpha = \frac{2x}{1 - (x^2 + y^2)} = \tan[(\alpha + i\beta) + (\alpha - i\beta)]$

⊕ Logarithm of Complex Numbers.

$x + iy = r e^{i\theta} ; r = \sqrt{x^2 + y^2}, \theta = \tan^{-1}\left(\frac{y}{x}\right).$

* $\log(x + iy) = \log r + i\theta = \frac{1}{2} \log(x^2 + y^2) + i \tan^{-1}\left(\frac{y}{x}\right)$
 $= \log r + i(2\alpha + \theta).$

Module-2 (Differential Calculus).

⊕ Derivative of n^{th} order.

1) $y = (ax+b)^m$

$$y_n = (m)(m-1)(m-2) \dots (m-n+1) a^n (ax+b)^{m-n} ; \quad n < m$$

$$= m! a^n ; \quad n = m$$

$$= 0 ; \quad n > m$$

i) $y = \frac{1}{ax+b} ; y_n = \frac{(-1)^n n! a^n}{(ax+b)^{n+1}}$ ii) $y = \frac{1}{x+b} ; y_n = \frac{(-1)^n n!}{(x+b)^{n+1}}$

2) $y = \log(ax+b) ; y_n = \frac{(-1)^{n-1} (n-1)! a^n}{(ax+b)^n}$

3) $y = a^{mx} ; y_n = m^n a^{mx} (\log a)^n$, $y = e^{mx} ; y_n = m^n e^{mx}$

4) $y = \sin(ax+b) ; y_n = a^n \sin(ax+b + \frac{n\pi}{2})$

$y = \cos(ax+b) ; y_n = a^n \cos(ax+b + \frac{n\pi}{2})$

5) $y = e^{ax} \sin(bx+c) ; y_n = (a^2+b^2)^{\frac{n}{2}} e^{ax} \sin(bx+c + n \tan^{-1}(\frac{b}{a}))$

$y = e^{ax} \cos(bx+c) ; y_n = (a^2+b^2)^{\frac{n}{2}} e^{ax} \cos(bx+c + n \tan^{-1}(\frac{b}{a}))$

⊕ Leibnitz's theorem (Convert in terms of y).

if $y = uv ;$

$$\Rightarrow y_n = {}^nC_0 u_n v + {}^nC_1 u_{n-1} v_1 + {}^nC_2 u_{n-2} v_2 + \dots + {}^nC_n u v_n$$

$$\Rightarrow y_n = u_n v + n u_{n-1} v_1 + \frac{n(n-1)}{2!} u_{n-2} v_2 + \frac{n(n-1)(n-2)}{3!} u_{n-3} v_3 + \dots$$

⊕ Maclaurin's Series.

$$f(x) = f(0) + x f'(0) + \frac{x^2}{2!} f''(0) + \frac{x^3}{3!} f'''(0) + \dots + \frac{x^n}{n!} f^{(n)}(0) + \dots$$

* Expansion

i) $e^x = 1 + x + \frac{x^2}{2!} + \dots$

ii) $e^{-x} = 1 - x + \frac{x^2}{2!} - \dots$

iii) $\sin x = x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots ; \sinh x = x + \frac{x^3}{3!} + \frac{x^5}{5!} + \dots$

iv) $\cos x = 1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots ; \cosh x = 1 + \frac{x^2}{2!} + \frac{x^4}{4!} + \dots$

v) $\tan x = x + \frac{x^3}{3} + \frac{2x^5}{15} + \dots ; \tanh x = x - \frac{x^3}{3} + \frac{2x^5}{15} - \dots$

vi) $\log(1+x) = x - \frac{x^2}{2!} + \frac{x^3}{3!} - \frac{x^4}{4!} + \dots$

$\log(1-x) = -x - \frac{x^2}{2!} - \frac{x^3}{3!} - \frac{x^4}{4!} - \dots$

vii) $(1+x)^m = 1 + mx + \frac{m(m-1)}{2!} x^2 + \frac{m(m-1)(m-2)}{3!} x^3 + \dots$

* Method of differentiation & Integration.

↳ used for expansion.

viii) $\tanh^{-1} x = x + \frac{x^3}{3} + \frac{x^5}{5} + \dots$

⊕ Taylor Series \Rightarrow Expand in powers of $(x-a)$.

$$f(x+h) = f(x) + hf'(x) + \frac{h^2}{2!} f''(x) + \dots + \frac{h^n}{n!} f^{(n)}(x) + \dots$$

$$f(x) = f(a) + (x-a)f'(a) + \frac{(x-a)^2}{2!} f''(a) + \dots + \frac{(x-a)^n}{n!} f^{(n)}(a) + \dots$$

* Rolle's Theorem $f(x)$

i) C in $[a, b]$, ii) D in (a, b) , iii) $f(a) = f(b)$

then there exists at least one C such that $f'(C) = 0$

* LMVT $f(x)$

i) C in $[a, b]$, ii) D in (a, b) , ~~iii~~

then there exist a C such that $f'(C) = \frac{f(b) - f(a)}{b - a}$

* CMVT $f(x)$ & $g(x)$

i) C in $[a, b]$ ii) D in (a, b)

$$\text{then } \frac{f'(C)}{g'(C)} = \frac{f(b) - f(a)}{g(b) - g(a)}$$

⊕ Infinite Series

* limit is finite \Rightarrow Convergent

limit is infinite \Rightarrow divergent

limit does not ~~unique~~ \Rightarrow oscillatory.

* P-test

$$\sum_{n=1}^{\infty} \frac{1}{n^p}$$

$p > 1 \Rightarrow$ convergent.

$p \leq 1 \Rightarrow$ divergent.

* Comparison test

if $\sum u_n$ & $\sum v_n$ are series of +ve terms.

$$\Rightarrow \lim_{n \rightarrow \infty} \left(\frac{u_n}{v_n} \right) = l \text{ (finite \& non-zero)}$$

$\Rightarrow u_n$ & v_n both converge/diverge.

* D'Alembert's Ratio test.

$$\lim_{n \rightarrow \infty} \frac{u_{n+1}}{u_n} = l$$

$\sum u_n$ is +ve series.

i) $\sum u_n$ is convergent if $l < 1$

ii) $\sum u_n$ is divergent if $l > 1$.

iii) Ratio test fails if $l = 1$.

Module-3 (Partial Differentiation).

$$\frac{\partial(\frac{\partial z}{\partial y})}{\partial y} = \frac{\partial^2 z}{\partial y^2} \quad \& \quad \frac{\partial}{\partial y}(\frac{\partial z}{\partial x}) = \frac{\partial^2 z}{\partial y \partial x} \quad \& \quad \frac{\partial}{\partial x}(\frac{\partial z}{\partial y}) = \frac{\partial^2 z}{\partial x \partial y}$$

$$(\frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial z})^2 u = (\frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial z})(\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} + \frac{\partial u}{\partial z})$$

→ Commutative property.

$$\Rightarrow \frac{\partial^2 z}{\partial y \partial x} = \frac{\partial^2 z}{\partial x \partial y} \Rightarrow \frac{\partial}{\partial y}(\frac{\partial z}{\partial x}) = \frac{\partial}{\partial x}(\frac{\partial z}{\partial y})$$

→ $(\frac{\partial u}{\partial x})_y$ → keep y (constant).

* Chain rule.

$$\Rightarrow \frac{\partial z}{\partial x} = \frac{\partial z}{\partial t} \cdot \frac{\partial t}{\partial x} ; \quad \frac{\partial z}{\partial y} = \frac{\partial z}{\partial t} \cdot \frac{\partial t}{\partial y}$$

* Composite function (one Variable).

$$\Rightarrow u = f(x, y) ; \quad x = \phi(t) ; \quad y = \psi(t)$$

$$\ominus \frac{\partial u}{\partial t} = \frac{\partial u}{\partial x} \times \frac{\partial x}{\partial t} + \frac{\partial u}{\partial y} \times \frac{\partial y}{\partial t}$$

$$\Rightarrow u = f(x, y, z) ; \quad x = \phi(t) ; \quad y = \psi(t) ; \quad z = \delta(t)$$

$$\ominus \frac{\partial u}{\partial t} = \frac{\partial u}{\partial x} \times \frac{\partial x}{\partial t} + \frac{\partial u}{\partial y} \times \frac{\partial y}{\partial t} + \frac{\partial u}{\partial z} \times \frac{\partial z}{\partial t}$$

* Composite function (two Variable)

$$\Rightarrow z = f(x, y) ; \quad x = \phi(u, v) ; \quad y = \psi(u, v)$$

$$\ominus \frac{\partial z}{\partial u} = \frac{\partial z}{\partial x} \times \frac{\partial x}{\partial u} + \frac{\partial z}{\partial y} \times \frac{\partial y}{\partial u} \quad \& \quad \frac{\partial z}{\partial v} = \frac{\partial z}{\partial x} \times \frac{\partial x}{\partial v} + \frac{\partial z}{\partial y} \times \frac{\partial y}{\partial v}$$

* Implicit function.

$$\Rightarrow \text{if } f(x, y) = c$$

$$\ominus \frac{dy}{dx} = - \frac{f_x / f_y}{f_y / f_y}$$

* Euler's theorem [Homogeneous functions] (2 Variables)

$$u = f(x, y), \quad u = f(x, y) = t^n f(x, y) \quad \text{Hom.}$$

where, $x = xt, \quad y = yt$ & (n) is degree of ~~fun~~ function

$$\Rightarrow x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} = nu$$

* Euler's theorem [Homogeneous function] (3 variables)

$$u = f(x, y, z), \quad u = f(x, y, z) = t^n f(x, y, z)$$

where, $x = xt, \quad y = yt, \quad z = zt$ & (n) is degree of Hom. function

$$\Rightarrow x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} + z \frac{\partial u}{\partial z} = nu$$

→ Deductions from Euler's Theorem.

$$1) x^2 \frac{\partial^2 u}{\partial x^2} + 2xy \frac{\partial^2 u}{\partial x \partial y} + y^2 \frac{\partial^2 u}{\partial y^2} = n(n-1)u.$$

$$2) x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} = n \frac{f(u)}{f'(u)} \quad \left. \begin{array}{l} \\ \end{array} \right\} \rightarrow z = f(u) \text{ \& } z = f(x, y)$$

$$x \frac{\partial z}{\partial x} + y \frac{\partial z}{\partial y} = nz$$

Similarly

$$x \frac{\partial u}{\partial x} + y \frac{\partial u}{\partial y} + z \frac{\partial u}{\partial z} = n \frac{f(u)}{f'(u)} \quad \left. \begin{array}{l} \\ \end{array} \right\} \rightarrow p = f(u) \text{ \& } p = f(x, y, z)$$

$$x \frac{\partial p}{\partial x} + y \frac{\partial p}{\partial y} + z \frac{\partial p}{\partial z} = np$$

$$3) z = f(u), \quad g(u) = n \frac{f(u)}{f'(u)}$$

↳ degree(n).

$$\Rightarrow x^2 \frac{\partial^2 u}{\partial x^2} + 2xy \frac{\partial^2 u}{\partial x \partial y} + y^2 \frac{\partial^2 u}{\partial y^2} = g(u)[g'(u)-1].$$

* Errors & Approximation.

$$u = f(x, y, z) \Rightarrow \delta u = \frac{\partial u}{\partial x} \delta x + \frac{\partial u}{\partial y} \delta y + \frac{\partial u}{\partial z} \delta z.$$

∴ $\delta x \Rightarrow$ Absolute error.

$\frac{\delta x}{x} \Rightarrow$ Relative error.

$\frac{\delta x}{x} \times 100 \Rightarrow$ Percentage error.

$$\rightarrow \text{Approx}(x) = x + \delta x.$$

* Maxima & Minima ($f(x, y)$)

1) Solve $\frac{\partial f}{\partial x} = 0$ & $\frac{\partial f}{\partial y} = 0$ simultaneously for x & y .

2) obtain values, $r = \frac{\partial^2 f}{\partial x^2}$; $s = \frac{\partial^2 f}{\partial x \partial y}$; $t = \frac{\partial^2 f}{\partial y^2}$.

3) If i) $rt - s^2 > 0$ $\xrightarrow{s} r < 0$ (or $t < 0$) \Rightarrow Maximum.
 $\xrightarrow{s} r > 0$ (or $t > 0$) \Rightarrow Minimum.

ii) $rt - s^2 < 0 \Rightarrow$ Neither maximum nor minimum.
 i.e saddle point.

iii) $rt - s^2 = 0 \Rightarrow$ failure point (No conclusion).

* Lagrange's method of Undetermined Multipliers.
 $\rightarrow \phi(x, y, z) = 0$ ① \rightarrow condition for $f(x, y, z)$ [stationary]
 [Maximum & Minimum]

$\rightarrow F(x, y, z) = f(x, y, z) + \lambda \phi(x, y, z)$

② $\rightarrow \frac{\partial F}{\partial x} = \frac{\partial f}{\partial x} + \lambda \frac{\partial \phi}{\partial x}$; ③ $\frac{\partial F}{\partial y} = \frac{\partial f}{\partial y} + \lambda \frac{\partial \phi}{\partial y}$; ④ $\frac{\partial F}{\partial z} = \frac{\partial f}{\partial z} + \lambda \frac{\partial \phi}{\partial z}$

\rightarrow find λ using ①, ②, ③, ④.

Module-4 (Matrices & Vectors).

\rightarrow diagonal matrix \Rightarrow All non-diagonal $= 0$

\rightarrow Trace = Sum of Principal diagonal elements.

\rightarrow Transpose \Rightarrow Interchange row by col & col by row.

\rightarrow Symmetric matrix $\Rightarrow a_{ij} = a_{ji} \Rightarrow A = A^T$

\rightarrow Skew Symmetric matrix $\Rightarrow a_{ij} = -a_{ji}$; $a_{ii} = 0 \Rightarrow A = -A^T$

\rightarrow Transposed Conjugate $\Rightarrow A^0 = \overline{A^T}$

\rightarrow Hermitian matrix $\Rightarrow A = A^0$ ($a_{ij} = \overline{a_{ji}}$)

\rightarrow Skew Hermitian matrix $\Rightarrow A = -A^0$ ($a_{ij} = -\overline{a_{ji}}$) &
 diagonal elements are either ~~purely real~~ purely imaginary or zero

\rightarrow Orthogonal matrix

i) for real matrix $\Rightarrow A_1^T A_2 = A_1 A_2^T = 0$

ii) for ~~the~~ complex matrix $\Rightarrow A_1^0 A_2 = A_1 A_2^0 = 0$

\rightarrow Unitary matrix $\Rightarrow A A^0 = I$

\rightarrow Singular $\Rightarrow |A| = 0$ &

Non-singular $\Rightarrow |A| \neq 0$.

\rightarrow Minor $\Rightarrow A_{11} = \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix}$ & Cofactor $\Rightarrow a_{11} = (-1)^{1+1} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix}$

\rightarrow Adjoint is transpose of Cofactors ($\text{Adj } A$).

\rightarrow Inverse $\Rightarrow A^{-1} = \frac{1}{|A|} \text{Adj } A$ & $A A^{-1} = I_n$.

\rightarrow Solution of non homogeneous by inverse.

$\Rightarrow AX = B \Rightarrow X = A^{-1}B$.

\rightarrow Equivalence $\Rightarrow A \sim B$

if B is obtained by elementary transformation of A .

② $A = I_n A$ ④ $\Rightarrow I_n = B A \Rightarrow B = A^{-1}$
 Reduce from row echelon $\Rightarrow I_n = A^{-1} A$

* Rank of A Matrix (if $\rho(A) = r$)

→ at least one minor of order (r) which is non-zero.

→ Every minor of order greater than r is zero.

i) Row-echelon form [Upper triangular matrix]

⇒ $\rho(A)$ = No. of Non zero rows in row echelon form

ii) Reduced normal form / Canonical form.

Conversion of matrix $A = \begin{bmatrix} I_r & 0 \\ 0 & 0 \end{bmatrix} \Rightarrow \rho(A) = r$

iii) PAQ form

⇒ if A is matrix of order $m \times n$

$$\Rightarrow [A] = PAQ = [I_m]A[I_n] \quad (\because P = I_m \text{ \& } Q = I_n)$$

$\& [A^{-1} = Q \cdot P]$

* Non homogeneous linear Equations ($AX=B$)

$[A|B] = [A:B] = [A : B] \rightarrow$ Augmented matrix.

a) consistent $\rho(A) = \rho(A:B) \Rightarrow$ One or more solution

i) If $\rho(A) = \rho(A:B) = n \Rightarrow$ Unique solutions.

ii) If $\rho(A) = \rho(A:B) < n \Rightarrow$ Infinite solutions.

b) Inconsistent $\rho(A) \neq \rho(A:B) \Rightarrow$ No solution

* homogeneous linear equations ($AX=0$)

↳ System is consistent when eqⁿ are homogeneous.

a) Non trivial (Non-zero solⁿ) $\Rightarrow \rho(A) < n$ \& $|A| = 0$

b) Trivial (All zero) $\Rightarrow (x_1 = x_2 = \dots = x_n = 0) \Rightarrow \rho(A) = n$ \& $|A| \neq 0$

* linear dependence \& Independence of Vectors.

~~Let~~ $x_1, x_2, x_3, \dots, x_r \Rightarrow$ Set of r Vectors.

$k_1, k_2, k_3, \dots, k_r \Rightarrow$ Set of r scalars.

Such that $k_1x_1 + k_2x_2 + k_3x_3 + \dots + k_rx_r = 0$ \rightarrow solve like non-homogeneous

a) linear dependence if $k_1, k_2, k_3, \dots, k_r$ are not all zero.
($\rho(A) < n$ \& $|A| = 0$)

b) linearly independence if $k_1 = k_2 = k_3 = \dots = k_r = 0$
($\rho(A) = n$ \& $|A| \neq 0$)

* for dependent vectors

No. of parameters = No. of Unknowns - Rank of Coefficient Matrix
(n) ($\rho(A)$)