# Face Anonymization

14 Kushal Shah

16 Nazish Shaikh

17 Sidra Shaikh

50 Atharva Tayade

53 Pratik Thorave

## Steps

- Face Detection
- Facial landmarks detection
- Finding face border
- Approximating nonlinear operations
- Finding triangles for image transformation
- Blending images together
- Video Stabilization

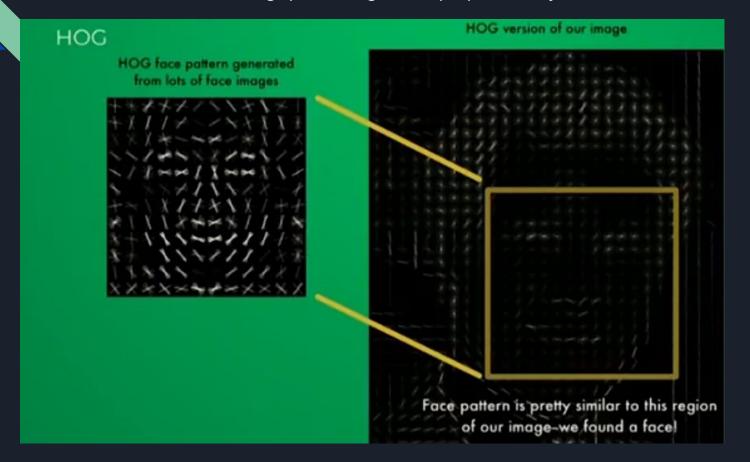
## What is Face Anonymization?

Anonymize: remove identifying particulars or details from something for certain purposes.

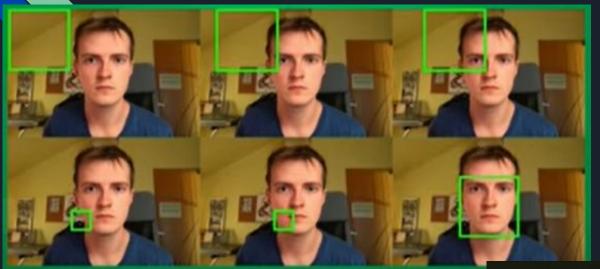
Face anonymization refers to anonymizing faces to keep identity of the person's face confidential.

HOG

The Histogram of Oriented Gradients(HOG) is a feature descriptor used in computer vision and image processing for the purpose of object detection.



### 1. Face Detection:



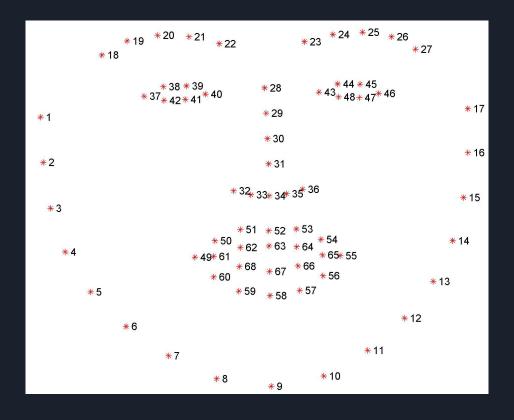
```
import cv2
import dlib

detector = dlib.get_frontal_face_detector()

img = cv2.imread('image.jpg')

rectangles = detector(img)
```

### 2. Face Landmarks Detection



- dlib Library
- 68 facial landmarks

#### Face Landmarks Detection

#### One millisecond Face Alignment



```
import cv2
import dlib

detector = dlib.get_frontal_face_detector()
predictor = dlib.shape_predictor("shape_predictor_68_face_landmarks.dat")

img = cv2.imread('image.jpg')

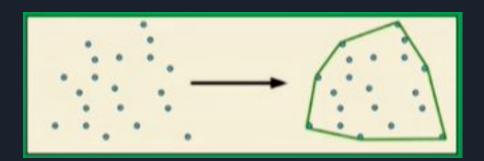
rectangles = detector(img)

face = max(rectangles, key=lambda r: r.area())
landmarks = predictor(img, face)
```

## 3. Find face border

Convex hull

Convex hull vs Contour







### Face Border

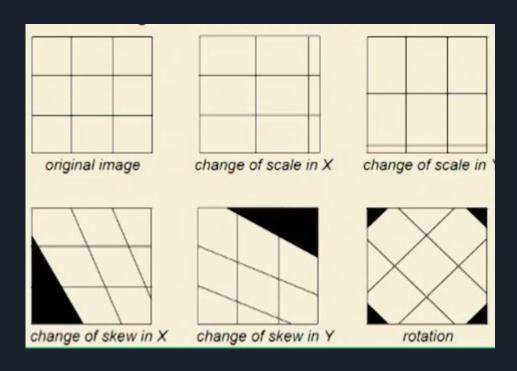
#### Convex hull

```
---
landmarks = predictor(img, face)

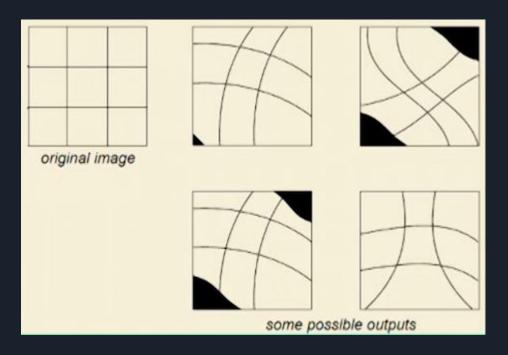
points = [(p.x, p.y) for p in landmarks.parts()]

hull = cv2.convexHull(np.array(points), returnPoints=False)
```

# Approximating non-linear operations with linear ones - Affine Transformation







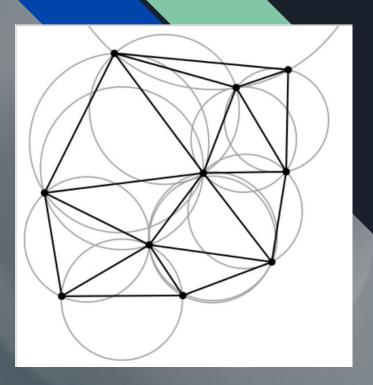
# Approximating non-linear operations with linear ones

There is no such operation in OpenCV. So to implement -

#### Steps:

- 1. Get coordinates of input triangle and output triangle.
- 2. Find bounding rectangles around those triangles with cv2.boundingRect().
- 3. Crop out these bounding rectangles out of the image.
- 4. Create a mask with 1.0 inside triangle, and 0.0 outside.
- 5. getAffineTransform() returns matrix of how to transform from triangle 1 to triangle 2
- 6. warpAffine() uses this matrix to transform bounding rect 1 to bounding rect 2
- 7. Multiply output of warpAffine with mask (inside triangle (1.0) stays, outside (0.0) is out)
- 8. Put the warped fragment back into image.

## 4. Finding Triangles



Find Delaunay Triangulation on first image

Find corresponding triangles on second image

Transform every triangle from first image to second image

```
mouth_points = [[60], [61], [62], [63], [64], [65], [66], [67]]
hull = np.concatenate([hull, mouth_points_indexes])

rect = (0, 0, img.shape[1], img.shape[0])
subdiv = cv2.Subdiv2D(rect)
subdiv.insert(hull)

triangles = subdiv.getTriangleList()
```



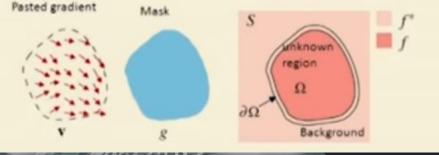


### 5. Blending two images

### Seamless Poisson cloning

· Given vector field v (pasted gradient), find the

$$\min_{f} \iint_{\Omega} |\nabla f - \mathbf{v}|^2 \text{ with } f|_{\partial\Omega} = f^*|_{\partial\Omega}$$
 optimize:



In this method, we don't copy the values of pixels, just copy the gradient.

```
dest = cv2.imread("image1.jpg")
source = cv2.imread("image2.jpg")
mask = np.zeros(source.shape[:2], dtype=np.float32)
rect = [(23, 25), (55, 112)]
mask = np.uint8(cv2.rectangle(mask, *rect, (1.0, 1.0, 1.0), -1) * 255)
center = 641, 395
cloned = cv2.seamlessClone(source, dest, mask, center,
cv2.MIXED CLONE)
```

### 6. Stabilization

• Stability is one of the most important part.

To avoid this shakiness Optical Flow with Lucas-Kanade Method is used.

Equation:-

(u,v) = (dx/dt, dy/dt)

### Assumptions:-

- 1) Brightness Constancy Assumptions.
- 2) Additional Assumption:- Lucas-Kanade Method.

Eg:-



## Code for Optical Flow:-

```
hull_next, * = cv2.calcOpticalFlowPyrLK(img_gray_prev, img_gray, hull_prev, hull)
```

# THANK YOU