l				
G. H. Raisoni College Of Engineering And Management, Wagholi Pune				
<u>2021- 2022</u>				
Assignment no :- 10				
Department	CE [SUMMER 2022 (Online)]			
Term / Section	III/B	Date O	f submission	<u>13-12-2021</u>
Subject Name /Code	Data Structures and Algorithms/ UCSL201/UCSP201			
Roll No.	SCOB77	Name	Pratham Rajkumar pitty	
Registration Number	2020AC0E1100107			

Experiment No 10.



Aim: you have abosiness with several offices

you want to lease phone lines to connect them up

with each other: and the phone company charges

different amounts of money to configer different

pairs of cities you want a set of lines that

connects all your offices with a minimum

total cost. Solve the problem by suggesting

appropriate data Structures

Theory:

poins algorithm to find Minimum rost
Spunning tree (as kruskal's algorithm) uses the
greedy approach. Prim's algorithm strakes a
Similarity with the Shortest Path first algorithms

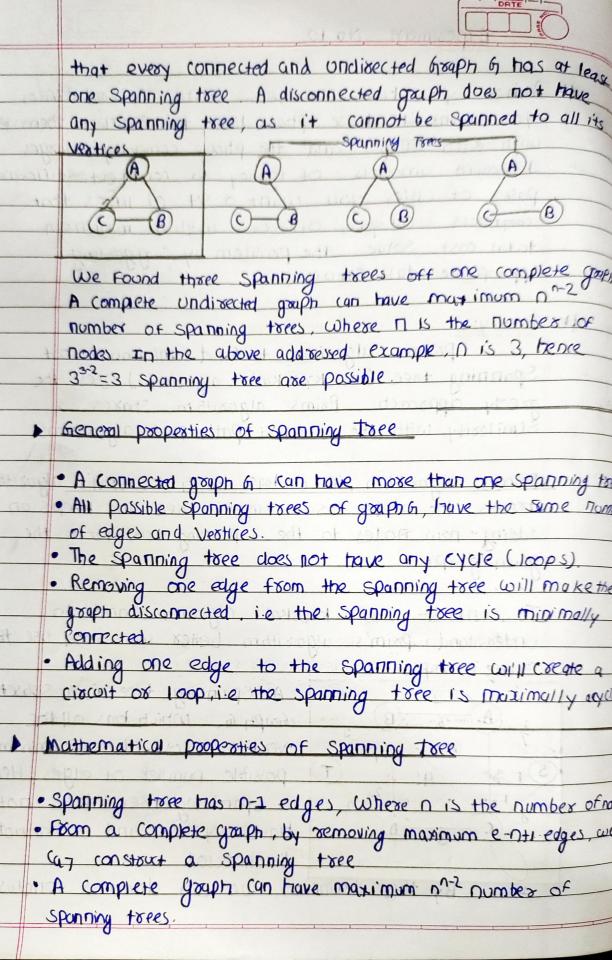
Prim's algorithm, in contrast with knuskais algorithm, treats the nodes as a single tree and keeps on adding new nodes to the spanning tree from the given graph.

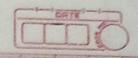
To contrast with knuskal's algorithm and to understand prim's algorithm better, we shall use the sume example.

A 6 B 5 T T 2 2 2

A Spanning tree is a subset of health by, which tras all the vertices covered with minimum possible number of edges. Hence, a spanning tree does not have cycles and it cannot be disconnected.

By this definition, we can drow a conclusion





Application of Spanning Tree

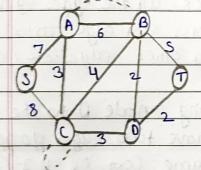
- · Civil Network Planning
 · Computer Network Routing protocol
- · Clustex Amplysis

Minimum spanning tree (MST)

In a weighted graph, a minimum spanning tree is a spanning tree that that minimum weight that all other Spanning trees of the Sume graph. In real-world situations, this weight can be measured as distance (ongestion traffic load or any arbitrary value.

MST Algorithm : + Kruskal's Algorithm · prim's Alyorithm

Steps:> Remove all loops and possible edges



Remove all loops and parallel edges from the given graph. In case of populled edges, keep the one which has the least cost associated and remove all others

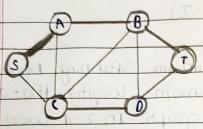
step 2: -> Choose any appitatory In this case, we chose snade as the root node of prim's spanning tree This node is arbitrarily chosen, so any node can be

the root node one may wonder why any video can be a root node so the answer is, in the spanning tree all the



modes of agraph are included and because it is connected then there must be at least one edge which will Join it to the rest of the tree.

Step 3- check outgoing edges and select the one with the



After Choosing the root node & we see that S. A. and S.C. are two Deages with weight 7 and 8, respectively we choose the edge S. A. as it is lesser than the other.

7 6 6

Now the tree S-7-A is treated as one node and we theck for all edges your out from it we select the one which has lowest cost and include it in the tree

After this Step, S-7-A-3-0 tree is formed now well again treat it as anode and will check all the edges again.

However, we will those only the least (Ost edge Inthis case we is the new edge which is less than other edges cost 8,6,0 etc.

33

Three, we now have two edges going out of it having the Sume cost, i.e D-2-T and D-2-B. Thus, we add either one But the

next Step will again yield 2 as the leave cost Hence we are showing a spanning tree with both edges included.

MST=7+3+3+2+2

MST = 17

Program code:-

```
#include <iostream>
#include <iomanip>
using namespace std;
const int MAX = 10;
class EdgeList; // forward declaration
class Edge // USED IN KRUSKAL
{
  int u, v, w;
public:
  Edge() {} // Empty Constructor
  Edge(int a, int b, int weight)
  {
    u = a;
    v = b;
    w = weight;
  }
  friend class EdgeList;
  friend class PhoneGraph;
};
//---- EdgeList Class ------
class EdgeList
{
  Edge data[MAX];
  int n;
public:
  friend class PhoneGraph;
```

```
EdgeList()
  {
    n = 0;
  }
  void sort();
  void print();
};
//----Bubble Sort for sorting edges in increasing weights' order ---//
void EdgeList::sort()
{
  Edge temp;
  for (int i = 1; i < n; i++)
    for (int j = 0; j < n - 1; j++)
       if (data[j].w > data[j + 1].w)
       {
         temp = data[j];
         data[j] = data[j + 1];
         data[j + 1] = temp;
      }
}
void EdgeList::print()
{
  int cost = 0;
  for (int i = 0; i < n; i++)
  {
    cout << "\n"
       << i + 1 << " " << data[i].v << " = " << data[i].w;
    cost = cost + data[i].w;
  }
  cout << "\nMinimum cost of Telephone Graph = " << cost;</pre>
}
```

```
//----- Phone Graph Class-----
class PhoneGraph
{
  int data[MAX][MAX];
  int n;
public:
  PhoneGraph(int num)
  {
    n = num;
  }
  void readgraph();
  void printGraph();
  int mincost(int cost[], bool visited[]);
  int prim();
  void kruskal(EdgeList &spanlist);
  int find(int belongs[], int vertexno);
  void unionComp(int belongs[], int c1, int c2);
};
void PhoneGraph::readgraph()
{
  cout << "Enter Adjacency(Cost) Matrix : \n";</pre>
  for (int i = 0; i < n; i++)
  {
    for (int j = 0; j < n; j++)
      cin >> data[i][j];
  }
}
void PhoneGraph::printGraph()
{
  cout << "\nAdjacency (COST) Matrix : \n";</pre>
```

```
for (int i = 0; i < n; i++)
  {
    for (int j = 0; j < n; j++)
    {
       cout << setw(3) << data[i][j];
    }
    cout << endl;
  }
}
int PhoneGraph::mincost(int cost[], bool visited[]) // finding vertex with minimum cost
{
  int min = 9999, min_index; // initialize min to MAX value(ANY) as temporary
  for (int i = 0; i < n; i++)
  {
    if (visited[i] == 0 \&\& cost[i] < min)
    {
       min = cost[i];
       min_index = i;
    }
  }
  return min_index; // return index of vertex which is not visited and having minimum cost
}
int PhoneGraph::prim()
{
  bool visited[MAX];
  int parents[MAX];
  int cost[MAX]; // saving minimum cost
  for (int i = 0; i < n; i++)
  {
    cost[i] = 9999; // set cost as infinity/MAX_VALUE
    visited[i] = 0; // initialize visited array to false
```

```
}
  cost[0] = 0; // starting vertex cost
  parents[0] = -1; // make first vertex as a root
  for (int i = 0; i < n - 1; i++)
  {
    int k = mincost(cost, visited);
    visited[k] = 1;
    for (int j = 0; j < n; j++)
    {
       if (data[k][j] \&\& visited[j] == 0 \&\& data[k][j] < cost[j])
       {
         parents[j] = k;
         cost[j] = data[k][j];
       }
    }
  }
  cout << "Minimum Cost Telephone Map : \n";</pre>
  for (int i = 1; i < n; i++)
  {
    cout << i << " -- " << parents[i] << " = " << cost[i] << endl;
  }
  int mincost = 0;
  for (int i = 1; i < n; i++)
    mincost += cost[i]; // data[i][parents[i]];
  return mincost;
//----- Kruskal's Algorithm
void PhoneGraph::kruskal(EdgeList &spanlist)
  int belongs[MAX]; // Separate Components at start (No Edges, Only vertices)
```

}

{

```
int cno1, cno2; // Component 1 & 2
  EdgeList elist;
  for (int i = 1; i < n; i++)
    for (int j = 0; j < i; j++)
    {
       if (data[i][j] != 0)
       {
         elist.data[elist.n] = Edge(i, j, data[i][j]); // constructor for initializing edge
         elist.n++;
       }
    }
  elist.sort(); // sorting in increasing weight order
  for (int i = 0; i < n; i++)
     belongs[i] = i;
  for (int i = 0; i < elist.n; i++)
  {
    cno1 = find(belongs, elist.data[i].u); // find set of u
    cno2 = find(belongs, elist.data[i].v); ///find set of v
    if (cno1 != cno2)
                                 // if u & v belongs to different sets
    {
       spanlist.data[spanlist.n] = elist.data[i]; // ADD Edge to spanlist
       spanlist.n = spanlist.n + 1;
       unionComp(belongs, cno1, cno2); // ADD both components to same set
    }
  }
void PhoneGraph::unionComp(int belongs[], int c1, int c2)
{
  for (int i = 0; i < n; i++)
  {
```

}

```
if (belongs[i] == c2)
      belongs[i] = c1;
  }
}
int PhoneGraph::find(int belongs[], int vertexno)
{
  return belongs[vertexno];
}
//----- MAIN PROGRAM-----
int main()
{
  cout << "\n\n SCOB77_Pratham_Pitty_Assignment_no_10 \n\n";</pre>
  int vertices, choice;
  EdgeList spantree;
  cout << "Enter Number of cities : ";</pre>
  cin >> vertices;
  PhoneGraph p1(vertices);
  p1.readgraph();
  do
  {
    cout << "\n1.Find Minimum Total Cost(By Prim's Algorithm)"</pre>
       << "\n2.Find Minimum Total Cost(by Kruskal's Algorithms)"
       << "\n3.Re-Read Graph(INPUT)"
       << "\n4.Print Graph"
       << "\n0. Exit"
       << "\nEnter your choice: ";
    cin >> choice;
    switch (choice)
    {
```

```
case 1:
      cout << " Minimum cost of Phone Line to cities is : " << p1.prim();</pre>
       break;
    case 2:
       p1.kruskal(spantree);
       spantree.print();
       break;
    case 3:
      p1.readgraph();
       break;
    case 4:
      p1.printGraph();
       break;
    default:
      cout << "\nWrong Choice!!!";</pre>
    }
  } while (choice != 0);
  return 0;
}
```

Output:-

