

# Quantitative Management Assignment 04

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```
#install.packages("lpSolve")  
library("lpSolve") #Activating the lpSolve Package
```

Further going down in order to solve the problem we need to define the objective, constraints, direction and constants

Objective Function

The Objective function  $Max \quad Z = 420(X_1L + X_2L + x_3L) + 360(X_1M + X_2M + X_3M) + 300(X_1S + X_2S + X_3S)$

Subject to the following constraints

$$\begin{aligned}X_1L + X_1M + X_1S &\leq 750 \\X_2L + X_2M + X_2S &\leq 900 \\X_3L + X_3M + X_3S &\leq 450 \\20X_1L + 15X_1M + 12X_1S &\leq 13000 \\20X_2L + 15X_2M + 12X_2S &\leq 12000 \\20X_3L + 15X_3M + 12X_3S &\leq 5000 \\X_1L + X_2L + X_3L &\leq 900 \\X_1M + X_2M + X_3M &\leq 1200 \\X_1S + X_2S + X_3S &\leq 750\end{aligned}$$

Non Negativity Constraints

$$X_1L, X_2L, X_3L, X_1M, X_2M, X_3M, X_1S, X_2S, X_3S \geq 0$$

constraints

$$\begin{aligned}X_1L + X_1M + X_1S + 0X_2L + 0X_2M + 0X_2S + 0X_3L + 0X_3M + 0X_3S &\leq 750 \\0X_1L + 0X_1M + 0X_1S + X_2L + X_2M + X_2S + 0X_3 + 0X_3M + 0X_3S &\leq 900 \\0X_1L + 0X_1M + 0X_1S + 0X_2L + 0X_2M + 0X_2S + X_3L + X_3M + X_3S &\leq 450 \\20X_1L + 15X_1M + 12X_1S + 0X_2L + 0X_2M + 0X_2S + 0X_3L + 0X_3M + 0X_3S &\leq 13000 \\0X_1L + 0X_1M + 0X_1S + 20X_2L + 15X_2M + 12X_2S + 0X_3L + 0X_3M + 0X_3S &\leq 12000 \\0X_1L + 0X_1M + 0X_1S + 0X_2L + 0X_2M + 0X_2S + 20X_3L + 15X_3M + 12X_3S &\leq 5000 \\X_1L + 0X_1M + 0X_1S + X_2L + 0X_2M + 0X_2S + X_3L + 0X_3M + 0X_3S &\leq 900 \\0X_1L + X_1M + 0X_1S + 0X_2L + X_2M + 0X_2S + 0M_3L + X_3M + 0X_3S &\leq 1200 \\0X_1L + 0X_1M + X_1S + 0X_2L + 0X_2M + X_2S + 0X_3L + 0X_3M + X_3S &\leq 750\end{aligned}$$

Objective Function - f.obj

```
f.obj <- c(420,360,300,420,360,300,420,360,300)
```

Defining Constraints - f.con

```
f.con <- matrix(c(1,1,1,0,0,0,0,0,0,
                 0,0,0,1,1,1,0,0,0,
                 0,0,0,0,0,0,1,1,1,
                 20,15,12,0,0,0,0,0,0,
                 0,0,0,20,15,12,0,0,0,
                 0,0,0,0,0,0,20,15,12,
                 1,0,0,1,0,0,1,0,0,
                 0,1,0,0,1,0,0,1,0,
                 0,0,1,0,0,1,0,0,1), nrow = 9, byrow=T)
```

Defining the Direction constraints - f.dir

```
f.dir <- c('<=',
          '<=',
          '<=',
          '<=',
          '<=',
          '<=',
          '<=',
          '<=',
          '<=')
```

constants of the right hand side - f.rhs

```
f.rhs <- c(750,900,450,13000,12000,5000,900,1200,750)
```

lp function to solve the problem the objective function to maximize

```
lp('max',f.obj,f.con,f.dir,f.rhs)
```

```
## Success: the objective function is 708000
```

the lp function to get the values of the variables

```
lp('max',f.obj,f.con,f.dir,f.rhs)$solution
```

```
## [1] 350.0000 400.0000  0.0000  0.0000 400.0000 500.0000  0.0000 133.3333
## [9] 250.0000
```