

Symbol	Values	Description
$r$	3	assumed constant
$\theta 1$	$60^\circ$	angle
$\theta 2$	$45^\circ$	angle
<b>A</b>	$\begin{pmatrix} 4.3 \\ 4.2 \end{pmatrix}$	point A
<b>B</b>	$\begin{pmatrix} 0 \\ 0 \end{pmatrix}$	point B
<b>C</b>	$\begin{pmatrix} 4 \\ 0 \end{pmatrix}$	point C
<b>D</b>	$\begin{pmatrix} 3 \\ 0 \end{pmatrix}$	point D
<b>E</b>	$\begin{pmatrix} 4.1 \\ 4 \end{pmatrix}$	point E