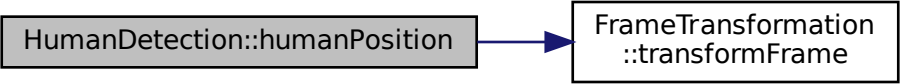


HumanDetection::humanPosition



```
graph LR; A[HumanDetection::humanPosition] --> B[FrameTransformation::transformFrame]
```

A diagram showing a call from the function `HumanDetection::humanPosition` to the function `FrameTransformation::transformFrame`. The first box is shaded gray and the second is white. A blue arrow points from the first box to the second.

FrameTransformation
::transformFrame