Real Time Bare Skinned Images Filtering Using CNN

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Introduction

Skin colour detection has been used in numerous computer vision applications like face detection, nudity recognition, hand gesture detection and person identification. Skin colour detection is a challenging task as the skin colour in an image is sensitive to various factors like illumination, camera characteristics, ethnicity, individual characteristics such as age, sex and body parts and other factors like makeup, hairstyle and glasses. All these factors affect appearance of skin colour. Another problem is that there is a significant overlap between the skin and non-skin pixels. However when these techniques are used in real-time, it is crucial to follow time deadlines and memory constraints. Sometimes, accuracy may need to be sacrificed when the skin detection strategy is used only as a preprocessing step to face detection, particularly in real time applications. In this study we have focused on the problem of developing an accurate and robust model for the human skin.

Objective

The model will offer child proof surfing on the internet without parent intervention. So that parents do not have to worry about their children coming across nude images at such an early age without knowing the actual meaning of it. That is it will monitor every page and filter all the images, hiding their details from the children and disabling their activation upon any click. Even if the people in the image is not completely nude, may it be just the upper or lower half of the person's body; the model will still blur that image once it reaches the minimum percentage of human pixel colour set by the classifier, thus ensuring guaranteed protection.

Neural Networks

Neural Networks is a machine learning algorithm, which is built on the principle of the organization and functioning of biological neural networks. Neural networks consist of individual units called neurons. Neurons are located in a series of groups — layers. Neurons in each layer are connected to neurons of the next layer. Data comes from the input layer to the output layer along these compounds. Each individual node performs a simple mathematical calculation. Then it transmits its data to all the nodes it is connected to.

Different types of neural network architecture are as follows:

- 1)Perceptrons
- 2)Convolutional Neural Networks
- 3) Recurrent Neural Networks
- 4)Long / Short Term Memory
- 5) Gated Recurrent Unit
- 6)Hopfield Network

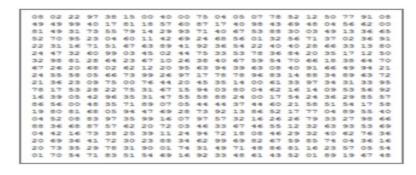
Why Convolution Neural Networks

Convolutional neural networks (CNN) is a special architecture of artificial neural networks, proposed by Yann LeCun in 1988. CNN uses some features of the visual cortex. One of the most popular uses of this architecture is image classification. For example Facebook uses CNN for automatic tagging algorithms, Amazon — for generating product recommendations and Google — for search through among users' photos. The main task of image classification is acceptance of the input image and the following definition of its class. This is a skill that people learn from their birth and are able to easily determine that the image in the picture is an elephant. But the computer sees the pictures quite differently:

What I see

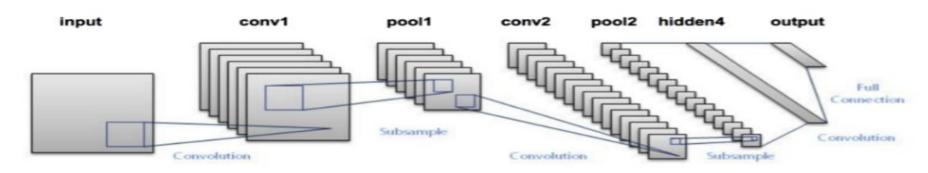


What a computer sees



Convolution Neural Network cont.....

Instead of the image, the computer sees an array of pixels. For example, if image size is 300 x 300. In this case, the size of the array will be 300x300x3. Where 300 is width, next 300 is height and 3 is RGB channel values. The computer is assigned a value from 0 to 255 to each of these numbers. This value describes the intensity of the pixel at each point. To solve this problem the computer looks for the characteristics of the base level. In human understanding such characteristics are for example the trunk or large ears. For the computer, these characteristics are boundaries or curvatures. And then through the groups of convolutional layers the computer constructs more abstract concepts. In more detail: the image is passed through a series of convolutional, nonlinear, pooling layers and fully connected layers, and then generates the output.



Output of Cat and Dog Tutorial with 4 Layers

```
Epoch 11/20
Epoch 12/20
Epoch 13/20
Epoch 14/20
Epoch 15/20
Epoch 16/20
Epoch 17/20
Epoch 18/20
Epoch 19/20
Epoch 20/20
>72.750
```

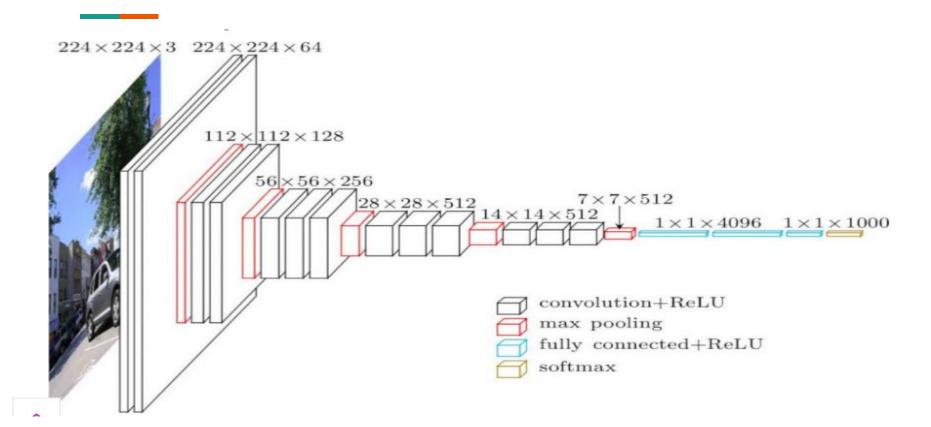
Using VGG16 model

```
Epoch 1/10
Epoch 2/10
Epoch 3/10
Epoch 4/10
Epoch 5/10
Epoch 6/10
Epoch 7/10
Epoch 8/10
Epoch 9/10
Epoch 10/10
>98.000
```

Predictions

```
content/drive/My Drive/major projects/cat and dog/test/dog.4024.jpg
content/drive/My Drive/major projects/cat and dog/test/cat.4134.jpg
content/drive/My Drive/major projects/cat and dog/test/dog.4025.jpg
content/drive/My Drive/major projects/cat and dog/test/cat.4183.jpg
content/drive/My Drive/major projects/cat and dog/test/dog.4166.jpg
content/drive/My Drive/major projects/cat and dog/test/cat.4138.jpg
content/drive/My Drive/major projects/cat and dog/test/cat.4040.jpg
content/drive/My Drive/major projects/cat and dog/test/cat.4162.jpg
content/drive/My Drive/major projects/cat and dog/test/dog.4102.jpg
content/drive/My Drive/major projects/cat and dog/test/dog.4134.jpg
content/drive/My Drive/major projects/cat and dog/test/cat.4014.jpg
content/drive/My Drive/major projects/cat and dog/test/dog.4014.jpg
content/drive/My Drive/major projects/cat and dog/test/dog.4033.jpg
```

VGG16 Architecture



VGG16

The input to cov1 layer is of fixed size 224 x 224 RGB image. The image is passed through a stack of convolutional (conv.) layers, where the filters were used with a very small receptive field: 3×3 (which is the smallest size to capture the notion of left/right, up/down, center). In one of the configurations, it also utilizes 1×1 convolution filters, which can be seen as a linear transformation of the input channels (followed by non-linearity). The convolution stride is fixed to 1 pixel; the spatial padding of conv. layer input is such that the spatial resolution is preserved after convolution, i.e. the padding is 1-pixel for 3×3 conv. layers. Spatial pooling is carried out by five max-pooling layers, which follow some of the conv. layers (not all the conv. layers are followed by max-pooling). Max-pooling is performed over a 2×2 pixel window, with stride 2. Three Fully-Connected (FC) layers follow a stack of convolutional layers (which has a different depth in different architectures): the first two have 4096 channels each, the third performs 1000-way ILSVRC classification and thus contains 1000channels (one for each class). The final layer is the soft-max layer. The configuration of the fully connected layers is the same in all networks.

VGG16 Layers

Model: "vgg16"		
Layer (type)	Output Shape	Param #
input_1 (InputLayer)	(None, 224, 224, 3)	9
block1_conv1 (Conv2D)	(None, 224, 224, 64)	1792
block1_conv2 (Conv2D)	(None, 224, 224, 64)	36928
block1_pool (MaxPooling2D)	(None, 112, 112, 64)	0
block2_conv1 (Conv2D)	(None, 112, 112, 128)	73856
block2_conv2 (Conv2D)	(None, 112, 112, 128)	147584
block2_pool (MaxPooling2D)	(None, 56, 56, 128)	0
block3_conv1 (Conv2D)	(None, 56, 56, 256)	295168
block3_conv2 (Conv2D)	(None, 56, 56, 256)	590080
block3_conv3 (Conv2D)	(None, 56, 56, 256)	590080
block3_pool (MaxPooling2D)	(None, 28, 28, 256)	0
block4_conv1 (Conv2D)	(None, 28, 28, 512)	1180160
block4_conv2 (Conv2D)	(None, 28, 28, 512)	2359808

VGG16 Layers

(None,	28, 28,	512)	2359808
(None,	14, 14,	512)	0
(None,	14, 14,	512)	2359808
(None,	14, 14,	512)	2359808
(None,	14, 14,	512)	2359808
(None,	7, 7, 5	12)	0
(None,	25088)		0
(None,	4096)		102764544
(None,	4096)		16781312
(None,	1000)		4097000
4	======		=======
	(None, (None, (None, (None, (None, (None, (None,	(None, 14, 14, (None, 14, 14, (None, 14, 14, (None, 14, 14, (None, 7, 7, 5) (None, 25088) (None, 4096) (None, 4096)	(None, 4096) (None, 4096) (None, 1000)

Bare Image Classification

```
Found 806 images belonging to 2 classes.
Found 200 images belonging to 2 classes.
Epoch 1/10
/usr/local/lib/python3.6/dist-packages/keras preprocessing/image/image data generator.py:716: UserWarning: This ImageDataGenerator speci
warnings.warn('This ImageDataGenerator specifies '
Epoch 2/10
Epoch 3/10
Epoch 4/10
Epoch 5/10
Epoch 6/10
Epoch 7/10
Epoch 8/10
13/13 [============================== - 636s 49s/step - loss: 0.4037 - acc: 0.9739 - val loss: 7.6236 - val acc: 0.4850
Epoch 9/10
Epoch 10/10
>41.000
```

Bare Image Classification

```
Epoch 8/20
Epoch 9/20
Epoch 10/20
Epoch 11/20
Epoch 12/20
Epoch 13/20
Epoch 14/20
Epoch 15/20
Epoch 16/20
Epoch 17/20
Epoch 18/20
Epoch 19/20
Epoch 20/20
>45.500
```

Creation Of Our Own Model

```
model = Sequential()
model.add(Conv2D(input shape=(200,200,3),filters=64,kernel size=(3,3),padding="same", activation="relu"))
model.add(Conv2D(filters=64,kernel size=(3,3),padding="same", activation="relu")
model.add(MaxPooling2D(pool size=(3,3),strides=(2,2)))
model.add(Conv2D(filters=128, kernel size=(3,3), padding="same", activation="relu"))
model.add(Conv2D(filters=128, kernel size=(3,3), padding="same", activation="relu"))
model.add(MaxPooling2D(pool size=(3,3),strides=(2,2)))
model.add(Conv2D(filters=256, kernel_size=(3,3), padding="same", activation="relu"))
model.add(Conv2D(filters=256, kernel size=(3,3), padding="same", activation="relu"))
model.add(Conv2D(filters=256, kernel size=(3,3), padding="same", activation="relu"))
model.add(Conv2D(filters=256, kernel size=(3,3), padding="same", activation="relu"))
model.add(MaxPooling2D(pool size=(3.3).strides=(2.2)))
model.add(Conv2D(filters=512, kernel size=(3,3), padding="same", activation="relu"))
model.add(Conv2D(filters=512, kernel size=(3,3), padding="same", activation="relu"))
model.add(Conv2D(filters=512, kernel size=(3,3), padding="same", activation="relu"))
model.add(Conv2D(filters=512,kernel size=(3,3),padding="same", activation="relu"))
model.add(MaxPooling2D(pool size=(3,3),strides=(2,2)))
model.add(Conv2D(filters=512, kernel size=(3,3), padding="same", activation="relu"))
model.add(Conv2D(filters=512, kernel size=(3,3), padding="same", activation="relu"))
model.add(Conv2D(filters=512, kernel size=(3,3), padding="same", activation="relu"))
model.add(Conv2D(filters=512,kernel size=(3,3),padding="same", activation="relu"))
model.add(MaxPooling2D(pool size=(3,3),strides=(2,2)))
model.add(Flatten())
model.add(Dense(units=1024,activation="relu"))
model.add(Dense(units=1000,activation="relu"))
model.add(Dense(units=500,activation="relu"))
model.add(Dense(units=128,activation="relu"))
model.add(Dense(units=128,activation="relu"))
model.add(Dense(units=64.activation="relu"))
model.add(Dense(units=1, activation="sigmoid"))
```

VGG19 Model With Some Additional Dense Layers

```
1 import sys
2 from matplotlib import pyplot
3 from keras.utils import to categorical
4 from keras.applications.vgg19 import VGG19
5 from keras.models import Model
6 from keras.layers import Dense
7 from keras.layers import Flatten
8 from keras.optimizers import SGD
10 model=VGG19(include top=False,input shape=(200,200,3))
11 for layer in model.layers:
    layer.trainable=False
13 flat1=Flatten()(model.layers[-1].output)
14 class1=Dense(500,activation='relu',kernel initializer="he uniform")(flat1)
15 class2=Dense(500,activation='relu',kernel initializer="he uniform")(class1)
16 class3=Dense(500,activation='relu',kernel initializer="he uniform")(class2)
17 class4=Dense(500,activation='relu',kernel initializer="he uniform")(class3)
18 output=Dense(1,activation='sigmoid')(class4)
19 model=Model(inputs=model.inputs,outputs=output)
```

Dataset

One of the most tedious parts of training an image classifier or working on any computer vision project is actually gathering the images that you'll be training your model on. So for our model there were no dataset available which were greater than 100- 200 images. So to train our model we had to collect a lot of images to get the desired accuracy. In the search of that we started scrapping images from the internet. We wrote our own code to scrap these images from individual list of links that we found on a github account. As of now we have trained our model with five thousand images giving us an accuracy of 87.29%. But we have collected a dataset of 25 thousand images and are going to train our model on that dataset. Hoping to get a better accuracy and more efficient model. This data collection was random so we also had to sort the images into nude and non-nude manually. We have animated images as well as real human images in order to cover all the bases possible.

Output of Our Model With 5604 training images

```
1 opt=SGD(lr=0.001,momentum=0.9)
2 model.compile(optimizer=opt, loss='binary crossentropy', metrics=['accuracy'])
3 model.fit(X train,Y train,validation data=(X test,Y test),batch size=128,epochs=15,verbose=1)
4 #model.save weights("weights.h5")
5 #model.save("final.h5")
Train on 5604 samples, validate on 999 samples
Epoch 1/15
5604/5604 [============== ] - 40s 7ms/step - loss: 0.6825 - acc: 0.5803 - val loss: 0.6212 - val acc: 0.7518
Epoch 2/15
Epoch 3/15
Epoch 4/15
Epoch 5/15
Epoch 6/15
Epoch 7/15
Epoch 8/15
Epoch 9/15
5604/5604 [============== ] - 38s 7ms/step - loss: 0.5239 - acc: 0.7514 - val loss: 0.5181 - val acc: 0.7708
Epoch 10/15
5604/5604 [============== ] - 38s 7ms/step - loss: 0.5199 - acc: 0.7521 - val loss: 0.4678 - val acc: 0.8078
Epoch 11/15
5604/5604 [============== ] - 38s 7ms/step - loss: 0.5038 - acc: 0.7630 - val loss: 0.4547 - val acc: 0.8438
Epoch 12/15
Epoch 13/15
Epoch 14/15
Epoch 15/15
5604/5604 [============== ] - 38s 7ms/step - loss: 0.4780 - acc: 0.7784 - val loss: 0.3424 - val acc: 0.8729
<keras.callbacks.History at 0x7f4ce2324860>
```

Output of VGG19 with 5604 training images

```
1 opt=SGD(lr=0.001,momentum=0.9)
 2 model.compile(optimizer=opt, loss='binary crossentropy', metrics=['accuracy'])
 3 model.fit(X train,Y train,validation data=(X test,Y test),batch size=128,epochs=15,verbose=1)
 4 #model.save weights("weights.h5")
 5 model.save("final.h5")
Train on 5604 samples, validate on 999 samples
Epoch 1/15
Epoch 2/15
Epoch 3/15
Epoch 4/15
Epoch 5/15
Epoch 6/15
Epoch 7/15
Epoch 8/15
Epoch 9/15
Epoch 10/15
Epoch 11/15
Epoch 12/15
Epoch 13/15
Epoch 14/15
Epoch 15/15
```

Comparison

OWN MODEL

1] It has 15 Convlotion Layers with 5 blocks

2] It has 5 MaxPooling Layers with pool size (3,3) and strides(2,2).

3] It has 7 Fully Connected Layers having: 1024 units in 1st layer,1000 units in 2nd layer,500 units in 3rd layer,128 units in 4th and 5th layer, 64 units in 6th layer and 1 unit in 7th i.e output layer.

4] Accuracy of Model with 15 epoches:87.29

VGG19 MODEL

1]It has 16 Convolution Layers with 5 blocks.

2] It has 5 MaxPooling Layers.

3] It has 5 Fully Connected Layers having: 500 units in all the 4 layers and 1 unit in 5th i.e output layer.

4]Accuracy of Model with 15 .epoches :85.39

Few of the Common Parameters

- Optimizer Used : Stochastic Gradient Descent(SGD)
- Activation Function : Sigmoid
- Learning Rate: 0.001
- Momentum: 0.9
- Batch Size: 128
- Loss: Binary Crossentropy
- Training Imgaes: 5604
- Testing Images:999
- No. of Epoches: 15

Analysis of model with different Optimizers and Activation Function

ACTIVATION FUNCTION	tahn	elu	sigmoid	hard_sigmoid	selu	softsign	softmax	softplus	relu	exponential	linear
OPTIMIZER											
SGD	81.48	67.47	87.29	79.98	79.98	43.04	20.02	79.68	79.98	60.16	79.98
RMSprop	79.98	79.98	79.98	20.02	79.98	20.02	20.02	79.98	79.98	79.98	79.98
Adagrad	20.02	79.98	20.02	79.98	79.98	79.98	20.02	79.98	79.98	20.02	79.98
Adadelta	80.68	57.26	60.96	78.18	82.98	80.48	20.02	60.76	82.08	47.65	74.17
Adam	79.98	79.98	79.98	79.98	79.98	79.98	20.02	79.98	79.98	20.02	79.98
Adamax	20.02	79.98	20.02	20.02	79.98	79.98	20.02	79.98	79.98	79.98	79.98
Nadam	79.98	79.98	79.98	79.98	79.98	79.98	20.02	79.98	79.98	79.98	79.98

Predictions

```
content/drive/My Drive/major projects/nude and non-nude/test/No444.jpg/
1.01
/content/drive/My Drive/major projects/nude and non-nude/test/Yes486.jpg
[0.9999287]
/content/drive/Mv Drive/major projects/nude and non-nude/test/No498.jpg
[2.7357288e-05]
/content/drive/My Drive/major projects/nude and non-nude/test/Yes500.jpg
[0.99979466]
/content/drive/My Drive/major projects/nude and non-nude/test/No402.jpg
[0.47208062]
<u>/content/drive/My_</u>Drive/major projects/nude and non-nude/test/No460.jpg
/content/drive/My Drive/major projects/nude and non-nude/test/No462.jpg
[0.00023309]
/content/drive/Mv Drive/major projects/nude and non-nude/test/No480.jpg
[9.990355e-081
/content/drive/My Drive/major projects/nude and non-nude/test/No458.jpg
[0.1
content/drive/My Drive/major projects/nude and non-nude/test/No484.jpg/
[0.00032475]
/content/drive/Mv Drive/major projects/nude and non-nude/test/Yes409.jpg
[0.99999991
/content/drive/My Drive/major projects/nude and non-nude/test/No428.jpg
/content/drive/My Drive/major projects/nude and non-nude/test/Yes434.jpg
[0.9999193]
<u>/content/drive/My_</u>Drive/major projects/nude and non-nude/test/Yes465.jpg
[0.96150035]
/content/drive/My Drive/major projects/nude and non-nude/test/Yes457.jpg
[0.9998764]
content/drive/My Drive/major projects/nude and non-nude/test/No447.jpg/
[1.8960392e-05]
/content/drive/My Drive/major projects/nude and non-nude/test/No419.jpg
[0.98673356]
/content/drive/My Drive/major projects/nude and non-nude/test/No442.jpg
[0.00457988]
content/drive/My Drive/major projects/nude and non-nude/test/No424.jpg/
[0.00057627]
content/drive/My Drive/major projects/nude and non-nude/test/Yes477.jpg/
[0.99999917]
```

Future Scope

To Create Google Chrome Extension Using the Trained model which will blur the Bare Skinned Images on the Webpage At RunTime as soon as the page gets loaded.

Also the hyperlink will be disabled if any with such type of images.

Thank You