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Q.2 b)
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Import numpy as npA = np.array([2, 1])

$$B = ([4, -1])$$

T = np.array([[1, 2], [2, 1]])

A_transformed = np.dot(T, A)

B_transformed = np.dot(T, B)

Extract coordinates of transformed points

X1_transformed, y1_transformed = A_transformed

X2_transformed, y2_transformed = B_transformed

M_transformed = (y2_transformed - y1_transformed) / (x2_transformed - x1_trAnsformed)

B_transformed = y1_transformed m_transformed * x1_transformed

Format the equation of the transformed line

Equation_transformed = f'y = {m_transformed} * x + {b_transformed}'

Print("Equation of transformed line: ", equation_transformed

Q.2 c)

$$X1, y1 = 0, 0$$

$$X2, y2 = 10, 10$$

Calculate midpoint

 $Midpoint_x = (x1 + x2) / 2$

 $Midpoint_y = (y1 + y2) / 2$

Print midpoint

Print("Midpoint: ({}, {})".format(midpoint_x, midpoint_y))

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Q.3 a) i)
From pulp import*
Model=LpProblem(name="Lp-Problem",sense=LpMinimize)
X=LpVariable(name='x',lowBound=0)
Y=LpVariable(name='y',lowBound=0)
Model+=(x+y>=5)
Model+=(x>=4)
Model+=(y<=2)
Model+=3.5*x+2*y
Model
Q.3 b) i)
Import numpy as np
P = np.array([4, -2])
# Reflection through y-axis
Reflection_y_axis = np.array([-1, 1]) * P
# Scaling in X-coordinates by factor 3
Scaling x = np.array([3, 1]) * P
# Scaling in Y-coordinates by factor 2.5
Scaling_y = np.array([1, 2.5]) * P
# Reflection through the line y = -x
Reflection_line = np.array([-P[1],-P[0]])
Print("Original point P:", P)
Print("Reflection through y-axis:", reflection_y_axis)
Print("Scaling in X-coordinates by factor 3:", scaling_x)
Print("Scaling in Y-coordinates by factor 2.5:", scaling_y)
Print("Reflection through the line y = -x:", reflection_line)
```